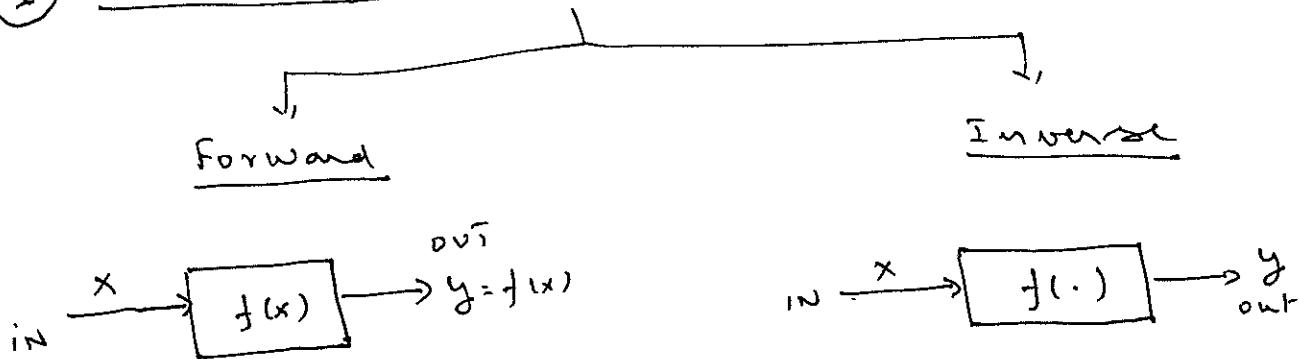


STATISTICAL LEAST SQUARESS. Lakshmi VarahanApril 30, 2022① A classification of problems:

- $f(x)$ is known
- x is given
- compute y

- x and y are given
- Identify $f(\cdot)$
- x is x -ray, y - x -ray picture
- Identify $f(\cdot)$

② Simple pendulum: $T = 2\pi \sqrt{\frac{l}{g}}$

- If l and g are given, Compute T - Forward
- If $(l_i, T_i), 1 \leq i \leq m$ given, estimate g - Inverse

③ Economics:

$$\underbrace{\text{change in}}_{\text{observe it.}} \underbrace{\text{unemployment}}_{\text{want to discover the relation}} \} = \underbrace{w_0 + w_1 * \text{change in}}_{\text{GDP}} + \text{noise}$$

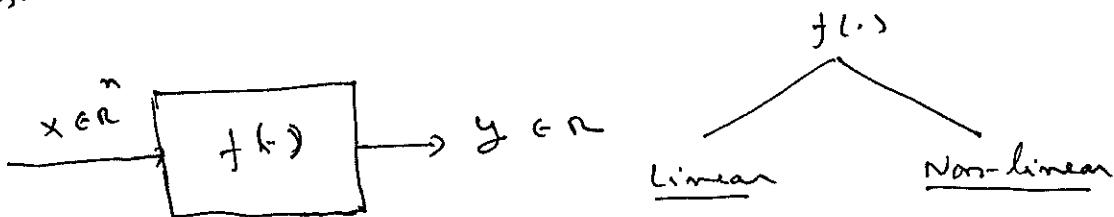
$\underbrace{\text{GDP}}_{= \text{output}}$
 \uparrow
We can observe it

(2)

① Satellite problem: Thermal energy radiated is proportional to the 4^{th} power of the temperature of the radiating surface: $E = \alpha T^4$

- Knowing E as measured by the satellite and α , estimate T .

② statistical least squares method is one of the methods for modeling that is used in solving inverse problems.



n-parametric Example 1: $y = x^T w + \eta$ & noise $\eta \sim N(0, \sigma^2)$
↑ Known

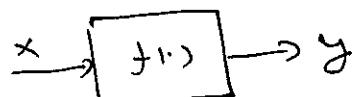
- Here y and x and properties of noise η are known. Find / Estimate w .
- Here $f(x) = x^T w$ is linear in x and w .

③ Example 2: $y = a e^{bx} + \eta$



- Here $f(x) = a e^{bx}$. It is nonlinear in the unknowns (a, b) and also nonlinear in x .

