

Basics of Applied Stochastic Processes

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Introduction

A discrete-time *stochastic process* $\{X_n : n \geq 0\}$ on a countable set S is a collection of S -valued random variables defined on a probability space $(\Omega, \mathcal{F}, \mathcal{P})$. The \mathcal{P} is a probability measure on a family of events \mathcal{F} (a σ -field) in an event-space Ω . The set S is the *state space* of the process, and the value $X_n \in S$ is the *state* of the process at *time* n . The n may represent a parameter other than time such as a length or a job number. The *finite-dimensional* distributions of the process are

$$P\{X_0 = i_0, \dots, X_n = i_n\}, \quad i_0, \dots, i_n \in S, n \geq 0 \quad (1)$$

These probabilities uniquely determine the probabilities of all events of the process.

Markov Chains

A Markov chain is defined as follows.

Definition 1. A stochastic process $X = \{X_n : n \geq 0\}$ on a countable set S is a *Markov Chain* if, for any $i, j \in S$ and $n \geq 0$,

$$P\{X_{n+1} = j | X_0, \dots, X_n\} = P\{X_{n+1} = j | X_n\} \quad (2)$$

$$P\{X_{n+1} = j | X_n\} = p_{ij} \quad (3)$$

The p_{ij} is the probability that the Markov chain jumps from state i to state j . These *transition probabilities* satisfy $\sum_{j \in S} p_{ij} = 1, i \in S$, and the matrix $\mathbf{P} = (p_{ij})$ is the *transition matrix* of the chain.

Markov Chains

Condition (2), called the *Markov property*, says that, at any time n , the next state X_{n+1} is conditionally independent of the past X_0, \dots, X_{n-1} given the present state X_n .

Condition (3) simply says the transition probabilities do not depend on the time parameter n ; the Markov chain is therefore “time-homogeneous”.