

$\{X_n, T_n\}$ abbreviation for $\{(X_n, T_n) : n = 0, 1, \dots\}$

$\{Y(t)\}$

Example \rightarrow Markov processes are MRP

Consider Markov process with generator $\begin{bmatrix} -3 & 3 & 0 \\ 2 & -5 & 3 \\ 0 & 2 & -2 \end{bmatrix}$

Fixed t

$Q(t)$ represent the matrix whose elements are $Q(i, j, t)$

$$Q(t) = \begin{bmatrix} 0 & 1 - e^{-3t} & 0 \\ 0.4(1 - e^{-5t}) & 0 & 0.6(1 - e^{-5t}) \\ 0 & 1 - e^{-2t} & 0 \end{bmatrix}$$

$Q(i, j, t) =$ prob. of going from state i to state j within t time units.

Fix (i, j) and consider the function $t \mapsto Q(i, j, t)$

$$\text{Let } P(i, j) = \lim_{t \rightarrow \infty} Q(i, j, t) \leq 1$$

$$P(i, j) \geq 0 \quad \forall i, j \quad \text{and} \quad \sum_j P(i, j) = 1 \Rightarrow P \text{ is a Markov matrix}$$

$\Rightarrow \{X_n\}$ is a Markov chain

$$P\{T_1 \leq t \mid X_0 = i, X_1 = j, X_2 = k\} = \frac{Q(i, j, t)}{P(i, j)} \quad \text{if } P(i, j) > 0$$

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

$\rightarrow P\{T_1 \leq t, X_1 = j, X_2 = k \mid X_0 = i\} = P\{X_1 = j, T_1 \leq t \mid X_0 = i\} P\{j, k\}$
 $\rightarrow P\{X_1 = j, X_2 = k \mid X_0 = i\} = P(i, j) P(j, k)$

$$P\{T_1 - T_0 \leq t_1, T_2 - T_1 \leq t_2, T_3 - T_2 \leq t_3, | X_0 = i_0, X_1 = i_1, X_2 = i_2\}$$

$$= G(i_0, i_1, t_1) G(i_1, i_2, t_2) G(i_2, i_3, t_3)$$

where $G(i, j, t) = \frac{Q(i, j, t)}{P(i, j)}$ with $\frac{Q}{P} = 1$

\Rightarrow increments $T_1 - T_0, T_2 - T_1, T_3 - T_2, \dots$ are conditionally independent given the Markov chain $\{X_n\}$
and the increment $T_{n+1} - T_n$ only depends on X_n and X_{n+1}

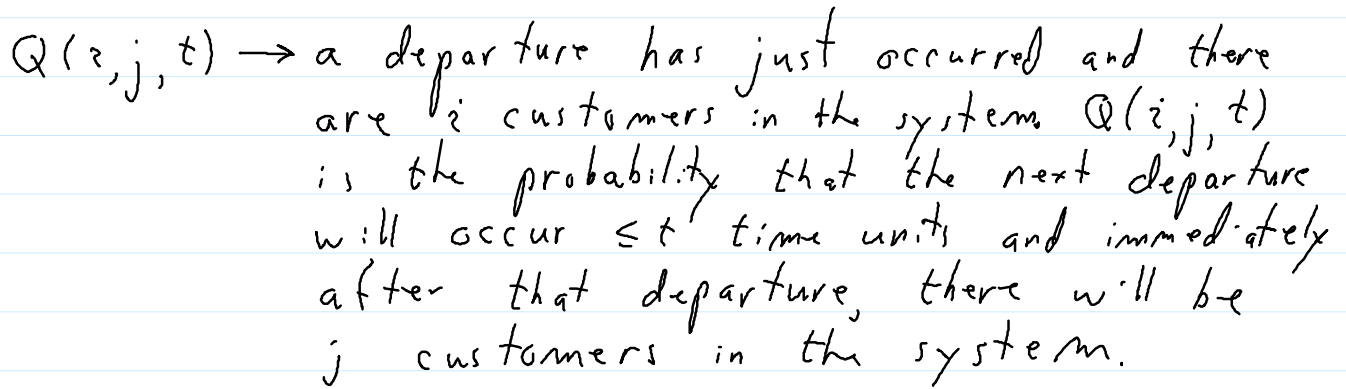
Corollary: If E has only one state, $\{T_n\}$ forms a renewal process

Counter Type I: $E = \{0, 1\} = \{\text{unlocked}, \text{locked}\}$

$Q(0, 1, t) \rightarrow$ probability of going from unlocked to locked in less than or equal to t time units

