Luyao Niu he/him/his

Curriculum Vitae

Postdoctoral Scholar
Network Security Lab
University of Washington, Seattle

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Research Interests

My research focuses on developing scalable algorithms with certifiable guarantees to ensure security and resilience of cyber-physical systems in the presence of attacks and faults. These solutions use an interplay of methodologies from optimization and control, game theory, formal methods, machine learning, and mechanism design. Potential application domains of the proposed solutions include power systems and smart transportation systems. My software implementations to guarantee system safety in the presence of faults and attacks have been transitioned to the community through open source code on Github, and awarded with a Badge of Reproducibility through independent third-party certification.

Education & Training

2022—present **Postdoctoral Scholar**, *Network Security Lab*, *Electrical and Computer Engineering*, **University of Washington**, Seattle, WA

Advisor: Prof. Radha Poovendran

2016–2022 **Ph.D.**, Electrical and Computer Engineering,

Worcester Polytechnic Institute, Worcester, MA

Dissertation Title: Secure Control for Autonomous Cyber-Physical Systems Under Linear

Temporal Logic Constraints Advisor: Prof. Andrew Clark

2013–2015 M.S., Electrical and Computer Engineering,

Worcester Polytechnic Institute, Worcester, MA

Advisor: Prof. Kaveh Pahlavan

2009–2013 B.S.E., Electro-Mechanical Engineering,

Xidian University, Xi'an, China

Awards and Honors

2023 Outstanding Mentorship Award

Department of Electrical and Computer Engineering, University of Washington

2022 Certification of Reproducibility Badge

ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS)

2020 Best Paper Session

ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS)

2018 Outstanding Paper Award

Springer Conference on Decision and Game Theory for Security (GameSec)

Teaching Experience

- Winter 2024 Instructor of EE 342 (Signals, Systems, and Data II), University of Washington. Responsibilities include prepare course materials, giving lectures weekly, and hosting office hours.
- Spring 2023 Instructor of EE 241 (Programming For Signal And Information Processing Applications), University of Washington. Responsibilities include giving lectures weekly, grading assignments, and hosting office hours.
 - Fall 2020 Teaching assistant of ECE 2010 (Introduction to Electrical and Computer Engineering), Worcester Polytechnic Institute. Responsibilities include leading lab sessions weekly, grading assignments, and maintaining office hours.

Records of Innovation / Patents

Dec. 9 2022 Provisional Patent filed with CoMotion at the University of Washington, Seattle
LDL: A Defense for Label-Based Membership Inference Attacks
Arezoo Rajabi, Dinuka Sahabandu, Luyao Niu, Bhaskar Ramasubramanian, Radha Poovendran

DEI Service

Fall 2023 UW ECE Graduate Applicant Support Program (GASP)

Provide mentorship and feedback on graduate school applications to underrepresented and marginalized applicants.

Professional Development

Winter 2024 MS Admissions Triage Committee

Department of Electrical and Computer Engineering, UW

Winter 2023 **FERPA 101**

Office of the University Registrar, UW

Winter 2023 NETI-1 Course Design and Student Engagement

National Effective Teaching Institute

- Winter 2022 Using Student Evaluations and Feedback to Improve Teaching and Learning
 Center for Teaching and Learning, UW
 - Fall 2022 Teaching Workshop on Well-being for Life and Learning: Designing Learning Environments that Support the Whole Student

