Solve the following initial value problem

$$X = \begin{bmatrix} 2 & 1 & 6 \\ 0 & 2 & 5 \\ 0 & 0 & 2 \end{bmatrix} X , X(0) = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$$

[1] Eigenvalues of A

$$A - \lambda I = \begin{bmatrix} 2 - \lambda & 1 & 6 \\ 0 & 2 - \lambda & 5 \\ 0 & 0 & 2 - \lambda \end{bmatrix}$$

Thus $\lambda = 2$

[2] Eigenvectors of A

$$(A - 2I)v = 0$$

$$\begin{bmatrix} 0 & 1 & 6 \\ 0 & 0 & 5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

R1:

$$v_2 + 6v_3 = 0$$
$$\Rightarrow v_2 = -6v_3$$

R2:

$$5v_3 = 0$$

$$v_3 = 0$$

Let $v_1=1$, $v_2=0$

$$(A - 2I)v_2 = v_1$$

$$\begin{bmatrix} 0 & 1 & 6 \\ 0 & 0 & 5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

R1:

$$v_2 + 6v_3 = 1$$

R2:

$$5v_3 = 0$$

$$v_3 = 0$$

Thus $v_2 = 1$

Let
$$v_1=0$$
 , $v_2=1$
$$(A-2I)v_2=v_1$$

$$\begin{bmatrix} 0 & 1 & 6 \\ 0 & 0 & 5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

R1:

$$v_2 + 6v_3 = 0$$

R2:

$$5v_3 = 1$$
$$v_3 = \frac{1}{5}$$

Thus
$$v_2 = -\frac{6}{5}$$

[3] General solution

$$X(t) = c_1 e^{2t} v_1 + c_2 e^{2t} (v_2 + t v_1) + c_3 e^{2t} (v_3 + t v_2 + \frac{t^2}{2} v_1)$$

$$\Rightarrow X(t) = c_1 e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 e^{2t} \begin{pmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{pmatrix} + c_3 e^{2t} \begin{pmatrix} \begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{t^2}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

[4] Apply Initial Conditions

$$\Rightarrow X(0) = c_1 e^0 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 e^0 \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) + c_3 e^0 \left(\begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{0^2}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\Rightarrow X(0) = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix}$$

Where initial condition is $\begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$

$$\Rightarrow X(0) = c_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$$

[4] Solve for
$$c_1$$
 , c_2 , c_3
$$c_1 = 2$$

$$c_2 - \frac{6}{5}c_3 = -3$$

$$\frac{1}{5}c_3 = 1$$

$$\Rightarrow c_3 = 5$$

For
$$c_2$$

$$c_2 - \frac{6}{5}(5) = -3$$

$$\Rightarrow c_2 - 6 = -3$$

$$\Rightarrow c_2 = 3$$

[5] Solution to the initial value problem

$$\Rightarrow X(t) = 2e^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 3e^{2t} \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) + 5e^{2t} \left(\begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{t^2}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\Rightarrow X(t) = e^{2t} \left(2 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 3 \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) + 5e^{2t} \left(\begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{t^2}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) \right)$$

$$\Rightarrow X(t) = e^{2t} \left(\begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 3t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ -\frac{6}{5} \\ \frac{1}{5} \end{bmatrix} + 5t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{5t^2}{2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\Rightarrow X(t) = e^{2t} \left(\begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix} + t \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ -6 \\ 1 \end{bmatrix} + t \begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix} + \begin{bmatrix} \frac{5t^2}{2} \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\Rightarrow X(t) = e^{2t} \begin{bmatrix} 2 + 3t + \frac{5t^2}{2} \\ -3 + t \\ 1 \end{bmatrix}$$

We know that if Φ is a fundamental matrix of $\dot{X}=AX$ at $t_{\scriptscriptstyle 0}=0$ and F(t) is continuous in t then

$$X_p(t) = \Phi(t) \int_{t_0}^t \Phi^{-1}(s) F(s) ds$$

is a particular solution of $\dot{X} = AX + F(t)$.

