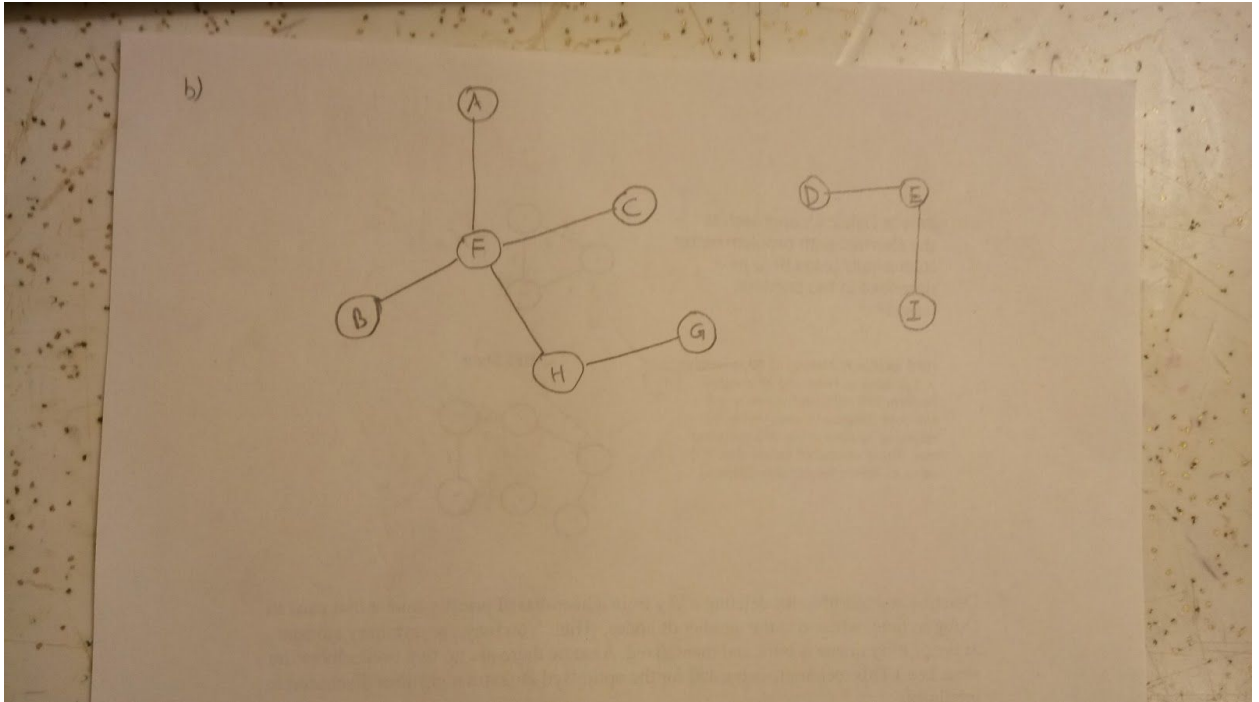


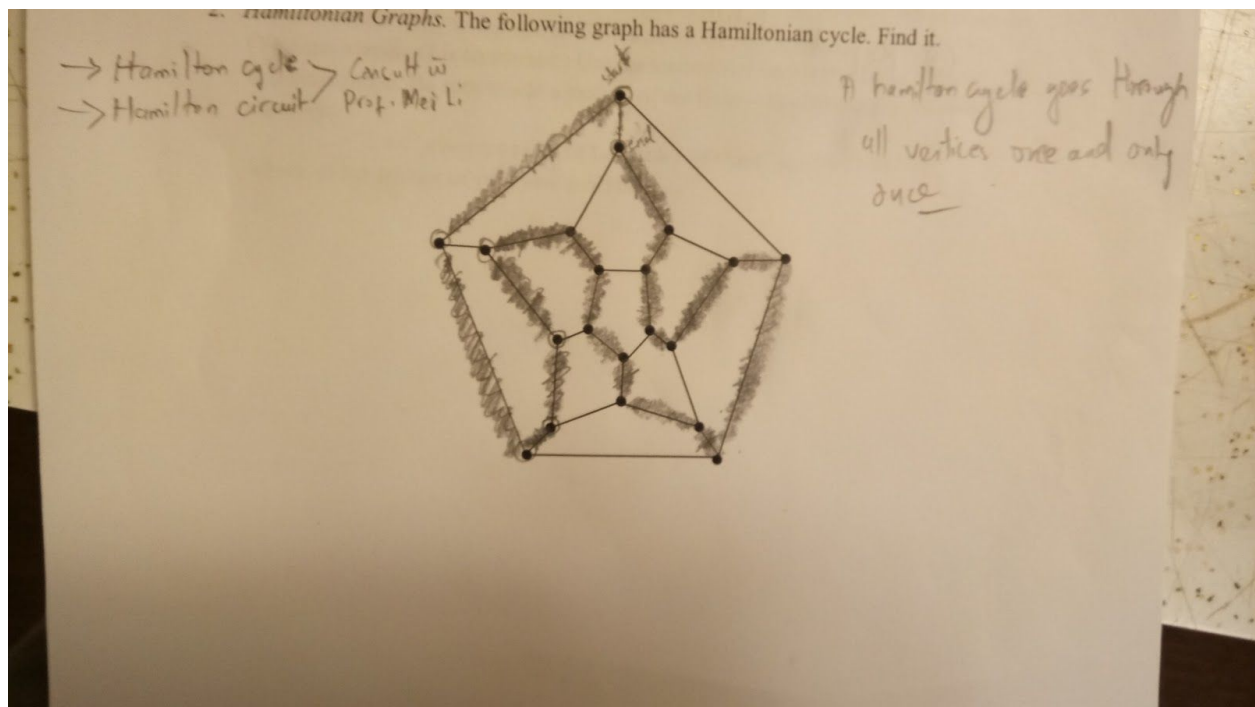
### Problem 1

- a) The graph is not connected. It has 2 connected components
- b) Spanning forest



- c) The graph cannot have a hamilton cycle because it's disconnected. Note that a hamilton cycle goes through all of vertices once.
- d) A vertex cover is a set of all vertices that cover all the edges . In our case of course there exists more than one vertex covers like  $\{F,A,G,E,D\}$

### Problem 2



### Problem 3

#### Algorithm: SmallestVertexCover

Input: A graph  $G$  whose set of vertices is denoted  $V$  and set of edges is denoted  $E$

Output: Smallest size of a vertex cover  $U$  for  $G$

$pow \leftarrow \text{PowerSet}(V)$

$minCover \leftarrow V$

$minVal \leftarrow |V|$

for each  $U$  in  $pow$  do

$isCover \leftarrow \text{true}$

    //verify  $U$  is a vertex cover

    for each  $e$  in  $E$  do

$(u,v) \leftarrow \text{computeEndpoints}(e)$

        if (  $!(\text{belongsTo}(u,U) \text{ and } \text{belongsTo}(v,U))$  )

$isCover \leftarrow \text{false}$

        if ( $isCover$  and  $U.size() < minCover.size()$ ) then

$minCover \leftarrow U$

$minVal \leftarrow |U|$

return  $minVal$

#### Problem 4

//Checking if there is a path bwn 2 vertices

```
public class PathExists extends BreadthFirstSearch {
    private Vertex target;
    private boolean pathFound = false;
    private int numComponents = 0;
    public PathExists(Graph graph) {
        super(graph);
    }
    @Override
    public void processVertex(Vertex w) {
        //Change value of pathFound only if we are working in
        //the 0th component.
        if(w.equals(target) && numComponents == 0) pathFound = true;
    }
    @Override
    public void additionalProcessing() {
        numComponents++;
    }
    public boolean pathExists(Vertex u, Vertex v) {
        target = v;
        start(u);
        return pathFound;
    }
}
```

//Checking if the graph is connected and how many components exist

```
public class IsConnected extends BreadthFirstSearch {
    private int numComponents = 0;
    public IsConnected(Graph graph) {
        super(graph);
    }