Center for Teaching and Learning, UW

Summer 2022 **Pronouns Training Program**

Diversity, Equity, and Inclusion, UW Human Resources

Publications: Journal Articles

- [J8] **L. Niu**, D. Sahabandu, A. Clark, and R. Poovendran, "A hybrid submodular optimization approach to controlled islanding with post-disturbance stability guarantees," *IEEE Transactions on Power Systems*, pp. 1–12, 2023. DOI: 10.1109/TPWRS.2023.3299280.
- [J7] A. A. Maruf, **L. Niu**, A. Clark, J. S. Mertoguno, and R. Poovendran, "A timing-based framework for designing resilient cyber-physical systems under safety constraint," *ACM Transactions on Cyber-Physical Systems*, vol. 7, no. 3, 2023. DOI: 10.1145/3594638.
- [J6] **L. Niu**, B. Ramasubramanian, A. Clark, and R. Poovendran, "Robust satisfaction of metric interval temporal logic objectives in adversarial environments," *Games*, vol. 14, no. 2, 2023. DOI: 10.3390/g14020030.
- [J5] Z. Li, **L. Niu**, and A. Clark, "LQG reference tracking with safety and reachability guarantees under unknown false data injection attacks," *IEEE Transactions on Automatic Control*, vol. 68, no. 2, pp. 1245–1252, 2023. DOI: 10.1109/TAC.2022.3153456.
- [J4] L. Niu and A. Clark, "A differentially private incentive design for traffic offload to public transportation," ACM Transactions on Cyber-Physical Systems, vol. 5, no. 2, pp. 1–27, 2021. DOI: 10.1145/3430847.
- [J3] B. Ramasubramanian, L. Niu, A. Clark, L. Bushnell, and R. Poovendran, "Secure control in partially observable environments to satisfy LTL specifications," *IEEE Transactions on Automatic Control*, vol. 66, no. 12, pp. 5665–5679, 2021. DOI: 10.1109/TAC.2020.3039484.
- [J2] **L. Niu**, J. Fu, and A. Clark, "Optimal minimum violation control synthesis of cyber-physical systems under attacks," *IEEE Transactions on Automatic Control*, vol. 66, no. 3, pp. 995–1008, 2021. DOI: 10.1109/TAC.2020.2989268.
- [J1] **L. Niu** and A. Clark, "Optimal secure control with linear temporal logic constraints," *IEEE Transactions on Automatic Control*, vol. 65, no. 6, pp. 2434–2449, 2020. DOI: 10.1109/TAC. 2019.2930039.

Publications: Peer-Reviewed Conference Publications

*indicates equal contribution, †indicates undergraduate mentee, and ‡indicates graduate mentee

- [C38] A. Mehta[†], L.Niu, D. Sahabandu, J. Lukuyu, and R. Poovendran, "A principled incentive mechanism to promote economic viability of mini-grids," in to Appear in IEEE PES General Meeting, 2024.
- [C37] H. Zhang, L.Niu, A. Clark, and R. Poovendran, "Fault tolerant neural control barrier functions for robotic systems under sensor faults and attacks," in to Appear in IEEE International Conference on Robotics and Automation (ICRA), 2024.
- [C36] A. A. Maruf, L.Niu, B. Ramasubramanian, A. Clark, and R. Poovendran, "Risk-aware distributed multi-agent reinforcement learning," in to Appear in American Control Conference (ACC), 2024
- [C35] Z. Xu[‡], F. Jiang[‡], **L.Niu**, J. Jia, B. Li, and R. Poovendran, "Brave: Byzantine-resilient and privacy-preserving peer-to-peer federated learning," in *5th AAAI Workshop on Privacy-Preserving Artificial Intelligence (PPAI)*, 2024. [Online]. Available: https://arxiv.org/abs/2401.05562.

- [C34] F. Jiang[‡], Z. Xu[‡], **L.Niu**, B. Wang, J. Jia, B. Li, and R. Poovendran, "Identifying and mitigating vulnerabilities in LLM-integrated applications," in *NeurIPS 2023 Workshop on Instruction Tuning and Instruction Following*, 2023. [Online]. Available: https://openreview.net/forum?id=V09d7AMh15.
- [C33] J. Jia, Z. Yuan, D. Sahabandu, L.Niu, A. Rajabi, R. Bhaskar, B. Li, and R. Poovendran, "FedGame: A game-theoretic defense against backdoor attacks in federated learning," in Thirty-seventh Conference on Neural Information Processing Systems (NeurIPS), 2023.
- [C32] A. Rajabi, S. Asokraj, F. Jiang[‡], L.Niu, R. Bhaskar, and R. Poovendran, "MDTD: A multi-domain Trojan detector for deep neural networks," in ACM Conference on Computer and Communications Security (CCS), 2023.
- [C31] L.Niu, A. A. Maruf, J. S. Mertoguno, A. Clark, and R. Poovendran, "A compositional resilience index for computationally efficient safety analysis of interconnected systems," in *IEEE Conference* on Decision and Control (CDC), IEEE, 2023.
- [C30] S. Cheng, L.Niu, A. Clark, and R. Poovendran, "A submodular energy function approach to controlled islanding with provable stability," in *IEEE Conference on Decision and Control* (CDC), IEEE, 2023.
- [C29] L.Niu, A. Clark, and R. Poovendran, "Necessary and sufficient conditions for satisfying linear temporal logic constraints using control barrier certificates," in *IEEE Conference on Decision* and Control (CDC), IEEE, 2023.
- [C28] A. A. Maruf, L.Niu, B. Ramasubramanian, A. Clark, and R. Poovendran, "Learning dissemination strategies for external sources in opinion dynamic models with cognitive biases," in *International Joint Conferences on Artificial Intelligence (IJCAI)*, 2023, pp. 3–11. DOI: 10.24963/ijcai.2023/1.
- [C27] L.Niu*, A. A. Maruf*, J. S. Mertoguno, A. Clark, and R. Poovendran, "POSTER: A common framework for resilient and safe cyber-physical system design," in ACM ASIA Conference on Computer and Communications Security (ASIACCS), ACM, 2023, pp. 1025–1027. DOI: 10.1145/3579856.3592826.
- [C26] A. A. Maruf, L.Niu, B. Ramasubramanian, A. Clark, and R. Poovendran, "Cognitive bias-aware dissemination strategies for opinion dynamics with external information sources," in ACM International Conference on Autonomous Agents and Multiagent Systems (AAMAS), ACM, 2023, pp. 2769–2771.
- [C25] A. Rajabi, D. Sahabandu, L.Niu, B. Ramasubramanian, and R. Poovendran, "LDL: A defense for label-based membership inference attacks," in ACM Asia Conference on Computer and Communications Security (AsiaCCS), ACM, 2023, pp. 95–108. DOI: 10.1145/3579856. 3582821.
- [C24] **L.Niu***, A. A. Maruf*, J. S. Mertoguno, A. Clark, and R. Poovendran, "An analytical framework for control synthesis of cyber-physical systems with safety guarantee," in *IEEE Conference on Decision and Control (CDC)*, IEEE, pp. 1533–1540. DOI: 10.1109/CDC51059.2022.9993062.

