

Appendix

A Proof of Lemma 1

Now give out the proof of lemma 1, i.e.,

Lemma 1. *The following event, i.e.,*

$$\xi_1 = \{\forall (h, i) \in T_t, \forall t : |\hat{\mu}_{h,i}^0(t) - f(v_{h,i})| < B(T_{h,i}(t), \delta, t)\}$$

establishes with the probability at least $1 - \delta$

The User's rewards to video $v_{h,i}$ are a sequence of i.i.d(independently identically distribution) random variables and belong to $[0,1]$, define event ξ_1^c is the opposite event of event ξ_1 , then according to Hoeffding's inequality, we have, i.e.,

$$\begin{aligned} P[\xi_1^c] &\leq \sum_{(h,i) \in T_t} \sum_{T_{h,i}(t)=1}^{\infty} 2\exp\left[\frac{-2T_{h,i}(t)^2}{T_{h,i}(t) \cdot 1^2} B(T_{h,i}(t), \delta, t)^2\right] \\ &= \sum_{(h,i) \in T_t} \sum_{T_{h,i}(t)=1}^{\infty} 2\exp\left[\log \frac{3\delta}{\pi^2 T_{h,i}(t)^2 |T_t|}\right] \\ &= \sum_{(h,i) \in T_t} \sum_{T_{h,i}(t)=1}^{\infty} \frac{6\delta}{\pi^2 T_{h,i}(t)^2 |T_t|} \\ &= \sum_{(h,i) \in T_t} \frac{\delta}{|T_t|} \\ &= \delta. \end{aligned}$$

so we have $P[\xi_1] > 1 - \delta$

B Proof of Lemma 2

The Lemma 2 is that, i.e.,

Lemma 2. *under event ξ_1 , for $\forall (h, i) \in T_t, \notin N_K(t), \forall (h_K, i_K) \in N_K(t), \forall t$, there exists, i.e.,*

$$\hat{\mu}_{(h,i),(h_K,i_K)}(t) - f(v_{h_K,i_K}) < B(T_{(h,i),(h_K,i_K)}(t), \delta, t) - \bar{\lambda}_{(h,i),(h_K,i_K)}(t)$$

$$\bar{\lambda}_{(h,i),(h_K,i_K)}(t) = \frac{1}{T_{(h,i),(h_K,i_K)}(t)} \sum_{s \in \phi_{(h,i),(h_K,i_K)}(t)} \lambda_s$$

The proof of it is as following,

$$\begin{aligned}
& \hat{\mu}_{(h,i),(h_K,i_K)}(t) \\
&= \frac{1}{T_{(h,i),(h_K,i_K)}(t)} \sum_{s \in \phi_{(h,i),(h_K,i_K)}(t)} (r_s - [\hat{\mu}_{h,i}(s) - \hat{\mu}_{h_K,i_K}(s) + B(T_{h,i}(s), \delta, s) + B(T_{h_K,i_K}(s), \delta, s) + \lambda_s]^+) \\
&\leq \frac{1}{T_{(h,i),(h_K,i_K)}(t)} \sum_{s \in \phi_{(h,i),(h_K,i_K)}(t)} (r_s - [\hat{\mu}_{h,i}(s) - \hat{\mu}_{h_K,i_K}(s) + B(T_{h,i}(s), \delta, s) + B(T_{h_K,i_K}(s), \delta, s) + \lambda_s]) \\
&\stackrel{(i)}{<} \frac{1}{T_{(h,i),(h_K,i_K)}(t)} \sum_{s \in \phi_{(h,i),(h_K,i_K)}(t)} (r_s - (f(v_{h,i}) - f(v_{h_K,i_K}) + \lambda_s)) \\
&= \hat{\mu}_{(h,i),(h_K,i_K)}^0(t) - f(v_{h,i}) + f(v_{h_K,i_K}) - \frac{1}{T_{(h,i),(h_K,i_K)}(t)} \sum_{s \in \phi_{(h,i),(h_K,i_K)}(t)} \lambda_s \\
&= \hat{\mu}_{(h,i),(h_K,i_K)}^0(t) - f(v_{h,i}) + f(v_{h_K,i_K}) - \bar{\lambda}_{(h,i),(h_K,i_K)}(t) \\
&\stackrel{(ii)}{<} f(v_{h,i}) + B(T_{(h,i),(h_K,i_K)}(t), \delta, t) - f(v_{h,i}) + f(v_{h_K,i_K}) - \bar{\lambda}_{(h,i),(h_K,i_K)}(t) \\
&= B(T_{(h,i),(h_K,i_K)}(t), \delta, t) + f(v_{h_K,i_K}) - \bar{\lambda}_{(h,i),(h_K,i_K)}(t) \rightarrow \\
&\hat{\mu}_{(h,i),(h_K,i_K)}(t) - f(v_{h_K,i_K}) < B(T_{(h,i),(h_K,i_K)}(t), \delta, t) - \bar{\lambda}_{(h,i),(h_K,i_K)}(t)
\end{aligned}$$

Lemma 2 has been proofed. (i) is because the event ξ_1 , and (ii) is because $\{r_s\}_{s \in \phi_{(h,i),(h_K,i_K)}(t)}$ is also a sequence of i.i.d variables and we can also use ξ_1 to deal with it.

C Proof of Lemma 3

The Lemma 3 is that, i.e.,

Lemma 3. Under Lemma 2, for $\forall (h, i) \in T_t, \notin N_K(t), \forall (h_K, i_K) \in N_K(t), \forall t$, there exists, i.e.,

$$\hat{\mu}_{h,i}(t) < \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} f(v_{h_{Ks}, i_{Ks}}) + B\left(\frac{T_{h,i}(t)}{|N_K(t)|}, \delta, t\right) - \bar{\lambda}_{h,i}(t)$$

$$\bar{\lambda}_{h,i}(t) = \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} \lambda_s$$

