

第二章 位势方程

§2.1 调和函数

$\Omega \subset \mathbb{R}^n$, $n=2,3$ 有界区域, $\partial\Omega \in C^\infty$

$u \in C^2(\Omega)$ $\Delta u = 0, \forall x \in \Omega$

平均值性质: ① $\forall B_r(x) \subset \Omega, u(x) = \frac{1}{|B_r(x)|} \int_{B_r(x)} u(y) dy$
 ② $\forall B_r(x) \subset \Omega, u(x) = \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y)$



定理 2.2. 若 $u \in C^2(\Omega)$ 是 Ω 上的调和函数

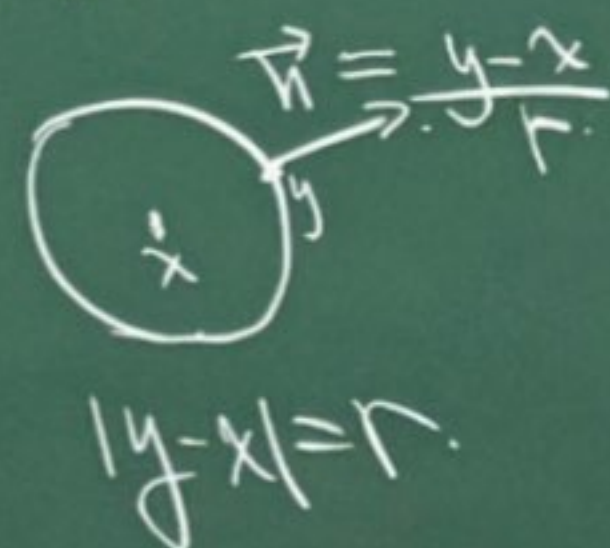
则对于任意的球 $B_r(x) \subset \Omega$,

$$u(x) = \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y)$$

证明: 由于 $\Delta u = 0$ in Ω , $\forall B_r(x) \subset \Omega$,

$$0 = \int_{B_r(x)} (\Delta u) dy = \int_{B_r(x)} \operatorname{div} \nabla u(y) dy \stackrel{\text{散度定理}}{=} \int_{|y-x|=r} \nabla u(y) \cdot \frac{y-x}{r} dS(y)$$

$$\begin{aligned} & \stackrel{y-x=rw}{=} \int_{|w|=1} (\nabla u)(x+rw) \cdot w r^2 dS(w) \\ & = r^2 \int_{|w|=1} \frac{d}{dr} (u(x+rw)) dS(w) \\ & = r^2 \frac{d}{dr} \int_{|w|=1} u(x+rw) dS(w) \end{aligned}$$



$$dS(y) = r^2 dS(w)$$

$$\Rightarrow \int_{|w|=1} u(x+rw) dS(w) = \int_{|w|=1} u(x) dS(w) = u(x) 4\pi$$

$$\Rightarrow \underline{u(x)} = \frac{1}{4\pi} \int_{|w|=1} u(x+rw) dS(w) \quad \forall B_r(x) \subset \Omega$$

$$\underline{\underline{y=x+rw}} \quad \frac{1}{4\pi r^2} \int_{\partial B_r(x)} u(y) dS(y)$$

$$= \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y)$$

$$\int_{B_r(x)} f(y) dy = 0$$

$$\Rightarrow f \equiv 0 \text{ in } \Omega$$

定理 2.3. 假设 $u \in C^2(\Omega)$ 满足对任意的 $B_r(x) \subset \Omega$,

$$u(x) = \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y)$$

则 u 是 Ω 上的调和函数.

$$\underline{\underline{\Delta u(x) = 0, \forall x \in \Omega}}$$

证明. 1. 取 $\frac{1}{r}$. $\forall B_r(x) \subset \Omega$,

$$\int_{\partial B_r(x)} (\Delta u)(y) dy = r^2 \frac{d}{dr} \int_{|w|=1} u(x+rw) dS(w)$$

由平均值性质,

$$u(x) = \frac{1}{4\pi r^2} \int_{|y-x|=r} u(y) dS(y)$$

$$\underline{\underline{y=x+rw}} \quad \frac{1}{4\pi} \int_{|w|=1} u(x+rw) dS(w)$$

$$\frac{d}{dr} \int_{\partial B_r(x)} (\Delta u)(y) dy = r^2 \frac{d}{dr} (4\pi u(x)) = 0 \quad (*)$$

Step 2. 要证 $\Delta u(x) = 0, \forall x \in \Omega$

否则, $\exists x_0 \in \Omega$, s.t. $(\Delta u)(x_0) > c > 0$.

由于 $u \in C^2(\Omega)$, 存在 $r_0 > 0$, s.t. $(\Delta u)(x) \geq \frac{c}{2}, \forall x \in B_{r_0}(x_0)$

$$\text{故 } \int_{\partial B_{r_0}(x_0)} (\Delta u)(y) dy \geq \frac{c}{2} |\partial B_{r_0}(x_0)| > 0$$

这与 (*) 矛盾! 故 $\Delta u \equiv 0$ in Ω .

