

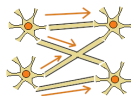
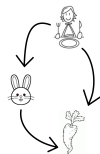
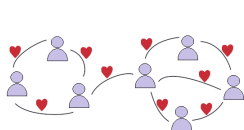
# A New Method to Build Higher-Order Representation of Graphs

Philip A. Knight and Luce le Gorrec

Mathematics and Statistics Department,  
University of Strathclyde

**Graphs:** entities (nodes) connected by relations (edges).

✓ Powerful tool to represent complex systems.



✗ Pairwise relationships: not always enough to capture key properties.

⇒ **Higher-order networks: a hot topic to circumvent this<sup>1</sup>.**

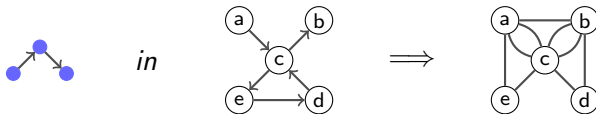
**This talk:** Two methods to build higher-order networks based on graphlets (motifs).

<sup>1</sup>Higher-order Network Analysis Takes Off, Fueled by Old Ideas and New Data, A.Benson, D.Gleich, D. Higham, SIAM News 2021.

- **Graphlet:** Small induced subgraph:



- **Higher-Order Representation:** Weighted motif adjacency matrix<sup>2</sup>:

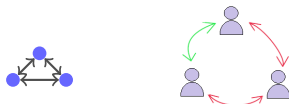


⇒ **Benson graph** (of some graphlet).

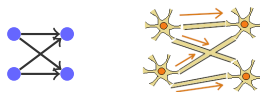
<sup>2</sup>Tools for higher-order networks analysis, A. Benson 2017.

- Graphlets express complex notions within networks:

*3-clique in friendship networks:*

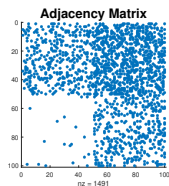
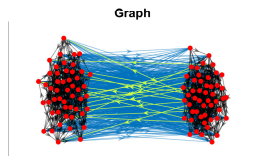


*bifan in neuronal networks:*

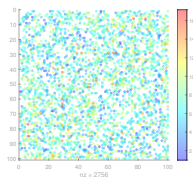
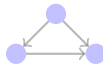


- Benson graphlet: a non-directed network that conveys this notion.

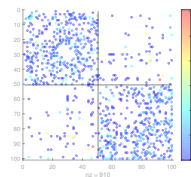
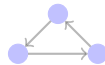
- Graphlets express complex notions within networks.
  - Benson graph: a non-directed network that conveys this notions.
- ⇒ Of particular interest for partitioning directed networks.



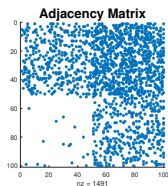
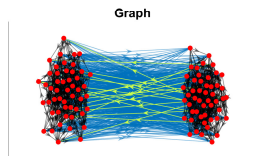
Benson graph  
of graphlet:



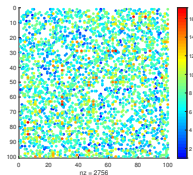
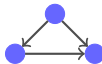
Benson Graph  
of graphlet:



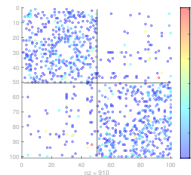
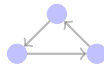
- Graphlets express complex notions within networks.
  - Benson graph: a non-directed network that conveys this notions.
- ⇒ Of particular interest for partitioning directed networks.



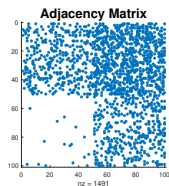
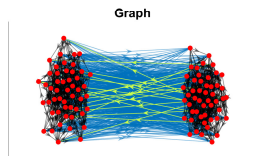
Benson graph  
of graphlet:



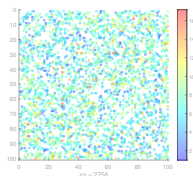
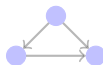
Benson Graph  
of graphlet:



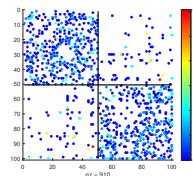
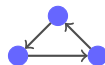
- Graphlets express complex notions within networks.
  - Benson graph: a non-directed network that conveys this notions.
- ⇒ Of particular interest for partitioning directed networks.



Benson graph  
of graphlet:



Benson Graph  
of graphlet:



Bottleneck for large networks: enumerating all graphlet instances.