The proof is as following,

$$\begin{aligned}
& \hat{\mu}_{h,i}(t) \\
&= \frac{1}{T_{h,i}(t)} \sum_{(h_K, i_K) \in N_K(t)} \hat{\mu}_{(h,i),(h_K,i_K)}(t) \cdot T_{(h,i),(h_K,i_K)}(t) \\
&\stackrel{(i)}{<} \frac{1}{T_{h,i}(t)} \sum_{(h_K, i_K) \in N_K(t)} (f(v_{h_K,i_K}) + B(T_{(h,i),(h_K,i_K)}(t), \delta, t) - \bar{\lambda}_{(h,i),(h_K,i_K)}(t)) T_{(h,i),(h_K,i_K)}(t) \\
&= \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} f(v_{h_{Ks}, i_{Ks}}) + \frac{1}{T_{h,i}(t)} \sum_{(h_K, i_K) \in N_K(t)} T_{(h,i),(h_K,i_K)}(t) B(T_{(h,i),(h_K,i_K)}(t), \delta, t) - \bar{\lambda}_{h,i}(t) \\
&= \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} f(v_{h_{Ks}, i_{Ks}}) + \frac{1}{T_{h,i}(t)} \sum_{(h_K, i_K) \in N_K(t)} \sqrt{\frac{T_{(h,i),(h_K,i_K)}(t)}{2} \ln \frac{\pi^2 T_{(h,i),(h_K,i_K)}(t)^2 |T_t|}{3\delta}} - \bar{\lambda}_{h,i}(t)
\end{aligned} \tag{1}$$

(i) is under Lemma 2. we define a function $g(N) = \sqrt{\frac{N}{2} \ln \frac{\pi^2 N^2 |T_t|}{3\delta}} (N \geq 1)$, because there exists $g(N)'' < 0$, so $g(N)$ is a Concave Function, then we have, i.e.,

$$\begin{aligned} & \sum_{(h_K, i_K) \in N_K(t)} g(T_{(h,i),(h_K, i_K)}(t)) \\ & < |N_K(t)| g\left(\frac{1}{|N_K(t)|} \sum_{(h_K, i_K) \in N_K(t)} T_{(h,i),(h_K, i_K)}(t)\right) \\ & = |N_K(t)| g\left(\frac{1}{|N_K(t)|} T_{h,i}(t)\right) \end{aligned}$$

Based on the above, we continue the proof with (1),

$$\begin{aligned} (1) & < \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} f(v_{h_{Ks}, i_{Ks}}) + \frac{1}{T_{h,i}(t)} \sqrt{\frac{|N_K(t)| \cdot T_{h,i}(t)}{2} \ln \frac{\pi^2 T_{h,i}(t)^2 |T_t|}{3\delta \cdot |N_K(t)|^2}} - \bar{\lambda}_{h,i}(t) \\ & = \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} f(v_{h_{Ks}, i_{Ks}}) + B\left(\frac{T_{h,i}(t)}{|N_K(t)|}, \delta, t\right) - \bar{\lambda}_{h,i}(t) \end{aligned}$$

The Lemma 3 has been proofed.

D Proof of Lemma 4

The Lemma 4 is about the height of cover-tree T_t , i.e.,

Lemma 4.

$$H(t) \leq H(t)_{max} < \log_m \left[\frac{\nu_1^2 (1 - \rho^2) t}{c^2} + 1 \right] + 1$$

$$m = \rho^{-2}, c = 2\sqrt{1/(1 - \rho)}$$

according to the HCT algorithm, a leaf node (h, i) is expanded when $\nu_1 \rho^h \geq c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h,i}(t)}}$, so we have, i.e.,

$$T_{h,i}(t) \geq \frac{c^2 \ln(1/\tilde{\delta}(t^+))}{\nu_1^2} \rho^{-2h} \geq \frac{c^2}{\nu_1^2} \rho^{-2h}$$

absolutely, when the tree is a linear tree, i.e. at each depth, only one node is been expanded, the tree is the deepest, so there exists,

$$\begin{aligned} T & \geq \sum_{h=1}^{H(T)-1} \frac{c^2}{\nu_1^2} \rho^{-2h} = \frac{c^2}{\nu_1^2} \sum_{h=1}^{H(T)-1} \rho^{-2h} \\ & = \frac{c^2}{\nu_1^2} \rho^{-2} \frac{1 - \rho^{-2(H(T)-1)}}{1 - \rho^{-2}} \\ & = \frac{c^2}{\nu_1^2} \frac{\rho^{-2(H(T)-1)} - 1}{1 - \rho^2} \rightarrow \\ & \rho^{-2(H(T)-1)} - 1 \leq \frac{\nu_1^2 (1 - \rho^2) T}{c^2} \rightarrow \\ & H(T) \leq \log_{\rho^{-2}} \left[\frac{\nu_1^2 (1 - \rho^2) T}{c^2} + 1 \right] + 1 \end{aligned}$$

Lemma 4 has been proofed.

E Proof of Lemma 5

The Lemma 5 is about the node number of cover-tree T_t , i.e.,

Lemma 5.

$$|T_t| \leq |T_t|_{max} < 4(t\nu_1^2(2 - \rho^2)/(2c^2) + 1)^E - 1$$

$$E = \log_{2\rho^{-2}} 2.$$

As in Lemma 4, a node will be expanded until $T_{h,i}(t) \geq \frac{c^2}{\nu_1^2} \rho^{-2h}$, so the height is bigger, the threshold is bigger, absolutely, when the cover-tree is a Complete Binary Tree, it has the max node number, then we have, i.e.,

$$\begin{aligned} T &\geq \sum_{h=1}^{H(T)-1} \frac{c^2}{\nu_1^2} \rho^{-2h} \cdot 2^h = \sum_{h=1}^{H(T)-1} \frac{c^2}{\nu_1^2} (2\rho^{-2})^h \\ &= 2 \frac{c^2}{\nu_1^2} \frac{(2\rho^{-2})^{H(T)-1} - 1}{2 - \rho^2} \rightarrow \\ (2\rho^{-2})^{H(T)-1} - 1 &\leq \frac{T\nu_1^2(2 - \rho^2)}{2c^2} \rightarrow \\ H(T) &\leq \log_{2\rho^{-2}} \left[\frac{T\nu_1^2(2 - \rho^2)}{2c^2} + 1 \right] + 1 \end{aligned}$$

Then we use $2^{H(T)+1} - 1$ to calculate the node number and get Lemma 5.