定理 2.3'. 假设 $u \in C(\Omega)$ 满足平均性质

$$\forall B_r(x) \subset \Omega, \quad u(x) = \frac{1}{|B_r(x)|} \int_{B_r(x)} u(y) dS(y).$$

则 u 在 Ω 上光滑的. \underline{A} u 在 Ω 上调和.

证明: 令 $\varphi \in C_0^\infty(B_1(0))$, ($\varphi \in C^\infty$, $\text{supp } \varphi \subset B_1(0)$)
 $\varphi \equiv 1$ on $B_{\frac{1}{2}}(0)$, $\int_{\mathbb{R}^n} \varphi(x) dx = 1$, $\varphi \geq 0$, radial ($\varphi(x) = \varphi(|x|)$)

$$\begin{aligned} |R| &= \int_{\mathbb{R}^n} \varphi(x) dx = \int_0^\infty \int_{|w|=1} \varphi(rw) r^2 dS(w) dr \\ &= \int_0^\infty \int_{|w|=1} \varphi(r) r^2 dS(w) dr \\ &= 4\pi \int_0^\infty \varphi(r) r^2 dr \end{aligned}$$

$$\begin{aligned} \varphi_\varepsilon(x) &= \frac{1}{\varepsilon^n} \varphi\left(\frac{x}{\varepsilon}\right), |R| \text{supp } \varphi_\varepsilon \subset B_\varepsilon(0). \\ (\varepsilon > \frac{2}{n(n+1)}). \end{aligned}$$

$$\int_{\mathbb{R}^n} \varphi_\varepsilon(x) dx = \int_{\mathbb{R}^n} \frac{1}{\varepsilon^n} \varphi\left(\frac{x}{\varepsilon}\right) dx \stackrel{y=\frac{x}{\varepsilon}}{=} \frac{1}{\varepsilon^n} \int_{\mathbb{R}^n} \varphi(y) \varepsilon^n dy = \int_{\mathbb{R}^n} \varphi(y) dy = 1.$$

claim: $u(x) = (u * \varphi_\varepsilon)(x)$. $\forall x \in \Omega$, $\varepsilon \frac{2}{n(n+1)} < 1$.

事实上, $\int_{\mathbb{R}^n} \varphi_\varepsilon(x-y) u(y) dy = \int_{B_\varepsilon(x)} \varphi_\varepsilon(x-y) u(y) dy = \int_{|y-x| < \varepsilon} \frac{1}{\varepsilon^n} \varphi\left(\frac{y-x}{\varepsilon}\right) u(y) dy$

$$\begin{aligned} \frac{y-x}{\varepsilon} = z, \quad \frac{1}{\varepsilon^n} dy = dz. \quad \int_{|z| < 1} \frac{1}{\varepsilon^n} \varphi(z) u(x+\varepsilon z) \varepsilon^n dz &= \int_{|z| < 1} \varphi(z) u(x+\varepsilon z) dz = \int_{\mathbb{R}^n} \varphi(z) u(x+\varepsilon z) dz \end{aligned}$$

用极坐标, $z = rw$

$$\begin{aligned} &= \int_0^\infty \int_{|w|=1} \varphi(r) u(x+\varepsilon rw) r^2 dS(w) dr \\ &= \int_0^\infty \varphi(r) r^2 \left(\int_{|w|=1} u(x+\varepsilon rw) dS(w) \right) dr \end{aligned}$$

由平均值性质, $u(x) = \frac{1}{4\pi r^2} \int_{\partial B_r(x)} u(y) dS(y)$
 $\stackrel{y=x+rw}{=} \frac{1}{4\pi} \int_{|w|=1} u(x+rw) dS(w)$

故 $\int \varphi_\varepsilon(x-y) u(y) dy = 4\pi u(x) \int_0^{+\infty} \varphi(r) r^2 dr = u(x)$.

因此, u 是光滑的. 再由定理 2.3, u 是调和的.

定理 2.4 (Harnack 不等式). 对于 Ω 上的任何连通紧子集 V , 存在一个仅与距离函数

$d(V, \partial\Omega) = \min_{x \in V, y \in \partial\Omega} |x-y|$ 和维数 n 有关的正

常数 C , 使得 $\sup_V u \leq C \inf_V u$, 其中

u 是 Ω 上的任意非负调和函数. 特别地,
 $\forall x, y \in V, \frac{1}{C} u(y) \leq u(x) \leq C u(y)$.

证: 要证 $\sup_V u \leq C \inf_V u$

只要证明 $\forall x, y \in V, u(x) \leq C u(y)$.

