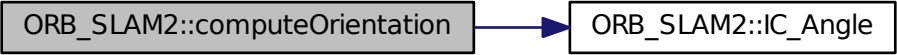


ORB_SLAM2::computeOrientation



```
graph LR; A[ORB_SLAM2::computeOrientation] --> B[ORB_SLAM2::IC_Angle]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ORB_SLAM2::computeOrientation'. The right box is white and contains the text 'ORB_SLAM2::IC_Angle'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

ORB_SLAM2::IC_Angle