Lecture 2: Linear Regression

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From intuition to implementation — simple and multiple linear regression, OLS theory, regularization (Ridge/Lasso), evaluation with R^2 , and practical diagnostics.

1. Learning Objectives

After this lecture, you will be able to:

- Explain the intuition behind simple and multiple linear regression.
- Derive the closed-form Ordinary Least Squares (OLS) solution.
- Interpret regression coefficients, residuals, and R^2 .
- Understand Ridge, Lasso, and Elastic Net regularization.
- Implement regression in Python and analyze model diagnostics.

2. Intuition

Linear regression models how a continuous target y changes with one or more predictors x_1, \ldots, x_p . We start with a straight line (simple regression), then extend to multiple features (multiple regression). Parameters are chosen to minimize squared prediction errors (least squares). This connects optimization, geometry (projection onto the column space of X), and statistics (assumptions about noise).

Example (simple): Predict house price from floor area. A line $\hat{y} = \beta_0 + \beta_1 x$ summarizes the trend; the best line is the one with the smallest average squared residual.

When predictors are many or correlated, OLS can overfit or become unstable. **Regularization** (Ridge/Lasso) shrinks coefficients to improve generalization and interpretability.

3. Simple Linear Regression

3.1 Population Model

Assume two real-valued random variables X and Y satisfy

$$Y \approx \beta_0 + \beta_1 X$$
.

The best linear approximation (smallest expected squared error) solves

$$\min_{\beta_0, \beta_1} E[(Y - \beta_0 - \beta_1 X)^2].$$

Differentiating and solving gives

$$\beta_1^* = \frac{\text{Cov}(X, Y)}{\text{Var}(X)}, \qquad \beta_0^* = E[Y] - \beta_1^* E[X].$$

3.2 Sample Model

Given samples (x_i, y_i) , i = 1, ..., n, estimate by minimizing the sum of squared errors (SSE):

$$\min_{\beta_0,\beta_1} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2.$$

The solution is

$$\hat{\beta}_1 = \frac{\sum_i (x_i - \bar{x})(y_i - \bar{y})}{\sum_i (x_i - \bar{x})^2}, \qquad \hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}.$$

Prediction for new x_{new} : $\hat{y}_{\text{new}} = \hat{\beta}_0 + \hat{\beta}_1 x_{\text{new}}$.

Notation note. In statistics, regression coefficients are denoted by β , while in machine learning literature, parameters are often written as θ or w. Throughout this course we use β for clarity.

4. Multiple Linear Regression

4.1 Model and Matrix Form

With p predictors,

$$y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_n x_{in} + \varepsilon_i.$$

In matrix form,

$$y = X\beta + \varepsilon$$
,

where $y \in \mathbb{R}^n$, $X \in \mathbb{R}^{n \times (p+1)}$ (first column of ones), and $\beta \in \mathbb{R}^{p+1}$.

4.2 Least Squares Solution

We minimize

$$J(\beta) = \|y - X\beta\|^2.$$

Setting $\nabla_{\beta} J = 0$ yields

$$\hat{\beta} = (X^T X)^{-1} X^T y,$$

if X^TX is invertible.

Non-full rank X. If X^TX is singular (e.g. p > n or exact collinearity), the minimum-norm least-squares solution uses the *Moore–Penrose pseudoinverse*:

$$\hat{\beta} = X^+ y.$$

Regularization (e.g. Ridge) always makes the matrix invertible.

4.3 Geometric Interpretation

The fitted values $\hat{y} = X\hat{\beta}$ are the projection of y onto the column space of X; residuals $r = y - \hat{y}$ are orthogonal to all columns of X, i.e. $X^T r = 0$.

5. Ordinary Least Squares (OLS)

5.1 Model Assumptions

$$y = X\beta + \varepsilon$$
, $E[\varepsilon] = 0$, $Var(\varepsilon) = \sigma^2 I$.

Errors are independent, mean-zero, and homoscedastic. These ensure OLS is BLUE (Gauss–Markov). Normality of ε is not required for unbiasedness but is often assumed for t/F inference.

5.2 Unbiasedness

$$E[\hat{\beta}] = (X^T X)^{-1} X^T E[y] = (X^T X)^{-1} X^T X \beta = \beta.$$

5.3 Gauss–Markov Theorem

Under the above assumptions, OLS is the **Best Linear Unbiased Estimator (BLUE)**:

$$Var(a^T\hat{\beta}) = \sigma^2 a^T (X^T X)^{-1} a$$

for any constant vector a.

6. Regularized Linear Models: Ridge and Lasso Regression

OLS may overfit when predictors are correlated or $p \gg n$. Regularized models add a penalty on coefficient magnitude to reduce variance.

6.1 Ridge Regression (ℓ_2 Regularization)

$$J(\beta) = ||y - X\beta||^2 + \lambda ||\beta||_2^2, \quad \hat{\beta}_{ridge} = (X^T X + \lambda I)^{-1} X^T y.$$

- Shrinks coefficients continuously toward zero.
- Reduces variance and stabilizes estimates under multicollinearity.
- $\lambda = 0$ gives OLS; $\lambda \to \infty$ shrinks all coefficients to zero.

6.2 Lasso Regression (ℓ_1 Regularization)

$$J(\beta) = \|y - X\beta\|^2 + \lambda \|\beta\|_1 = \|y - X\beta\|^2 + \lambda \sum_{j=1}^{p} |\beta_j|.$$

No closed form; solved by coordinate descent.

- Encourages sparsity—some coefficients exactly zero (automatic feature selection).
- Improves interpretability with many predictors.

6.3 Comparison and Bias-Variance

	Ridge	Lasso
Penalty	ℓ_2	ℓ_1
Closed form	Yes	No
Feature selection	No	Yes
Effect	Shrinkage	Shrinkage + sparsity

Regularization increases bias but can substantially reduce variance, often lowering test error. λ is tuned by cross-validation.