- [C23] A. A. Maruf*, L. Niu*, A. Clark, J. S. Mertoguno, and R. Poovendran, "A compositional approach to safety-critical resilient control for systems with coupled dynamics," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2022, pp. 910–917. DOI: 10.1109/CDC51059.2022.9992810.
- [C22] L. Niu, Z. Li, and A. Clark, "Abstraction-free control synthesis to satisfy temporal logic constraints under sensor faults and attacks," in *IEEE Conference on Decision and Control* (CDC), IEEE, 2022, pp. 1568–1575. DOI: 10.1109/CDC51059.2022.9992935.
- [C21] H. Zhang, S. Cheng, L. Niu, and A. Clark, "Barrier certificate based safe control for LiDAR-based systems under sensor faults and attacks," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2022, pp. 2256–2263. DOI: 10.1109/CDC51059.2022.9992432.
- [C20] D. Sahabandu*, L. Niu*, A. Clark, and R. Poovendran, "A hybrid submodular optimization approach to controlled islanding with heterogeneous loads," in *IEEE International Conference on Communications, Control, and Computing Technologies for Smart Grids (SmartGridComm)*, 2022, pp. 252–258. DOI: 10.1109/SmartGridComm52983.2022.9960986.
- [C19] D. Sahabandu*, L. Niu*, A. Clark, and R. Poovendran, "A submodular optimization approach to stable and minimally disruptive controlled islanding in power systems," in *IEEE American Control Conference (ACC)*, IEEE, 2022, pp. 4587–4594. DOI: 10.23919/ACC53348.2022.9867317.
- [C18] L. Niu, D. Sahabandu, A. Clark, and R. Poovendran, "Verifying safety for resilient cyber-physical systems via reactive software restart," in ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS), ACM, 2022, pp. 104–115. DOI: 10.1109/ICCPS54341.2022.00016, Certification Badge of Reproducibility.
- [C17] L. Niu, H. Zhang, and A. Clark, "Safety-critical control synthesis for unknown sampled-data systems via control barrier functions," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2021, pp. 6806–6813. DOI: 10.1109/CDC45484.2021.9683019.
- [C16] B. Ramasubramanian, L. Niu, A. Clark, and R. Poovendran, "Reinforcement learning beyond expectation," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2021, pp. 1528–1535. DOI: 10.1109/CDC45484.2021.9683261.
- [C15] D. Sahabandu*, L. Niu*, A. Clark, and R. Poovendran, "Scalable planning in multi-agent MDPs," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2021, pp. 5932–5939. DOI: 10.1109/CDC45484.2021.9683385.
- [C14] L. Niu, D. Sahabandu, A. Clark, and R. Poovendran, "A game-theoretic framework for controlled islanding in the presence of adversaries," in *International Conference on Decision* and Game Theory for Security (GameSec), Springer, 2021, pp. 231–250. DOI: 10.1007/978– 3-030-90370-1_13.
- [C13] L. Niu and A. Clark, "Control barrier functions for abstraction-free control synthesis under temporal logic constraints," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2020, pp. 816–823. DOI: 10.1109/CDC42340.2020.9304255.
- [C12] B. Ramasubramanian, **L. Niu**, A. Clark, L. Bushnell, and R. Poovendran, "Privacy-preserving resilience of cyber-physical systems to adversaries," in *IEEE Conference on Decision and Control* (CDC), IEEE, 2020, pp. 3785–3792. DOI: 10.1109/CDC42340.2020.9304080.

