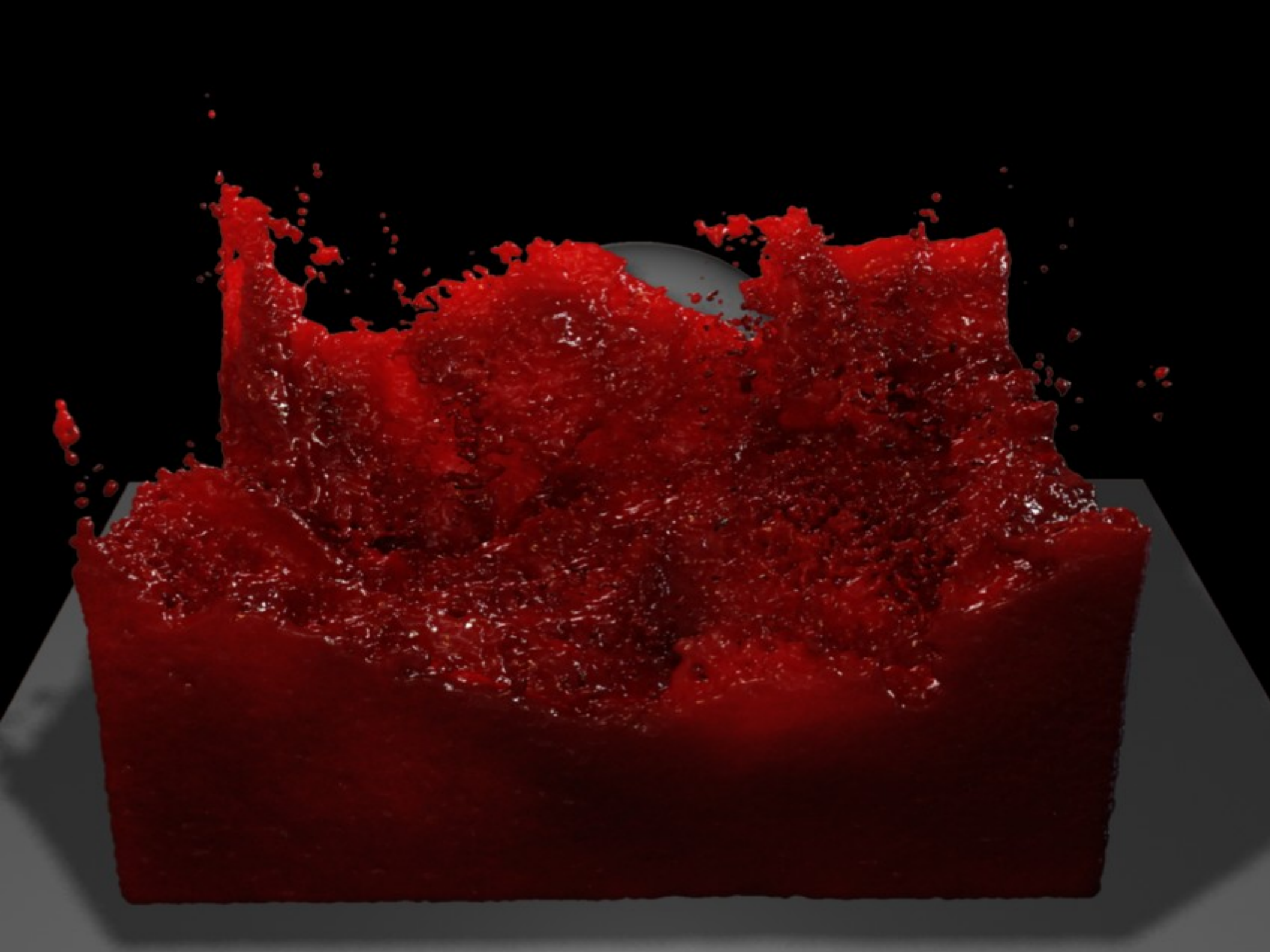


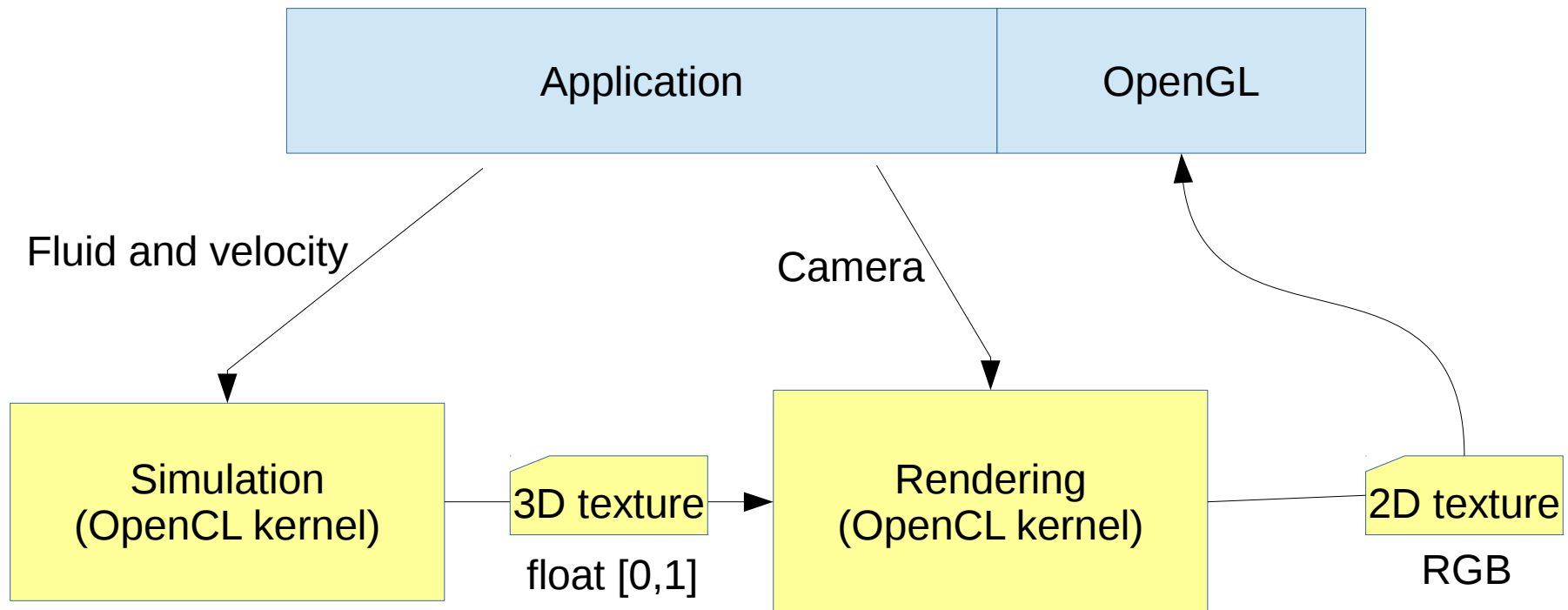
Performance auto-tuning of a fluid simulation on heterogeneous devices

