

Predicting Rainfall with Machine Learning



By Lynne, Naresh, Deepak, Mridul

DS207 Spring 2025

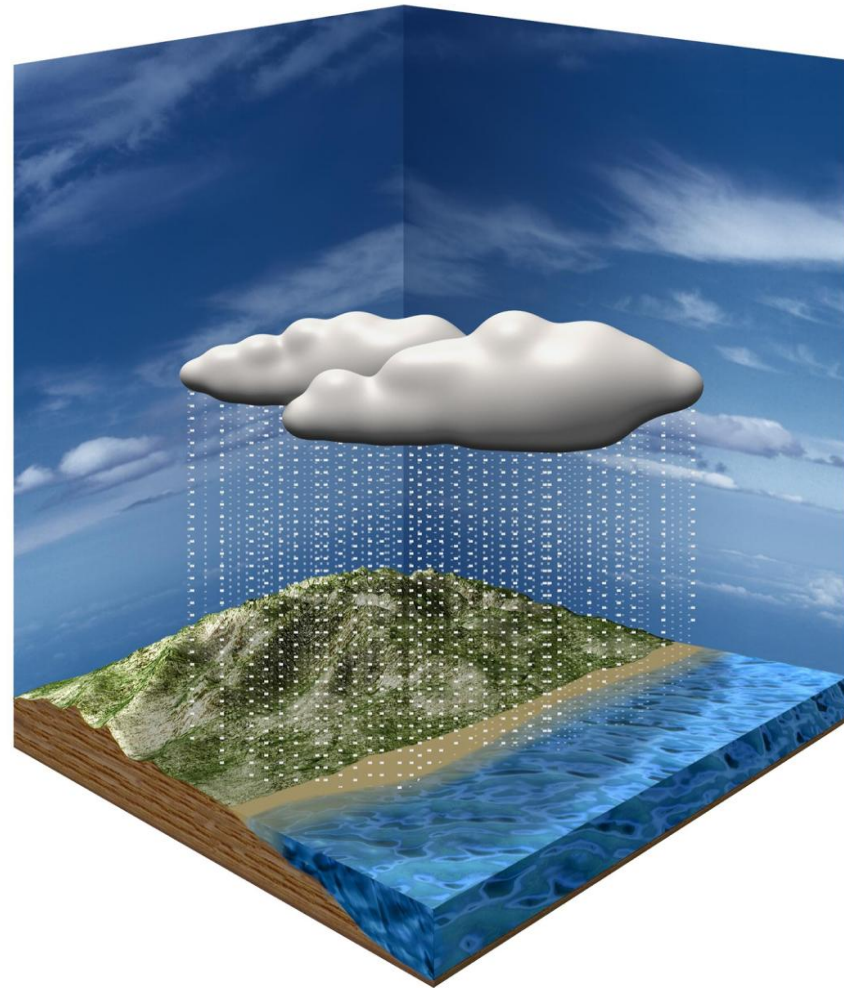
April 17 2025

[Dataset: Kaggle · Playground Prediction Competition](#)

https://github.com/lwang9/mids-w207-final_project_team2

Motivation

- Question: Will it rain on any given day?
- Why is it interesting? Real-World Impact:
 - Agriculture.
 - Disaster preparedness.
 - Urban planning.
 - Commute/travel planning.
 -



Previous Forecasting Methods

- Numerical Weather Prediction (NWP) Models.
- Statistical Models.
- Satellite-Based Models.

