Notes on Implementing MC's Method

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EXPLICIT RUNGE-KUTTA SCHEME

For the fundamental theorem of calculus,

$$y(t_{n+1}) = y(t_n) + \int_{t_n}^{t_{n+1}} f(y(\tau), \tau) d\tau = y(t_n) + h \int_0^1 f(y(t_n + h\tau), t_n + h\tau) d\tau$$
 (1)

replace the integral with a quadrature approximation

$$y_{n+1} = y_n + h\sum_{i=1}^{s} b_i f(y(t_n + c_i h), t_n + c_i h)$$
(2)

then we have to construct an approximation, denoted by $Y_i \simeq y(t_n + c_i h)$. With explicit Runge-Kutta methods you construct Y_i using

$$Y_1 = y_n, \quad f(Y_1, t_n), \quad f(Y_2, t_n + hc_2), \quad \dots, \quad f(Y_{i-1}, t_n + hc_{i-1}).$$
 (3)

Then

$$Y_{s} = y_{n} + h \sum_{i=1}^{s-1} a_{si} f(Y_{i}, t_{n} + hc_{i}).$$

$$Y_{s} = y_{n} + h \sum_{i=1}^{s} b_{s} f(Y_{i}, t_{n} + hc_{i}).$$
(4)

$$y_{n+1} = y_n + h\sum_{i=1}^{s} b_i f(Y_i, t_n + hc_i)$$
(5)

More

$$y' = f(y, t) \tag{6}$$

$$y'' = \frac{d}{dt}y' = \left(\frac{\partial}{\partial t} + f\frac{\partial}{\partial y}\right)f = \frac{\partial f}{\partial t} + f\frac{\partial f}{\partial y}$$

$$y''' = \frac{d}{dt}y'' = \left(\frac{\partial}{\partial t} + f\frac{\partial}{\partial y}\right)\left(\frac{\partial f}{\partial t} + f\frac{\partial f}{\partial y}\right)$$

$$= \frac{\partial^2 f}{\partial t^2} + f\frac{\partial^2 f}{\partial t\partial y} + \frac{\partial f}{\partial t}\frac{\partial f}{\partial y} + f\frac{\partial^2 f}{\partial y\partial t} + f\frac{\partial f}{\partial y}\frac{\partial f}{\partial y} + f^2\frac{\partial^2 f}{\partial y^2}$$

$$= \frac{\partial^2 f}{\partial t^2} + f^2\frac{\partial^2 f}{\partial y^2} + 2f\frac{\partial^2 f}{\partial t\partial y} + \frac{\partial f}{\partial t}\frac{\partial f}{\partial y} + f\left(\frac{\partial f}{\partial y}\right)^2$$
(8)

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Consider $t_n = 0, y(t) = t \Rightarrow y(0) = 0, y' = 1$. For first order accuracy, need to obtain the exact solution of y(t) = t.

$$Y_i = y_n + h \sum_{i=1}^{i-1} a_{ij} \simeq y(t_n + c_i h) = y_n + h c_i,$$
(9)

$$y_{n+1} = y_n + h\sum_{i=1}^{s} b_i = y_n + h. (10)$$

$$\Rightarrow \begin{cases} \sum_{j=1}^{i-1} a_{ij} = c_i, \\ \sum_{i=1}^{s} b_i = 1. \end{cases} \Rightarrow \begin{cases} a_{21} = c_2 \end{cases}$$
 (11)

where is necessary for first-order accuracy.

For up to the 3-order conditions, it suffices to study the case of **autonomous** differential equations, y' = f(y).

$$y' = f, (12)$$

$$y'' = (f\frac{\partial}{\partial y})f = ff_y, \tag{13}$$

$$y''' = \left(f\frac{\partial}{\partial y}\right)(ff_y) = ff_y f_y + f^2 f_{yy} \tag{14}$$

Taylor expansion of k_i for RK4 up to $\mathcal{O}(h^3)$

Following the convention of Mongwane, we defined

$$k_i = hf(Y_i, t_n + hc_i) (15)$$

then

$$k_1 = hy', (16)$$

$$k_2 = hy' + \frac{h^2}{2}y'' + \frac{h^3}{8}(y''' - f_y y''), \tag{17}$$

$$k_3 = hy' + \frac{h^2}{2}y'' + \frac{h^3}{8}(y''' + f_y y''). \tag{18}$$

where $f_y y'' \equiv (y'')^2 / y' = \frac{4(k_3^{(c)} - k_2^{(c)})}{h^3}$, and y', y'', y''' can be represented with $k_i^{(c)}$ of coarse grid using the dense output

B. Taylor expansion of Y_i for RK4 up to $\mathcal{O}(h^3)$

Similarly, we can also expand Y_i instead of k_i , and we have

$$Y_1 = y_n, (19)$$

$$Y_2 = y_n + \frac{h}{2}y', (20)$$

$$Y_3 = y_n + \frac{h}{2}y' + \frac{h^2}{4}y'' + \frac{h^3}{16}(y''' - f_y y'')$$
(21)

$$Y_4 = y_n + hy' + \frac{h^2}{2}y'' + \frac{h^3}{8}(y''' + f_y y'')$$
(22)

where $f_y y'' \equiv (y'')^2 / y' = \frac{4(k_3^{(c)} - k_2^{(c)})}{h^3}$, and y', y'', y''' can be represented with $k_i^{(c)}$ of coarse grid using the dense output formula,

$$y(t_n + \theta h) = y_n + \sum_{i=1}^{4} b_i(\theta) k_i^{(c)} + \mathcal{O}(h^4),$$
(23)

$$y(t_n + \theta h) = y_n + \sum_{i=1}^4 b_i(\theta) k_i^{(c)} + \mathcal{O}(h^4),$$

$$\frac{d^{(m)}}{dt^{(m)}} y(t_n + \theta h) = \frac{1}{h^m} \sum_{i=1}^s k_i^{(c)} \frac{d^{(m)}}{d\theta^{(m)}} b_i(\theta) + \mathcal{O}(h^{4-m}).$$
(23)

where $b_1(\theta) = \theta - \frac{3}{2}\theta^2 + \frac{2}{3}\theta^3$, $b_2(\theta) = b_3(\theta) = \theta^2 - \frac{2}{3}\theta^3$, $b_4(\theta) = -\frac{1}{2}\theta^2 + \frac{2}{3}\theta^3$.

$1. \quad Pseudo\ code$

- 1. integrate coarse grid from t_n to $t_n + h^{(c)}$ and store $k_i^{(c)}$ somewhere,
- 2. interpolate in time for y,y',y'',y''' using (23)-(24)
 - (a) at $\theta = 0.0$ for the first fine step,
 - (b) at $\theta = 0.5$ for the second fine step,
- 3. calculate Y_i for the fine grid using (19)-(22).
- 4. interpolate in space to fill Y_i in the fine ghost points.