$Q(1, 0, t) \rightarrow$ prob. of going from locked to unlocked in $\leq t$ time units

$$\bar{Q}(t) = \begin{bmatrix} 0 & 1 - e^{-\lambda t} \\ \psi(t) & 0 \end{bmatrix}$$



$$Q(z, t) = \int_{[0, t]} \psi(ds) e^{-\lambda s} \leftarrow \text{no arrivals before service}$$

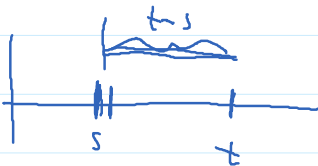
$$Q(3, 3, t) = \int_{[0, t]} \varphi(ds) \boxed{e^{-\lambda s} (\lambda s)} \leftarrow \text{exactly one arrival during service time}$$

$$Q(3, 4, t) = \int_{[0, t]} \varphi(ds) \frac{e^{-\lambda s} (\lambda s)^2}{2!} \leftarrow \text{exactly two arrivals during service time}$$

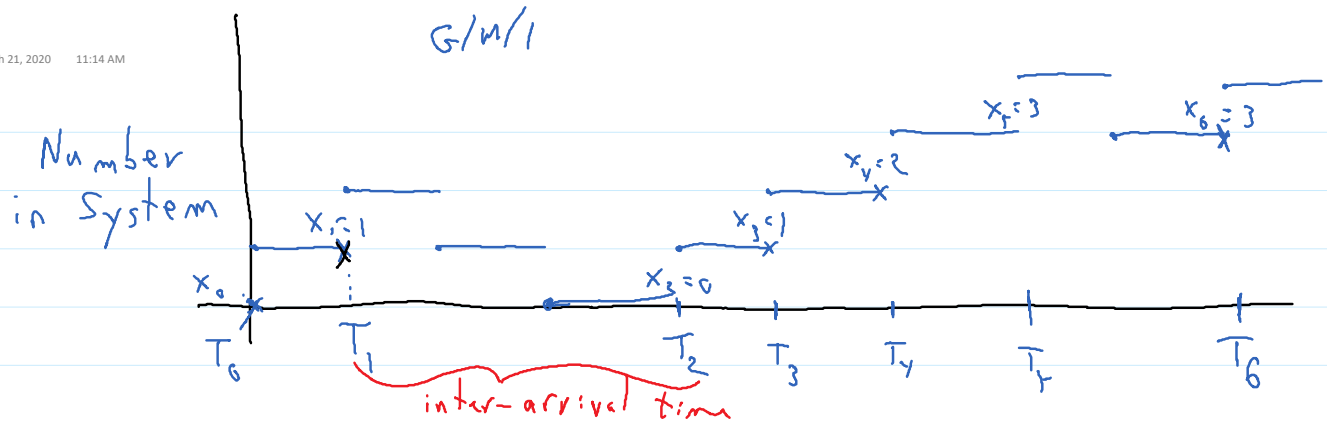
$$g_n(t) = \int_{[0,t]} \dot{\varphi}(ds) \frac{e^{-\lambda s} (\lambda s)^n}{n!}$$

$$Q(0,0,t) = \int_{[0,t]} \lambda e^{-\lambda s} f_0(t-s) ds$$

$$Q(t) = \begin{bmatrix} p_0(t) & p_1(t) & p_2(t) & p_3(t) & \dots \\ q_0(t) & q_1(t) & q_2(t) & q_3(t) & \dots \\ 0 & q_0(t) & q_1(t) & q_2(t) & \dots \\ 0 & 0 & q_0(t) & q_1(t) & \dots \\ 0 & 0 & 0 & q_0(t) & \dots \end{bmatrix}$$



$$p_n(t) = \int_{[0, t]} \lambda e^{-\lambda s} g_n(t-s) ds$$



$Q(i, j, t)$ = arrival just occurred and i are in system, not including the arriving customer. $Q(i, j, t)$ is prob. next arrival occurs before t and j in system at arrival time, not counting the arriving customer.

$$Q(t) = \begin{bmatrix} r_0(t) & q_0(t) & & & 0 \\ r_1(t) & q_1(t) & q_0(t) & & \\ r_2(t) & q_2(t) & q_1(t) & q_0(t) & \\ r_3(t) & q_3(t) & q_2(t) & q_1(t) & q_0(t) \end{bmatrix}$$

$$q_n(t) = \int_{[0, t]} \varphi(ds) \frac{e^{-\mu s} (\mu s)^n}{n!} \leftarrow n \text{ departure during an inter-arrival time}$$

$$r_n(t) = \varphi(t) - \sum_{k=0}^n q_k(t)$$