<https://www.pivotalweather.com>

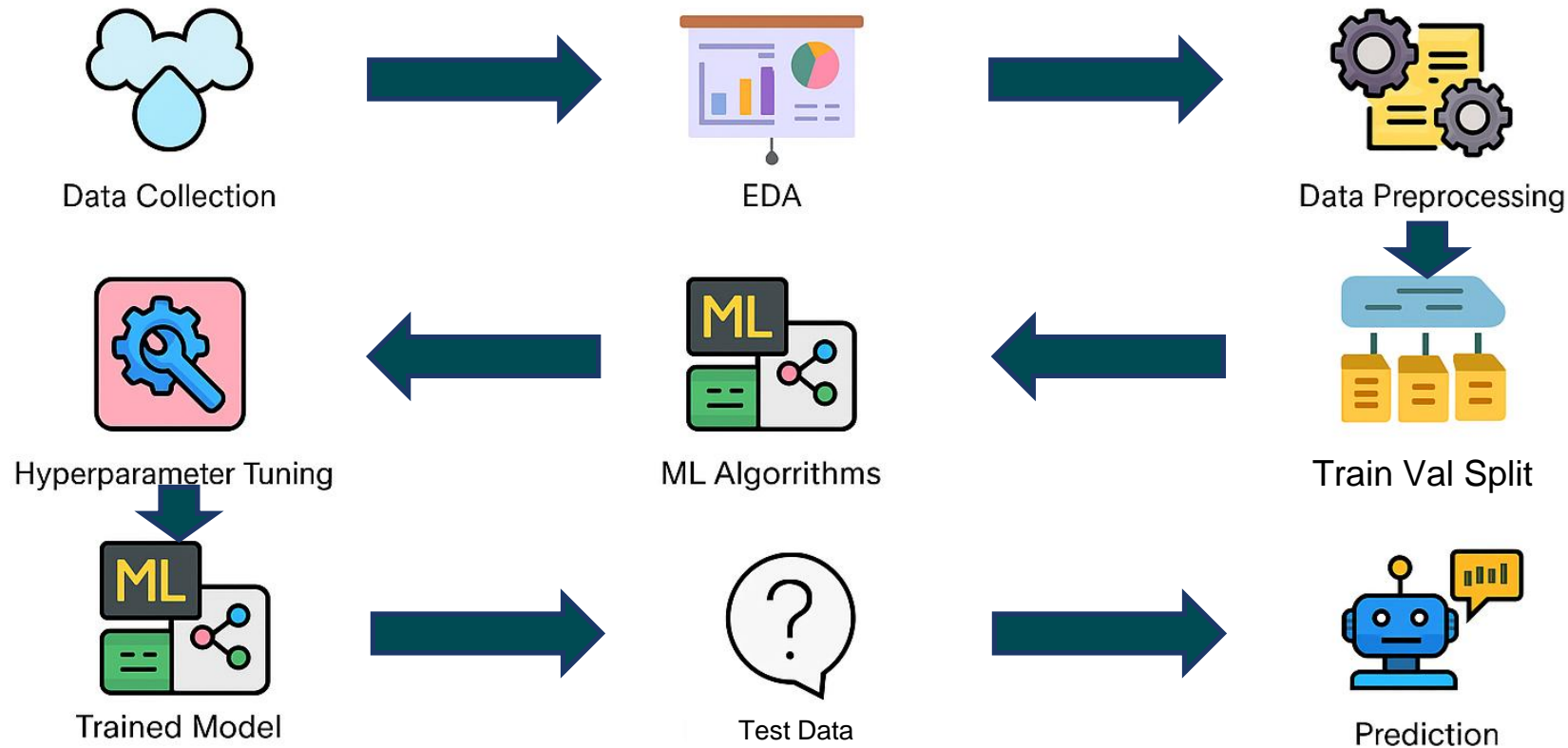


Binary Classification

- Given Input Features:
ID, day, pressure, maxtemp,
temperature, mintemp, dewpoint,
humidity, cloud, sunshine, wind
direction, windspeed (2190 rows)
- Output: rainfall
1 = rain, 0 = no rain






Overall Plan



Summary of Findings

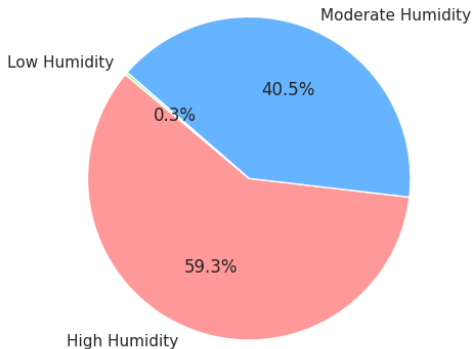
- Many models perform reasonably well.
- Ensemble modeling achieved near-top leaderboard performance on Kaggle (rank 21/4382).

#	△	Team	Members	Score
1	▲ 812	Guillaume HIMBERT		0.90654
21	▲ 2242	AvasthiPrakhar		0.90376
 submission_ensemble.csv Complete (after deadline) · Lynne Wang · 7d ago				0.90376

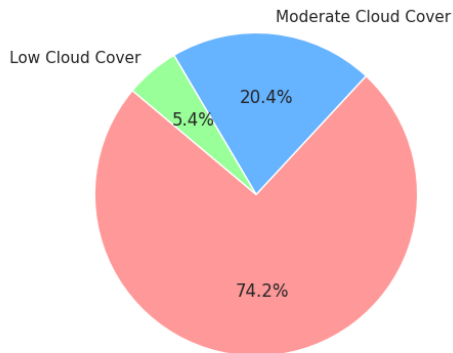
EDA - Comparison of key variables (train & test)