Use this result with $t_{\scriptscriptstyle 0}=0$ to find a general solution of

$$\dot{X} = \begin{bmatrix} 0 & 3 \\ 3 & 0 \end{bmatrix} X + \begin{bmatrix} 0 \\ 12e^{3t} \end{bmatrix}$$

[1] Eigenvalues of A Solve for

$$\dot{X}=AX$$
 , $\dot{X}=\begin{bmatrix}0&3\\3&0\end{bmatrix}$ $A-\lambda I=\begin{bmatrix}-\lambda&3\\3&-\lambda\end{bmatrix}$ Thus $\lambda=3$, $\lambda=-3$

[2] Eigenvectors of A

For
$$\lambda = 3$$

$$A - 3I = \begin{bmatrix} -3 & 3 \\ 3 & -3 \end{bmatrix}$$

$$(A - 3I)v = 0$$

$$\Rightarrow \begin{bmatrix} -3 & 3 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$$

$$\Rightarrow 3x_1 + 3x_2 = 0$$

$$x_1 = 0 \quad \& \quad x_2 = 0$$

$$v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

For
$$\lambda = -3$$

$$A - 3I = \begin{bmatrix} 3 & 3 \\ 3 & 3 \end{bmatrix}$$

$$(A + 3I)v = 0$$

$$\Rightarrow \begin{bmatrix} 3 & 3 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$$

$$\Rightarrow 3x_1 + 3x_2 = 0$$

$$x_1 = -x_2$$

$$v_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

[3] Fundamental matrix homogeneous solution

$$X_h(t) = c_1 e^{3t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\Phi(t) = \begin{bmatrix} e^{3t} & e^{-3t} \\ e^{3t} & -e^{-3t} \end{bmatrix}$$

Inverse of Fundamental matrix [4]

$$\det(\Phi(t)) = \begin{bmatrix} e^{3t} & e^{-3t} \\ e^{3t} & -e^{-3t} \end{bmatrix}$$
$$\Rightarrow -e^{3t}e^{-3t} - e^{3t}e^{-3t} = -2$$

$$\Rightarrow -e^{3t}e^{-3t} - e^{3t}e^{-3t} = -2$$

$$\operatorname{adj}(\Phi(t)) = \begin{bmatrix} -e^{3t} & -e^{-3t} \\ -e^{3t} & e^{3t} \end{bmatrix}$$

Therefore,

$$\Rightarrow \Phi^{-1}(t) = \frac{1}{-2} \begin{bmatrix} -e^{3t} & -e^{-3t} \\ -e^{3t} & e^{3t} \end{bmatrix}$$

$$\Rightarrow \Phi^{-1}(t) = \frac{1}{-2} \begin{bmatrix} -e^{3t} & -e^{-3t} \\ -e^{3t} & e^{3t} \end{bmatrix}$$
$$\Rightarrow \Phi^{-1}(t) = \frac{1}{2} \begin{bmatrix} e^{-3t} & e^{-3t} \\ e^{3t} & -e^{3t} \end{bmatrix}$$

[5] Find $X_p(t)$

$$X_p(t) = \Phi(t)$$

$$X_p(t) = \Phi(t) \int_{t_0}^t \Phi^{-1}(s) F(s) ds$$

Given
$$\begin{bmatrix} 0 \\ 12e^{3t} \end{bmatrix}$$

$$\Rightarrow X_p(t) = \frac{1}{2} \begin{bmatrix} e^{-3t} & e^{-3t} \\ e^{3t} & -e^{3t} \end{bmatrix} \begin{bmatrix} 0 \\ 12e^{3t} \end{bmatrix}$$

$$\Rightarrow X_p(t) = \frac{1}{2} \begin{bmatrix} 12e^{-3t} \cdot e^{-3t} \\ -12e^{3t} \cdot e^{3t} \end{bmatrix}$$

$$\Rightarrow X_p(t) = \frac{1}{2} \begin{bmatrix} 12\\ -12e^{6t} \end{bmatrix}$$

$$\Rightarrow X_p(t) = \begin{bmatrix} 6\\ -6e^{6t} \end{bmatrix}$$

$$\int_{t_0}^{t} \begin{bmatrix} 6 \\ -6e^{6s} \end{bmatrix} ds$$

$$\Rightarrow \begin{bmatrix} 6s \\ \int_{t_0}^{t} 6e^{6s} ds \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 6t \\ -[e^{6s}]_{0}^{t} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 6t \\ -[\frac{1}{6}e^{6s}] \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 6t \\ -[\frac{1}{6}[e^{6t} - 1]] \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 6t \\ -[\frac{1}{6}e^{6t} + 1] \end{bmatrix}$$