Elastic Net. Combines both penalties:

$$J(\beta) = ||y - X\beta||^2 + \lambda_1 ||\beta||_1 + \lambda_2 ||\beta||_2^2.$$

Implementation details. Standardize features before regularization, and never penalize the intercept.

7. Python Implementation: Ridge and Lasso

```
import numpy as np
from sklearn.linear_model import Ridge, Lasso
from sklearn.preprocessing import StandardScaler
from sklearn.metrics import r2_score

# Data
X = np.array([[1], [2], [3], [4], [5]])
y = np.array([2.2, 4.1, 5.9, 8.2, 10.1])

# Always scale features for regularization
scaler = StandardScaler().fit(X)
X_scaled = scaler.transform(X)

ridge = Ridge(alpha=1.0).fit(X_scaled, y)
lasso = Lasso(alpha=0.1).fit(X_scaled, y)
print("Ridge coef:", ridge.coef_, "R^2:", r2_score(y, ridge.predict(X_scaled)))
print("Lasso coef:", lasso.coef_, "R^2:", r2_score(y, lasso.predict(X_scaled)))
```

8. Coefficient of Determination and Error Metrics

8.1 R^2 Definition

$$R^{2} = 1 - \frac{\text{RSS}}{\text{TSS}}, \quad \text{RSS} = \sum_{i} (y_{i} - \hat{y}_{i})^{2}, \quad \text{TSS} = \sum_{i} (y_{i} - \bar{y})^{2}.$$

8.2 Adjusted R^2

$$R_{\text{adj}}^2 = 1 - \frac{(1 - R^2)(n - 1)}{n - p - 1},$$

where p is the number of predictors (excluding the intercept).

8.3 Related Metrics

MSE = RSS/n, RMSE =
$$\sqrt{\text{MSE}}$$
, RSE (residual std. error) $\hat{\sigma} = \sqrt{\text{RSS}/(n-p-1)}$.

Uncertainty intervals. A $(1 - \alpha)$ confidence interval (CI) for the mean response at x_0 is narrower than a prediction interval (PI) for a new observation, since PI adds noise variance σ^2 .

9. Algorithm: Gradient Descent

When p is large or data are streaming, minimize

$$J(\beta) = \frac{1}{n} ||y - X\beta||^2$$

iteratively:

$$\beta^{(t+1)} = \beta^{(t)} - \eta \frac{2}{n} X^T (X \beta^{(t)} - y),$$

where η is the learning rate. Converges to the OLS solution if properly tuned.

10. Interpretation and Diagnostics

- Slope (β_j) : expected change in y per unit increase in x_j (others fixed).
- Intercept (β_0): predicted y when all $x_j = 0$.
- Residuals: should have zero mean, constant variance, and no visible pattern.
- Outliers: distort slope; examine residual plots.

Hat matrix and leverage. $\hat{y} = Hy$ where $H = X(X^TX)^{-1}X^T$. Diagonal h_{ii} measures leverage; large values indicate influential points. Use Cook's distance to assess influence.

Multicollinearity. Highly correlated predictors inflate variance of $\hat{\beta}$. The Variance Inflation Factor (VIF) for feature j is VIF_j = $1/(1 - R_j^2)$, where R_j^2 is from regressing x_j on the remaining predictors.

Heteroscedasticity and autocorrelation. Breusch-Pagan and Durbin-Watson tests help detect these violations.

5

11. Practical Tips

- Standardize or center features; centering makes $\beta_0 = \bar{y}$ and improves conditioning.
- Use Ridge/Lasso for correlated or many predictors.
- Check residuals and leverage before trusting coefficients.
- Use train/validation/test or K-fold cross-validation to tune λ and estimate generalization error.
- Avoid data leakage: fit preprocessing only on training data.
- Do not extrapolate far beyond observed x range.

12. Summary

We studied simple and multiple linear regression, derived OLS from first principles, and interpreted its geometry as a projection. Under Gauss–Markov assumptions, OLS is BLUE; with many or correlated predictors, regularization (Ridge/Lasso) improves stability and can yield sparse, interpretable models. We evaluated fit with R^2 and error metrics, explored gradient descent for large-scale data, and reviewed diagnostics for reliable inference.

- Simple \rightarrow multiple regression: $y = X\beta + \varepsilon$.
- OLS closed form $(X^TX)^{-1}X^Ty$; pseudoinverse for singular X.
- Assumptions: linearity, independence, homoscedasticity (normality for inference only).
- Regularization: Ridge (ℓ_2) for shrinkage, Lasso (ℓ_1) for sparsity, Elastic Net combines both.
- Evaluation: RSS/MSE/RMSE, \mathbb{R}^2 , adjusted \mathbb{R}^2 , CIs and PIs.
- Diagnostics: residuals, leverage, multicollinearity (VIF).
- Practice: scale features, cross-validate, avoid extrapolation.

13. Exercises

- 1. Derive the OLS estimator from $J(\beta) = ||y X\beta||^2$.
- 2. Prove that $E[\hat{\beta}] = \beta$.
- 3. Implement gradient descent for linear regression from scratch.
- 4. Compare Ridge and Lasso on a dataset using cross-validation.
- 5. Compute VIF and identify multicollinearity.
- 6. Interpret R_{adj}^2 and RMSE differences between models.

14. Further Reading

- Ryan Tibshirani, Lecture 3: Linear Regression and Prediction, UC Berkeley, 2023.
- Andrew Ng, CS229 Lecture Notes: Linear Regression.
- James et al., An Introduction to Statistical Learning, Ch. 3.
- Hastie et al., The Elements of Statistical Learning, Ch. 3.