④ Example 3: $y = a_0 + a_1 x + a_2 x^2 + \eta$



- $f(x) = a_0 + a_1 x + a_2 x^2$. Nonlinear in x and linear in parameters (a_0, a_1, a_2) .

③ Linear least squares problem: (statistical)

$$\text{Let } y_i = w_0 + x_{i1}w_1 + x_{i2}w_2 \dots + \boxed{x_{in}w_n} + v_i \rightarrow ①$$

for $1 \leq i \leq m$, where assume $m > n$.

Define $y = (y_1, y_2, \dots, y_m)^T \in \mathbb{R}^m$

$$w = (w_0, w_1, \dots, w_{n-1})^T \in \mathbb{R}^n$$

$$x = \begin{bmatrix} 1 & x_{11} & x_{12} & \dots & x_{1,n-1} \\ 1 & x_{21} & x_{22} & \dots & x_{2,n-1} \\ \vdots & & & & \\ 1 & x_{m1}, x_{m2}, \dots, x_{m,n-1} \end{bmatrix} \in \mathbb{R}^{m \times n}$$

$$v = [v_1, v_2, \dots, v_m]^T \in \mathbb{R}^m$$

① becomes in matrix-vector notation:

$$y = xw + v \rightarrow ②$$

where $v \sim N(0, \sigma^2 I)$, σ^2 is known, $R = \sigma^2 I_m$

define residual

$$r(w) = y - xw \rightarrow ③$$

④ Cost function: $J: \mathbb{R}^n \rightarrow \mathbb{R}$

$$J(w) = \frac{1}{2} (y - xw)^T R^{-1} (y - xw)$$

is the weighted sum of squared residuals.

Goal is to minimize $J(w)$ w.r.t. w .

This is a multivariate minimization problem.

(4)

- Rewrite $J(w)$ by multiplying out:

$$J(w) = \frac{1}{2} [y^T R^{-1} y - y^T R^{-1} x w - (x^T w)^T R^{-1} y + \cancel{\bullet} (x^T w)^T R^{-1} (x^T w)] \rightarrow (3)$$

. Recall: $(x^T w)^T = w^T x^T$
 $\therefore (x^T w)^T R^{-1} y = w^T x^T R^{-1} y \quad \rightarrow (4)$

- Recall, if a is a scalar: $a^T = a$.

- Since $y^T R^{-1} x w$ is scalar:

$$y^T R^{-1} x w = (y^T R^{-1} x w)^T = w^T x^T R^{-1} y \rightarrow (5)$$

where since R is symmetric, so is R^{-1} and
 $(R^{-1})^T = R^{-1}$.

- using (4) and (5) in (3):

$$J(w) = \frac{1}{2} \left[\underbrace{y^T R^{-1} y}_{\text{Independent of } w} - \underbrace{2 y^T R^{-1} x w}_{\text{Linear in } w} + \underbrace{w^T (x^T R^{-1} x) w}_{\substack{\text{Quadratic in } w}} \right] \rightarrow (6)$$

[Recall: $f(w) = a^T w \Rightarrow \nabla f(w) = a \quad (a \in \mathbb{R}^n)$] (7)

$A = A^T$

$$f(w) = w^T A w \Rightarrow \nabla f(w) = 2 A w$$

. Consider the linear term: Set $a^T = y^T R^{-1} x$

$$\left. \begin{aligned} & (y^T R^{-1} x) w = a^T w \\ & \nabla [\quad] = a \end{aligned} \right\} \Rightarrow \nabla [(y^T R^{-1} x) w] = x^T R^{-1} y \rightarrow (8)$$