[7] Particular Solution

$$X_{p}(t) = \begin{bmatrix} e^{3t} & e^{-3t} \\ e^{3t} & -e^{-3t} \end{bmatrix} \begin{bmatrix} 6t \\ -e^{6t} + 1 \end{bmatrix}$$

$$\Rightarrow X_{p}(t) = \begin{bmatrix} 6te^{3t} - e^{3t} + e^{-3t} \\ 6te^{3t} + e^{3t} - e^{-3t} \end{bmatrix}$$

[8] Homogeneous and Particular Solutions:

$$\begin{split} X(t) &= X_h(t) + X_p(t) \\ \Rightarrow c_1 e^{3t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 6te^{3t} - e^{3t} + e^{-3t} \\ 6te^{3t} + e^{3t} - e^{-3t} \end{bmatrix} \end{split}$$

If Φ is a normalized fundamental matrix $\dot{X}=AX$ at $t_0=0$ and if F is continuous in t, then

$$X_p(t) = \int_{t_0}^t \Phi(t - s) F(s) ds$$

is a particular solution of $\dot{X} = AX + F$. Use the result above to find a general solution of

$$\dot{X} = \begin{bmatrix} 2 & 1 \\ -4 & 2 \end{bmatrix} X + \begin{bmatrix} te^{2t} \\ -e^{2t} \end{bmatrix}$$

[1] Eigenvalues of A Solve for

$$\dot{X} = AX$$
 , $\dot{X} = \begin{bmatrix} 2 & 1 \\ -4 & 2 \end{bmatrix}$

$$A - \lambda I = \begin{bmatrix} 2 - \lambda & 1 \\ -4 & 2 - \lambda \end{bmatrix}$$

$$\Rightarrow (2 - \lambda)^2 + 4$$

$$\Rightarrow \lambda^2 - 4\lambda + 8 = 0$$

Thus
$$\lambda = 2 \pm 2i$$

[2] Eigenvectors of A

For
$$\lambda = 2 + 2i$$

 $(A - \lambda I)v = 0$

$$\Rightarrow \begin{bmatrix} 2 - (2 + 2i) & 1 \\ -4 & 2 - (2 + 2i) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$$

$$\Rightarrow \begin{bmatrix} -2i & 1 \\ -4 & -2i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$$

$$v_1 = \begin{bmatrix} 1 \\ 2i \end{bmatrix}$$

For
$$\lambda = 2 - 2i$$

$$(A - \lambda I)v = 0$$

$$\Rightarrow \begin{bmatrix} 2 - (2 - 2i) & 1 \\ -4 & 2 - (2 - 2i) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$$

$$\Rightarrow \begin{bmatrix} 2i & 1 \\ -4 & 2i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = 0$$

$$v_1 = \begin{bmatrix} 1 \\ -2i \end{bmatrix}$$

[3] Fundamental matrix Given by e^{At} , here A is the coefficient matrix of the homogeneous system $\dot{X} = AX$

$$A = \begin{bmatrix} 2 & 1 \\ -4 & 2 \end{bmatrix}$$

$$\Phi(t) = e^{At} = Pe^{Jt}P^{-1}$$

where P is the matrix of eigenvectors

J is the Jordan form

[4] Jordan form

$$J = \begin{bmatrix} 2+2i & 0 \\ 0 & 2-2i \end{bmatrix}$$
$$P = \begin{bmatrix} 1 & 1 \\ 2i & -2i \end{bmatrix}$$

