

## Lv, Zhaoyang

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<b>Current Work</b>	<b>Research Scientist</b> Surreal team, Reality Lab Research Meta Research areas: neural reconstruction & rendering, contextualized AI, multi-modal learning Featured work: <ul style="list-style-type: none"><li>• Neural 3D Video Synthesis: demonstrate the first experience of photorealistic dynamic 3D video replay using neural reconstruction; Project lead</li><li>• CVPR 2022 tutorial for Project Aria; Tutorial lead</li><li>• Contextualized AI using ego-centric Aria videos</li></ul>	Sept. 2019 - Present Redmond, U.S.
<b>Education</b>	<b>Ph.D. in Robotics</b> RIM center, School of Interactive Computing Georgia Institute of Technology <ul style="list-style-type: none"><li>• Phd Thesis: <i>Visual Dense Three-Dimensional Motion Estimation in the Wild</i></li><li>• Advisor: James Rehg, Frank Dellaert (co-advised)</li><li>• Qualifier exam areas: Perception, AI and Control.</li></ul>	Aug.2014 - Aug.2019 Atlanta, U.S.
	<b>M.Sc.</b> Artificial Intelligence in Computing The Imperial College of Science, Technology and Medicine <ul style="list-style-type: none"><li>• Master Thesis: <i>KinfuSeg: A Dynamic SLAM Approach Based on KinectFusion.</i></li><li>• Courses: Distinction (Highest level awarded top 15%)</li><li>• Awards: Distinguished Thesis (3 among 71), Top 5%.</li></ul>	Sept.2012 - Sept.2013 London, U.K.
	<b>B.Sc.</b> Electrical Engineering in Aeronautics Northwestern Polytechnical University (CN) <ul style="list-style-type: none"><li>• Courses: 89.5, Top 5%;</li><li>• Bachelor Thesis: <i>Quadrotor Design and its Navigation</i>, 90.0, Top 5%</li></ul>	Sept.2008 - July 2012 Xi'an, P.R.China
<b>Selected Publications</b>	<i>Neural 3D Video Synthesis from Multi-view Video</i> , Tianye Li, Mira Slavcheva, Michael Zollhoefer, Simon Green, Christoph Lassner, Changil Kim, Tanner Schmidt, Steven Lovegrove, Michael Goesele, Richard Newcombe, <b>Zhaoyang Lv</b> Computer Vision and Pattern Recognition (CVPR) 2022, Oral Presentation (~5%) Project lead	
	<i>STaR: Self-supervised Tracking and Reconstruction of Rigid Objects in Motion with Neural Rendering</i> , Wentao Yuan, <b>Zhaoyang Lv</b> , Tanner Schmidt, Steven Lovegrove Computer Vision and Pattern Recognition (CVPR) 2021	
	<i>SENSE: A Shared Encoder Network for Scene-flow Estimation</i> , Huaizu Jiang, Deqing Sun, Varun Jampani, <b>Zhaoyang Lv</b> , Erik Learned-Miller, Jan Kautz, International Conference on Computer Vision (CVPR) 2019, Oral Presentation (~5%)	
	<i>Taking a Deeper Look at the Inverse Compositional Algorithm</i> , <b>Zhaoyang Lv</b> , Frank Dellaert, James M. Rehg, Andreas Geiger, Computer Vision and Pattern Recognition (CVPR) 2019, Oral Presentation (~5%), Best Paper Finalist (<1%)	

*Learning Rigidity in Dynamic Scenes with a Moving Camera for 3D Motion Field Estimation*,  
**Zhaoyang Lv**, Kihwan Kim, Alejandro Troccoli, Deqing Sun, James M. Rehg, Jan Kautz,  
 European Conference on Computer Vision (ECCV) 2018

*Multi-class Classification without Multi-class Labels*,  
 Yen-Chang Hsu, **Zhaoyang Lv**, Joel Schlosser, Phillip Odom, Zolt Kira,  
 International Conference on Learning Representations (ICLR) 2019

*Learning to Cluster in Order to Transfer across Domains and Tasks* ,  
 Yen-Chang Hsu, **Zhaoyang Lv**, Zolt Kira,  
 International Conference on Learning Representations (ICLR) 2018

*A Continuous Optimization Approach for Efficient and Accurate Scene Flow*,  
**Zhaoyang Lv**, Chris Beall, Pablo F. Alcantarilla, Fuxin Li, Zolt Kira, Frank Dellaert,  
 European Conference on Computer Vision (ECCV) 2016

## Patents

*Learning rigidity of dynamic scenes for three-dimensional scene flow estimation*,  
**Zhaoyang Lv**, Kihwan Kim, Deqing Sun, Alejandro Jose Troccoli, Jan Kautz,  
 US Patent App. 16/052.528

*Motion Planning and Intention Prediction for Autonomous Driving in Highway Scenarios via Graphical Model-based Factorization*,  
**Zhaoyang Lv**, Aliakbar Aghamohammadi, Amir Tamjidi,  
 US Patent App. 15/601.047

*Holistic Planning with Multiple Intentions for Self-driving Cars*,  
**Zhaoyang Lv**, Aliakbar Aghamohammadi,  
 US Patent App. 15/604,437

## Prior Experience

**Research Intern** Learning and Perception Research Group Jan. 2019 - May 2019  
 Nvidia Research Santa Clara, U.S.

Director: Jan Kautz  
 Mentors: Kihwan Kim, Deqing Sun, Alejandro Troccoli

**PhD Intern** Autonomous Vision Group June 2018 - Nov. 2018  
 Max Planck Institute Intelligent System Tuebingen, Germany

Advisor: Andreas Geiger

**Research Intern** Learning and Perception Research Group May 2017 - Aug 2017  
 Nvidia Research Santa Clara, U.S.

Director: Jan Kautz;  
 Mentors: Kihwan Kim, Deqing Sun, Alejandro Troccoli

**Research Intern** Autonomous Vehicle Sensor Fusion May 2016 - Aug. 2016  
 Qualcomm R&D San Diego, U.S.

Manager: Ali-akbar Agha-mohammadi (Ali Agha)

**Research Intern** Computer Vision Group Dec.2013 - July 2014  
 State Key Lab of CAD&CG, Zhejiang University Hangzhou, P.R. China

Advisor: Guofeng Zhang

## Misc

**Project lead** *CVPR 2022 Tutorial: Towards always-on egocentric vision research using Metas Aria glasses* June 2022

**Teaching Instructor** *Georgia Tech Computer Vision 4476 Course* Summer 2019  
**Organizer** *Georgia Tech Computer Vision Reading Group* Fall 2015 - Fall 2018  
**Teaching Assistant** *Georgia Tech Deep Learning 7643* Fall 2017  
**Teaching Assistant** *Georgia Tech Computer Vision 4476/6476* Fall 2016  
**Vice President in Public Relation** of Georgia Tech *RoboGrads* Fall 2016 - May 2017  
**Journal Reviewer** for T-PAMI, IJCV, T-Multimedia  
**Conference Reviewer** for CVPR, ECCV, ICCV, AAAI, IROS, ICRA

**Software**  
**(Primary)**

**Programming Languages:** C++, Python  
**Deep Learning:** Pytorch