# **Optimization Theory**

Lecture 03

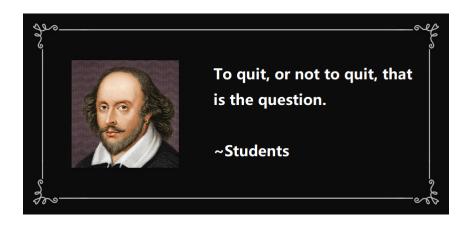
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- Convex Set
- 2 Convex Function
- Optimal Condition
- Subgradient and Subdifferential

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- 4 Subgradient and Subdifferential

### Convex Analysis



You can make the decision after the sections of convex analysis.

### Convex Set

We say a set  $C \subseteq \mathbb{R}^n$  is convex if for all  $\mathbf{x}, \mathbf{y} \in C$  and  $\alpha \in [0, 1]$ , it holds that

$$\alpha \mathbf{x} + (1 - \alpha)\mathbf{y} \in \mathcal{C}.$$

Geometrically, a set  $\mathcal C$  is convex means that the line-segment connecting any two points in  $\mathcal C$  also belongs to  $\mathcal C$ .

Given any collection of convex sets (finite, countable or uncountable), their intersection is itself a convex set.

### Projection

Given a closed and convex set  $\mathcal{C} \subseteq \mathbb{R}^n$  and any point  $\mathbf{y} \in \mathbb{R}^d$ , we define the projection of  $\mathbf{y}$  onto  $\mathcal{C}$  in Euclidean norm as the point in  $\mathcal{C}$  that is closest to  $\mathbf{y}$  as

$$\mathrm{proj}_{\mathcal{C}}(\boldsymbol{y}) = \mathop{\text{arg\,min}}_{\boldsymbol{x} \in \mathcal{C}} \|\boldsymbol{y} - \boldsymbol{x}\|_2^2 \,.$$

### Projection

Some properties of the projection:

- **1** The projection  $\operatorname{proj}_{\mathcal{C}}(\mathbf{y})$  exists and is uniquely defined.
- ② If  $\mathbf{y} \not\in \mathcal{C}$ , then  $\mathbf{z} = \mathrm{proj}_{\mathcal{C}}(\mathbf{y})$  lies on the boundary of  $\mathcal{C}$  and the hyperplane

$$\{\mathbf{x}: \langle \mathbf{y} - \mathbf{z}, \mathbf{x} - \mathbf{z} \rangle = 0\}$$

separates  ${\bf y}$  and  ${\cal C}$  in that they lie on different sides, that is

$$\langle \textbf{y}-\textbf{z},\textbf{y}-\textbf{z}\rangle>0\quad\text{and}\quad \langle \textbf{y}-\textbf{z},\textbf{x}-\textbf{z}\rangle\leq 0$$

for any  $\mathbf{x} \in \mathcal{C}$ . It implies

$$\|\mathbf{x} - \mathbf{z}\|_2^2 < \|\mathbf{x} - \mathbf{y}\|_2^2$$

for any  $\mathbf{x} \in \mathcal{C}$ .

- Convex Set
- 2 Convex Function
- Optimal Condition
- 4 Subgradient and Subdifferential

#### Convex Function

A function  $f: \mathcal{C} \to \mathbb{R}$ , defined on a convex set  $\mathcal{C}$ , is convex if it holds

$$f(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \le \alpha f(\mathbf{x}) + (1 - \alpha)f(\mathbf{y})$$

for all  $\mathbf{x}, \mathbf{y} \in \mathcal{C}$  and  $\alpha \in [0, 1]$ .

## **Epigraph**

The epigraph of a function  $f: \mathcal{C} \to \mathbb{R}$  is defined as the set

epi 
$$f \triangleq \{(\mathbf{x}, u) \in \mathcal{C} \times \mathbb{R} : f(\mathbf{x}) \leq u\}.$$

We say a function  $f(\mathbf{x})$  is closed if its epigraph is closed.

#### Theorem

A function f(x) is convex if and only if its epigraph is a convex set.