[5] matrix of eigenvectors

Thus,
$$P^{-1} = \frac{1}{\det(P)} \begin{bmatrix} -2i & -1 \\ -2i & 1 \end{bmatrix}$$

$$det(P) = 1 \times -2i - 1 \times 2i$$

$$\Rightarrow -4i$$

$$P^{-1} = \frac{1}{-4i} \begin{bmatrix} -2i & -1 \\ -2i & 1 \end{bmatrix}$$

$$P^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{1}{4i} \\ \frac{1}{2} & -\frac{1}{4i} \end{bmatrix}$$

$$P^{-1} = \begin{bmatrix} \frac{1}{2} & -\frac{i}{4} \\ \frac{1}{2} & \frac{1}{4i} \end{bmatrix}$$

[6] compute e^{Jt}

$$e^{Jt} = \begin{bmatrix} e^{(2+2i)t} & 0\\ 0 & e^{(2-2i)t} \end{bmatrix}$$

$$\Rightarrow e^{Jt} = \begin{bmatrix} e^{(\cos(2t)+i\sin(2t))} & 0\\ 0 & e^{2t}(\cos(2t)-i\sin(2t)) \end{bmatrix}$$

[7] compute $Pe^{Jt}P^{-1}$ $\Phi(t) = Pe^{Jt}P^{-1}$

$$\Rightarrow \phi(t) = \begin{bmatrix} 1 & 1 \\ 2i & -2i \end{bmatrix} \begin{bmatrix} e^{(\cos(2t) + i\sin(2t))} & 0 \\ 0 & e^{2t}(\cos(2t) - i\sin(2t)) \end{bmatrix} \begin{bmatrix} \frac{1}{2} & -\frac{1}{4} \\ \frac{1}{2} & \frac{1}{4i} \end{bmatrix}$$

$$\text{Let } a = e^{2t}(\cos(2t) + i\sin(2t)) \text{, } b = e^{2t}(\cos(2t) + i\sin(2t))$$

$$\Rightarrow \phi(t) = \begin{bmatrix} 1 & 1 \\ 2i & -2i \end{bmatrix} \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \begin{bmatrix} \frac{1}{2} & -\frac{1}{4} \\ \frac{1}{2} & \frac{1}{4i} \end{bmatrix}$$

$$\Rightarrow \phi(t) = \begin{bmatrix} a & b \\ 2ia & -2ib \end{bmatrix} \begin{bmatrix} \frac{1}{2} & -\frac{1}{4} \\ \frac{1}{2} & \frac{1}{4i} \end{bmatrix}$$

$$\text{If } a = e^{2t}(\cos(2t) + i\sin(2t)) \text{ , } b = e^{2t}(\cos(2t) - i\sin(2t)) \text{ , } then$$

$$(1,1) \\ \Rightarrow \phi(t) = a \times -\frac{1}{2} + b \times -\frac{1}{2}$$

$$\Rightarrow -\frac{1}{2}(a + b) \\ \Rightarrow -\frac{1}{2}(e^{2t}(\cos(2t) + i\sin(2t)) + e^{2t}(\cos(2t) - i\sin(2t)))$$

$$\Rightarrow 2e^{2t}\cos(2t)$$

$$(1,2) \\ \Rightarrow \phi(t) = a \times -\frac{1}{4i} + b \times \frac{1}{4i}$$

$$\Rightarrow \frac{1}{4i}(e^{2t}(\cos(2t) + i\sin(2t)) - e^{2t}(\cos(2t) - i\sin(2t)))$$

$$\Rightarrow \frac{1}{4}(2e^{2t}\sin(2t))$$

$$\Rightarrow e^{2t}\sin(2t)$$

$$(2,1) \\ \Rightarrow \phi(t) = 2ia \times -\frac{1}{2} + 2ib \times -\frac{1}{2}$$

$$\Rightarrow -ia + ib \\ \Rightarrow 2e^{2t}\sin(2t)$$

$$(2,2) \\ \Rightarrow \phi(t) = 2ia \times -\frac{1}{4i} - 2ib \times \frac{1}{4i}$$

$$\Rightarrow -\frac{1}{2}(a + b)$$

$$\Rightarrow -\frac{1}{2}(2e^{2t}\cos(2t))$$

$$\Rightarrow -e^{2t}\cos(2t)$$

$$\text{Thus, } \phi(t) = \begin{bmatrix} 2e^{2t}\cos(2t) & e^{2t}\cos(2t) \\ 2e^{2t}\sin(2t) & -e^{2t}\cos(2t) \end{bmatrix}$$

$$\Rightarrow \phi(t) = e^{2t}\begin{bmatrix} \cos(2t) & e^{2t}\sin(2t) \\ 2e^{2t}\sin(2t) & -e^{2t}\cos(2t) \end{bmatrix}$$

$$\Rightarrow \phi(t) = e^{2t}\begin{bmatrix} \cos(2t) & -\sin(2t) \\ 2e^{2t}\sin(2t) & -e^{2t}\cos(2t) \end{bmatrix}$$