. Consider the quadratic term: $A = x^T R^{-1} x$
Verify $A^T = A$

$$\nabla [x^T A x] = 2Ax = 2(x^T R^{-1} x) w \rightarrow ⑦$$

Combining (7) to (9) with (6) and simplify:

$$\nabla J(w) = \frac{1}{2} [-2x^T R^{-1} y + 2x^T R^{-1} x w]$$

$$= -x^T R^{-1} [y - x w] \longrightarrow ⑩$$

Hessian of $J(w)$:-

$$\nabla^2 J(w) = (x^T R^{-1} x) \in \mathbb{R}^{n \times n} - \text{SPD}$$

Equate the gradient to zero:

$$\nabla J(w) = 0 \Rightarrow (x^T R^{-1} x) w = x^T R^{-1} y \rightarrow ⑪$$

If $R = \sigma^2 I_m$, $R^{-1} = \frac{1}{\sigma^2} I_m$ and ⑪

becomes

$$\boxed{(x^T x) w = x^T y} \longrightarrow ⑫$$

⑫ is called Normal equation. Assume $X \in \mathbb{R}^{m \times n}$ is a full rank matrix: $\text{Rank}(X) = n$. This guarantees $x^T x$ is SPD:

$$a^T (x^T x) x = (x a)^T (x a) = \|x a\|_2^2 \geq 0 \text{ with}$$

equality only if $a = 0$ since the columns of x are linearly independent.

The least square solution: \hat{w}_{LS} :

Solving (12) :

(6)

use cholesky } To solve
· QR decomp.] (13)

$$\boxed{\hat{w}_{LS} = (x^T x)^{-1} x^T y} \longrightarrow (13)$$

(4) Unbiasedness: $y = w + v$

$$\begin{aligned}\therefore \hat{w}_{LS} &= (x^T x)^{-1} x^T [w + v] \\ &= (x^T x)^{-1} (x^T x) w + (x^T x)^{-1} x^T v\end{aligned}$$

$$\therefore \boxed{\hat{w}_{LS} = w + (x^T x)^{-1} x^T v} \longrightarrow (14)$$

$$\therefore E[\hat{w}_{LS}] = w + (x^T x)^{-1} x^T E(v) = w \rightarrow (15)$$

$\therefore \hat{w}_{LS}$ is unbiased.

$$(5) \underline{\text{Covariance of } \hat{w}_{LS}} : \quad \boxed{\text{cov}(\hat{w}_{LS}) = \sigma^2 (x^T x)^{-1}}$$

$$\text{cov}(\hat{w}_{LS}) = E[(\hat{w}_{LS} - E(\hat{w}_{LS})) (\hat{w}_{LS} - E(\hat{w}_{LS}))^T] \rightarrow (16)$$

$$\text{From (14): } \hat{w}_{LS} - E(\hat{w}_{LS})$$

$$= w + (x^T x)^{-1} x^T v - w = (x^T x)^{-1} x^T v \rightarrow (17)$$

Substituting (17) in (16)

$$\text{cov}(\hat{w}_{LS}) = E[(x^T x)^{-1} x^T v (x^T x)^{-1} x^T v^T]$$

$$= E[(x^T x)^{-1} x^T (v v^T) x^T (x^T x)^{-1}]$$

$$= (x^T x)^{-1} x^T \underbrace{E(v v^T)}_{= R = \sigma^2 I_m} x^T (x^T x)^{-1}$$

$$= \sigma^2 (x^T x)^{-1} (x^T x) (x^T x)^{-1} = \sigma^2 (x^T x)^{-1} \rightarrow (18)$$

(7)

. Recall $x \in \mathbb{R}^{m \times n}$. Do an SVD of x

$$x = U \Delta^{\frac{1}{2}} V^T, \quad \begin{cases} (x^T x) v = v \Delta \\ (x^T x) u = u \Delta \end{cases} \rightarrow (19)$$

. What is the total sum of the variance of the components of \hat{w}_{LS} ? This is the $\text{tr} [\text{cov}(\hat{w}_{LS})]$

$$\text{tr} [\text{cov}(\hat{w}_{LS})] = \text{tr} [\sigma^2 (x^T x)^{-1}]$$

$$= \sigma^2 \text{tr} [(x^T x)^{-1}]$$

$$= \sigma^2 \text{tr} [v \Delta v^T]^{-1}$$

$$= \sigma^2 \text{tr} [v \Delta^{-1} v^T]$$

$$v^T v = I$$

$$= \sigma^2 \text{tr} [v^T v \Delta^{-1}]$$

$$= \sigma^2 \text{tr} [\Delta^{-1}]$$

$$= \sigma^2 \sum_{i=1}^n \frac{1}{\lambda_i} \rightarrow (20)$$

i. Consequences: The smallest eigenvalue of $(x^T x)$

determine the behavior of the total variance of the components of \hat{w}_{LS} . Thus, if the columns of x inherit collinearity property, then λ_n may be positive but very small and $\frac{1}{\lambda_n}$ can be very large.