Presentation 3

Olafs Vandans, s1139243

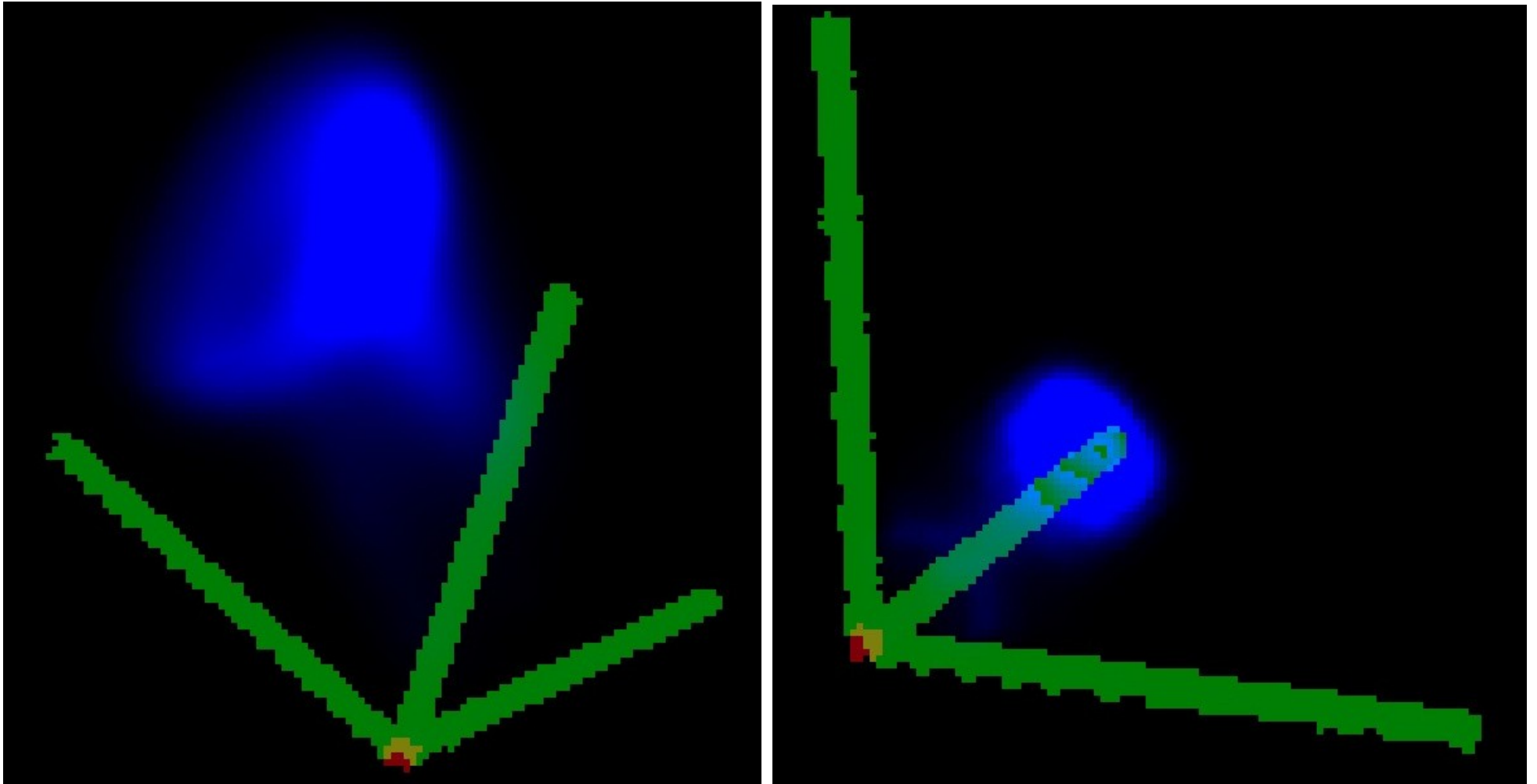


December progress



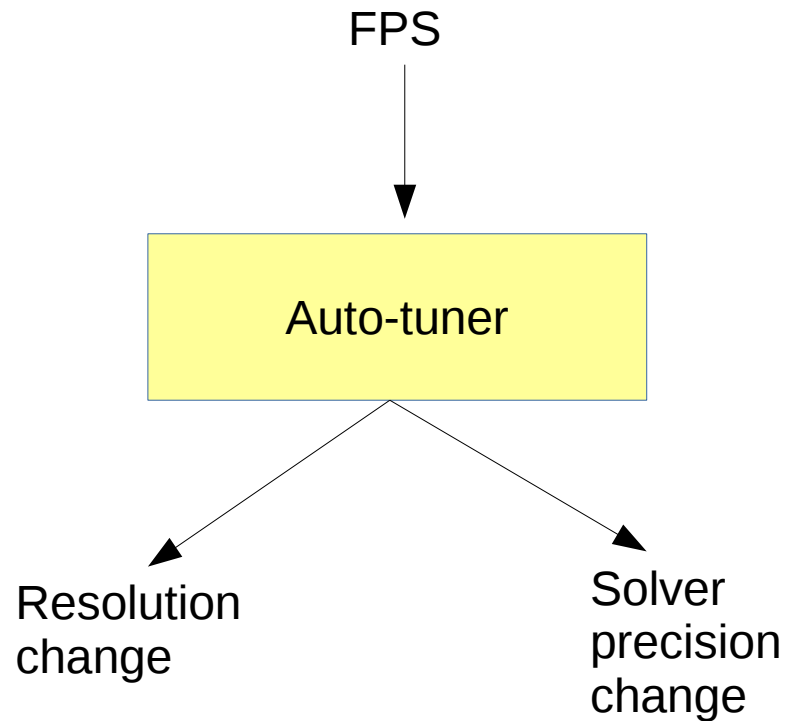
December progress

- Rendering



Current progress

- Simulation parallelised fully
- Functional auto-tuning of parameters



Parallelisation

- Each simulation step \rightarrow OpenCL kernel(s)

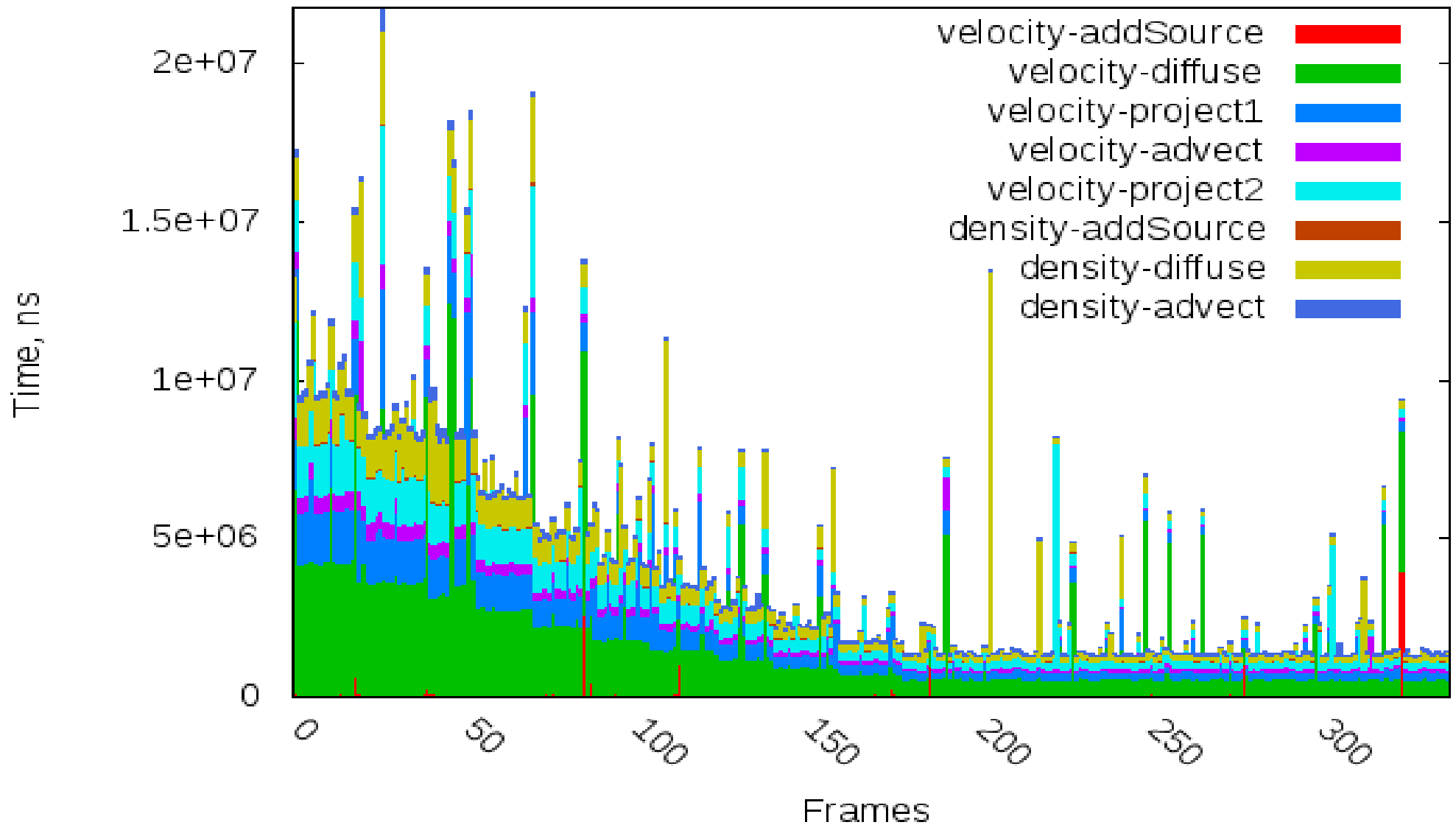
- | kernel | runtime | used in |
|-----------|-----------|-------------------------------------|
| addSource | $O(n^3)$ | density, velocity step |
| diffuse | $O(Sn^3)$ | density, velocity step |
| advect | $O(n^3)$ | density, velocity step |
| project1 | $O(n^3)$ | velocity step |
| project2 | $O(Sn^3)$ | velocity step |
| project3 | $O(n^3)$ | velocity step |
| setBound | $O(n^2)$ | advect, diffuse, project operations |