F Proof of Theorem 1

The Theorem 1 implies the higher-bound of the cost, i.e.,

Theorem 1.

$$\begin{aligned} C(T) &\leq 2(f_{max} - f_{min} + 4B(1, \delta, T))|T_T| \frac{\left(\sqrt{\frac{|N_K(T)|}{2} \ln \frac{\pi^2 T^2 |T_T|}{3\delta \cdot |N_K(T)|^2}} + 2c\sqrt{\ln(1/\tilde{\delta}(T^+))} \right)^2}{\alpha_T^2} \\ &= O\left(\frac{1}{\alpha_T^2} (\ln T)^3 T^E\right) \end{aligned}$$

establishes with the probability at least $1 - \delta$, $E = \log_{2\rho^{-2}} 2$, $T^+ = 2^{\lfloor \ln T \rfloor + 1}$, $\tilde{\delta}(t) = \min\{c_1 \delta_u/t, 1\}$ ($c_1 = \sqrt[8]{\rho/(3\nu_1)}$) and $\alpha_T > \min_{(h_a, i_a), (h_b, i_b) \in T_T} \{|f(v_{h_a, i_a}) - f(v_{h_b, i_b})|\}$.

First, we make an assumption that at round t , the user chooses a node (h, i) excluding the target video v_K along a path P_t , in the path, we have, i.e.,

$$B_{h', i'}(t) \leq U_{h, i}(t) (h' < h, (h', i') \in P_t). \quad (2)$$

Because root node contains video v_K , so along the path, there must be a node (h_K, i_K) ($h_K < h$) containing video v_K . At the same time, because when the user chooses a node containing video v_K , the attacker won't attack, so we still can use the property of the typical HCT algorithm, i.e. event ξ_t at Lemma 3 in [azar, M.G., Lazaric, A. Brunskill, E.. (2014). Online Stochastic Optimization under Correlated Bandit Feedback.[C] Proceedings of the

31st International Conference on Machine Learning, in PMLR 32(2):1557-1565] to analyze it, then under ξ_t , we have, i.e.,

$$\begin{aligned} U_{h_K, i_K}(t) &= \hat{\mu}_{h_K, i_K}(t) + \nu_1 \rho^{h_K} + \sqrt{\frac{c^2 \log(1/\tilde{\delta}(t^+))}{T_{h_K, i_K}(t)}} \\ &\stackrel{(i)}{\geq} f(x_{h_K, i_K}) + \nu_1 \rho^{h_K} \\ &\geq f(v_K). \end{aligned}$$

(i) is because under the event ξ_t ($P[\xi_t] \geq 1 - \delta$). For the leaf node (h_n, i_n) containing video v_K , obviously, we have, i.e.,

$$B_{h_n, i_n}(t) = U_{h_n, i_n}(t) \geq f(v_K),$$

also according to the definition of B -value in HCT , we have

$$B_{h_K, i_K}(t) = \min [U_{h_K, i_K}(t), \max_{j \in \{2i_K-1, 2i_K\}} B_{h_K+1, j}(t)], \quad (3)$$

established, and between nodes $(h_K + 1, 2i_K - 1)$ and $(h_K + 1, 2i_K)$, there must have a node containing video v_K , also node (h_K, i_K) must be the ancestor of node (h_n, i_n) , now by propagating the bound backward from (h_n, i_n) to (h_K, i_K) through the (3) we can show that $B_{h_K, i_K}(t)$ is still a valid upper bound of $f(v_K)$.

Then from Inq.(2), we have, i.e.,

$$\begin{aligned} U_{h, i}(t) &\geq B_{h_K, i_K}(t) > f(v_K) \rightarrow \\ \hat{\mu}_{h, i}(t) + \nu_1 \rho^h + c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h, i}(t)}} &\geq f(v_K) \stackrel{(i)}{\rightarrow} \\ f(v_K) &\leq \frac{1}{T_{h, i}(t)} \sum_{s \in \phi_{h, i}(t)} f(v_{h_{Ks}, i_{Ks}}) + B\left(\frac{T_{h, i}(t)}{|N_K(t)|}, \delta, t\right) - \bar{\lambda}_{h, i}(t) + \nu_1 \rho^h + c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h, i}(t)}} \\ &< \frac{1}{T_{h, i}(t)} \sum_{s \in \phi_{h, i}(t)} f(v_{h_{Ks}, i_{Ks}}) + B\left(\frac{T_{h, i}(t)}{|N_K(t)|}, \delta, t\right) - \bar{\lambda}_{h, i}(t) + 2c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h, i}(t)}} \rightarrow \\ f(v_K) + \bar{\lambda}_{h, i}(t) - \frac{1}{T_{h, i}(t)} \sum_{s \in \phi_{h, i}(t)} f(v_{h_{Ks}, i_{Ks}}) &< B\left(\frac{T_{h, i}(t)}{|N_K(t)|}, \delta, t\right) + 2c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h, i}(t)}} \rightarrow \\ \alpha_t &< B\left(\frac{T_{h, i}(t)}{|N_K(t)|}, \delta, t\right) + 2c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h, i}(t)}} (\alpha_t = f(v_K) + \bar{\lambda}_{h, i}(t) - \frac{1}{T_{h, i}(t)} \sum_{s \in \phi_{h, i}(t)} f(v_{h_{Ks}, i_{Ks}})) \\ &= \sqrt{\frac{|N_K(t)| \ln \frac{\pi^2 T_{h, i}(t)^2 |T_t|}{3\delta \cdot |N_K(t)|^2}}{2T_{h, i}(t)}} + 2c \sqrt{\frac{\ln(1/\tilde{\delta}(t^+))}{T_{h, i}(t)}} \end{aligned}$$

We regard $T_{h, i}(t)$ as the unknown, then deal with the inequality and get, i.e.,

$$T_{h, i}(t) < \frac{\sqrt{\frac{|N_K(t)| \ln \frac{\pi^2 T_{h, i}(t)^2 |T_t|}{3\delta \cdot |N_K(t)|^2}}{2}} + 2c \sqrt{\ln(1/\tilde{\delta}(t^+))}}{\alpha_t^2}$$