Question: How tame the estimate \hat{w}_{LS} in this case?

$$\begin{aligned} & \text{tr}(ABC) \\ &= \text{tr}(CAB) \\ &= \text{tr}[BCA] \\ & \quad v^T = v^{-1} \end{aligned}$$

$$\lambda_1 > \lambda_2 > \dots > \lambda_n > 0$$

↑ max ↓ min

- ⑥ Estimation of σ^2 :
 We assumed σ^2 is known. If not, can be estimate σ^2 ?

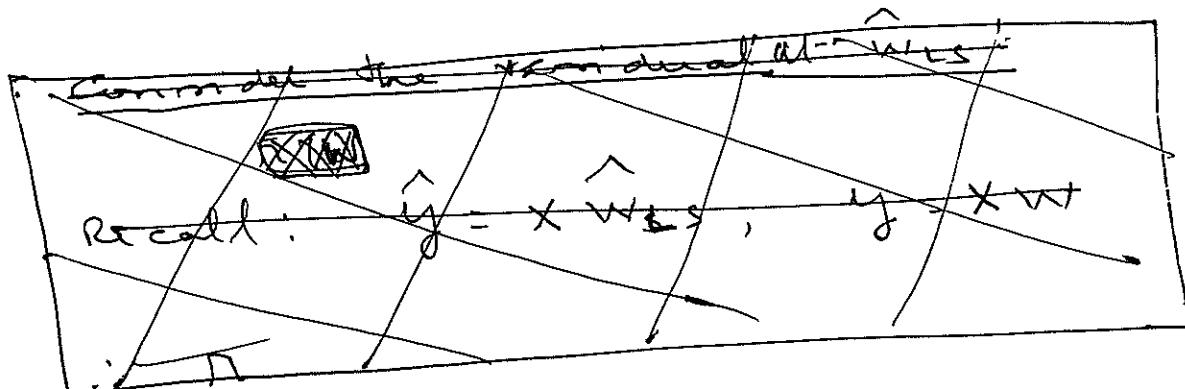
Recall $\hat{w}_{LS} = (x^\top x)^{-1} x^\top y = x^+ y \rightarrow (21)$

where $x^+ = (x^\top x)^{-1} x^\top$ is called generalized inverse of x .

- Define a new matrix

$$P = x x^+ = x (x^\top x)^{-1} x^\top$$

- Verify $P^\top = P$ and $P^2 = P \rightarrow (22)$



- Define fitted value of y given by \hat{y} :

$$\hat{y} = x \hat{w}_{LS} = x (x^\top x)^{-1} x^\top y = Py \rightarrow (23)$$

- ~~Define~~ Define error e :

$$e = y - \hat{y} = y - Py = (I - P)y \rightarrow (24)$$

- Verify $(I - P)x = x - Px = x - x(x^\top x)^{-1}(x^\top x)$
 $= x - x = 0$

$$\begin{aligned} E(e) &= E[(I - P)y] \\ &= E[(E - P)(x w + v)] \end{aligned}$$

(7)

$$\therefore e = (I - P)y = (I - P)(\cancel{w} + v)$$

$$= \underbrace{[(I - P)x]}_{=0} w + (I - P)v$$

$$= (I - P)v.$$

$$\therefore E(e) = (I - P)E(v) = 0 \Rightarrow$$

Mean of e is zero

~~Explanatory variables~~ $\rightarrow 25$

Total Variance in the Components of e :

$$\begin{aligned} E(e^T e) &= E[\{(I - P)v\}^T \{(I - P)v\}] \\ &= E[v^T (I - P)^T (I - P)v] \\ &= E[\underbrace{v^T (I - P)}_{\text{scalar}} v^T] \\ &= E[\text{tr}[v^T (I - P)v]] \end{aligned}$$

