

view_frames Result

Recorded at time: 1767681455.125

map

Broadcaster: /Husky1/rovioli/rovioli
Average rate: 20.202 Hz
Most recent transform: 94.550 (1767681360.575 sec old)
Buffer length: 4.950 sec

mission

Broadcaster: /Husky1/rovioli/rovioli
Average rate: 20.202 Hz
Most recent transform: 94.550 (1767681360.575 sec old)
Buffer length: 4.950 sec

imu

imu_0_BASE

Broadcaster: /Husky1/maplab_node
Average rate: 20.202 Hz
Most recent transform: 94.550 (1767681360.575 sec old)
Buffer length: 4.950 sec

ncamera_0

Broadcaster: /Husky1/maplab_node
Average rate: 20.202 Hz
Most recent transform: 94.550 (1767681360.575 sec old)
Buffer length: 4.950 sec

camera_0.0

odometry_6dof_sensor_0

Broadcaster: /Husky1/maplab_node
Average rate: 20.202 Hz
Most recent transform: 94.550 (1767681360.575 sec old)
Buffer length: 4.950 sec

lidar_sensor_0

Broadcaster: /Husky1/maplab_node
Average rate: 20.202 Hz
Most recent transform: 94.550 (1767681360.575 sec old)
Buffer length: 4.950 sec