

§4.2. 初边值问题 — 分离变量法

$$\begin{cases} \partial_t^2 u - \partial_x^2 u = f(x, t) \\ u(x, 0) = \varphi(x), \partial_t u(x, 0) = \psi(x) \\ u(0, t) = g_1(t), u(L, t) = g_2(t) \end{cases}$$

$$0 \leq x \leq L, t \geq 0$$

$$\star \begin{cases} g_1(t) \equiv g_2(t) \equiv 0, f(x, t) \equiv 0 \\ -\partial_x^2 u(0) = 0, u(L) = 0 \end{cases}$$

$$-\partial_x^2 u(0) = 0, u(L) = 0$$

将(*)代入

$$\begin{cases} \partial_t^2 u - \partial_x^2 u = 0 \\ u(x, 0) = \varphi(x), \partial_t u(x, 0) = \psi(x) \\ u(0, t) = 0, u(L, t) = 0 \end{cases} \Rightarrow \begin{cases} \sum_{n=1}^{\infty} T_n''(t) X_n(x) - \sum_{n=1}^{\infty} T_n(t) X_n''(x) = 0 \\ \sum_{n=1}^{\infty} T_n(0) X_n(x) = \varphi(x), \sum_{n=1}^{\infty} T_n'(0) X_n(x) = \psi(x) \end{cases}$$

由 Sturm-Liouville $\{X_n(x)\}_{n=1}^{\infty}$ 特征函数

构成 $L^2([0, L])$ 中的完备正交基

$$u(x, t) = \sum_{n=1}^{\infty} T_n(t) X_n(x) \quad (*)$$

$$\begin{cases} -X_n''(x) = \lambda_n X_n(x) \\ X_n(0) = 0, X_n(L) = 0 \end{cases}$$

$$\begin{cases} \sum_{n=1}^{\infty} (T_n''(t) X_n(x) + \lambda_n T_n(t) X_n(x)) = 0 \\ \sum_{n=1}^{\infty} T_n(0) X_n(x) = \varphi(x) \\ \sum_{n=1}^{\infty} T_n'(0) X_n(x) = \psi(x) \end{cases}$$

$$\Rightarrow \begin{cases} T_n''(t) + \lambda_n T_n(t) = 0 \\ T_n(0) = \frac{\int_0^L \varphi(x) X_n(x) dx}{\int_0^L X_n^2(x) dx} \\ T_n'(0) = \frac{\int_0^L \psi(x) X_n(x) dx}{\int_0^L X_n^2(x) dx} \end{cases}$$

$$(f, g) = \int_0^L f(x) g(x) dx$$

$$\sum_{n=1}^{\infty} (T_n''(t) X_n(x) + \lambda_n T_n(t) X_n(x), X_{n_0}(x)) = 0$$

$$\Rightarrow T_{n_0}''(t) (X_{n_0}, X_{n_0}) + \lambda_{n_0} T_{n_0}(t) (X_{n_0}, X_{n_0}) = 0$$

$$\Rightarrow T_{n_0}''(t) + \lambda_{n_0} T_{n_0}(t) = 0$$

$$T_{n_0}(0) (X_{n_0}, X_{n_0}) = (\varphi, X_{n_0})$$

Step 1. $\frac{\partial}{\partial t} u(x,t) = T(t)X(x)$. R.I.

$$\begin{cases} T''(t)X(x) - T(t)X''(x) = 0 \\ T(t)X(0) = 0, T(t)X(L) = 0 \end{cases}$$

$$\begin{cases} \frac{T''(t)}{T(t)} = \frac{X''(x)}{X(x)} \triangleq -\lambda \\ X(0) = 0, X(L) = 0 \end{cases}$$

$$\Rightarrow \begin{cases} X''(x) + \lambda X(x) = 0 \\ X(0) = 0, X(L) = 0 \end{cases}$$

$$\begin{aligned} \frac{+}{-} \lambda < 0, X(x) &= C_1 e^{\sqrt{-\lambda}x} + C_2 e^{-\sqrt{-\lambda}x} \\ \begin{cases} X(0) = C_1 + C_2 = 0 \\ X(L) = C_1 e^{\sqrt{-\lambda}L} + C_2 e^{-\sqrt{-\lambda}L} = 0 \end{cases} &\Rightarrow C_1 = C_2 = 0 \end{aligned}$$

$$\begin{aligned} \frac{+}{-} \lambda = 0, \text{ R.I. } X(x) &= C_1 x + C_2 \quad X(0) = C_2 = 0 \\ X(L) = C_1 L = 0 &\Rightarrow C_1 = 0 \end{aligned}$$

