

分离变量法

例. 令 $B = \{(x, y) \mid x^2 + y^2 < 1\}$. 求 \bar{B} 上 $\Delta u = 0$ 的解.

Laplace 方程 $\begin{cases} \Delta u = 0 & \text{in } B \\ u = \varphi & \text{on } \partial B. \end{cases}$

解. 用极坐标 (r, θ) .

$$\Delta u + \frac{1}{r} \partial_r u + \frac{1}{r^2} \partial_\theta^2 u = 0.$$

$$u(r, \theta) = R(r) \Theta(\theta).$$

$$\partial_x^2 u - \partial_t^2 u = f \quad 0 \leq x \leq L, t \geq 0$$

$$\rightarrow u(x, 0) = \varphi(x), \partial_t u(x, 0) = \psi(x)$$

$$u(0, t) = 0, u(L, t) = 0$$

$$u(x, t) = T(t) X(x)$$

$$\begin{cases} \frac{T''(t)}{T(t)} = \frac{X'(x)}{X(x)} = -\lambda \\ X(0) = 0, X(L) = 0. \end{cases}$$

Step 1 $\{X_n(x)\}_{n=1}^\infty$

Step 2. $u(x, t) = \sum_{n=1}^\infty T_n(t) X_n(x)$

$$T_n(t)$$

$$R''(r) \Theta(\theta) + \frac{1}{r} R'(r) \Theta(\theta) + \frac{1}{r^2} R(r) \Theta''(\theta) = 0.$$

$$\Rightarrow \frac{R''(r) + \frac{1}{r} R'(r)}{R(r)} + \frac{1}{r^2} \frac{\Theta''(\theta)}{\Theta(\theta)} = 0$$

$$\Rightarrow \frac{r^2 R''(r) + r R'(r)}{R(r)} = - \frac{\Theta''(\theta)}{\Theta(\theta)} = \lambda$$

由边界条件 $u(r=1, \theta) = \varphi(r \cos \theta, r \sin \theta) = \varphi(\cos \theta, \sin \theta)$

$$\frac{R(r) \Theta''(\theta)}{R(r) \Theta(\theta)} \Big|_{r=1} = \varphi(\cos \theta, \sin \theta)$$

$$\begin{cases} \Theta''(\theta) + \lambda \Theta(\theta) = 0 \\ \Theta(\theta) = \Theta(\theta + 2\pi) \end{cases}$$

若 $\lambda < 0$, 则 $\Theta(\theta) = c_1 e^{-\sqrt{-\lambda} \theta} + c_2 e^{\sqrt{-\lambda} \theta} \Rightarrow \Theta(\theta) = 0$

若 $\lambda = 0$, 则 $\Theta(\theta) = c_1 \theta + c_2$ 由 $\Theta(\theta) = \Theta(\theta + 2\pi)$, $\Rightarrow c_1 \theta + c_2 = c_1(\theta + 2\pi) + c_2 \Rightarrow c_1 = 0$.

$$\Theta_0(\theta) = 1.$$

若 $\lambda > 0$, $R(\theta) = C_1 \cos(\sqrt{\lambda}\theta) + C_2 \sin(\sqrt{\lambda}\theta)$.

$\sqrt{\lambda} \cdot 2\pi = 2k\pi$, $\cos(\sqrt{\lambda}\theta) = \cos(\sqrt{\lambda}\theta + 2k\pi)$
 $\Rightarrow \lambda = k^2, k=1, 2, \dots$ $\Rightarrow \sqrt{\lambda} \cdot 2\pi = 2k\pi$.

$\theta_k(\theta) = C_1 \cos(k\theta) + C_2 \sin(k\theta)$.

再求 $R(r)$: $r^2 R''(r) + r R'(r) - k^2 R(r) = 0$.

令 $r = e^t$, 则 $\frac{d^2 R}{dt^2} - k^2 R = 0$.

若 $k \neq 0$, $R(e^t) = D_1 e^{kt} + D_2 e^{-kt}$.

$\Rightarrow R(r) = D_1 r^k + D_2 r^{-k}$
 $R_k(r) = r^k, k \neq 0$.

若 $k = 0$, $R(e^t) = D_1 t + D_2$.

$\Rightarrow R(r) = D_1 \ln r + D_2$
 $R_0(r) = D_2$.

于是 $u(x) = D_0 + \sum_{k=1}^{\infty} r^k (C_k \cos(k\theta) + D_k \sin(k\theta))$

由边界条件, $u|_{\partial B} = D_0 + \sum_{k=1}^{\infty} (C_k \cos(k\theta) + D_k \sin(k\theta)) = \varphi(\cos\theta, \sin\theta) \triangleq \tilde{\varphi}(\theta)$.