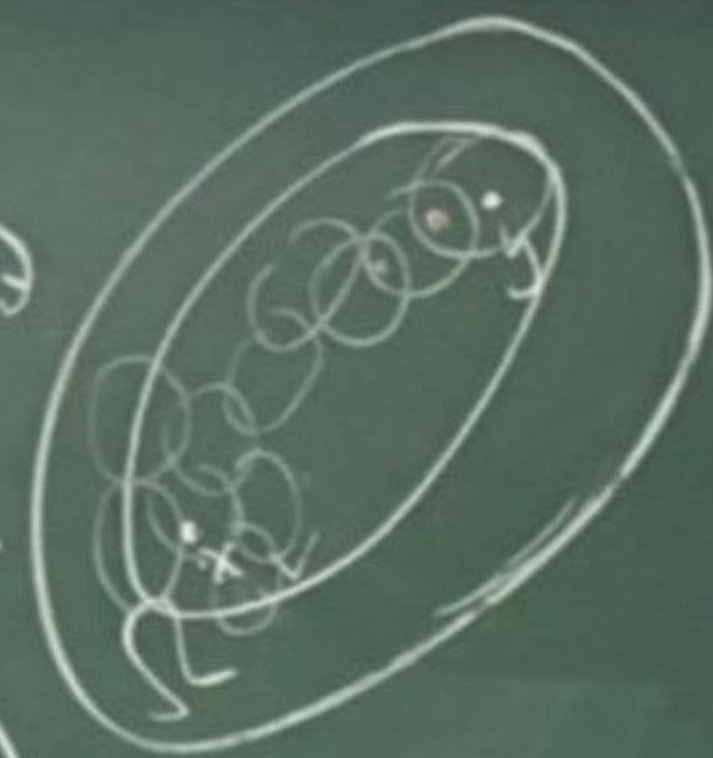
Step 1. $|x-y| < r$. 则 $B_r(x) \subset B_{2r}(y) \subset \Omega$
 (取 $r < \frac{1}{4} d(V, \partial\Omega)$).

因为 u 是调和的, u 满足平均值性质.

$$u(y) = \frac{1}{|B_{2r}(y)|} \int_{B_{2r}(y)} u(z) dz = \frac{1}{\frac{4}{3}\pi (2r)^3} \int_{B_{2r}(y)} u(z) dz \geq \frac{1}{\frac{4}{3}\pi r^3} \int_{B_r(x)} u(z) dz = \frac{1}{2^3} u(x)$$

Step 2. $\forall x, y \in V$.

由于 V 是紧连通, 存在有限个球 $B_r(x_i)$, $i=1, \dots, N$, $x, y \in \bigcup_{i=1}^N B_r(x_i)$



存在有限个球 $B_r(x_i)$, $i=1, \dots, N$, $x, y \in \bigcup_{i=1}^N B_r(x_i)$

$\bigcap_{i=1}^N B_r(x_i) \neq \emptyset$

重复利用 Step 1,

$$u(y) \geq \frac{1}{2^{nN}} u(x)$$

$$\text{故 } u(x) \leq 2^{nN} u(y)$$

$$\Rightarrow \sup u \leq 2^{nN} \inf u.$$

定理2.7. 若 $u \in C(\overline{B_R})$ 是调和的 ($B_R = B_R(x_0)$)

(梯度估计) 则 $|\nabla u(x)| \leq \frac{n}{R} \max_{\overline{B_R}} u$

证: 由于 u 是调和的, 故 u 满足平均值性质

再由定理2.3, u 是光滑的. 于是在 $\Delta u = 0$ 两边同时作用 ∂_{x_i} , 可得 $\Delta \partial_{x_i} u = 0$.

再由平均值性质,

$$\partial_{x_i} u(x) = \frac{1}{|B_R(x)|} \int_{B_R(x)} \partial_{x_i} u(y) dy = \frac{1}{|B_R(x)|} \int_{B_R(x)} \operatorname{div}(0, \dots, u, \dots, 0) dy$$

散度定理 $\frac{1}{\frac{4}{3}\pi R^3} \int_{\partial B_R(x_0)} u v^i dS(y)$

$$\Rightarrow |\partial_{x_i} u(x)| \leq \frac{1}{\frac{4}{3}\pi R^3} \int_{\partial B_R(x_0)} |u| dS(y).$$

$$\leq \frac{1}{\frac{4}{3}\pi R^3} \max_{\overline{B_R(x_0)}} |u| \cdot 4\pi R^2 = \frac{3}{R} \max_{\overline{B_R}} |u|.$$

定理 2.8. (Liouville 定理). 假设 u 是 \mathbb{R}^n 上的有界调和函数, 则 u 是常数.

证明: 设 $|u(x)| \leq M, \forall x \in \mathbb{R}^n$. 由于 u 在 \mathbb{R}^n 上调和, 故 $\forall R > 0, u$ 在 B_R 上调和. 且 $u \in C(\bar{B}_R)$.

由梯度估计, $|\nabla u(x)| \leq \frac{n}{R} \max_{\mathbb{R}^n} |u| \leq \frac{nM}{R}, \forall x$.

令 $R \rightarrow +\infty$, 则 $|\nabla u| = 0$. 故 u 是常数.