$$\frac{+}{-} \lambda > 0, X(x) = C_1 \cos(\sqrt{\lambda}x) + C_2 \sin(\sqrt{\lambda}x)$$

$$X(0) = C_1 = 0$$

$$X(L) = C_2 \sin(\sqrt{\lambda}L) = 0$$

$$\Rightarrow \sqrt{\lambda}L = n\pi, n=1,2,\dots$$

$$\Rightarrow \lambda_n = \left(\frac{n\pi}{L}\right)^2$$

$$X_n(x) = \sin\left(\frac{n\pi}{L}x\right), n=1,2,\dots$$

Step 2. $\varphi_n = \frac{2}{L} \int_0^L \varphi(x) \sin\left(\frac{n\pi}{L}x\right) dx$,

$$\psi_n = \frac{2}{L} \int_0^L \psi(x) \sin\left(\frac{n\pi}{L}x\right) dx$$

R.I. $\begin{cases} T_n''(t) + \left(\frac{n\pi}{L}\right)^2 T_n(t) = 0 \\ T_n(0) = \varphi_n, T_n'(0) = \psi_n \end{cases}$

$$\frac{\partial}{\partial t} T_n(t) = A_n \cos\left(\frac{n\pi}{L}t\right) + B_n \sin\left(\frac{n\pi}{L}t\right)$$

R.I. $T_n(0) = A_n = \varphi_n, T_n'(0) = \frac{n\pi}{L} B_n = \psi_n$

$$\Rightarrow T_n(t) = \varphi_n \cos\left(\frac{n\pi}{L}t\right) + \frac{L}{n\pi} \psi_n \sin\left(\frac{n\pi}{L}t\right)$$

$$u(x,t) = \sum_{n=1}^{\infty} \left(\varphi_n \cos\left(\frac{n\pi}{L}t\right) + \frac{L}{n\pi} \psi_n \sin\left(\frac{n\pi}{L}t\right) \right) \sin\left(\frac{n\pi}{L}x\right)$$

是无穷级数的和

★ $f(x,t)$ 不恒为零, $g_1(t) = g_2(t) \equiv 0$.

$$\Rightarrow (T_n''(t) + \lambda_n T_n(t))(X_n, X_n) = (f, X_n).$$

$$\Rightarrow \begin{cases} T_n''(t) + \lambda_n T_n(t) = \frac{(f, X_n)}{(X_n, X_n)} \triangleq \underline{f_n(t)}. \\ T_n(0) = \varphi_n, \quad T_n'(0) = \psi_n. \end{cases}$$

$$u(x,t) = \sum_{n=1}^{\infty} T_n(t) X_n(x) \quad \text{且} \quad \sum_{n=1}^{\infty} \varphi_n^2 < \infty$$

★ $f(x,t), g_1(t), g_2(t)$ 都不恒为零.

$$\hat{=} v(x,t) = u(x,t) - \left(\frac{L-x}{L} g_1(t) + \frac{x}{L} g_2(t) \right).$$

$$\text{则 } v(0,t) = u(0,t) - g_1(t) = 0$$

$$v(L,t) = u(L,t) - g_2(t) = 0$$

$$\begin{cases} \partial_t^2 v - \partial_x^2 v = f(x,t) - \left(\frac{L-x}{L} g_1''(t) + \frac{x}{L} g_2''(t) \right) \\ v(x,0) = \varphi(x) - \left(\frac{L-x}{L} g_1(0) + \frac{x}{L} g_2(0) \right), \quad \partial_t v(0) = \psi(x) - \left(\frac{L-x}{L} g_1'(0) + \frac{x}{L} g_2'(0) \right) \\ v(0,t) = 0, \quad v(L,t) = 0 \end{cases}$$

$$\begin{cases} \partial_t^2 v - \partial_x^2 v = f(x,t) - \left(\frac{L-x}{L} g_1''(t) + \frac{x}{L} g_2''(t) \right) \\ v(x,0) = \varphi(x) - \left(\frac{L-x}{L} g_1(0) + \frac{x}{L} g_2(0) \right), \quad \partial_t v(0) = \psi(x) - \left(\frac{L-x}{L} g_1'(0) + \frac{x}{L} g_2'(0) \right) \\ v(0,t) = 0, \quad v(L,t) = 0 \end{cases}$$

例. 解方程 $\begin{cases} \partial_t u - \partial_x^2 u = 0, & 0 \leq x \leq L, t \geq 0 \\ u(x,0) = \varphi(x) \end{cases}$

$$u(0,t) = 0, \quad u_x(L,t) + h u(L,t) = 0, \quad h > 0.$$

解: Step 1. 求特征值.