Parameter changing

- Resolution
 - 3D-resize the simulation space
 - Separate kernel
 - Fast enough not to notice
- Precision of the linear equation solvers
 - Affects diffuse and projection steps
 - Changes number of iterations

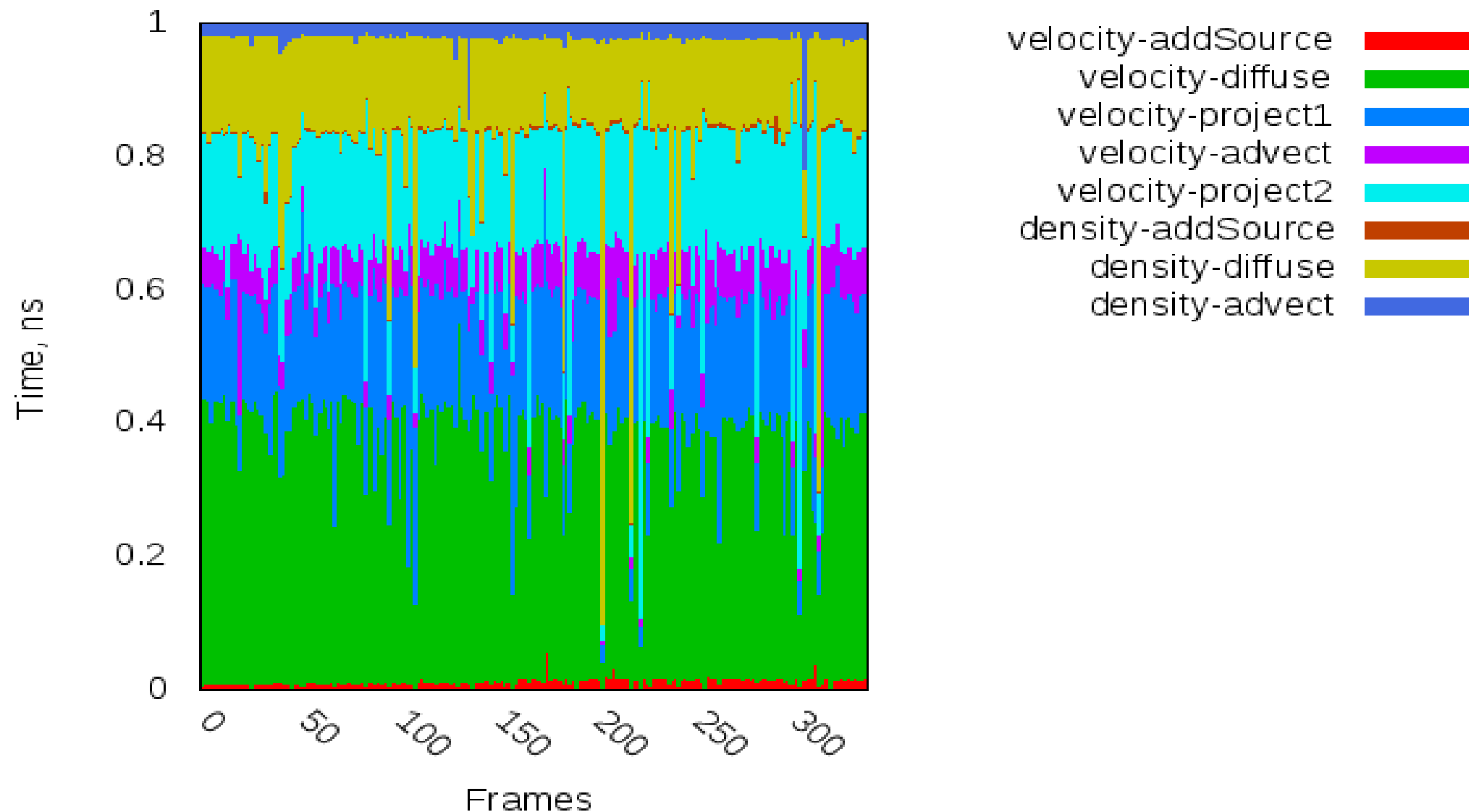
Test run - CPU

Fluid steps execution times over 338 frames
Plot as stacked histogram



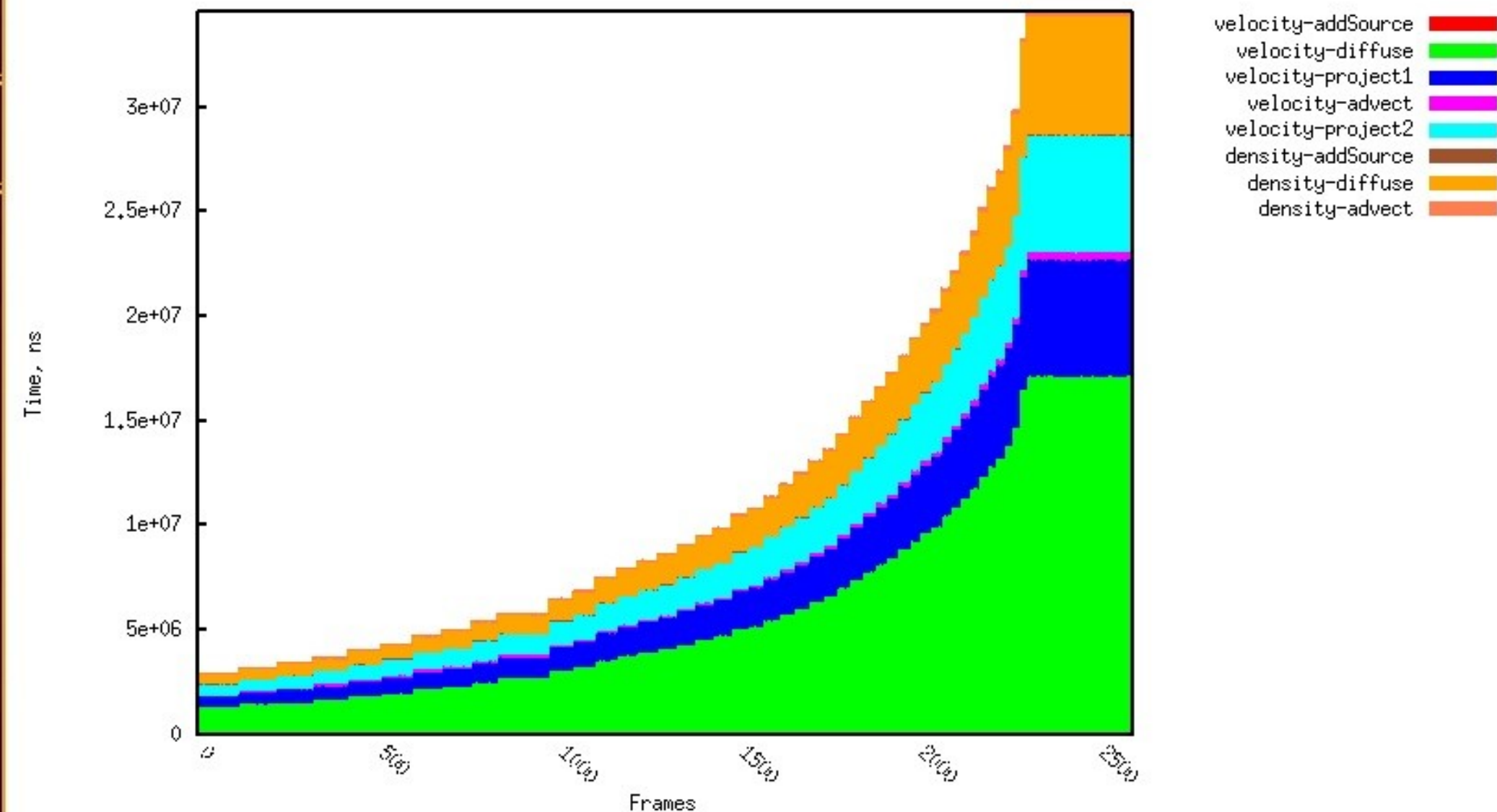
Test run - CPU

Fluid steps execution times over 338 frames
Plot as stacked histogram