We assume that the node excluding video v_K have been selected for $A(t)$ times until round t , then we have, i.e.,

$$\begin{aligned}
A(T) &= \sum_{(h,i) \in T_T, v_K \notin \mathcal{P}_{h,i}} T_{h,i}(T) \\
&< \sum_{(h,i) \in T_T, v_K \notin \mathcal{P}_{h,i}} \frac{\sqrt{\frac{|N_K(T)|}{2} \ln \frac{\pi^2 T_{h,i}(T)^2 |T_T|}{3\delta \cdot |N_K(T)|^2}} + 2c\sqrt{\ln(1/\tilde{\delta}(T^+))}}{\alpha_T^2} \\
&< |T_T| \frac{\left(\sqrt{\frac{|N_K(T)|}{2} \ln \frac{\pi^2 T^2 |T_T|}{3\delta \cdot |N_K(T)|^2}} + 2c\sqrt{\ln(1/\tilde{\delta}(T^+))} \right)^2}{\alpha_T^2}
\end{aligned} \tag{4}$$

Because $v_K \in (h_{Ks}, i_{Ks})$, so approximately, we think that $f(v_K) \approx \frac{1}{T_{h,i}(t)} \sum_{s \in \phi_{h,i}(t)} f(v_{h_{Ks}, i_{Ks}})$, then $\alpha_t \approx \bar{\lambda}_{h,i}(t) > \min_{(h_a, i_a), (h_b, i_b) \in T_t} \{|f(v_{h_a, i_a}) - f(v_{h_b, i_b})|\}$. And at the same time, we define the function $h(N) = B(N, \delta, t)(N \geq 1)$, absolutely, function $h(N)$ is a decreasing function, so $h(1) \geq h(N)$. Then for $\forall (h_a, i_a), (h_b, i_b) \in T_t$, there exists, i.e.,

$$\begin{aligned}
&\hat{\mu}_{h_a, i_a}^0(t) - \hat{\mu}_{h_b, i_b}^0(t) + B(T_{h_a, i_a}(t), \delta, t) + B(T_{h_b, i_b}(t), \delta, t) \\
&< (\hat{\mu}_{h_a, i_a}^0(t) - B(T_{h_a, i_a}(t), \delta, t)) - (\hat{\mu}_{h_b, i_b}^0(t) + B(T_{h_b, i_b}(t), \delta, t)) + 2B(T_{h_a, i_a}(t), \delta, t) + 2B(T_{h_b, i_b}(t), \delta, t) \\
&\stackrel{(i)}{<} f(v_{h_a, i_a}) - f(v_{h_b, i_b}) + 2B(T_{h_a, i_a}(t), \delta, t) + 2B(T_{h_b, i_b}(t), \delta, t) \\
&< f(v_{h_a, i_a}) - f(v_{h_b, i_b}) + 4B(1, \delta, t) \\
&< f_{max} - f_{min} + 4B(1, \delta, t)
\end{aligned}$$

(i) is under event ξ_1 .

Then we give out a higher-bound of η_t , i.e.,

$$\eta_t \leq -I\{(h_t, i_t) \notin N_K(t)\} (2(f_{max} - f_{min} + 4B(1, \delta, t))) \tag{5}$$

Finally, combine Inq.(4), Inq.(5), Lemma 4 and Lemma 5, we get Theorem 1.

G Proof of Theorem 2

The Theorem gives out a lower-bound of HCT algorithm's regret under the proposed attack, i.e.,

Theorem 2.

$$\begin{aligned}
R(T) &> \Omega[(f_{max} - f(v_K))A - (\ln(A/\delta_u))^{1/(d+2)} A^{(d+1)/(d+2)} - \sqrt{2A \ln(A/\delta)}] \\
&\quad + \Omega[(f_{max} - f(v_K))B - (\ln(B/\delta_u))^{1/(d+2)} B^{(d+1)/(d+2)} - \sqrt{2B \ln(B/\delta)}] \\
&= \Omega((f_{max} - f(v_K))T)
\end{aligned}$$

with probability at least $(1 - \delta_u)(1 - \delta)$.

According to the definition of regret, we have, i.e.,

$$\begin{aligned}
R(T) &= T f_{max} - \sum_{t=1}^T r_t \\
&= \sum_{t=1}^T (f_{max} - r_t) \\
&= \sum_{s \in \mathcal{A}^c} (f_{max} - r_s) + \sum_{s \in \mathcal{A}} (f_{max} - r_s) \\
&= \widehat{R}(T) + \tilde{R}(T)
\end{aligned}$$

We begin to deal with $\widehat{R}(T)$, in \mathcal{A}^c , the attacker chooses not to attack, which means that the user chooses a node (h, i) containing video v_K . Firstly, we make some transformations to $\widehat{R}(T)$, i.e.,

$$\begin{aligned}
\widehat{R}(T) &= \sum_{s \in \mathcal{A}^c} (f_{max} - r_s) \\
&= \sum_{s \in \mathcal{A}^c} (f_{max} - f(v_{h_s, i_s}) + f(v_{h_s, i_s}) - r_s) \\
&= \sum_{s \in \mathcal{A}^c} [f_{max} - f(v_K) + f(v_K) - f(v_{h_s, i_s}) + f(v_{h_s, i_s}) - r_s] \\
&= \sum_{s \in \mathcal{A}^c} (f_{max} - f(v_K)) - \sum_{s \in \mathcal{A}^c} (f(v_{h_s, i_s}) - f(v_K)) - \sum_{s \in \mathcal{A}^c} (r_s - f(v_{h_s, i_s})) \\
&= \sum_{s \in \mathcal{A}^c} (f_{max} - f(v_K)) - (a) - (b). \tag{6}
\end{aligned}$$

For (b), because $\{f(v_{h_s, i_s}) - r_s\}_{s \in \mathcal{A}^c}$ is a bounded martingale difference sequence and we have $|f(v_{h_s, i_s}) - r_s| \leq 1$, so according to Azuma's inequality, we leads to, i.e.,

$$(b) = \sum_{s \in \mathcal{A}^c} (r_s - f(v_{h_s, i_s})) \leq \sqrt{2B \log(B/\delta)}. \tag{7}$$

with probability at least $1 - \delta/B$.