$$\text{设 } u(x,t) = T(t) X(x), \text{ 则 } \begin{cases} T'(t) X(x) - T(t) X''(x) = 0 \\ T(t) X(0) = 0, \quad T(t) X'(L) + h T(t) X(L) = 0. \end{cases}$$

$$\Rightarrow \begin{cases} \frac{T'(t)}{T(t)} = \frac{X''(x)}{X(x)} = -\lambda \\ X(0) = 0, \quad X'(L) + h X(L) = 0. \end{cases}$$

$$\begin{cases} X''(x) + \lambda X(x) = 0 \\ X(0) = 0, \quad X'(L) + h X(L) = 0. \end{cases}$$

$$\begin{aligned} \text{① 若 } \lambda < 0, \text{ 则 } X(x) &= C_1 e^{\sqrt{-\lambda}x} + C_2 e^{-\sqrt{-\lambda}x} \\ X(0) = C_1 + C_2 &= 0 \Rightarrow C_1 = -C_2 \Rightarrow X(x) = C_1 (e^{\sqrt{-\lambda}x} - e^{-\sqrt{-\lambda}x}) \\ X'(L) + h X(L) &= C_1 (\sqrt{-\lambda} e^{\sqrt{-\lambda}L} + \sqrt{-\lambda} e^{-\sqrt{-\lambda}L}) \\ &\quad + C_1 h (e^{\sqrt{-\lambda}L} - e^{-\sqrt{-\lambda}L}) = 0 \\ \Rightarrow C_1 &= 0 \end{aligned}$$

$$\textcircled{2} \lambda=0, \quad X(x)=C_1 x+C_2$$

$$X(0)=C_2=0 \Rightarrow X(x)=C_1 x$$

$$X'(l)+hX(l)=C_1+hC_1 l=C_1(1+hl)=0 \Rightarrow C_1=0$$

$$\textcircled{3} \lambda>0$$

$$X(x)=C_1 \cos(\sqrt{\lambda} x)+C_2 \sin(\sqrt{\lambda} x)$$

$$X(0)=C_1=0 \Rightarrow X(x)=\sin(\sqrt{\lambda} x)$$

$$X'(l)+hX(l)=\sqrt{\lambda} \cos(\sqrt{\lambda} l)+h \sin(\sqrt{\lambda} l)=0$$

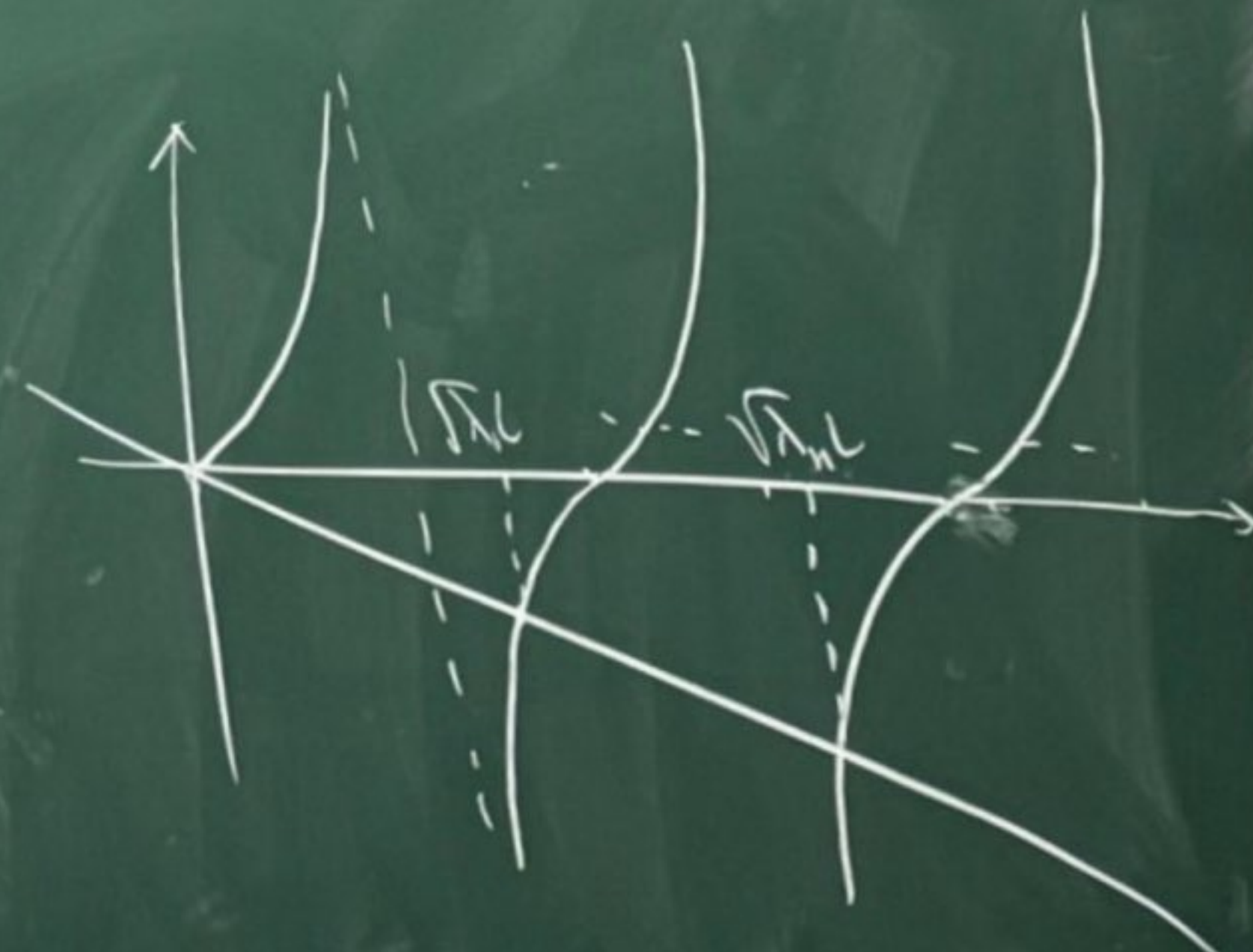
$$\Rightarrow \tan(\sqrt{\lambda} l)=-\frac{\sqrt{\lambda} l}{h}$$