- [C11] L. Niu, B. Ramasubramanian, A. Clark, L. Bushnell, and R. Poovendran, "Control synthesis for cyber-physical systems to satisfy metric interval temporal logic objectives under timing and actuator attacks," in *ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS)*, IEEE, 2020, pp. 162–173. DOI: 10.1109/ICCPS48487.2020.00023, Best Paper Session.
- [C10] **L. Niu** and A. Clark, "A framework for joint attack detection and control under false data injection," in *International Conference on Decision and Game Theory for Security (GameSec)*, Springer, 2019, pp. 352–363. DOI: 10.1007/978-3-030-32430-8_21.
- [C9] B. Ramasubramanian, L. Niu, A. Clark, L. Bushnell, and R. Poovendran, "Linear temporal logic satisfaction in adversarial environments using secure control barrier certificates," in *International Conference on Decision and Game Theory for Security (GameSec)*, Springer, 2019, pp. 385–403. DOI: 10.1007/978-3-030-32430-8_23.
- [C8] L. Niu, Z. Li, and A. Clark, "LQG reference tracking with safety and reachability guarantees under false data injection attacks," in *IEEE American Control Conference (ACC)*, IEEE, 2019, pp. 2950–2957. DOI: 10.23919/ACC.2019.8814821.
- [C7] L. Niu, J. Fu, and A. Clark, "Minimum violation control synthesis on cyber-physical systems under attacks," in *IEEE Conference on Decision and Control (CDC)*, IEEE, 2018, pp. 262–269. DOI: 10.1109/CDC.2018.8619174.
- [C6] L. Niu and A. Clark, "A differentially private and truthful incentive mechanism for traffic offload to public transportation," in *International Conference on Decision and Game Theory for Security (GameSec)*, Springer, 2018, pp. 366–385. DOI: 10.1007/978-3-030-01554-1_21, Outstanding Paper Award.
- [C5] L. Niu and A. Clark, "Secure control under linear temporal logic constraints," in *IEEE American Control Conference (ACC)*, IEEE, 2018, pp. 3544–3551. DOI: 10.23919/ACC.2018.8431595.
- [C4] A. Clark and L. Niu, "Linear quadratic Gaussian control under false data injection attacks," in IEEE American Control Conference (ACC), IEEE, 2018, pp. 5737–5743. DOI: 10.23919/ACC. 2018.8431459.
- [C3] L. Niu, Y. Guo, H. Li, and M. Pan, "A Nash bargaining approach to emergency demand response in colocation data centers," in *IEEE Global Communications Conference (GLOBECOM)*, IEEE, 2016, pp. 1–6. DOI: 10.1109/GLOCOM.2016.7841520.
- [C2] L. Niu and Y. Guo, "Enabling reliable data center demand response via aggregation," in ACM International Conference on Future Energy Systems (e-Energy), ACM, 2016, pp. 1–11. DOI: 10.1145/2934328.2934350.
- [C1] L. Niu, Y. Fan, K. Pahlavan, G. Liu, and Y. Geng, "On the accuracy of Wi-Fi localization using robot and human collected signatures," in *IEEE International Conference on Consumer Electronics (ICCE)*, IEEE, 2016, pp. 375–378. DOI: 10.1109/ICCE.2016.7430654.

Professional Service – Review Activities

IEEE Transactions on Automatic Control

Elsevier Automatica

IEEE Transactions on Control Systems Technology

IEEE Transactions on Information Forensics & Security

IEEE Transactions on Vehicular Technology

IEEE Robotics and Automation Letters

IEEE Control Systems Letters

Elsevier Pervasive and Mobile Computing

Springer International Journal of Wireless Information Networks

IEEE Conference on Decision and Control

IEEE Conference on Robotics and Automation

IEEE American Control Conference