

Mar 4-7:57 AM

$$P_{t}(i,j) = P\{Y(t) = j \mid Y(6) = i\}$$

$$P_{s}(i,j) = P\{Y(t+s) = j \mid Y(t) = i\}$$

$$epend on t$$

$$epend on t$$

$$for each t and s$$

$$P_{t}(i,j) \geq 0$$

$$P_{t}(i,j) \geq 0$$

$$P_{t}(i,j) \geq 0$$

$$P_{t}(i,k) = 1$$

Let
$$V(t) = \inf \{ s > 0 : Y(t+s) \neq Y(t) \}$$

 $\uparrow : me to next jump$
 $P\{V(t) > u| Y(t) = i \} = e^{-\lambda(i)u} \quad for u \ge 0$

Det. A state is is called absorbing if $\lambda(i)=0$. State is stable if $0 < \lambda(i) < \infty$. State is instantaneous if $\lambda(i) = \infty$.

$$T_{n} = 0$$

$$T_{n+1} = T_n + V(T_n)$$

$$X_n = Y(T_n)$$

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$$P\{X_{n+i}=j, T_{n+i}=T_n > u \mid X_{o}, \dots, X_{n}; T_{o}, \dots, T_{n}\} = Q(i,j)e$$

$$P\{T_{n+i}=T_n > u \mid X_{n}=i, X_{n+i}=j\} = P\{T_{n+i}=T_n > u \mid X_{n}=i\} = e$$

$$P\{X_{n+i}=j \mid X_{n}=i\} = Q(i,j)$$

$$F_{ij} \leq \sum_{k=0}^{n} \frac{1-P_{k}(i,k)}{t} = \sum_{k=0}^{n} \frac{1-e^{-\lambda(i)}t}{t} = \lambda(i)$$

$$F_{ij} \leq \sum_{k=0}^{n} \frac{1-P_{k}(i,j)}{t} = \lambda(i)Q(i,j)$$

$$F_{ij} \leq \sum_{k=0}^{n} \frac{P_{k}(i,j)}{t} = \lambda(i)Q(i,j)$$

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Kolmogorov backword eq.

$$P((i,j)) = \sum_{k} P_{s}(i,k) P_{t}(k,j)$$

$$= \sum_{k \neq i} P_{s}(i,k) P_{t}(k,j) + P_{s}(i,k) P_{t}(i,j) + P_{t}(i,j)$$

$$= \sum_{k \neq i} P_{s}(i,k) P_{t}(k,j) + P_{s}(i,k) P_{t}(i,j) + P_{t}(i,j)$$

$$= \sum_{k \neq i} P_{s}(i,k) P_{t}(k,j) - \left[1 - P_{s}(i,k) P_{t}(i,j) - \sum_{s \neq i} P_{s}(i,k) P_{t}(k,j) - \left[1 - P_{s}(i,k) P_{t}(i,j) - \sum_{s \neq i} P_{s}(i,k) P_{t}(k,j) - \sum_{s \neq i} P_{s}(i,k) P_{t}(i,j) + P_{s}(i,k) P_{t}(i,j) - \sum_{s \neq i} P_$$

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$$f'(t) = a f(t) \implies f(t) = e^{at}$$

$$P'(t) = G P(t) \implies P(t) = e^{Gt}$$

$$P_{t}(i,j) = e^{Gt}(i,j)$$

$$e^{a} = \sum_{n=0}^{\infty} \frac{a^{n}}{n!}$$

$$e^{a} = \sum_{n=0}^{\infty} \frac{A^{n}}{n!}$$

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If the imbedded Markov chain is recurrent, then the Markov process is called recurrent.

For a recurrent Markov process

lun P(Y(t)=j|Y(0)=i)=p(j) where

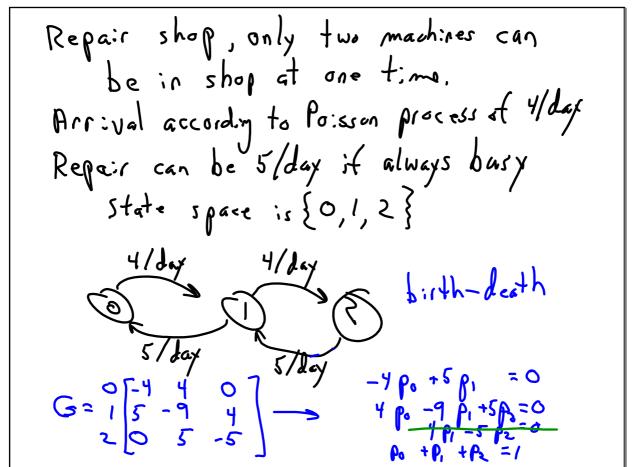
t=00

pG=0 and Ep(j)=1

thin t f(Y(s))ds = p.f = in (0,t)

where f(i) is rate of reward while is state i

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