# Extended Arithmetic Operations

We shall define convex function with possibly infinite values, which leads to arithmetic calculations involving  $+\infty$  and  $-\infty$ :

• 
$$-(-\infty) = +\infty$$

• 
$$\alpha \pm (+\infty) = (+\infty) \pm \alpha = +\infty$$
 for  $\alpha \in \mathbb{R}$ ,

• 
$$\alpha \pm (-\infty) = (-\infty) \pm \alpha = -\infty$$
 for  $\alpha \in \mathbb{R}$ ,

• 
$$\alpha \cdot (\pm \infty) = (\pm \infty) \cdot \alpha = \pm \infty$$
 for  $\alpha \in (0, +\infty)$ 

• 
$$\alpha \cdot (\pm \infty) = (\pm \infty) \cdot \alpha = \mp \infty$$
 for  $\alpha \in (-\infty, 0)$ 

• 
$$\alpha/(\pm\infty) = 0$$
 for  $\alpha \in (-\infty, +\infty)$ 

• 
$$(\pm \infty)/\alpha = \pm \infty$$
 for  $\alpha \in (0, +\infty)$ 

• 
$$(\pm \infty)/\alpha = \mp \infty$$
 for  $\alpha \in (-\infty, 0)$ 

• 
$$\inf \emptyset = +\infty$$
,  $\sup \emptyset = -\infty$ 

The extended real number system  $\overline{\mathbb{R}}$ , defined as

$$[-\infty, +\infty]$$
 or  $\mathbb{R} \cup \{-\infty, +\infty\}$ .

$$\mathbb{R}\cup\{-\infty,+\infty\}$$
 .

## **Extended Arithmetic Operations**

The expressions

$$(+\infty)-(+\infty)$$
,  $(-\infty)+(+\infty)$ ,  $\frac{+\infty}{-\infty}$  and  $\frac{-\infty}{+\infty}$ .

are undefined and are avoided.

In the context of convex analysis, we also define

$$0 \cdot \infty = \infty \cdot 0 = 0$$
 and  $0 \cdot (-\infty) = (-\infty) \cdot 0 = 0$ .

# **Proper Convex Function**

One may extend a convex function with domain  $\mathcal{C} \subset \mathbb{R}^d$  to a proper convex function

$$f_{\mathcal{C}}(\mathbf{x}) = \begin{cases} f(\mathbf{x}), & \text{if } \mathbf{x} \in \mathcal{C}, \\ +\infty, & \text{if } \mathbf{x} \notin \mathcal{C}. \end{cases}$$

We define

$$\operatorname{dom} f \triangleq \{\mathbf{x} : f(\mathbf{x}) < +\infty\}.$$

We say a convex function is proper if its domain is non-empty and its values are all larger than  $-\infty$ .

We say a function  $f(\mathbf{x})$  on  $\mathbb{R}^d$  is concave if  $-f(\mathbf{x})$  is convex. Linear functions are both convex and concave.

#### Convex Function

#### Some properties of convex function:

- Given any  $\mathbf{g}: \mathbb{R}^d \to \mathbb{R}^k$  such that each component  $g_j(\mathbf{x})$  is convex, then the set  $\mathcal{C} = \{\mathbf{x}: \mathbf{g}(\mathbf{x}) \leq \mathbf{0}\}$  is convex.
- The supremum over a family of convex functions is convex.
- The positively weighted sum of convex functions is convex.
- The partial infimum of a convex function is convex.
- The composition of convex functions may not preserve convexity.

#### Indicator Function

Given a closed convex set  $C \in \mathbb{R}^d$ , we can define a convex function  $\mathbb{1}_C(\mathbf{x})$  on  $\mathbb{R}^d$ , called the indicator function of C on  $\mathbb{R}^d$ , as

$$\mathbb{1}_{\mathcal{C}}(\mathbf{x}) \triangleq \begin{cases} 0, & \text{if } \mathbf{x} \in \mathcal{C}, \\ +\infty, & \text{if } \mathbf{x} \not\in \mathcal{C}. \end{cases}$$

We may write  $f_{\mathcal{C}}(\mathbf{x}) = f(\mathbf{x}) + \mathbb{1}_{\mathcal{C}}(\mathbf{x})$  and the problem

$$\min_{\mathbf{x} \in \mathcal{C}} f(\mathbf{x})$$

is equivalent to

$$\min_{\mathbf{x} \in \mathbb{R}^d} f_{\mathcal{C}}(\mathbf{x}) = f(\mathbf{x}) + \mathbb{1}_{\mathcal{C}}(\mathbf{x}).$$

#### **Closed Convex Function**

We shall focus on closed functions in convex optimization.