- Techniques for enumerating some specific graphlets.
  - ✗ Often for undirected graphs. Adapted to directed ones to a cost.
  - ✗ Not every graphlets (triangles<sup>3,4</sup>, quadrangles and cliques<sup>4</sup>).

⇒ What if no prior knowledge about graphlets of interest?

- Techniques for counting some or all graphlets<sup>5,6</sup>.
  - ✗ Enumeration come as a byproduct (post-processing).
  - ✗ More work than needed.

## A gap to fill

We propose 2 frameworks based on linear algebra to build the Benson graphs of any 3-and-4-node graphlet.

<sup>3</sup> *Parallel Triangle Counting and Enumeration using Matrix Algebra*, A. Azad et al., 2015.

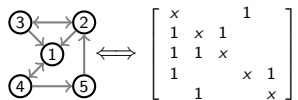
<sup>4</sup> *Arboricity and Subgraph Listing Algorithms*, N. Chiba, T. Nishizeki, 1985.

<sup>5</sup> *Efficient Detection of Network Motifs*, S. Wernicke, 2006.

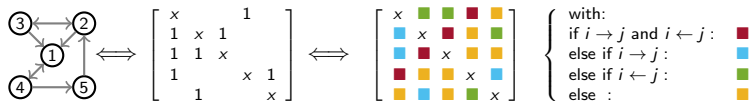
<sup>6</sup> *G-Tries: a Data Structure for Storing and Finding Subgraphs*, P. Ribeiro, F. Silva, 2014.



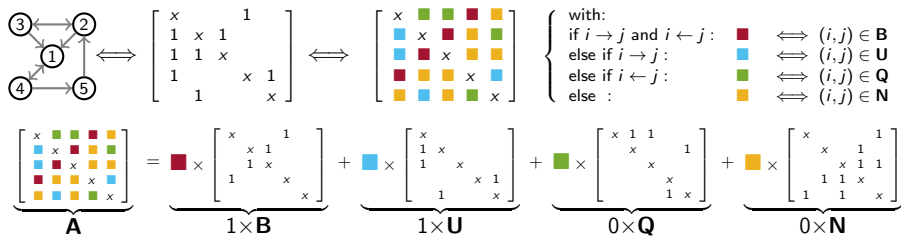
A graph  $G = (V, E) \iff$  4 “sparse” matrices that “partition  $V \times V$ ”.



A graph  $G = (V, E) \iff$  4 “sparse” matrices that “partition  $V \times V$ ”.



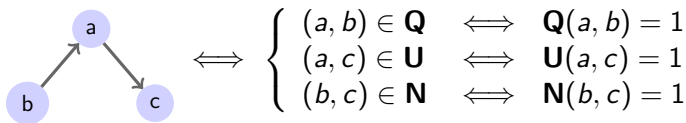
A graph  $G = (V, E) \iff$  4 “sparse” matrices that “partition  $V \times V$ ”.



A graph  $G = (V, E) \iff$  4 “sparse” matrices that “partition  $V \times V$ ”.



A  $k$ -node graphlet  $\iff$  a sequence of  $k(k-1)/2$  such matrices:



A graph  $G = (V, E) \iff$  4 “sparse” matrices that “partition  $V \times V$ ”.



A 3-node graphlet  $\mathcal{M} = (\{a, b, c\}, E_{\mathcal{M}}) \iff$

3 matrices  $\mathbf{X}, \mathbf{Y}, \mathbf{Z} \in \{\mathbf{B}, \mathbf{U}, \mathbf{Q}, \mathbf{N}\}$  such that

$$\begin{cases} (a, b) \in \mathbf{X} \\ (a, c) \in \mathbf{Y} \\ (b, c) \in \mathbf{Z} \end{cases}$$

A graph  $G = (V, E)$ , a graphlet  $\mathcal{M} = (\{a, b, \dots\}, E_{\mathcal{M}})$ :

$\mathbf{R}_{a,b} \iff$  the **Role matrix** of  $(a, b)$  in  $G$ , i.e.:

$\forall i, j \in V, \mathbf{R}_{a,b}(i, j) = \#i \text{ \& } j \text{ play jointly the role of } a \text{ \& } b, \text{ resp.}$

A graph  $G = (V, E)$ , a graphlet  $\mathcal{M} = (\{a, b, \dots\}, E_{\mathcal{M}})$ :

$\mathbf{R}_{a,b} \iff$  the **Role matrix** of  $(a, b)$  in  $G$ , i.e.:

$\forall i, j \in V, \mathbf{R}_{a,b}(i, j) = \#i \text{ \& } j \text{ play jointly the role of } a \text{ \& } b, \text{ resp.}$

