reachability analysis for continuous one counter automata

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• Continuous one counter automata

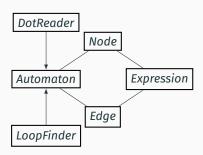
- · Continuous one counter automata
 - · No parameters

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 - Operations: +, -

- · Continuous one counter automata
 - No parameters
 - · Operations: +, -
 - Conditions: <=, >=, =

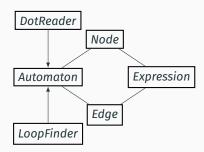
Automaton

· Convert dot to Automaton



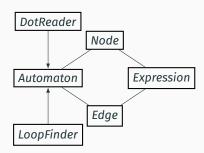
Automaton

- · Convert dot to Automaton
- · Ensure conformance
 - · Initial node
 - · Operations in edge
 - · Conditions in node

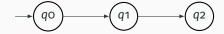


Automaton

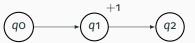
- · Convert dot to Automaton
- Ensure conformance
 - · Initial node
 - · Operations in edge
 - · Conditions in node
- · Detect all loops
 - · Breadth first search



Initial node

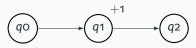


Given a node with an operation label

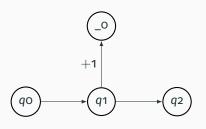


- Given a node with an operation label
- · Insert a new node

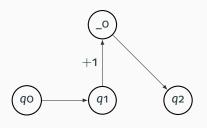




- Given a node with an operation label
- · Insert a new node
- · Create an edge to this node
- Add the operation to the edge



- Given a node with an operation label
- · Insert a new node
- · Create an edge to this node
- Add the operation to the edge
- Reconnect all pre-existing edges



 Given an edge with a conditional label

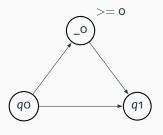


- Given an edge with a conditional label
- · Insert a new node
- Add the condition to the node

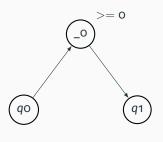




- Given an edge with a conditional label
- · Insert a new node
- Add the condition to the node
- Connect the two nodes via the new node

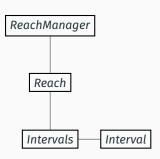


- Given an edge with a conditional label
- · Insert a new node
- Add the condition to the node
- Connect the two nodes via the new node
- · Remove the old edge



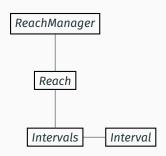
Reachability

• Initialise Reach per node



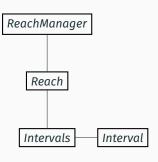
Reachability

- · Initialise Reach per node
- · Update Reach instances
 - · Do one update step
 - · Rescale Reach
 - · Check loop acceleration
 - · Check end condition



Reachability

- · Initialise Reach per node
- · Update Reach instances
 - · Do one update step
 - · Rescale Reach
 - · Check loop acceleration
 - · Check end condition
- Reachability
 - Node has a Reach that is not empty



Remaining work

• Add support for parametric counter automata

Remaining work

- Add support for parametric counter automata
- Apply to a (or more) bigger use case(s)
- · Document the results