


Robot::moveBodyWithImpulse



```
graph LR; A[Robot::moveBodyWithImpulse] --> B[Robot::allowMotorRotation]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray fill and a black border, containing the text 'Robot::moveBodyWithImpulse'. The right box has a white fill and a black border, containing the text 'Robot::allowMotorRotation'. A dark blue arrow points from the right side of the left box to the left side of the right box.

Robot::allowMotorRotation