then for (a), we have, i.e.,

$$\begin{aligned}
(a) &= \sum_{s \in \mathcal{A}^c} (f(v_{h_s, i_s}) - f(v_K)) \\
&= \sum_{(h, i) \in T_t} \sum_{s \in \mathcal{A}^c} (f(v_{h, i}) - f(v_K)) I_{(h_s, i_s) = (h, i)} \\
&\leq \sum_{(h, i) \in T_t} \sum_{s \in \mathcal{A}^c} (\nu_1 \rho^h) I_{(h_s, i_s) = (h, i)} \\
&\stackrel{(i)}{\leq} \sum_{(h, i) \in T_t} \sum_{s \in \mathcal{A}^c} c \sqrt{\frac{\log(1/\tilde{\delta}(s^+))}{T_{h, i}(s)}} I_{(h_s, i_s) = (h, i)} \\
&\stackrel{(ii)}{\leq} \left(\frac{2^{2(d+3)} \nu_1^{2(d+1)} C \nu_2^{-d} \rho^d}{(1 - \rho)^{d/2+3}} \right)^{\frac{1}{d+2}} \left(\log \left(\frac{2B}{\delta_u} \sqrt{\frac{3\nu_1}{\rho}} \right) \right)^{\frac{1}{d+2}} B^{\frac{d+1}{d+2}}. \tag{8}
\end{aligned}$$

(i) is because the property of the *OptTraverse* function in HCT that the loop in the function will ends with a node meeting the condition, i.e.,

$$\nu_1 \rho^h < c \sqrt{\frac{\log(1/\tilde{\delta}(t^+))}{T_{h,i}(t)}}. \quad (9)$$

(ii) is from the Theorem 1 in [azar, M.G., Lazaric, A. Brunskill, E.. (2014). Online Stochastic Optimization under Correlated Bandit Feedback.[C] Proceedings of the 31st International Conference on Machine Learning, in PMLR 32(2):1557-1565], and with a probability at least $1 - \delta_u$.

Then combine (6),(7) and (8), we have, i.e.,

$$\begin{aligned} \hat{R}(T) &\geq B(f_{max} - f(v_K)) - \sqrt{2B \log(B/\delta)} - \\ &\quad \left(\frac{2^{2(d+3)} \nu_1^{2(d+1)} C \nu_2^{-d} \rho^d}{(1-\rho)^{d/2+3}} \right)^{\frac{1}{d+2}} \left(\log \left(\frac{2B}{\delta_u} \sqrt{\frac{3\nu_1}{\rho}} \right) \right)^{\frac{1}{d+2}} B^{\frac{d+1}{d+2}}. \end{aligned} \quad (10)$$

Then we analyze $\tilde{R}(T)$, i.e.,

$$\begin{aligned} \tilde{R}(T) &= \sum_{s \in \mathcal{A}} (f_{max} - r_s) \\ &\geq \sum_{s \in \mathcal{A}} (f_{max} - (r_s^0 - \hat{\mu}_{h_s, i_s}^0(s) + \hat{\mu}_{h_{Ks}, i_{Ks}}^0(s) - B(T_{h_s, i_s}(s), \delta, s) - B(T_{h_{Ks}, i_{Ks}}(s), \delta, s) - \lambda_s)) \\ &\stackrel{(i)}{\geq} \sum_{s \in \mathcal{A}} (f_{max} - (r_s^0 - f(v_{h_s, i_s}) + f(v_{h_{Ks}, i_{Ks}}) - \lambda_s)) \\ &\geq \sum_{s \in \mathcal{A}} [f_{max} - f(v_{h_{Ks}, i_{Ks}}) - (r_s^0 - f(v_{h_s, i_s})) + \lambda_s] \\ &= \sum_{s \in \mathcal{A}} [f_{max} - f(v_K) + [\lambda_s - (f(v_{h_{Ks}, i_{Ks}}) - f(v_K))] - (r_s^0 - f(v_{h_s, i_s}))] \\ &= \sum_{s \in \mathcal{A}} [f_{max} - f(v_K)] + (c) - (d) \end{aligned} \quad (11)$$

For (d), similarly to (b), according to Azuma's inequality, we leads to, i.e.,

$$(d) = \sum_{s \in \mathcal{A}} (r_s^0 - f(v_{h_s, i_s})) \leq \sqrt{2A \log(A/\delta)} \quad (12)$$

with probability at least $1 - \delta/A$.

for (c), according to the definition of λ_s and the fact that $v_{h_{Ks}, i_{Ks}}, v_K \in \mathcal{P}_{h_{Ks}, i_{Ks}}$, so there exists, i.e.,

$$(c) = \sum_{s \in \mathcal{A}} \lambda_s - (f(v_{h_{Ks}, i_{Ks}}) > 0$$

Then combine inq.(11), inq.(12), we have, i.e.,

$$\tilde{R}(T) > A(f_{max} - f(v_K)) - \sqrt{2A \log(A/\delta)} \quad (13)$$

Finally, we combine Inq.(10) and Ieq.(13) to get Theorem 2.