- (4.1) Write the companion system for the equation given below. $\Rightarrow y^{(3)} y^{(2)} + 2y^{(1)} 5y = \sin t$ Write your final answer in terms of the appropriate trigonometric functions.
- [1] Re-write as First-order differential equation $y^{(3)}-y^{(2)}+2y^{(1)}-5y=\sin t$ $y^{(3)}=y^{(2)}-2y^{(1)}+5y+\sin t$

And

$$y^{(1)} = (0 \quad 1 \quad 0)$$

 $y^{(2)} = (0 \quad 0 \quad 1)$

Thus,

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 5 & -2 & 1 \end{bmatrix}$$

[2] Re-write in matrix form

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = A \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \sin t \end{bmatrix}$$
$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 5 & -2 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \sin t \end{bmatrix}$$

(4.2) Find the series solution of the blow system of first order differential equations using the power series method

$$\dot{X} = \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} X \quad \text{with } X(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Write your final answer in terms of the appropriate trigonometric functions.

[1] Power series

$$X(t) = \sum_{n=0}^{\infty} X_n t^n$$

$$X_3t^3\ldots)$$

$$\Rightarrow \sum_{n=1}^{\infty} n X_n t^{n-1} = X_0 \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -2 \\ 1 & 0 & -2 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -2 \\ 1 & 0 & -2 \end{bmatrix} + X_1 t \begin{bmatrix} -1 & 2 &$$

$$X_2t^2\begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} + X_3t^3\begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix} \dots$$

$$\Rightarrow nX_n = X_{n-1} \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$X_0 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$X_1 = X_0 \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\Rightarrow X_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\Rightarrow X_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$X_2 = \frac{1}{2} X_1 \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\Rightarrow X_2 = \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\mathbf{v} = \begin{bmatrix} -1.5 \\ 1 \end{bmatrix}$$

$$\Rightarrow X_2 = \begin{bmatrix} -1.5 \\ 0 \\ 0 \end{bmatrix}$$

$$X_3 = \frac{1}{3} X_2 \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\Rightarrow X_3 = \frac{1}{3} \begin{bmatrix} -1.5 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} -1 & 2 & -2 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\Rightarrow X_3 = \begin{bmatrix} 0.5 \\ -0.5 \\ -0.5 \end{bmatrix}$$

Thus

$$X(t) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} t + \begin{bmatrix} -1.5 \\ 0 \\ 0 \end{bmatrix} t^2 + \begin{bmatrix} 0.5 \\ -0.5 \\ -0.5 \end{bmatrix} t^3$$

We know that if Φ is a normalized fundamental matrix of $\dot{X}=AX$ at $t_0=0$; then

$$\Phi(s+t) = \Phi(s) \Phi(t)$$

for all real numbers s and t. Use this hypothesis and (5.1) Show that for all real numbers s and t

$$\Phi(t) + \Phi(s) = \Phi(s)\Phi(t)$$

[1] Initial Condition If I is the identity matrix, at $t_0 = 0$ we have:

$$\Phi(0) = I$$

[2] Fundamental matrix Given by e^{At} , here A is the coefficient matrix of the homogeneous system $\dot{X} = AX$

$$\Phi(t) = e^{At}$$

[3] Matrix Exponential

Given a homogeneous system $\dot{X}=AX$, the fundamental matrix $\Phi(t)$ can be expressed as e^{At} , where e^{At} is the matrix exponential.