$D_0 = \int_0^{2\pi} \tilde{\varphi}(\theta) d\theta$, $C_k \int_0^{2\pi} \cos^2(k\theta) d\theta = \int_0^{2\pi} \tilde{\varphi}(\theta) \cos(k\theta) d\theta \Rightarrow C_k = \dots k=1, 2, \dots$

$D_k \int_0^{2\pi} \sin^2(k\theta) d\theta = \int_0^{2\pi} \tilde{\varphi}(\theta) \sin(k\theta) d\theta \Rightarrow D_k = \dots k=1, 2, \dots$

$$\begin{cases} u_{tt} - u_{xx} = f(x,t) & 0 < x < L, t > 0 \\ u(x,0) = p(x), \quad \partial_t u(x,0) = \psi(x), & 0 \leq x \leq L \\ (-u_x + \alpha u)|_{x=0} = g_1(t), & \alpha, \beta > 0 \\ (u_x + \beta u)|_{x=L} = g_2(t) \end{cases}$$

$$\begin{aligned} \Rightarrow v(x) &= u(x) - \left(C_1 x^2 g_1(t) + C_2 (L-x)^2 g_2(t) \right) \\ (-v_x + \alpha v)|_{x=0} &= g_1(t) - (2C_1 - 0)g_1(t) + \alpha C_2 L^2 g_2(t) = 0 \end{aligned}$$

$$v_x + \beta v = g_2(t) - (2C_1 L g_1(t) + \beta C_1 L^2 g_1(t)) = 0$$

$$\begin{aligned} \Rightarrow g_2(t) &= C_1 (2L + \beta L^2) g_1(t) \\ &= C_1 (2L + \beta L^2) C_2 (-2L + \alpha L^2) g_2(t) \end{aligned}$$

$$\text{If } C_1 = \frac{1}{\alpha L^2 - 2L}, \quad C_2 = \frac{1}{2L + \beta L^2} \quad \text{or}$$

$$v(x) = u(x) - \left(\frac{1}{\alpha L^2 - 2L} x^2 g_1(t) + \frac{(L-x)^2}{2L + \beta L^2} g_2(t) \right)$$

$$\begin{aligned} \text{II} \quad \begin{cases} v_{tt} - v_{xx} &= f(x,t) - \left(\frac{1}{\alpha L^2 - 2L} x^2 g_1''(t) + \frac{1}{2L + \beta L^2} (L-x)^2 g_2''(t) - \frac{2}{\alpha L^2 - 2L} g_1(t) - \frac{2}{2L + \beta L^2} g_2(t) \right) \triangleq F(x,t) \\ v(x,0) &= p(x) - \left(\frac{1}{\alpha L^2 - 2L} x^2 g_{1,0} + \frac{1}{2L + \beta L^2} (L-x)^2 g_{2,0} \right) \triangleq \Phi(x) \\ \partial_t v(x,0) &= \psi(x) - \left(\frac{1}{\alpha L^2 - 2L} x^2 g_{1,0}' + \frac{1}{2L + \beta L^2} (L-x)^2 g_{2,0}' \right) \triangleq \Psi(x) \\ (-v_x + \alpha v)|_{x=0} &= 0 \\ (v_x + \beta v)|_{x=L} &= 0 \end{cases} \end{aligned}$$

$$\frac{\partial^2}{\partial x^2} v(x,t) = T(t)X(x), [R.]$$

$$\begin{cases} T'(t)X(x) - T(t)X''(x) = 0 \\ T(t)(-X'(x) + \alpha X(x))|_{x=0} = 0 \\ T(t)(X'(x) + \beta X(x))|_{x=L} = 0 \end{cases} \Rightarrow \frac{T''(t)}{T(t)} = \frac{X''(x)}{X(x)} = -\lambda$$

$$\Rightarrow C_1 = C_2 = 0$$

$$\begin{cases} X'(x) + \lambda X(x) = 0 \\ -X'(0) + \alpha X(0) = 0 \\ X'(L) + \beta X(L) = 0 \end{cases}$$

$$\frac{\pi}{2} \lambda < 0, \quad X(x) = C_1 e^{-\sqrt{-\lambda}x} + C_2 e^{\sqrt{-\lambda}x}$$

$$\begin{cases} -C_1(-\sqrt{-\lambda}) - C_2(\sqrt{-\lambda}) + \alpha(C_1 + C_2) = 0 \\ C_1(-\sqrt{-\lambda})e^{-\sqrt{-\lambda}L} + C_2\sqrt{-\lambda}e^{\sqrt{-\lambda}L} + \beta(C_1 e^{-\sqrt{-\lambda}L} + C_2 e^{\sqrt{-\lambda}L}) = 0 \end{cases}$$

$$\text{若 } \lambda = 0, \quad X(x) = C_1 x + C_2$$

$$\begin{cases} -C_1 + \alpha C_2 = 0 \\ C_1 + \beta(C_1 + C_2) = 0 \end{cases} \Rightarrow C_1 = C_2 = 0$$

$$\frac{\pi}{2} \lambda > 0, \quad [R.] \quad X(x) = C_1 \cos(\sqrt{\lambda}x) + C_2 \sin(\sqrt{\lambda}x)$$

$$X'(x) = -C_1 \sqrt{\lambda} \sin(\sqrt{\lambda}x) + C_2 \sqrt{\lambda} \cos(\sqrt{\lambda}x)$$