H Additional Experiments

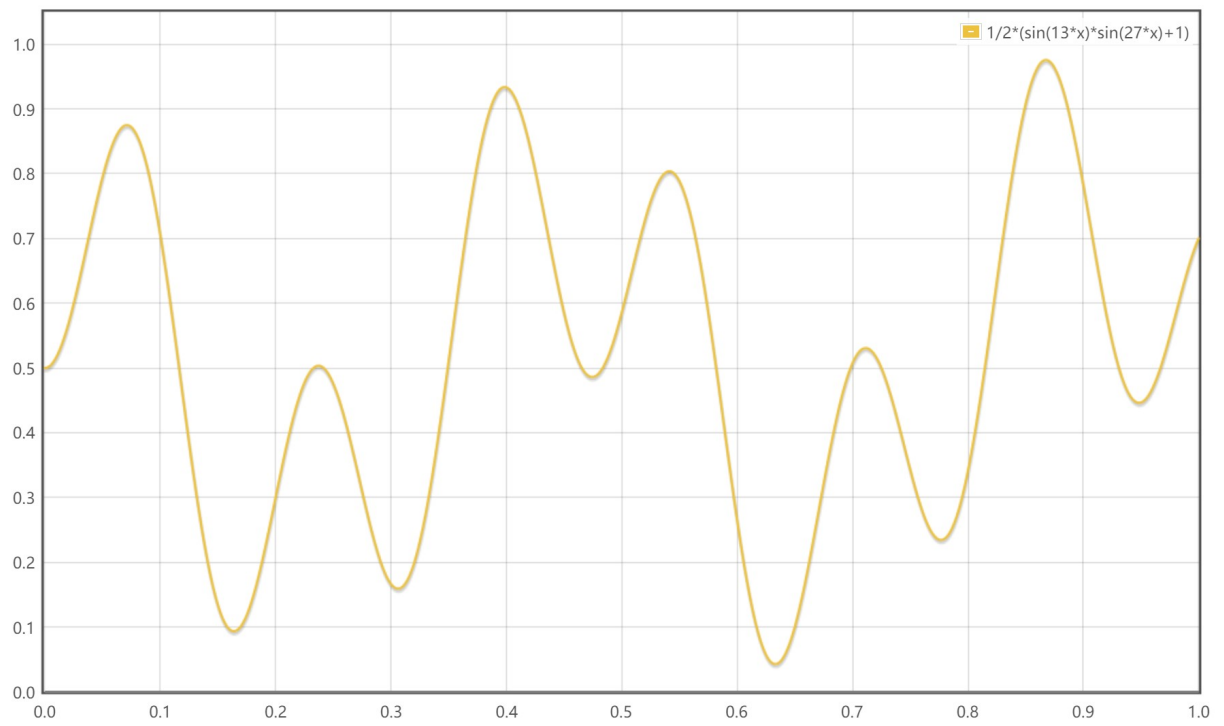
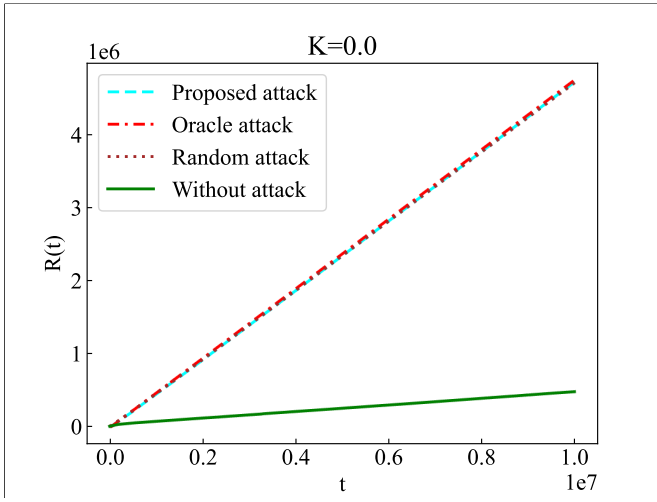
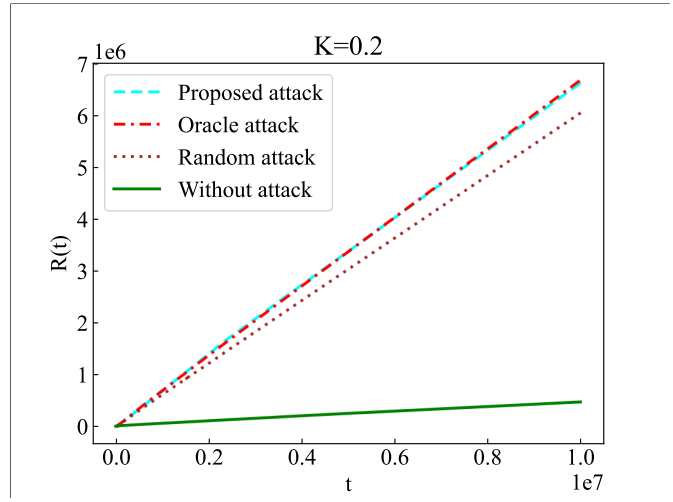


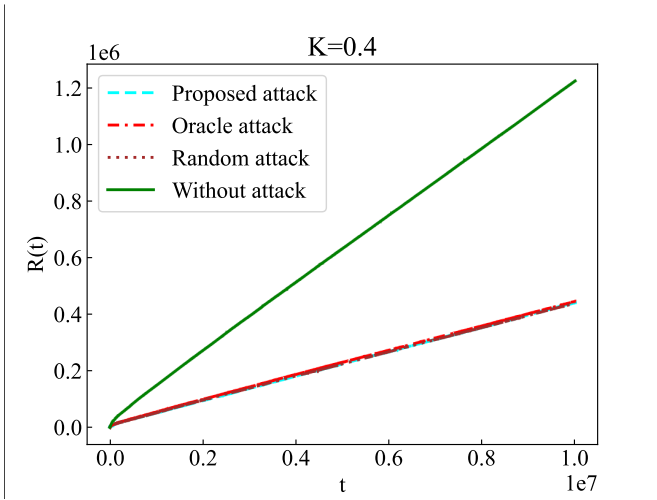
Figure 1: $f(x) = \frac{1}{2}(\sin(13x)\sin(27x) + 1)$