- All convex functions can be made closed by taking the closure of its epigraph.
- In some pessimistic case, a closed convex function may not be continuous at the boundary of its domain. Consider the function

$$f(x,y) = \begin{cases} \frac{x^2}{y}, & (x,y) \neq (0,0) \\ 0, & (x,y) = (0,0) \end{cases}$$

with domain  $\{(x,y): y>0\} \cup \{(0,0)\}.$ 

We focus on only consider problems where the optimal solution can be achieved at a point that is continuous.

- Convex Set
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- 4 Subgradient and Subdifferential

### Convex Optimization

Why do we love convex optimization?

#### Theorem

Let  $f(\mathbf{x})$  be a convex function defined on a convex set  $\mathcal{C}$  and  $\mathbf{x}^*$  be a local solution of

$$\min_{\mathbf{x} \in \mathcal{C}} f(\mathbf{x}). \tag{1}$$

That is, there exist some  $\delta > 0$  such that any  $\hat{\mathbf{x}} \in \mathcal{B}_{\delta}(\mathbf{x}^*) \cap \mathcal{C}$  holds

$$f(\mathbf{x}^*) \leq f(\hat{\mathbf{x}}).$$

Then the local solution  $\mathbf{x}^*$  is a global solution of problem (1).

### First-Order Condition

#### **Theorem**

If a function f is differentiable on open set  $\mathcal{C}$ , then it is convex on  $\mathcal{C}$  if and only if

$$f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle$$

hols for any  $\mathbf{x}, \mathbf{y} \in \mathcal{C}$ .

However, the gradient may not exist in general case.

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# Subgradient and Subdifferential

We say a vector  $\mathbf{g} \in \mathbb{R}^d$  is a subgradient of a proper convex function  $f : \mathbb{R}^d \to \mathbb{R}$  at  $\mathbf{x} \in \text{dom } f$  if

$$f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \mathbf{g}, \mathbf{y} - \mathbf{x} \rangle$$

holds for any  $\mathbf{y} \in \mathbb{R}^d$ .

The set of subgradients at  $\mathbf{x} \in \text{dom } f$  is called the subdifferential of f at  $\mathbf{x}$ , defined as

$$\partial f(\mathbf{x}) \triangleq \big\{\mathbf{g} \in \mathbb{R}^d : f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \mathbf{g}, \mathbf{y} - \mathbf{x} \rangle \text{ holds for any } \mathbf{y} \in \mathbb{R}^d \big\}.$$

# **Examples of Subdifferential**

**1** The subdifferential of f(x) = |x| at 0 is the set

$$\partial f(x) = [-1, 1].$$

What about the general norm?

② The subdifferential of an indicator function  $\mathbb{1}_{\mathcal{C}}(\mathbf{x})$  is

$$\partial \mathbb{1}_{\mathcal{C}}(\mathbf{x}) = \mathcal{N}_{\mathcal{C}}(\mathbf{x}),$$

where

$$\mathcal{N}_{\mathcal{C}}(\mathbf{x}) = \left\{ \mathbf{g} \in \mathbb{R}^d : \langle \mathbf{g}, \mathbf{y} - \mathbf{x} \rangle \leq 0 \text{ for all } \mathbf{y} \in \mathcal{C} 
ight\}$$

is called the normal cone of C at  $\mathbf{x}$ .

 $\odot$  If a convex function f is differentiable at  $\mathbf{x}$ , then

$$\partial f(\mathbf{x}) = \{\nabla f(\mathbf{x})\}.$$