$\exists \lambda_1 < \lambda_2 < \dots$, 使得

$$\tan(\sqrt{\lambda_n} l)=-\frac{\sqrt{\lambda_n} l}{h}$$

$$\boxed{\tan x = -\frac{x}{hl}}$$

$$\tan(\sqrt{\lambda_n} l)=-\frac{\sqrt{\lambda_n} l}{h} = -\frac{\sqrt{\lambda_n}}{h}$$



$$\text{Step 2. } \frac{T_n'(t)}{T_n(t)} = -\lambda_n$$

$$\sum_{n=1}^{\infty} T_n(t) X_n(x) = \varphi(x) = \sum_{n=1}^{\infty} \varphi_n X_n(x)$$

$$T_n(t)(X_n, X_n) = (\varphi, X_n)$$

$$\Rightarrow \begin{cases} T_n'(t) + \lambda_n T_n(t) = 0 \\ T_n(0) = \frac{(\varphi, X_n)}{(X_n, X_n)} \triangleq \varphi_n \end{cases}$$

$$\Rightarrow T_n(t) = e^{-\lambda_n t} \varphi_n$$

原方程的解为

$$u(x, t) = \sum_{n=1}^{\infty} e^{-\lambda_n t} \varphi_n \sin(\sqrt{\lambda_n} x)$$

$$u(x, t) = \sum_{n=1}^{\infty} T_n(t) X_n(x)$$

$$\sum_{n=1}^{\infty} T_n'(t) X_n(x) - \sum_{n=1}^{\infty} T_n(t) X_n''(x) = 0$$

$$\sum_{n=1}^{\infty} (T_n'(t) + \lambda_n T_n(t)) X_n(x) = 0$$

例. 令 $B = \{(x, y) \mid x^2 + y^2 < 1\}$. 求在 B 上的方程

$$\begin{cases} \Delta u = 0 & \text{in } B \\ u = \varphi & \text{on } \partial B. \end{cases}$$

用极坐标 (r, θ)

$$\Delta u = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = 0.$$

$$u(r, \theta) \Big|_{r=1} = \varphi(\cos \theta, \sin \theta).$$

$$\text{令 } u(r, \theta) = R(r) \Theta(\theta)$$

$$R''(r) \Theta(\theta) + \frac{1}{r} R'(r) \Theta(\theta) + \frac{1}{r^2} R(r) \Theta''(\theta) = 0.$$

$$\Rightarrow \left(R''(r) + \frac{1}{r} R'(r) \right) \Theta(\theta) + \frac{R(r)}{r^2} \Theta''(\theta) = 0.$$

$$\Rightarrow \frac{r^2 R'(r) + r R(r)}{R(r)} = - \frac{\Theta''(\theta)}{\Theta(\theta)} \triangleq \lambda.$$

$$\Theta''(\theta) + \lambda \Theta(\theta) = 0$$

$$\Theta(\theta + 2\pi) = \Theta(\theta)$$