If  $\mathcal{M} = (\{a, b, c\}, E_{\mathcal{M}})$  with  $\begin{cases} (a, b) \in \mathbf{X}, \\ (a, c) \in \mathbf{Y}, \\ (b, c) \in \mathbf{Z}, \end{cases}$  , then:

$$\mathbf{R}_{a,b}(i, j) = |\{u \in V : (i, j) \in \mathbf{X} \& (i, u) \in \mathbf{Y} \& (j, u) \in \mathbf{Z}\}|$$

A graph  $G = (V, E)$ , a graphlet  $\mathcal{M} = (\{a, b, \dots\}, E_{\mathcal{M}})$ :

$\mathbf{R}_{a,b} \iff$  the **Role matrix** of  $(a, b)$  in  $G$ , i.e.:

$\forall i, j \in V, \mathbf{R}_{a,b}(i, j) = \#i \text{ \& } j \text{ play jointly the role of } a \text{ \& } b, \text{ resp.}$

If  $\mathcal{M} = (\{a, b, c, d\}, E_{\mathcal{M}})$  with  $\left\{ \begin{array}{lll} (a, b) \in \mathbf{S}, & (a, c) \in \mathbf{T}, & (a, d) \in \mathbf{W} \\ (b, c) \in \mathbf{X}, & (b, d) \in \mathbf{Y}, & (c, d) \in \mathbf{Z} \end{array} \right. :$

$$\mathbf{R}_{a,b}(i, j) = \left| \left\{ u, v \in V : \begin{array}{lll} (i, j) \in \mathbf{S}, & (i, u) \in \mathbf{T}, & (i, v) \in \mathbf{W}, \\ (j, u) \in \mathbf{X}, & (j, v) \in \mathbf{Y}, & (u, v) \in \mathbf{Z} \end{array} \right\} \right|$$



A graph  $G = (V, E)$ , a graphlet  $\mathcal{M} = (\{a, b, \dots\}, E_{\mathcal{M}})$ :

$\mathbf{R}_{a,b} \iff$  the **Role matrix** of  $(a, b)$  in  $G$ , i.e.:

$\forall i, j \in V, \mathbf{R}_{a,b}(i, j) = \#i \text{ \& } j \text{ play jointly the role of } a \text{ \& } b, \text{ resp.}$

and the **Benson matrix**  $\Omega$  of  $\mathcal{M}$  in  $G$  is

$$\Omega \propto \mathbf{R}_{a,b} + \mathbf{R}_{b,a} + \mathbf{R}_{a,c} + \mathbf{R}_{c,a} + \dots$$

$\implies$  Our frameworks consist in computing these Role matrices.

Graph  $G = (V, E)$ :

Given  $\mathcal{M} = (\{a, b, c\}, E_{\mathcal{M}})$  with  $(a, b) \in \mathbf{X}, (a, c) \in \mathbf{Y}, (b, c) \in \mathbf{Z}$  :

$$\mathbf{R}_{a,b} = \mathbf{X} \circ (\mathbf{Y} \times \mathbf{Z}^T)$$

**✗ Main limitation:** When  $\mathbf{Y}$  or  $\mathbf{Z}$  is the dense matrix  $\mathbf{N}$ .

**✓ Solution:** Working with  $\overline{\mathbf{N}} = \mathbf{J} - \mathbf{N}$  instead<sup>1</sup>.

• If  $\mathbf{Y} = \mathbf{N}$  : 
$$\mathbf{R}_{a,b} = \mathbf{X} \circ (\mathbf{Y}\mathbf{Z}^T) = \mathbf{X} \circ (\underbrace{\mathbf{J}\mathbf{Z}^T}_{\text{rank1}} - \overline{\mathbf{N}}\mathbf{Z}^T).$$

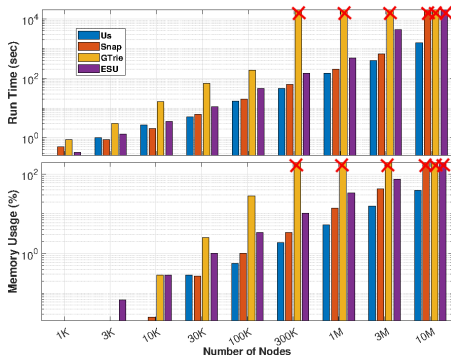
• If  $\mathbf{Z} = \mathbf{N}$  : 
$$\mathbf{R}_{a,b} = \mathbf{X} \circ (\mathbf{Y}\mathbf{Z}^T) = \mathbf{X} \circ (\underbrace{\mathbf{Y}\mathbf{J}}_{\text{rank1}} - \mathbf{Y}\overline{\mathbf{N}}).$$

NB : No more than 1 matrix among  $\mathbf{X}, \mathbf{Y}, \mathbf{Z}$  can be equal to  $\mathbf{N}$ .

