

Report

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1 Entropy Regularized POMDP Model

Assume when $\alpha = 1$, namely using standard Gumbel distribution, the related functions and parameters are $U_\tau^{(1)}, V_t^{(1)}, Q_t^{(1)}, r^{(1)}, \pi^{(1)}, \theta^{(1)}$. Then for any $\alpha \neq 1$, then we have the following equations

- $U_\tau^\alpha = \alpha \cdot U_\tau^{(1)}$
- $V_t^\alpha = \alpha \cdot V_t^{(1)}$
- $Q_t^\alpha = \alpha \cdot Q_t^{(1)}$
- $r^\alpha = \alpha \cdot r^{(1)}$
- $\theta_1^\alpha = \alpha \cdot \theta_1^{(1)}$
- $\pi^\alpha = \pi^{(1)}$
- $\sigma^\alpha = \sigma^{(1)}$
- $\lambda^\alpha = \lambda^{(1)}$
- $\theta_2^\alpha = \theta_2^{(1)}$

Parameter	α	$\theta_{3,0,0}$	$\theta_{3,0,1}$	$\theta_{3,0,2}$	$\theta_{3,1,0}$	$\theta_{3,1,1}$	$\theta_{3,1,2}$	$\theta_{2,0}$	$\theta_{2,1}$	$\theta_{1,0}$	$\theta_{1,1}$	RC
Good State	1	0.039	0.333	0.590	*	*	*	0.949	*	0.219	*	9.257
	0.1									0.022	0.926	
	0.01									0.002		
Bad State	1	*	*	*	0.181	0.759	0.061	*	0.988	*	1.165	0.093
	0.1									0.116		
	0.01									0.012		
log-Likelihood	-3819											

TABLE 1. PARAMETER ESTIMATES AND LOG-LIKELIHOOD PROVIDED BY THE POMDP MODEL ON GROUP 4 DATA SET

2 Appendix: Reasons

$$\begin{aligned}
U_{\tau,\theta}(h_\tau) &= \sup_{\pi \in \Pi} \mathbb{E} \left[\sum_{t \geq \tau} \beta^{t-\tau} [r_{\theta_1}(z_t, s_t, a_t) + \alpha \mathcal{H}(\pi(\cdot|h_t))] \right] \\
&= \sup_{\pi \in \Pi} \mathbb{E} \left[r_{\theta_1}(z_\tau, s_\tau, a_\tau) + \alpha \mathcal{H}(\pi(\cdot|h_\tau)) \right. \\
&\quad \left. + \beta \sum_{t \geq \tau+1} \beta^{t-(\tau+1)} [r_{\theta_1}(z_t, s_t, a_t) + \alpha \mathcal{H}(\pi(\cdot|h_t))] \right]
\end{aligned}$$

$$\begin{aligned}
U_{t,\theta}(h_t) &= \max_{\pi(\cdot|h_t)} \left\{ \sum_{a_t} \sum_{s_t} r_{\theta_1}(z_t, s_t, a_t) x_{t,\theta_2}(s_t) \pi(a_t|h_t) \right. \\
&\quad \left. + \alpha \mathcal{H}(\pi(\cdot|h_t)) \right. \\
&\quad \left. + \beta \sum_{z_{t+1}} \sum_{a_t} \mathbb{P}_{\theta_2}(z_{t+1}|h_t, a_t) \pi(a_t|h_t) U_{t+1,\theta}(h_{t+1}) \right\}. \tag{2.1}
\end{aligned}$$

$$\sigma_{\theta_2}(z_{t+1}, z_t, x_{t,\theta_2}, a_t) \triangleq \sum_{s'} \sum_s x_{t,\theta_2}(s) \mathbb{P}_{\theta_2}(z_{t+1}, s' | z_t, s, a_t),$$

$$\lambda_{\theta_2}(z_{t+1}, z_t, x_{t,\theta_2}, a_t) \triangleq \frac{x_{t,\theta_2}^\top P_{\theta_2}(z_{t+1}, z_t, a_t)}{\sigma_{\theta_2}(z_{t+1}, z_t, x_{t,\theta_2}, a_t)}, \tag{2.2}$$

assuming $\sigma_{\theta_2}(z_{t+1}, z_t, x_{t,\theta_2}, a_t) \neq 0$, where we denote the (s, s') element of the matrix $[P_{\theta_2}(z_{t+1}, z_t, a_t)]_{s,s'} \triangleq \mathbb{P}_{\theta_2}(z_{t+1}, s' | z_t, s, a_t)$, $s, s' \in S$, x_{t,θ_2}^\top is the transpose of x_{t,θ_2} , and

$$\begin{aligned}
&[x_{t,\theta_2}^\top P_{\theta_2}(z_{t+1}, z_t, a_t)]_{s_{t+1}} \\
&\triangleq \sum_s x_{t,\theta_2}(s) \mathbb{P}_{\theta_2}(z_{t+1}, s_{t+1} | z_t, s, a_t).
\end{aligned}$$

$$r_{\theta_1}(z_t, x_{t,\theta_2}, a_t) \triangleq \sum_s r_{\theta_1}(z_t, s, a_t) x_{t,\theta_2}(s).$$

Proposition 1.

$$\begin{aligned}
V_{t,\theta}(z, x) &= \max_{\pi(\cdot|z,x)} \left\{ \sum_a r_{\theta_1}(z, x, a) \pi(a|z, x) + \alpha \mathcal{H}(\pi(\cdot|z, x)) \right. \\
&\quad \left. + \beta \sum_a \sum_{z'} \sigma_{\theta_2}(z', z, x, a) V_{t+1,\theta}(z', x'(a)) \pi(a|z, x) \right\} \\
[\mathcal{B}_\theta Q](z, x, a) &= r_{\theta_1}(z, x, a) + \beta \sum_{z'} \sigma_{\theta_2}(z', z, x, a) V(z', x'), \tag{2.3}
\end{aligned}$$

where $x' = \lambda_{\theta_2}(z', z, x, a)$ and

$$\frac{1}{\alpha} V(z, x) \triangleq \max_{\hat{\pi}(\cdot|z,x)} \left[\sum_a \frac{1}{\alpha} Q(z, x, a) \hat{\pi}(a|z, x) + \mathcal{H}(\hat{\pi}(\cdot|z, x)) \right].$$

Theorem 1. (a) $V(z, x) = \alpha \log \sum_a \exp(\frac{1}{\alpha} Q(z, x, a))$ for all $Q \in \mathcal{Q}$. (b) $\mathcal{B}_\theta : \mathcal{Q} \rightarrow \mathcal{Q}$ is a contraction mapping with modulus $\beta \in (0, 1)$ and (c) the optimal policy is of the form:

$$\pi_\theta(a|z, x) = \frac{\exp \frac{1}{\alpha} Q_\theta(z, x, a)}{\sum_{a' \in A} \exp \frac{1}{\alpha} Q_\theta(z, x, a')}, \tag{2.4}$$

where Q_θ is the unique fixed point of \mathcal{B}_θ (i.e. $Q_\theta = \mathcal{B}_\theta Q_\theta$).