$E(vv^T) = \sigma^2 I_m$

$$= E[\text{tr}[v v^T (I - P)]]$$

$$= \text{tr}[E(vv^T) (I - P)]$$

$$= \sigma^2 \text{tr}[I_m - P]$$

$$= \sigma^2 \left[\underbrace{\text{tr}[I_m]}_{=m} - \underbrace{\text{tr}[P]}_{=n} \right]$$

$$= \sigma^2 (m - n) \rightarrow 26$$

$\text{tr}(I_m) = m$

$$\begin{aligned} P &= X(X^T X)^{-1} X^T \\ &= \text{tr}[X(X^T X)^{-1} X^T] \\ &= \text{tr}[X^T X (X^T X)^{-1}] \\ &= \text{tr}[I_n] \\ &= n \end{aligned}$$

- This suggests an estimator for σ^2 :

$$\hat{\sigma}^2 = \frac{e^T e}{(m-n)} \rightarrow 27$$

- This is an unbiased estimator of σ^2 .

- ⑦ Now to the case when x is such that $(x^T x)$ is nearly singular, or multicollinearity in x

$$\text{let } \gamma_1, \gamma_2, \gamma_3, \dots, \gamma_n > 0 \rightarrow 28$$

be the eigenvalues of $(x^T x) \in \mathbb{R}^{n \times n}$. Smaller
eigenvalue of x . Then

$$\gamma_1 > \gamma_2 > \dots > \gamma_n > 0 \rightarrow 29$$

are the singular values of x .

- $\text{Jc}(x) = \frac{\gamma_1}{\gamma_n}$ is a measure of the
collinearity: larger $\text{Jc}(x)$ more likely $(x^T x)$
is near singular.

In this case: $(x^T x) V = V \Delta V^T$, $V V^T = V^T V = I$
 $V^{-1} = V^T$

$$\Rightarrow (x^T x)^{-1} = V \Delta V^T$$

$$(x^T x)^{-1} = (V \Delta V^T)^{-1} = (V^T)^{-1} \Delta^{-1} V^{-1}$$

$$= V \Delta^{-1} V^T = \sum_{i=1}^n \frac{1}{\gamma_i} V_i V_i^T \rightarrow 30$$

- \therefore If γ_n is very small, small changes
in γ_n will reflect as big changes
in $(x^T x)^{-1}$ and hence $\hat{W}_{LS} = (x^T x)^{-1} x^T y \rightarrow 31$

- (8) One solution to reduce this sensitivity is (11)
Ridge regression:

Reformulate by changing the cost function:

$$J_R(w) = \frac{1}{2\sigma^2} (y - xw)^T (y - xw) + \frac{1}{2} \alpha \|w\|_2^2 \rightarrow (32)$$

where α is the penalty parameter.

This penalty term is called a regularization term.

$$\nabla J_R(w) = \frac{1}{2\sigma^2} [-2x^T y + 2(x^T x)w + \cancel{\alpha 2w}] \\ = 0$$

$$\Rightarrow (x^T x + \alpha I) = x^T y$$

$$\widehat{w}_{LS}^R = (x^T x + \alpha I)^{-1} x^T y \quad \begin{matrix} \leftarrow x^+ \\ \therefore x^+ = (x^T x + \alpha I)^{-1} x^T y \end{matrix} \rightarrow (33)$$

- (9) To make sense of (33) express x in SVD.

$$(x^T x) v = v \Delta \quad (x v^T) v = v \Delta, \quad x = v \Delta^{1/2} v^T$$

$$\text{From (33): } (x^T x) = v \Delta v^T, \quad v^T v = v v^T = I \rightarrow (34)$$

$$\begin{aligned} x^+ &= [v \Delta v^T + \alpha v v^T]^{-1} [v \Delta^{1/2} v^T]^T \\ &= [v (\Delta + \alpha I) v^T]^{-1} [v \Delta^{1/2} v^T]^T \\ &= v^T (\Delta + \alpha I)^{-1} \underbrace{v^T v}_{=I_m} \Delta^{1/2} v^T \end{aligned}$$