---

<sup>1</sup> $\mathbf{J}$  is the matrix of 1s.

# 3-Node Graphlet Framework



**Task:** Finding all 3-node graphlet Benson Graphs on my laptop.

- All in C/C++, 8 threads.
- Us : Our framework (GraphBlas<sup>7</sup>).
- SNAP : Own // of the code from<sup>8</sup>.
- GTrie: // version of the GTrie algorithm<sup>9</sup>.
- ESU: Own implementation of <sup>10</sup>.
- X  $\iff$  Unfinished (>3hours).

$\implies$  **Our method outperforms the others**, both in terms of runtime and memory usage. SNAP is only slightly worse.

<sup>7</sup> *Parallel GraphBLAS with OpenMP*, M. Aznaveh et al., GrAPL 2019.

<sup>8</sup> *Higher-order Organization of Complex Networks.*, A. Benson et al., Science 2016.

<sup>9</sup> *Parallel subgraph counting for multicore architectures*, D. Aparicio et al., ISPA 2014.

<sup>10</sup> *Efficient Detection of Network Motifs*, S. Wernicke, 2006.

A Graph  $G = (V, E)$ :

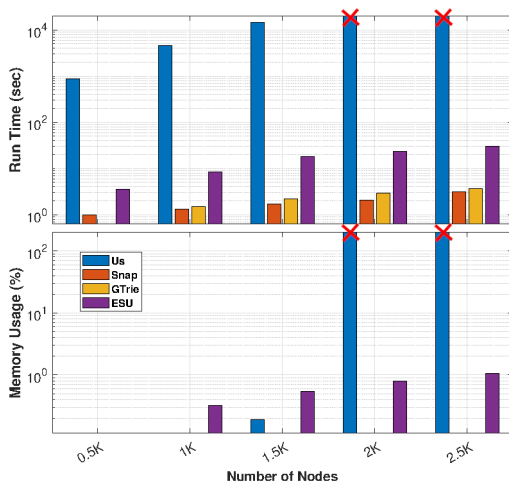
Given  $\mathcal{M} = (\{a, b, c, d\}, E_{\mathcal{M}})$  with  $\begin{cases} (a, b) \in \mathbf{S}, & (a, c) \in \mathbf{T}, & (a, d) \in \mathbf{W} \\ (b, c) \in \mathbf{X}, & (b, d) \in \mathbf{Y}, & (c, d) \in \mathbf{Z} \end{cases}$

$\mathbf{R}_{a,b} = \mathbf{S} \circ \Psi$ , with  $\Psi$  “just” a reshape of

$$\left( \begin{bmatrix} \mathbf{Y} \times \mathcal{D}(\mathbf{W}(1,:)) \\ \vdots \\ \mathbf{Y} \times \mathcal{D}(\mathbf{W}(n,:)) \end{bmatrix} \circ \begin{bmatrix} \mathbf{X} \times \mathcal{D}(\mathbf{T}(1,:)) \times \mathbf{Z} \\ \vdots \\ \mathbf{X} \times \mathcal{D}(\mathbf{T}(n,:)) \times \mathbf{Z} \end{bmatrix} \right) \times \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

which **involves**  $|V|$  **matrix-matrix products**.

# 4-Node Graphlet Framework



## Task:

- GTrie and ESU: finding all 4-node graphlets.
- Snap<sup>11</sup> and Us: finding quadrangles.

✗ Our method is extremely slow ( $\sim 10^3$ sec for a 500-node network).

Why? This version works directly with dense matrix  $\mathbf{N}$ .

⇒ Deriving tricks to avoid  $\mathbf{N}$  is a work in progress.

⇒ Good hope it will improve the perf. significantly.

<sup>11</sup> *Arboricity and Subgraph Listing Algorithms*, N. Chiba, T. Nishizeki, SIAM Journal on Computing, 1985.

- **Benson graphs improve the potential of classical networks** by conveying additional information.
- There is **a gap to fill to efficiently build these graphs**.
- We have proposed **two methods** to build them **for any 3-and-4 node graphlets**, with **no prior knowledge** about the graphlet.
- An implementation for **3-node graphlets competitive with state-of-the-art** techniques.
- Room for improvement considering 4-node graphlets.



Codes available soon on [github.com/luleg/](https://github.com/luleg/).



**Royal Academy  
of Engineering**



Thank you for your attention.  
Any question ?