


ORB_SLAM2::computeDescriptors



```
graph LR; A[ORB_SLAM2::computeDescriptors] --> B[ORB_SLAM2::computeOrbDescriptor]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ORB_SLAM2::computeDescriptors'. The right box is white with a black border and contains the text 'ORB_SLAM2::computeOrbDescriptor'. A blue arrow points from the right side of the gray box to the left side of the white box.

ORB_SLAM2::computeOrbDescriptor