


Robot::gripSide



```
graph LR; A[Robot::gripSide] --> B[Robot::getWheel]
```

A diagram illustrating a function call. On the left, a gray rectangular box with a black border contains the text "Robot::gripSide". A dark blue arrow points from the right side of this box to the left side of a white rectangular box with a black border on the right. This second box contains the text "Robot::getWheel".

Robot::getWheel