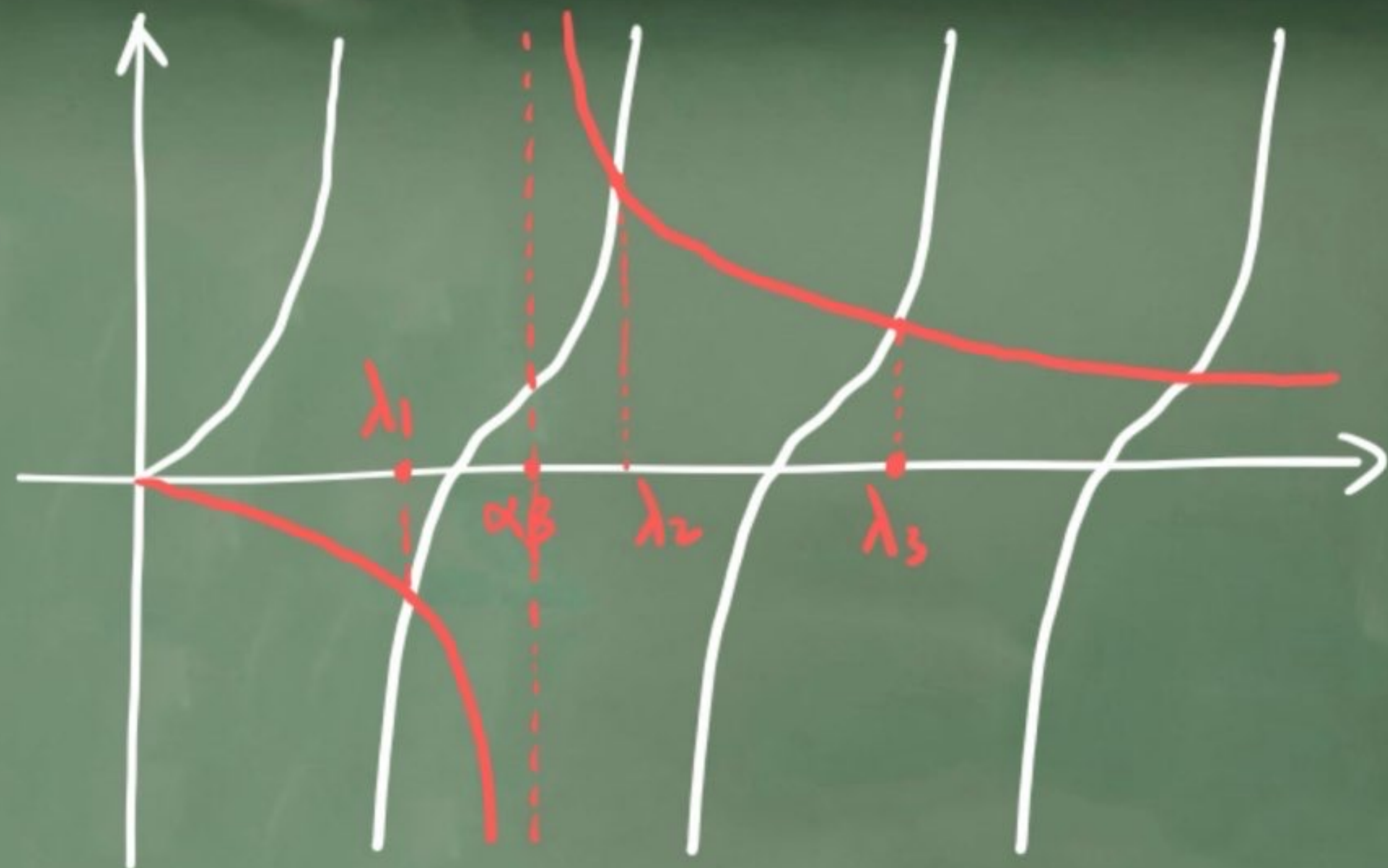
$$-C_2 \sqrt{\lambda} + \alpha C_1 = 0$$

$$-C_1 \sqrt{\lambda} \sin(\sqrt{\lambda}L) + \underbrace{C_2 \sqrt{\lambda} \cos(\sqrt{\lambda}L)}_{\frac{\beta \alpha C_1}{\sqrt{\lambda}}} + \beta C_1 \cos(\sqrt{\lambda}L) + \beta \underbrace{C_2 \sin(\sqrt{\lambda}L)}_{\frac{\alpha C_1}{\sqrt{\lambda}}} = 0$$