    @Override
    public void additionalProcessing() {
        numComponents++;
    }

    public boolean isConnected() {
        start();
        return numComponents == 1;
    }
}
```

```

    }

}
//Checking if there is a cycle

public class HasCycle extends BreadthFirstSearch {
//    private ArrayList<Edge> tree = new ArrayList<Edge>();
    private int numTreeEdges = 0;
    private int numGraphEdges = 0;
    public HasCycle(Graph graph) {
        super(graph);
        numGraphEdges = graph.edges().size();
    }
    protected void processEdge(Edge e) {
        //tree.add(e);
        ++numTreeEdges;
    }

    public boolean hasCycle() {
        start();
        return numGraphEdges > numTreeEdges;
    }
}

```

## Problem 5

```

public class ShortestPath extends BreadthFirstSearch {
    private HashMap<Vertex, Integer> levelsMap = new HashMap<Vertex, Integer>();
    private HashMap<Vertex, Vertex> parentMap = new HashMap<Vertex, Vertex>();
    /** Assumes g is connected */
    public ShortestPath(Graph g) {
        super(g);
    }
    protected void processVertex(Vertex v) {
        Vertex parent = parentMap.get(v);
        if(parent == null) // v has no parent, v is the starting vertex
            levelsMap.put(v, 0);
        else
            levelsMap.put(v, levelsMap.get(parent) + 1);
    }
}

```

```

    }
    @Override
    protected void processEdge(Edge e) {
        //first component is child, second component is parent
        parentMap.put(e.u, e.v);
    }
    public int computeShortestPathLength(Vertex s, Vertex v) {
        start(s);
        //now levels and parents have been computed
        return levelsMap.get(v);
    }

    public List<Edge> computeShortestPath(Vertex s, Vertex v) {
        start(s);
        //now levels and parents have been computed
        return shortestPath(new ArrayList<Edge>(), s, v);
    }

    private List<Edge> shortestPath(List<Edge> temp, Vertex s, Vertex v) {
        if(v.equals(s)) {
            return temp;
        }
        Vertex w = parentMap.get(v);
        temp.add(0, new Edge(w, v)); //add to the front of the list
        return shortestPath(temp, s, w);
    }
}

```