

# Advanced Natural Language Processing

## Assignment 2: Intent Classification with Feedforward Neural Network

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December 9, 2025

## 1 ReLU and Sigmoid Advantages/Disadvantages

### 1.1 ReLU

Looking at Figure 1, you see that the ReLU function outputs zero for all negative inputs and increases linearly for positive inputs, while its derivative is a step function.

Some advantages of ReLU are that it is a simple  $\max(0, z)$  operation and therefore computationally very effective and inexpensive. It has a constant gradient of 1 for  $z > 0$ , which helps to mitigate the vanishing gradient problem compared to activation functions such as sigmoid or tanh. ReLU is also fast in comparison to other activation functions.

On the other hand, ReLU has some disadvantages. The dying ReLU problem occurs when updates get stuck outputting 0 if  $z \leq 0$  during training. Once the gradient becomes 0, the neuron can stop updating and may not recover.

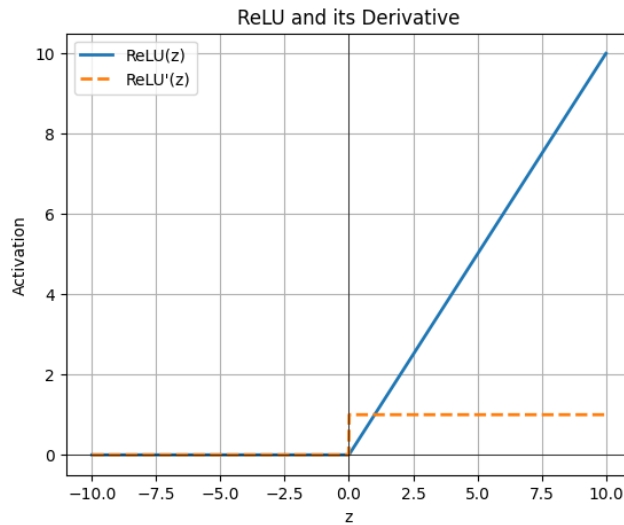


Figure 1: ReLU function and its derivative. The function outputs  $\max(0, z)$ , and the derivative is 1 for  $z > 0$  and 0 otherwise.

### 1.2 Sigmoid Function

In Figure 2, you see the sigmoid function as a S-shaped curve with outputs reaching from 0 to 1, while its derivative forms a bell-shaped curve that peaks at  $z = 0$  and vanishes for large  $|z|$ .

Unlike ReLU, sigmoid is continuous and therefore differentiable everywhere. This ensures stable gradients for small input values. Sigmoid also always outputs a value between  $[0, 1]$ , even when  $z \leq 0$ , making it well suited for modeling probabilities.

Sigmoid has the disadvantage of the vanishing gradient problem: when  $|z|$  gets too large, the gradient gets very close to zero. This results in exponentially shrinking gradients during backpropagation, which slows down the learning in deeper networks.

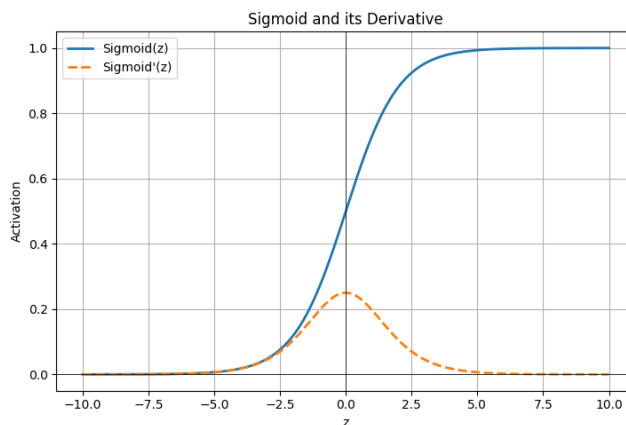
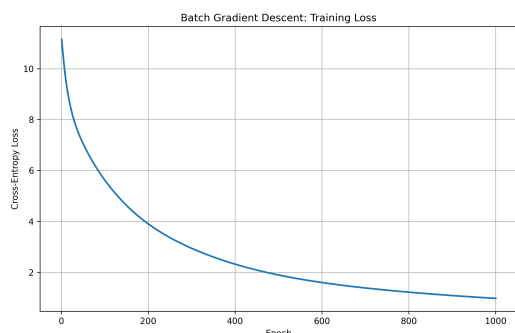
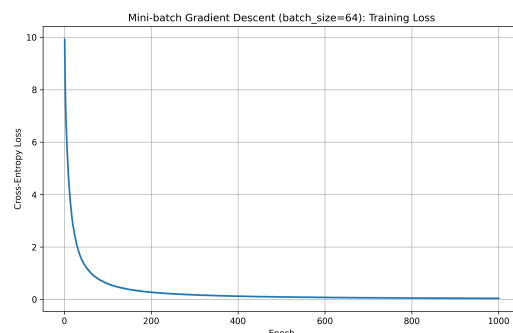


Figure 2: Sigmoid function and its derivative. The function outputs values in  $(0, 1)$ , and the derivative peaks at  $z = 0$  and approaches zero for large  $|z|$ .

### 1.3 Batch and Mini-Batch Gradient Descent Loss



(a) Batch Gradient Descent



(b) Mini-batch Gradient Descent (batch\_size=64)

Figure 3: Training loss over 1000 epochs for batch GD and mini-batch GD.

#### 1.3.1 Observation: Batch GD

The loss decreases from more than 10 to 0.98. During the first epochs, the loss drops drastically, followed by a smooth convergence. The accuracy starts at 12.2% and improves to 75.40%, which shows that the network was trained successfully.

#### 1.4 Observation: Mini-Batch GD

With mini-batch training, the loss decreases even more dramatically than with batch GD. From a loss of 10.0 it decreases to 0.04, where the first 100 epochs show the most drastic drop from 10.0 to 0.59, followed by a continued steady decrease throughout training. The accuracy, same as for batch GD, starts at 12.2%, representing random guessing. Mini-batch improves to 99.30%, which is significantly higher than the accuracy from batch GD. Mini-batch has an increased number of weight updates per epoch, which allows the network to learn more effectively.

### 1.5 GitHub Repository

GitHub Repository: <https://github.com/luzecode/aNLP-Assignment1-Hate-Speech-Detection.git>

Last commit hash: 3f9c7d1a