$$\Phi(t) = e^{At}$$

$$\Rightarrow \Phi(s+t) = e^{A(s+t)}$$

$$\Rightarrow \Phi(s+t) = e^{As+At}$$

$$\Rightarrow \Phi(s+t) = e^{A(s)}e^{A(t)}$$

$$\Rightarrow \Phi(s+t) = \Phi(s)\Phi(t)$$

(5.2) Show that if Φ is a normalized fundamental matrix at $t_0=0$; then

$$\Phi^{-1}(t) = \Phi(-t)$$
 for all t

[1] Initial Condition If I is the identity matrix, at $t_0 = 0$ we have:

$$\Phi(0) = I$$

[2] Fundamental matrix Given by e^{At} , here A is the coefficient matrix of the homogeneous system $\dot{X} = AX$

$$\Phi(t) = e^{At}$$

[3] Inverse of the Fundamental Matrix

$$\Phi(t) = e^{At}$$

$$\Rightarrow \Phi^{-1}(t) = (e^{At})^{-1}$$

$$\Rightarrow \Phi^{-1}(t) = e^{-At}$$

$$\Rightarrow \Phi(-t) = e^{-At}$$

Thus,
$$\Phi^{-1}(t) = \Phi(-t) = e^{-At}$$

Classify the critical points of the plane autonomous system corresponding to the second order non-linear differential equation:

derivative

$$\ddot{x} + 2(1 - x^3)\dot{x} - 3x = 0$$

Re-write as First-order differential equation [1]

$$\ddot{x} + 2(1 - x^3)\dot{x} - 3x = 0$$

 $\Rightarrow \ddot{x} = -2(1 - x^3)\dot{x} + 3x$

Thus $\dot{x} = 0$ and $\ddot{x} = 0$

$$\Rightarrow 0 = -2(1 - x^3) \times 0 + 3x$$

$$\Rightarrow 0 = 3x$$

$$\Rightarrow x = 0$$

[2] Jacobian matrix

$$\dot{x} = y$$

$$\frac{\partial \dot{x}}{\partial x} = 0$$

$$\frac{\partial \dot{x}}{\partial y} = 1$$

(2,1)

$$\ddot{x} = -2(1-x^3)\dot{x} + 3x$$

$$\Rightarrow \dot{y} = -2(1 - x^3)y + 3x$$

$$\Rightarrow \frac{\partial \dot{y}}{\partial x} = -2(-3x^2)y + 3$$
$$\Rightarrow \frac{\partial \dot{y}}{\partial x} = 3$$

$$\Rightarrow \frac{\partial \dot{y}}{\partial x} = 3$$

(2,2)
$$\frac{\partial \dot{y}}{\partial y} = -2(1-x^3)$$

$$\Rightarrow \frac{\partial \dot{y}}{\partial y} = -2$$

$$\Rightarrow \frac{\partial \dot{y}}{\partial y} = -2$$

$$J = \begin{bmatrix} \frac{\partial \dot{x}}{\partial x} & \frac{\partial \dot{x}}{\partial y} \\ \frac{\partial \dot{y}}{\partial x} & \frac{\partial \dot{y}}{\partial y} \end{bmatrix}$$

$$\Rightarrow J(0,0) = \begin{bmatrix} 0 & 1 \\ 3 & -2 \end{bmatrix}$$

[3] Eigenvalues of J

$$\det(J - \lambda I) = 0$$

$$\Rightarrow \det\begin{bmatrix} -\lambda & 1\\ 3 & -2 - \lambda \end{bmatrix} = 0$$

Thus
$$\lambda^2 + 2\lambda + 3 = 0$$

[4] Solve for
$$\lambda$$

Solve for
$$\lambda$$

$$\lambda = \frac{-2 \pm \sqrt{2^2 - 4 \times 1 \times 3}}{2 \times 1}$$

$$\Rightarrow \lambda = \frac{-2 \pm \sqrt{-8}}{2}$$

$$\Rightarrow \lambda = \frac{-2 \pm 2i\sqrt{2}}{2}$$

$$\Rightarrow \lambda = -1 \pm i\sqrt{2}$$

$$\Rightarrow \lambda = \frac{-2 \pm 2i\sqrt{2}}{2}$$

$$\Rightarrow \lambda = -1 + i\sqrt{2}$$