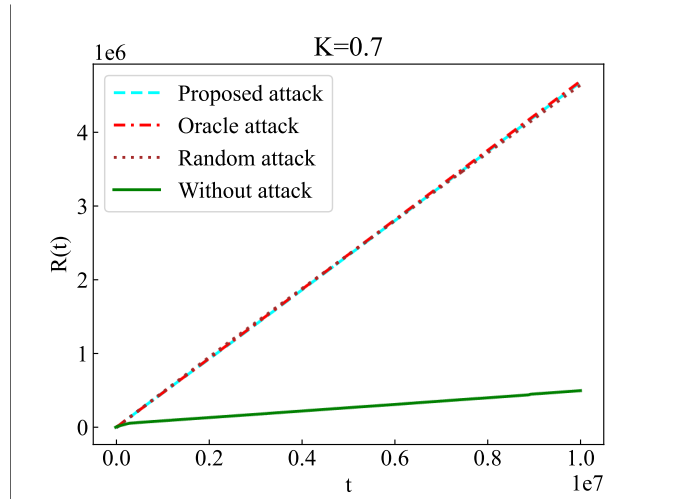
(a) $|v_K| = 0.0$



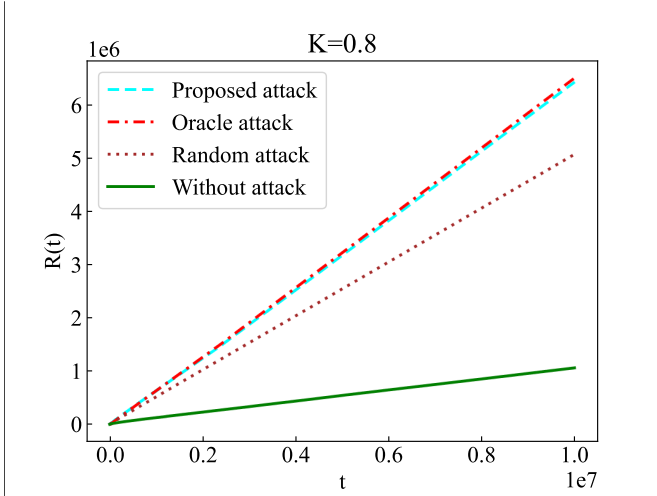
(b) $|v_K| = 0.2$



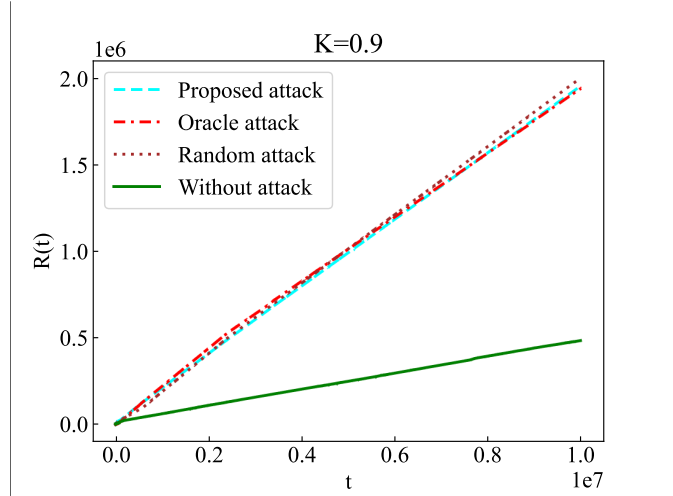
(c) $|v_K| = 0.4$



(d) $|v_K| = 0.7$

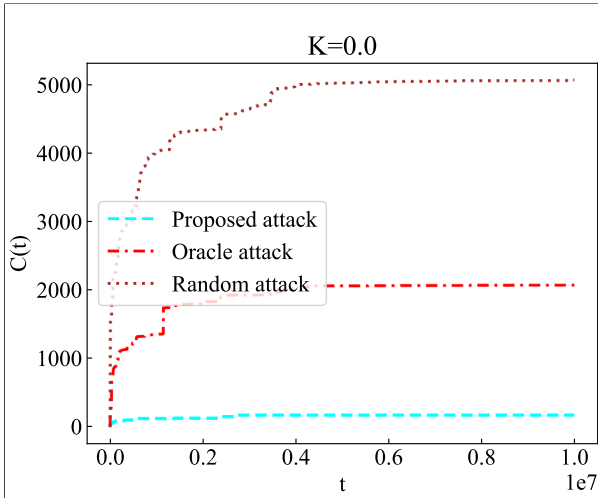


(e) $|v_K| = 0.8$

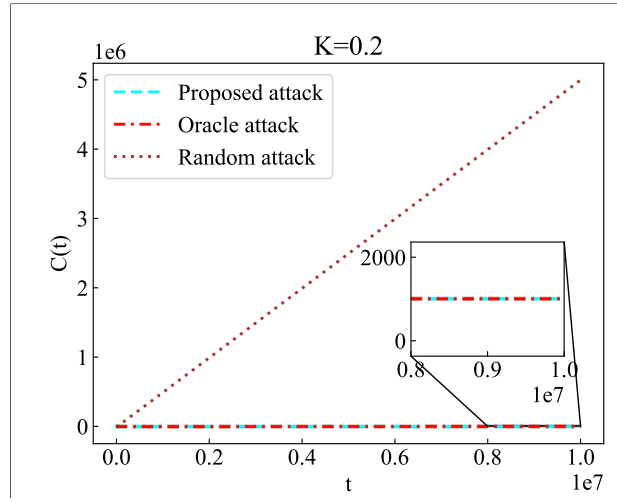


(f) $|v_K| = 0.9$

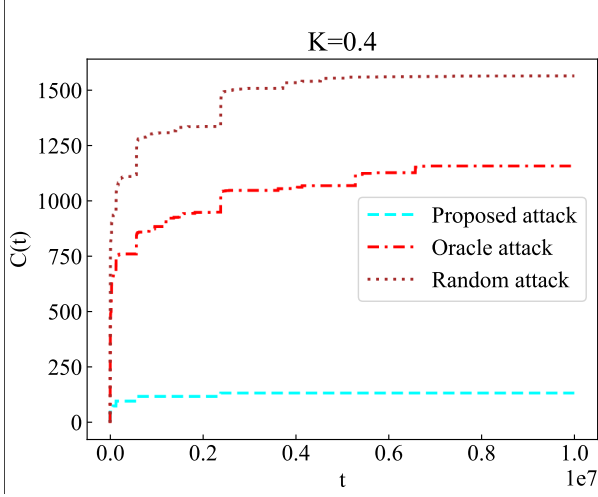
Figure 2: The *Regret* performance of HCT under our attack.



