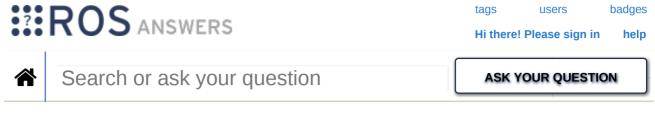
0



message filters PoseWithCovarianceStamped message_filters

Follow Dear Ros Users. I tried to use a message filters to sync asked Apr 6 '15 ver two PoseWithCovarianceStamped topics 133 •34 •41 •47 rss feed updated Apr 6 '15 void callback(const geometry_msgs::PoseWithCovarianceStampedPtr& pose_1, c onst geometry_msgs::PoseWithCovarianceStampedPtr& pose_2) Apr 6 '15 266 times } Apr 06 '15 message_filters::**Subscriber**<geometry_msgs::posewithcovariancestamped> pose _sub_1(nh, "pose_1", 1); stions message_filters::Subscriber<geometry_msgs::posewithcovariancestamped> pose _sub_2(nh, "pose_2", 1); ith ROS message message_filters::TimeSynchronizer <geometry_msgs::PoseWithCovarianceStampe d, geometry_msgs::PoseWithCovarianceStamped> sync(pose_sub_1, pose_sub_2, ation with sync.registerCallback(boost::bind(&callback, _1, _2));

but I got error at compile time:

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Rospy message_filter ApproximateTimeSynchronizer issue

/usr/include/boost/bind/bind.hpp:313:34: error: invalid initialization of reference of type ApproximateTime corrupt data 'const

boost::shared_ptr<geometry_msgs::posewithcovariancestamped_<std::allocator<void> >>&' from expression of type 'const boost::shared ptr<const geometry_msgs::posewithcovariancestamped_<std::allocator<void= unwrapper<f>::unwrap(f, 0)(a[base type::a1], a[base type::a2]);

errors while using cache filter in message_filters

Problem with message filter inizialization

How to get/set the allowed timestamp mismatch for a Time Synchronizer message filter?

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> **How to configure Time sequence** message filter

This error message is trying to tell you answered Jul 29 '17 that it expects your callback to take a boost::shared_ptr (or the ConstPtr message subtype) for the first argument; not a reference to a object.

How to use registerCallback of message_filters with unpublished topics?

How to Connect a tf::messageFilter to

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Leo Campos 41 •1

Try this instead: two subscribers

void callback(const geometry_msgs::PoseWithCovarianceSta
mpedConstPtr& pose_1, const geometry_msgs::PoseWithCovar
ianceStampedConstPtr& pose_2)

link

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