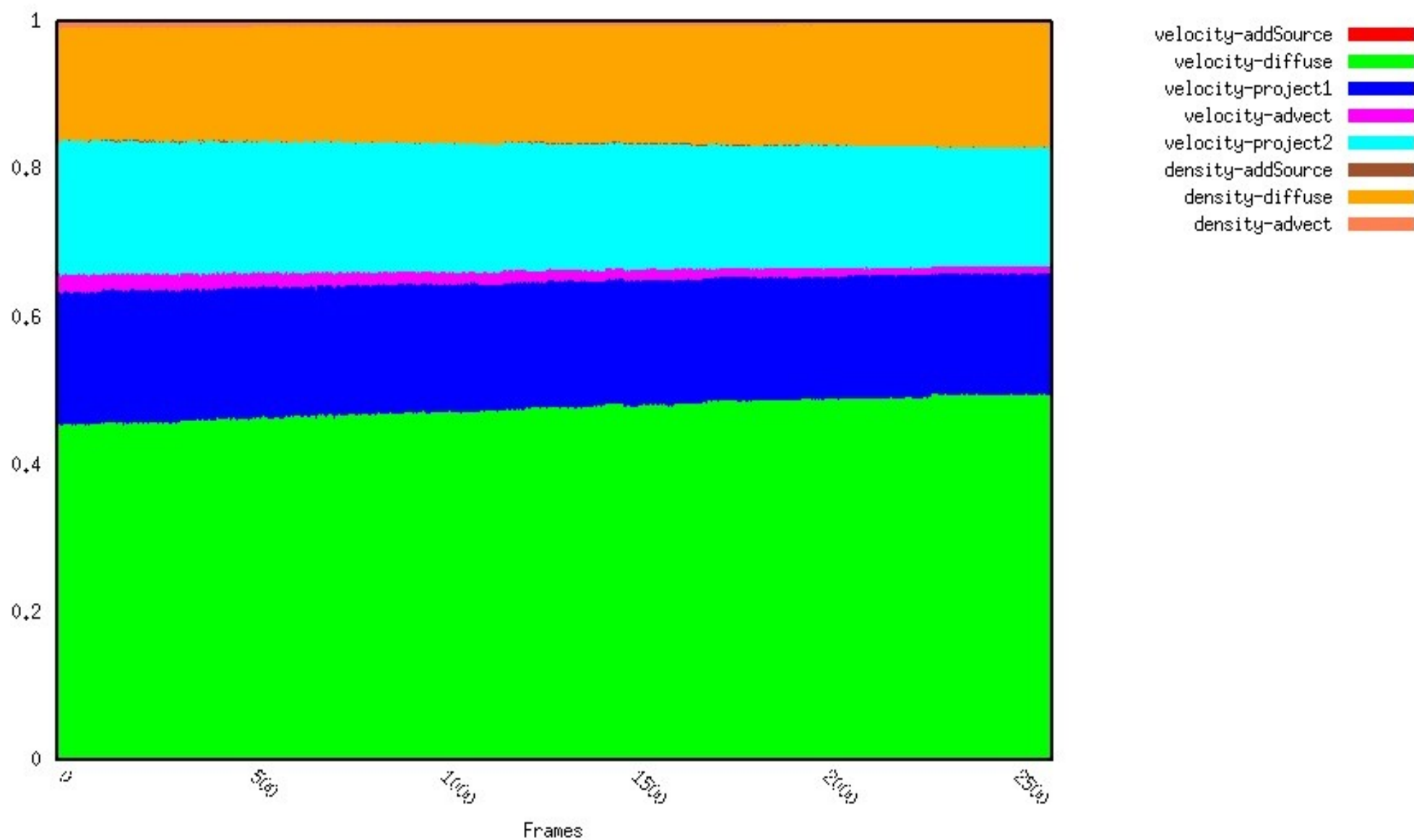
Test run - GPU

Fluid steps execution times over 2600 frames
Plot as stacked histogram

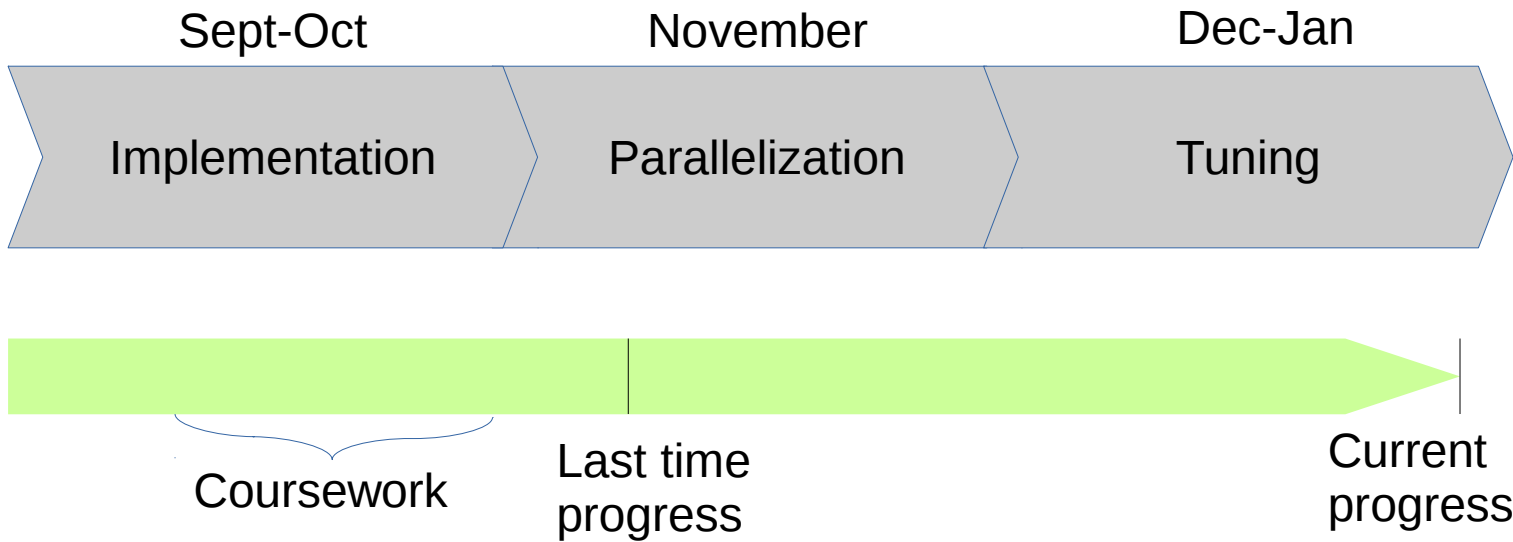


Test run - GPU

Fluid steps execution times over 2600 frames
Plot as stacked histogram



Roadmap



Things to do

- Parallel optimizations
 - Local reductions
 - Coalesced memory access
- Useful output (fire)
- Better parameter tuning - explore the impact on FPS of each parameter, devise the optimum configuration)