



人工智能实验

中山大学计算机学院
人工智能
本科生实验报告
(2023学年春季学期)

课程名称：Artificial Intelligence

| | | | |
|------|----------|--------|----------------|
| 教学班级 | DCS315 | 专业（方向） | 计算机科学与技术（系统结构） |
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1 实验题目

实验五：PDDL求解实际问题

一、算法原理

- 算法原理

PDDL（Planning Domain Definition Language）是一种用于描述问题领域和规划任务的语言，它被广泛应用于人工智能规划领域。PDDL是一种领域描述语言，它描述了问题的初始状态、目标状态、动作集合以及动作之间的影响关系。PDDL的算法原理通常指的是基于PDDL描述的规划问题的求解算法。

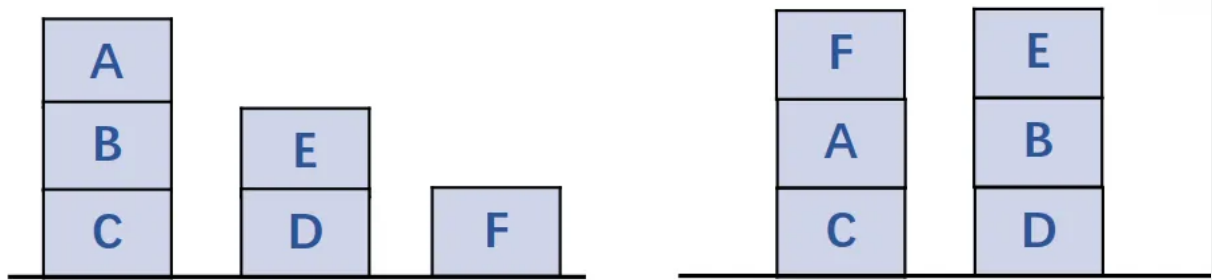
- 滑块问题

论域 (Domain) :

- 物体 (Objects) : 物体可以是任何代表实体的东西, 通常是块, 如A、B、C等。
- 动作 (Actions) : 动作是可以在块世界中执行的操作。
 - move: 移动一个块到另一个块的上方
 - moveToTable: 将一个块移动到桌面上。
- 谓词 (Predicates) : 谓词描述了块世界中的状态。
 - (ontable ?x – physob): x是否在桌面上
 - (clear ?x – physob): x上方是否清空
 - (on ?x ?y – physob): x是否在y的上方

问题定义 (Problem Definition) :

- 初始状态 (Initial State) : 初始状态描述了问题开始时块世界的状态, 包括各个物体的位置和状态。通常。
- 目标状态 (Goal State) : 目标状态描述了问题的目标, 即我们希望达到的状态。通常, 目标状态也由一系列谓词描述, 表示某些条件下块世界的期望状态。



- 15-puzzle

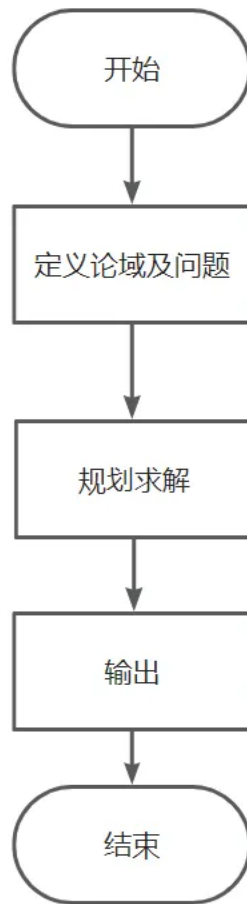
论域 (Domain) :

- 类型 (Types) : 在这个问题中, 有两种类型: 数字 (num) 和位置 (loc) 。
- 常量 (Constants) : 只有一个常量 B, 代表空白空间。
- 谓词 (Predicates) :
 - (at ?n – num ?l – loc) : 表示数字 ?n 在位置 ?l。
 - (adjacent ?l1 ?l2 – loc) : 表示位置 ?l1 和位置 ?l2 是相邻的。
- 动作 (Actions) :
 - slide: 表示将一个数字滑动到相邻的空位置上。

问题定义 (Problem Definition) :

- 问题名称 (Problem Name) : PPT1
- 论域 (Domain) : puzzle
- 对象 (Objects) :
 - num1 到 num15: 代表15个数字。
 - loc-1-1 到 loc-4-4: 代表4x4网格中的位置。
- 初始状态 (Initial State) : 描述了数字的初始位置, 以及空白空间的位置, 以及位置之间的相邻关系。
- 目标状态 (Goal State) : 描述了我们希望达到的状态, 即数字按照特定顺序排列在网格中, 而空白空间在右下角位置。

