Nondimentionalization

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Force balance equation

The following force balance equation is considered here;

$$F_{\rm H} + F_{\rm R} = 0. \tag{1}$$

The hydrodynamic interaction is assumed to be linear form of velocities.

$$F_{\rm H} = -R \cdot U. \tag{2}$$

Representative quantities

From shear rate

Particle radius is commonly considered as the representative length in our particle simulations: $L^* = a$.

One way to give the representative particle velocity in a sheared suspension is

$$U_{\rm H}^* = a\dot{\gamma}.\tag{3}$$

The typical hydrodynamic force is given by the typical velocity $U_{\rm H}^*$ and Stokes-drag form;

$$F_{\rm H}^* = 6\pi\eta_0 a U_{\rm H}^*. \tag{4}$$

Here, we indicate nondimensionalized variables in the hydrodynamic unit by using 'tilde', i.e., $F_{\rm H} = F_{\rm H}^* \tilde{F}_{\rm H}$, etc.

From repulsive force

The repulsive force F_R is a function of particle-to-particle distance. We take the amplitude F_R^* to represent the typical strength:

$$F_{\rm R} = F_{\rm R}^* \hat{F}_{\rm R},\tag{5}$$

where 'hat' indicates nondimensionalized variables based on this repulsive force. The corresponding velocity can also be given via the Stokes-drag form;

$$U_{\rm R}^* = \frac{F_{\rm R}^*}{6\pi n_0 a}. (6)$$

Hydrodynamic (or shear-rate) unit

In the hydrodynamic unit, the nondimensionalized force balance equation is

$$\frac{\mathbf{F}_{\mathrm{H}}}{F_{\mathrm{H}}^{*}} + \frac{\mathbf{F}_{\mathrm{R}}}{F_{\mathrm{H}}^{*}} = 0 \quad \Longrightarrow \quad -\mathbf{R}' \cdot \tilde{\mathbf{U}} + \tilde{\mathbf{F}}_{\mathrm{R}} = 0 \tag{7}$$

where $\mathbf{R}' \equiv \mathbf{R}/6\pi\eta_0 a$.

In order to see the shear rate dependence, it is convenient to represent the typical repulsive force $F_{\mathbb{R}}^*$.

$$-\tilde{R}\cdot\tilde{U} + \frac{1}{\alpha}\hat{F}_{R} = 0 \tag{8}$$

This α indicates the competition between two forces:

$$\alpha \equiv \frac{F_{\rm H}^*}{F_{\rm p}^*} = \frac{\dot{\gamma}}{F_{\rm p}^*/6\pi\eta_0 a^2} \tag{9}$$

The unit of time is

$$t_{\rm H}^* \equiv \frac{L^*}{U_{\rm H}^*} = \frac{1}{\dot{\gamma}}.\tag{10}$$

Therefore, the nondenominational time \tilde{t} is shear strain (when shear rate is constant):

$$\tilde{t} = \frac{t}{t_{\text{II}}^*} = t\dot{\gamma} \tag{11}$$

The nondimensionalized shear rate is

$$\tilde{\dot{\gamma}} = \dot{\gamma} t_{\rm H}^* = 1 \tag{12}$$

[note] We call this unit system "hydrodynamic". But, the essential origin for this unit system is the way to give typical velocity, i.e., $U^* = a\dot{\gamma}$. "Simple shear" unit would be more proper name.

Repulsive force unit

In the repulsive unit, the nondimensionalized force balance equation is

$$\frac{\mathbf{F}_{H}}{F_{R}^{*}} + \frac{\mathbf{F}_{R}}{F_{R}^{*}} = 0 \quad \Longrightarrow \quad -\mathbf{R}' \cdot \hat{\mathbf{U}} + \hat{\mathbf{F}}_{R} = 0 \tag{13}$$

The time unit is

$$t_{\rm R}^* \equiv \frac{L^*}{U_{\rm R}^*} = \frac{6\pi\eta_0 a^2}{F_{\rm R}^*} \tag{14}$$

The nondimensionalized shear rate is

$$\hat{\dot{\gamma}} = \dot{\gamma} t_{\rm R}^* = \alpha \tag{15}$$

In rate controlled simulations, the relation between the nondimensionalized time $\hat{t} \equiv t/t_{\rm R}^*$ and shear strain is

$$\gamma \equiv \dot{\gamma}t = \dot{\gamma}t_{\rm R}^*\hat{t} = \frac{F_{\rm H}^*}{F_{\rm R}^*}\hat{t} = \alpha\hat{t}$$
 (16)

where α is defined in (9).

In stress controlled simulations, the strain is simply given by

$$\gamma = \int_{-t}^{t} \dot{\gamma} dt = \int_{-t}^{t} \alpha d\hat{t}. \tag{17}$$

Simulation data

Hydrodynamic (or shear-rate) unit

ND time \tilde{t} strain $\gamma = \tilde{t}$ relative viscosity $\eta_{\rm r} = 6\pi\tilde{\sigma}$ ND shear rate 1 ND stress $\tilde{\sigma}$

Repulsive force unit

ND time \hat{t} strain (rate controlled) $\gamma = \alpha \hat{t}$ relative viscosity $\eta_r = 6\pi \hat{\sigma}/\alpha$ ND shear rate $\hat{\gamma} = \alpha$ ND stress $\hat{\sigma}$