

Optimization Theory

Lecture 05

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- 1 Second-Order Characterization
- 2 Examples and Applications

1 Second-Order Characterization

2 Examples and Applications

Second-Order Characterization

Theorem (Smoothness and Convexity)

Let $f(\cdot)$ be a twice differentiable function defined on \mathbb{R}^d

- ① It is L -smooth if and only if $-L\mathbf{I} \preceq \nabla^2 f(\mathbf{x}) \preceq L\mathbf{I}$ for all $\mathbf{x} \in \mathbb{R}^d$.
- ② It is convex if and only if $\nabla^2 f(\mathbf{x}) \succeq \mathbf{0}$ for all $\mathbf{x} \in \mathbb{R}^d$.
- ③ It is μ -strongly-convex if and only if $\nabla^2 f(\mathbf{x}) \succeq \mu\mathbf{I}$ for all $\mathbf{x} \in \mathbb{R}^d$.

Sometimes, we say $f(\cdot)$ is ℓ -weakly convex if the function

$$g(\mathbf{x}) = f(\mathbf{x}) + \frac{\ell}{2} \|\mathbf{x}\|_2^2$$

is convex for some $\ell > 0$.

Theorem

Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a twice differentiable function. Suppose that $\nabla^2 f(\cdot)$ is continuous in an open neighborhood of $\mathbf{x}^* \in \mathbb{R}^d$.

① If \mathbf{x}^* is a local minimizer of $f(\cdot)$, then it holds that

$$\nabla f(\mathbf{x}^*) = \mathbf{0} \quad \text{and} \quad \nabla^2 f(\mathbf{x}^*) \succeq \mathbf{0}.$$

② If it holds that

$$\nabla f(\mathbf{x}^*) = \mathbf{0} \quad \text{and} \quad \nabla^2 f(\mathbf{x}^*) \succ \mathbf{0},$$

then the point \mathbf{x}^* is a strict local minimizer of $f(\cdot)$.

Outline

1 Second-Order Characterization

2 Examples and Applications

Examples

- ① For unconstrained quadratic problem

$$\min_{\mathbf{x} \in \mathbb{R}^d} f(\mathbf{x}) \triangleq \frac{1}{2} \mathbf{x}^\top \mathbf{A} \mathbf{x} - \mathbf{b}^\top \mathbf{x},$$

where $\mathbf{A} \in \mathbb{R}^{d \times d}$. We have $\nabla^2 f(\mathbf{x}) = \mathbf{A}$.

- ② For regularized generalized linear model

$$\min_{\mathbf{x} \in \mathbb{R}^d} f(\mathbf{x}) \triangleq \frac{1}{n} \sum_{i=1}^n \phi_i(\mathbf{a}_i^\top \mathbf{x}) + \frac{\lambda}{2} \|\mathbf{x}\|_2^2.$$

where $\phi_i : \mathbb{R}^d \rightarrow \mathbb{R}$ is twice differentiable. We have

$$\nabla f(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^n \phi'_i(\mathbf{a}_i^\top \mathbf{x}) \mathbf{a}_i + \lambda \mathbf{x}$$

and

$$\nabla^2 f(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^n \phi''_i(\mathbf{a}_i^\top \mathbf{x}) \mathbf{a}_i \mathbf{a}_i^\top + \lambda \mathbf{I}.$$

Applications in Matrix Approximation

Given a symmetric positive-definite matrix $\mathbf{K} \in \mathbb{R}^{d \times d}$ and we sample a subset of columns $\mathbf{C} \in \mathbb{R}^{d \times m}$, where $m < d$.

We want to establish the estimator of \mathbf{K} by the formulation

$$\min_{\mathbf{U} \in \mathbb{R}^{m \times m}, \delta \in \mathbb{R}} f(\mathbf{U}, \delta) \triangleq \left\| \mathbf{K} - (\mathbf{CUC}^\top + \delta \mathbf{I}_d) \right\|_F^2.$$

It has global solution

$$\mathbf{U}^{\text{ss}} = \mathbf{C}^\dagger \mathbf{K} (\mathbf{C}^\dagger)^\top - \delta^{\text{ss}} (\mathbf{C}^\top \mathbf{C})^\dagger$$

and

$$\delta^{\text{ss}} = \frac{1}{d - m} \left(\text{tr}(\mathbf{K}) - \text{tr}(\mathbf{C}^\dagger \mathbf{K} \mathbf{C}) \right).$$

Applications in Matrix Approximation

We can show that

$$\mathbf{C}\mathbf{U}^{\text{ss}}\mathbf{C}^\top + \delta^{\text{ss}}\mathbf{I}_d \succ \mathbf{0}$$

and

$$\begin{aligned} & (\mathbf{Q}\mathbf{U}^{\text{ss}}\mathbf{Q}^\top + \delta^{\text{ss}}\mathbf{I}_d)^{-1} \\ &= (\delta^{\text{ss}})^{-1}\mathbf{I}_n - (\delta^{\text{ss}})^{-2}\mathbf{Q}(\mathbf{I}_m + (\delta^{\text{ss}})^{-1}\mathbf{U}^{\text{ss}})^{-1}\mathbf{U}^{\text{ss}}\mathbf{Q}^\top. \end{aligned}$$

is well-defined, where $\mathbf{Q} \in \mathbb{R}^{d \times m}$ is the orthogonal basis of $\mathbf{C} \in \mathbb{R}^{d \times m}$.