• 流程图



二、伪代码

```
1  定义 (domain blocks)
2    需求 (:strips :typing :equality
3          :universal-preconditions
4          :conditional-effects)
5    类型 (physob)
6    谓词
7      (ontable ?x - physob) ; 物体 x 在桌面上
8      (clear ?x - physob) ; 物体 x 上方没有其他物体
9      (on ?x ?y - physob) ; 物体 x 在物体 y 上方
10
11   动作 move
12     参数 (?x ?y - physob) ; 物体 x 和物体 y
13     先决条件 (and (clear ?x) (clear ?y) (not (= ?x ?y))) ; 物体 x 和物体
14     y 都是清空的, 并且它们不相同
15     效果 (and (on ?x ?y)
16               (not (clear ?y))
17               (forall (?z - physob) (when (on ?x ?z) (and (not (on ?
18 x ?z)) (clear ?z))))))
19
20   动作 moveToTable
21     参数 (?x - physob) ; 物体 x
22     先决条件 (and (clear ?x) (exists (?y - physob) (on ?x ?y))) ; 物体
23     x 是清空的, 并且存在一个物体 y, 在物体 x 下方
24     效果 (and (ontable ?x)
25               (forall (?z - physob) (when (on ?x ?z) (and (not (on ?
26 x ?z)) (clear ?z)))))) ; x在桌子上, x下面的z变成不在x下面, 并且clear
27   )
28
```

```
1  定义 (domain puzzle)
2    需求 (:strips :equality :typing)
3    类型 (num loc)
4    常量 (B - num) ; B 表示空白位置
5    谓词
6      (at ?n - num ?l - loc) ; 数字 n 在位置 l
7      (adjacent ?l1 ?l2 - loc) ; 位置 l1 和 l2 是相邻的
8
9    动作 slide
10     参数 (?n - num ?from - loc ?to - loc) ; 数字 n 从位置 from 滑动到位置
to
11     先决条件 (and (at ?n ?from) (at B ?to) (adjacent ?from ?to)) ; 数字
n 在位置 from, 空白位置在位置 to, 并且位置 from 和位置 to 是相邻的
12     效果 (and
13         (not (at ?n ?from))
14         (at ?n ?to)
15         (not (at B ?to))
16         (at B ?from)
17     )
18 )
```

三、关键代码展示

完整代码见../code, 此处只展示修改的部分

- block.pddl

```
1 (define (domain blocks)
2   (:requirements :strips :typing :equality
3                 :universal-preconditions
4                 :conditional-effects)
5   (:types physob)
6   (:predicates
7     (ontable ?x - physob)
8     (clear ?x - physob)
9     (on ?x ?y - physob))
10
11   (:action move
12     :parameters (?x ?y - physob)
13     :precondition (and (clear ?x) (clear ?y) (not (= ?x ?y)))
14     :effect (and (on ?x ?y)
15                 (not (clear ?y))
16                 (forall (?z - physob) (when (on ?x ?z) (and (
17 not (on ?x ?z)) (clear ?z))))))
17   )
18
19   (:action moveToTable
20     :parameters (?x - physob)
21     :precondition (and (clear ?x) (exists (?y - physob) (on ?x
22 ?y)))
23     :effect (and (ontable ?x)
24                 (forall (?z - physob) (when (on ?x ?z) (and (
25 not (on ?x ?z)) (clear ?z))))))
24   )
25   )
```

- puzzle.pddl

```
1 (define (domain puzzle)
2   (:requirements :strips :equality :typing)
3   (:types num loc)
4   (:constants B - num) ; B represents the empty space
5   (:predicates
6     (at ?n - num ?l - loc) ; ?n is at location ?l
7     (adjacent ?l1 ?l2 - loc) ; ?l1 and ?l2 are adjacent locations
8   )
9
10  (:action slide
11    :parameters (?n - num ?from - loc ?to - loc)
12    :precondition (and (at ?n ?from) (at B ?to) (adjacent ?from ?to))
13    :effect (and
14      (not (at ?n ?from))
15      (at ?n ?to)
16      (not (at B ?to))
17      (at B ?from)
18    )
19  )
20 )
```

