

Assignment 1: Imitation Learning

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Collaborators: YOUR COLLABORATORS

1 Behavioral Cloning (9.75 pt)

1.1 Part 2 (1.5 pt)

TODO

Table 1: Report your result in this table.

Metric/Env	Ant-v2	Humanoid-v2	Walker2d-v2	Hopper-v2	HalfCheetah-v2
Mean	4713.653	10344.518	5566.846	3772.670	4205.778
Std.	12.197	20.981	9.238	1.948	83.039

1.2 Part 3 (5.25 pt)

TODO

Table 2: BC vs Expert performance comparison.

Hyperparameters: learning_rate=4e-3, n_layers=5, n_iter=1, eval_batch_size=5000, ep_len=1000 (approximately 5 evaluation trajectories per environment).

Ant-v2 achieves 91.7% expert performance (>30% threshold), while Humanoid-v2 achieves 3.1% expert performance (<30% threshold).

Env	Ant-v2		Humanoid-v2	
Metric	Mean	Std.	Mean	Std.
Expert	4713.653	12.197	10344.518	20.981
BC	4323.741	509.877	320.130	48.081

1.3 Part 4 (3 pt)

I tested the learning rate hyperparameter on Ant-v2, varying it from 1e-4 to 5e-2. Learning rate controls the gradient step size during training.

The results show optimal performance at lr=4e-3 (4103 return), with our Part 3 result of 4324 falling within the standard deviation range. Lower rates (1e-4) lead to undertraining, while higher rates (5e-2) cause instability. The performance drops significantly at the extremes.

See Figure 1 on the next page for a summary of these results.

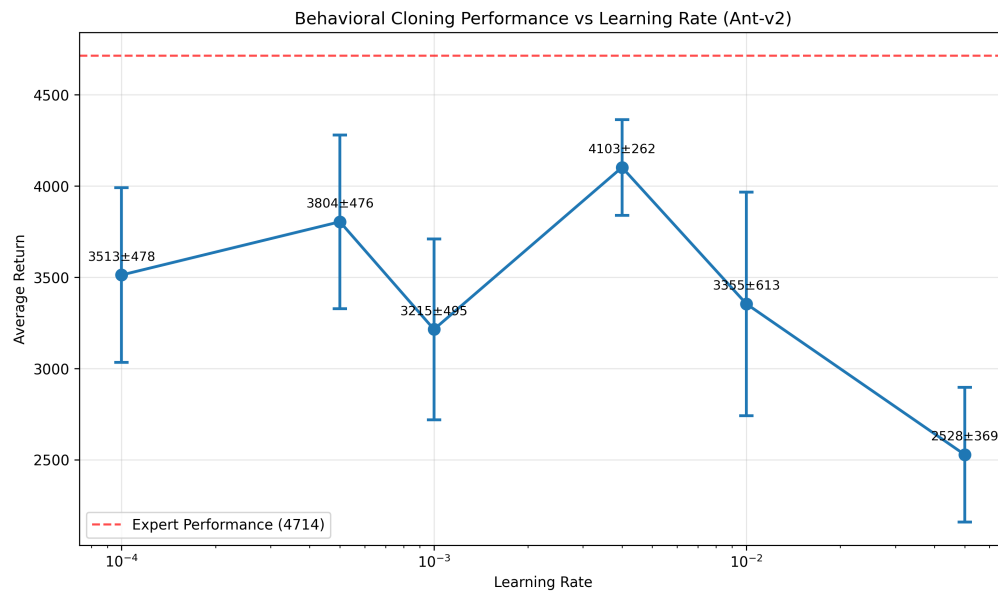


Figure 1: BC agent's performance varies with the learning rate parameter in the Ant-v2 environment. Peak performance at $lr=4e-3$, with worse performance at very low and high rates. Error bars show std over 5 runs.

2 DAgger (5.25 pt)

2.1 Part 2 (5.25 pt)

Report the results for Ant-v2 and HalfCheetah-v2 in Fig. 2:

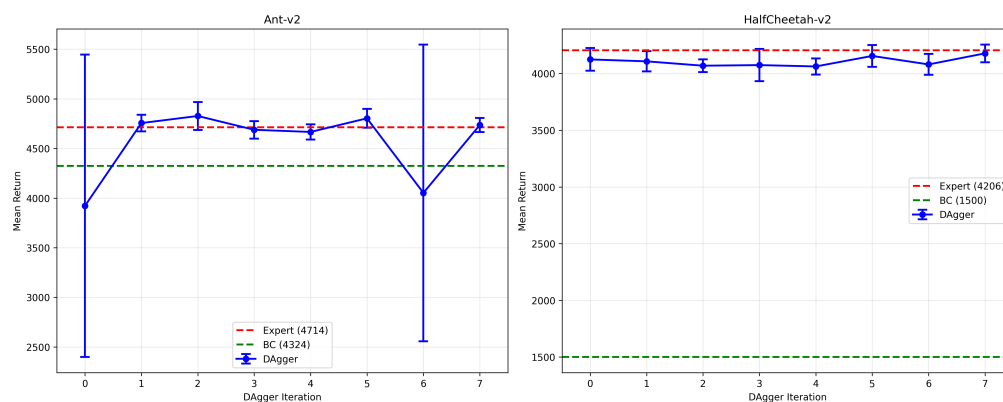


Figure 2: Learning curve, plotting the number of DAgger iterations vs. the policy's mean return, with error bars to show the standard deviation. Please show the Ant-v2 environment results on the left and the results from HalfCheetah-v2 on the right. Network architecture: 3-layer MLP. DAgger was run for 8 iterations with expert relabeling at each iteration.