$v^T = v$
 $(AB)^{-1} = B^{-1} A^{-1}$

$$= \sqrt{(\Delta + \alpha I)^{-1}} \Delta^{-1/2} U^T = \underbrace{\text{SVD of } X^+}_{\rightarrow 35} \quad (12)$$

$$= \sqrt{D} U^T \text{ where } D = \text{diag}(d_{11}, d_{22}, \dots, d_{nn})$$

$$d_{ii} = \frac{\lambda_i^{1/2}}{\lambda_i + \alpha} \quad (1 \leq i \leq n)$$

$$\therefore x_n^+ = \sum_{i=1}^n \left(\frac{\lambda_i^{1/2}}{\lambda_i + \alpha} \right) v_i u_i^T \rightarrow (36)$$

The addition of α to λ_n stabilizes the estimate.

\hat{w}_{ls}

(10) For Comparison: Consider a special case
when columns of X are ~~orthogonal~~:

that is: $X^T X = nI$. Then

$$\hat{w}_{ls}^R = (\underline{X^T X + \alpha I})^{-1} \underline{X^T} [\underline{XW + NV}] = (\underline{X^T X + \alpha I})^{-1} [\underline{X^T XW + X^T NV}]$$

$$= (nI + \alpha I)^{-1} \cancel{nI} W + \cancel{(X^T X + \alpha I)^{-1} X^T N}$$

$$= \left(\frac{n}{\alpha + n} \right) W + \frac{\underline{X^T N}}{\alpha + n}$$

$$\therefore E[\hat{w}_{ls}^R] = \left(\frac{n}{n + \alpha} \right) W + \left(\frac{\underline{X^T N}}{n + \alpha} \right) E(N) = 0$$

$$= \left(\frac{n}{n + \alpha} \right) W \neq W \Rightarrow \underline{\text{biased}}$$

$$\begin{aligned}
 \text{cov}(\hat{w}_{LS}^R) &= \text{cov}\left(\frac{n}{n+\alpha} w + \frac{x^T v}{n+\alpha}\right) \\
 &= \text{cov}\left(\frac{x^T v}{n+\alpha}\right) \\
 &= \frac{1}{(n+\alpha)^2} E\left[(x^T v)(x^T v)^T\right] \\
 &= \frac{1}{(n+\alpha)^2} x^T \underbrace{E(vv^T)}_{=\sigma^2 I_m} x \\
 &= \frac{\sigma^2 I_m}{(n+\alpha)^2} \cancel{x^T x} = \frac{n \sigma^2}{(n+\alpha)^2} \cancel{I_m} \\
 &= \frac{n}{(n+\alpha)^2} \sigma^2 \boxed{n(x^T x)^{-1}} \\
 &= \frac{n^2 \sigma^2}{(n+\alpha)^2} (x^T x)^{-1}
 \end{aligned}$$

Recall $\text{cov}(\hat{w}_{LS}) = \sigma^2 (x^T x)^{-1}$

$$\begin{aligned}
 \therefore \text{cov}(\hat{w}_{LS}^R) &\leq \text{cov}(\hat{w}_{LS}) \\
 \text{since } \frac{n^2}{(n+\alpha)^2} \sigma^2 (x^T x)^{-1} &\leq \sigma^2 (x^T x)^{-1} \\
 \therefore \text{cov}(\hat{w}_{LS}) - \text{cov}(\hat{w}_{LS}^R) &= \\
 &= \sigma^2 (x^T x)^{-1} - \frac{n^2}{(n+\alpha)^2} \sigma^2 (x^T x)^{-1}
 \end{aligned}$$

$$= \sigma^2 (x^T x)^{-1} \left[1 - \frac{n}{(n+\alpha)^2} \right]$$

$$= \sigma^2 (x^T x)^{-1} \left[\frac{(2n+\alpha)}{(n+\alpha)^2} \right] > 0$$

(ii) Bias in $\hat{w}_{LS}^R = \frac{n}{n+\alpha}$

$$\text{Difference in Variance} = \left[1 - \frac{n}{(n+\alpha)^2} \right] > 0$$

(iii) \hat{w}_{LS}^R has lesser variance but biased.

This is called bias - covariance trade-off

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