- PPT1.pddl


```

1  (define (problem PPT1)
2    (:domain puzzle)
3    (:objects
4      num1 num2 num3 num4 num5 num6 num7 num8 num9 num10 num11 num12 num13 num14 num15 - num
5      loc-1-1 loc-1-2 loc-1-3 loc-1-4
6      loc-2-1 loc-2-2 loc-2-3 loc-2-4
7      loc-3-1 loc-3-2 loc-3-3 loc-3-4
8      loc-4-1 loc-4-2 loc-4-3 loc-4-4 - loc
9    )
10   (:init
11     (at num14 loc-1-1) (at num10 loc-1-2) (at num6 loc-1-3) (at B loc-1-4)
12     (at num4 loc-2-1) (at num9 loc-2-2) (at num1 loc-2-3) (at num8 loc-2-4)
13     (at num2 loc-3-1) (at num3 loc-3-2) (at num5 loc-3-3) (at num11 loc-3-4)
14     (at num12 loc-4-1) (at num13 loc-4-2) (at num7 loc-4-3) (at num15 loc-4-4)
15     ; Add adjacency relations here
16     (adjacent loc-1-1 loc-1-2) (adjacent loc-1-1 loc-2-1)
17     (adjacent loc-1-2 loc-1-1) (adjacent loc-1-2 loc-1-3) (adjacent loc-1-2 loc-2-2)
18     (adjacent loc-1-3 loc-1-2) (adjacent loc-1-3 loc-1-4) (adjacent loc-1-3 loc-2-3)
19     (adjacent loc-1-4 loc-1-3) (adjacent loc-1-4 loc-2-4)
20     (adjacent loc-2-1 loc-1-1) (adjacent loc-2-1 loc-2-2) (adjacent loc-2-1 loc-3-1)
21     (adjacent loc-2-2 loc-1-2) (adjacent loc-2-2 loc-2-1) (adjacent loc-2-2 loc-2-3) (adjacent loc-2-2 loc-3-2)
22     (adjacent loc-2-3 loc-1-3) (adjacent loc-2-3 loc-2-2) (adjacent loc-2-3 loc-2-4) (adjacent loc-2-3 loc-3-3)
23     (adjacent loc-2-4 loc-1-4) (adjacent loc-2-4 loc-2-3) (adjacent loc-2-4 loc-3-4)
24     (adjacent loc-3-1 loc-2-1) (adjacent loc-3-1 loc-3-2) (adjacent loc-3-1 loc-4-1)
25     (adjacent loc-3-2 loc-2-2) (adjacent loc-3-2 loc-3-1) (adjacent loc-3-2 loc-3-3) (adjacent loc-3-2 loc-4-2)
26     (adjacent loc-3-3 loc-2-3) (adjacent loc-3-3 loc-3-2) (adjacent loc-3-3 loc-3-4) (adjacent loc-3-3 loc-4-3)
27     (adjacent loc-3-4 loc-2-4) (adjacent loc-3-4 loc-3-3) (adjacent loc-3-4 loc-4-4)
28     (adjacent loc-4-1 loc-3-1) (adjacent loc-4-1 loc-4-2)

```

```

29      (adjacent loc-4-2 loc-3-2) (adjacent loc-4-2 loc-4-1) (adjacent l
oc-4-2 loc-4-3)
30      (adjacent loc-4-3 loc-3-3) (adjacent loc-4-3 loc-4-2) (adjacent l
oc-4-3 loc-4-4)
31      (adjacent loc-4-4 loc-3-4) (adjacent loc-4-4 loc-4-3)
32      )
33      (:goal (and
34      (at num1 loc-1-1) (at num2 loc-1-2) (at num3 loc-1-3) (at num4 lo
c-1-4)
35      (at num5 loc-2-1) (at num6 loc-2-2) (at num7 loc-2-3) (at num8 lo
c-2-4)
36      (at num9 loc-3-1) (at num10 loc-3-2) (at num11 loc-3-3) (at num12
loc-3-4)
37      (at num13 loc-4-1) (at num14 loc-4-2) (at num15 loc-4-3) (at B lo
c-4-4)
38      ))
39      )
40      ; 14 10 6 0
41      ; 4 9 1 8
42      ; 2 3 5 11
43      ; 12 13 7 15

```

四、创新点&优化

无

3 实验结果及分析

1. 实验结果展示示例（可图可表可文字，尽量可视化）

由于输出行数过多，在实验报告中只展示截图，具体数据请见/result

PDDL Overview
(a) blocks.pddl

Planner output

E5_22336216 > domains > blocks > (a) blocks.pddl > {} mov

```

1  (define (domain blocks)
2    (:requirements :strips :typing :equality
3      :universal-precondition
4      :conditional-effects)
5    Show hierarchy
6    (:types physob)
7    (:predicates
8      (ontable ?x - physob)
9      (clear ?x - physob)
10     (on ?x ?y - physob))
11
12    You, 5天前 | 1 author (You)
13    (:action move
14      :parameters (?x ?y - physob)
15      :precondition (and (clear ?x)
16        :effect (and (on ?x ?y)
17          (not (clear ?y))
18          (forall (?z - ph
19
20    You, 5天前 | 1 author (You)
21    (:action moveToTable
22      :parameters (?x - physob)
23      :precondition (and (clear ?x)
24      :effect (and (ontable ?x)
25      (forall (?z - ph

```

```

moveToTable A
  move F A
    moveToTable B
      move E C
        move B D
          move E B
            moveToTable F
              move A C
                move F A

```

physob

| | | |
|---|------|------|
| A | m... | m... |
| B | m... | m... |
| C | m... | m... |
| D | m... | |
| E | m... | m... |
| F | m... | m... |

object

physob

问题
输出
调试控制台
终端
端口
GITLENS

Planner output

```

0.00400: (MOVE B D)
0.00500: (MOVE E B)
0.00600: (MOVETOTABLE F)
0.00700: (MOVE A C)
0.00800: (MOVE F A)
Metric: 0.008
Makespan: 0.008
States evaluated: undefined
[ ] problem.pddl (1.839 sec)
Planner found 1 plan(s) in 1.839secs.

```


无