$$\Rightarrow \left(-C_1 \sqrt{\lambda} + \frac{\beta \alpha C_1}{\sqrt{\lambda}} \right) \sin(\sqrt{\lambda}L) + (\alpha C_1 + \beta C_1) \cos(\sqrt{\lambda}L) = 0$$

$$\Rightarrow \tan(\sqrt{\lambda}L) = -\frac{\alpha + \beta}{-\sqrt{\lambda} + \frac{\alpha \beta}{\sqrt{\lambda}}} = \frac{\sqrt{\lambda}(\alpha + \beta)}{\lambda - \alpha \beta}$$

$$\exists \lambda_n, n=1, 2, \dots \text{ 使得上式成立}$$



$$X_n(x) = C_1 \cos(\sqrt{\lambda_n} x) + C_2 \sin(\sqrt{\lambda_n} x).$$

$$\text{令 } U(x,t) = \sum_{n=1}^{\infty} T_n(t) X_n(x) \quad [R.]$$

$$\sum_{n=1}^{\infty} (T_n''(t) X_n(x) + \lambda_n T_n(t) X_n(x)) = F(x,t) \quad X_n'' = -\lambda_n X_n$$

$$\Rightarrow \begin{cases} T_n''(t) + \lambda_n T_n(t) = F_n(t), & F_n(t) = \frac{\int_0^L F(x,t) X_n(x) dx}{\int_0^L |X_n(x)|^2 dx} \\ T_n(0) = \Phi_n, & T_n'(0) = \Psi_n \end{cases}$$

$$\Phi_n = \frac{\int_0^L \Phi(x) X_n(x) dx}{\int_0^L |X_n(x)|^2 dx},$$

$$\Psi_n = \frac{\int_0^L \Psi(x) X_n(x) dx}{\int_0^L |X_n(x)|^2 dx}.$$

$$T_n(t) = \Phi_n \cos(\sqrt{\lambda_n} t) + \Psi_n \frac{\sin(\sqrt{\lambda_n} t)}{\sqrt{\lambda_n}} + \int_0^t \frac{\sin((t-s)\sqrt{\lambda_n})}{\sqrt{\lambda_n}} F_n(s) ds.$$

$$\Rightarrow U(x,t) = \dots$$

能量估计

考虑波动方程

$$\int_{\Omega} \operatorname{div} \vec{F} dx = \int_{\partial \Omega} \vec{F} \cdot \vec{n} dS$$

$\vec{F} = (F_1, \dots, F_n)$

格林恒等式乘 $\partial_t u$

$$\int_{\partial \Omega} uv dS - \int_{\Omega} uv_x$$

$$\begin{cases} \partial_t^2 u - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x), \partial_t u(x, 0) = \psi(x) \\ u|_{\partial \Omega} = 0 \end{cases}$$

$$e(u) = \frac{1}{2}(\partial_t u)^2 + \frac{1}{2}|\nabla u|^2$$

能量密度

$$\partial_t u (\partial_t^2 u - \Delta u) = \partial_t u f$$

$$\partial_t \left(\frac{1}{2}(\partial_t u)^2 \right) - \operatorname{div}(\partial_t u \nabla u) + \partial_t \left(\frac{1}{2}|\nabla u|^2 \right) = \partial_t u f$$

bdd
 $x \in \Omega \subset \mathbb{R}^n, t \geq 0$

$$\operatorname{grad} u = \nabla u = \begin{pmatrix} u_{x_1} \\ \vdots \\ u_{x_n} \end{pmatrix}$$

$$\operatorname{div} \vec{F} = \frac{\partial F_1}{\partial x_1} + \dots + \frac{\partial F_n}{\partial x_n}$$

乘 $\frac{1}{2}$

$$a \nabla u + b u_t + c x \cdot \nabla u$$

$$\sum_{i=1}^n \partial_{x_i} \partial_{x_i} u$$

$$= \partial_{x_i} (\partial_t u \partial_{x_i} u) - \partial_t \partial_{x_i} u \partial_{x_i} u = \partial_{x_i} (\partial_t u \partial_{x_i} u) - \partial_t \frac{1}{2}(\partial_{x_i} u)^2$$

$$\partial_t u \nabla u = \begin{pmatrix} \partial_t u u_{x_1} \\ \vdots \\ \partial_t u u_{x_n} \end{pmatrix}$$

$$|\nabla u|^2 = u_{x_1}^2 + \dots + u_{x_n}^2$$

$$\boxed{\partial_t u}$$

$$\lim_{t \rightarrow 0} \frac{u(x, t+t_0) - u(x, t)}{t_0} = (\partial_t u)(x, t)$$