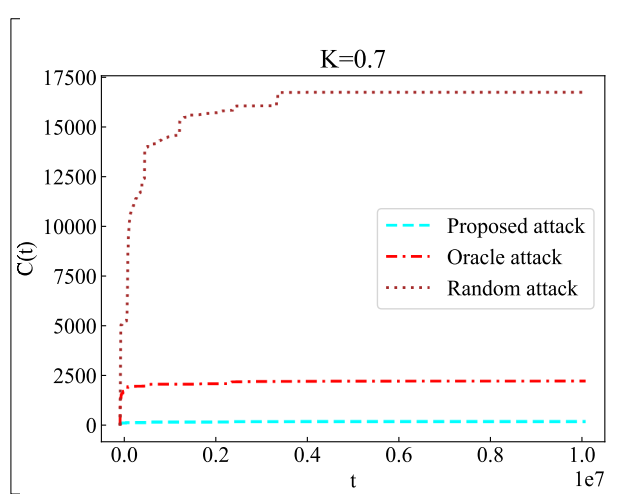
(a) $|v_K| = 0.0$



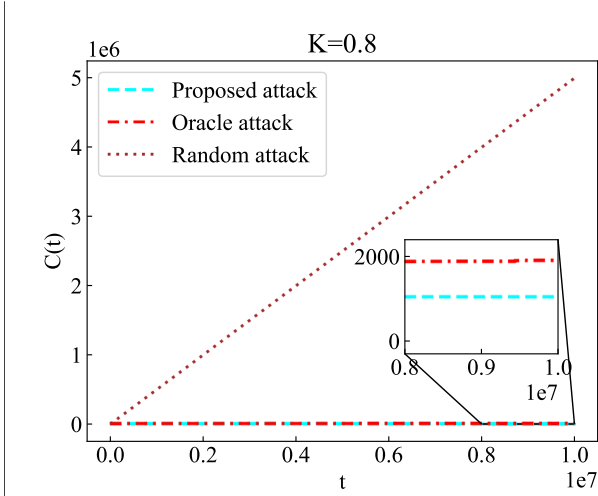
(b) $|v_K| = 0.2$



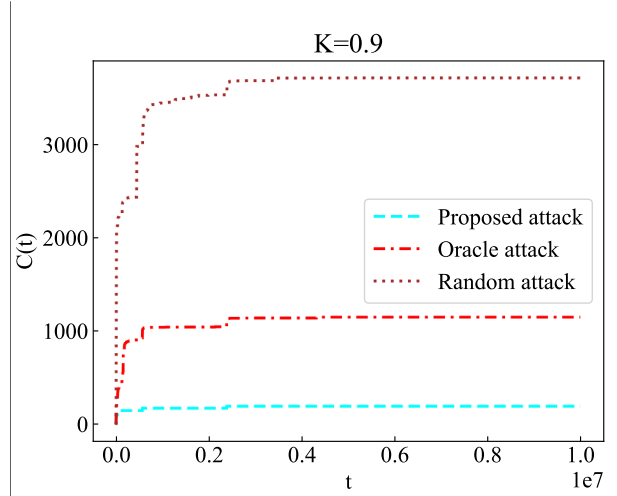
(c) $|v_K| = 0.4$



(d) $|v_K| = 0.7$



(e) $|v_K| = 0.8$



(f) $|v_K| = 0.9$

Figure 3: The $Cost$ performance of our attack.

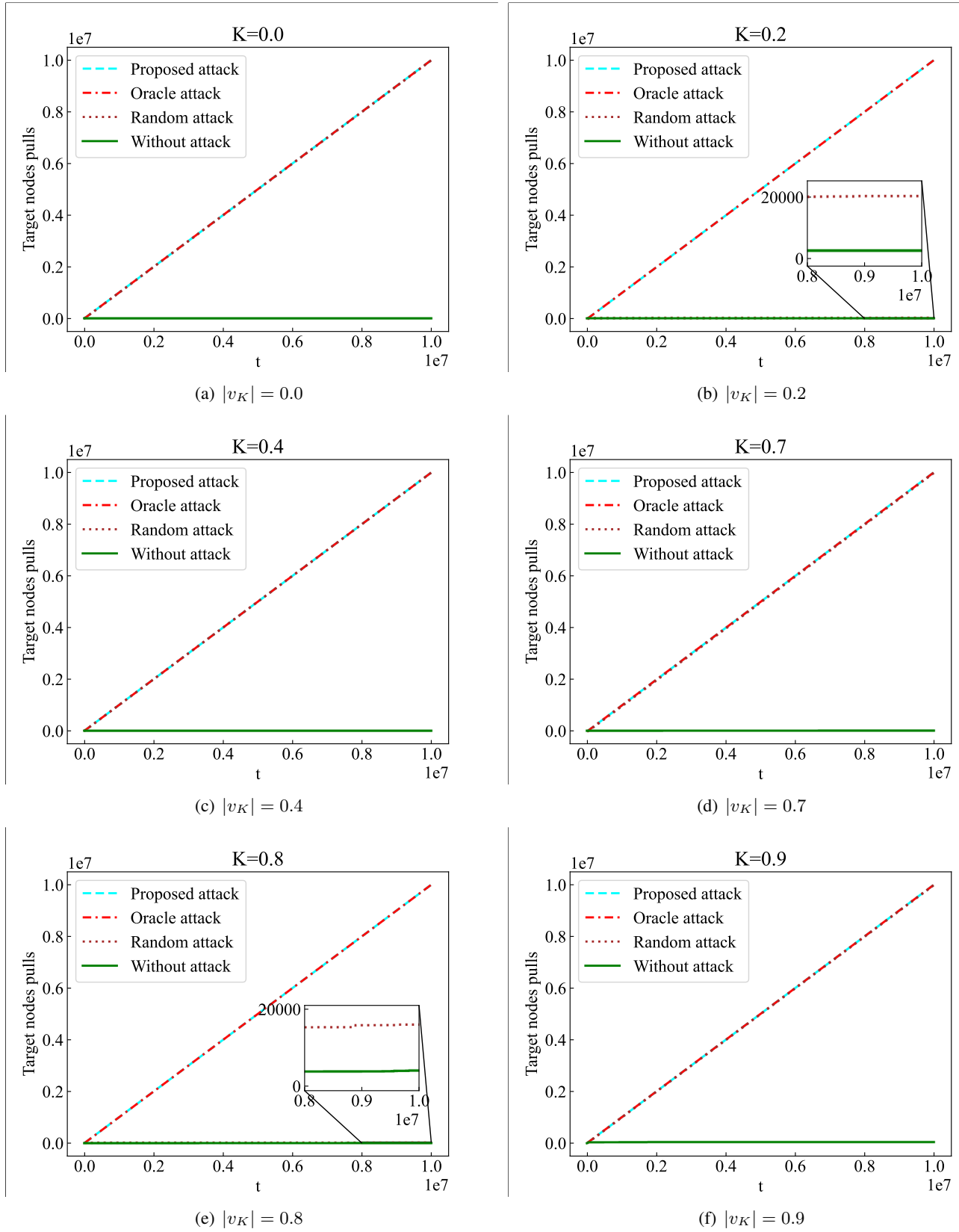


Figure 4: The *Target nodes pulls* performance of our attack.