Train Data

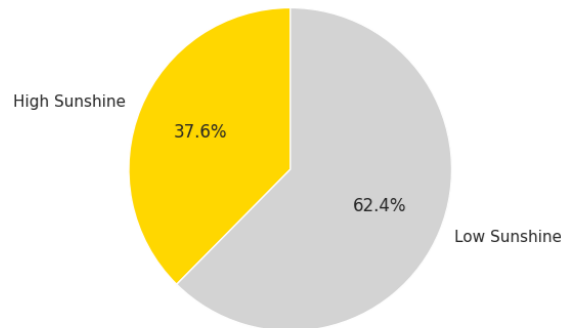
Humidity Distribution(Train Data)



Cloud Cover Distribution(Train Data)

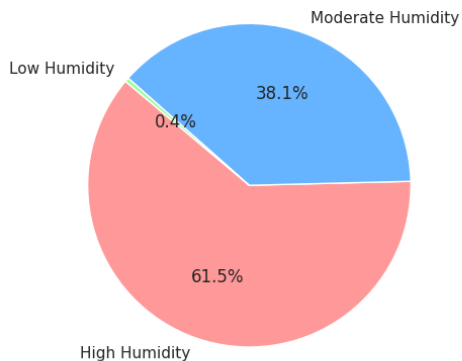


Sunshine Distribution(Train Data)

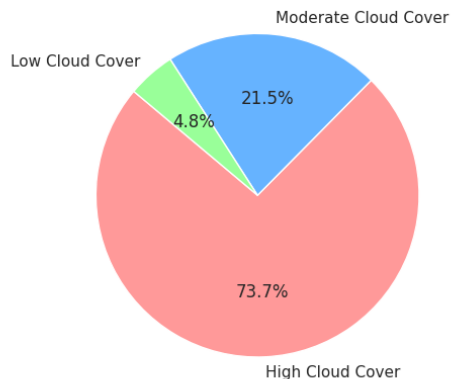


Test Data

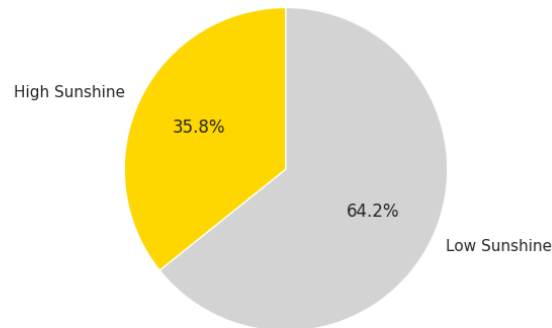
Humidity Distribution(Test Data)



Cloud Cover Distribution(Test Data)



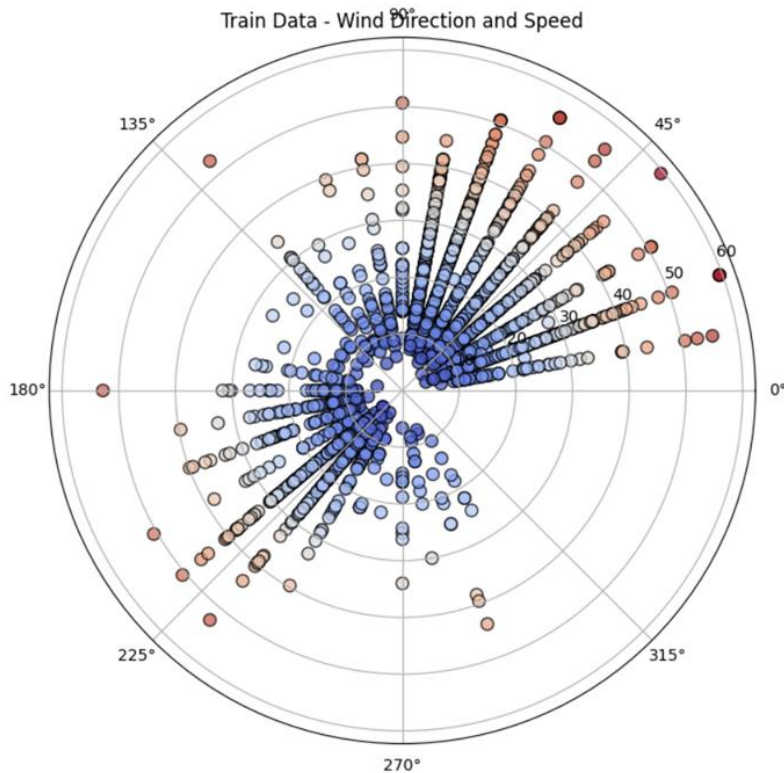
Sunshine Distribution(Test Data)



EDA - Wind Direction & Speed

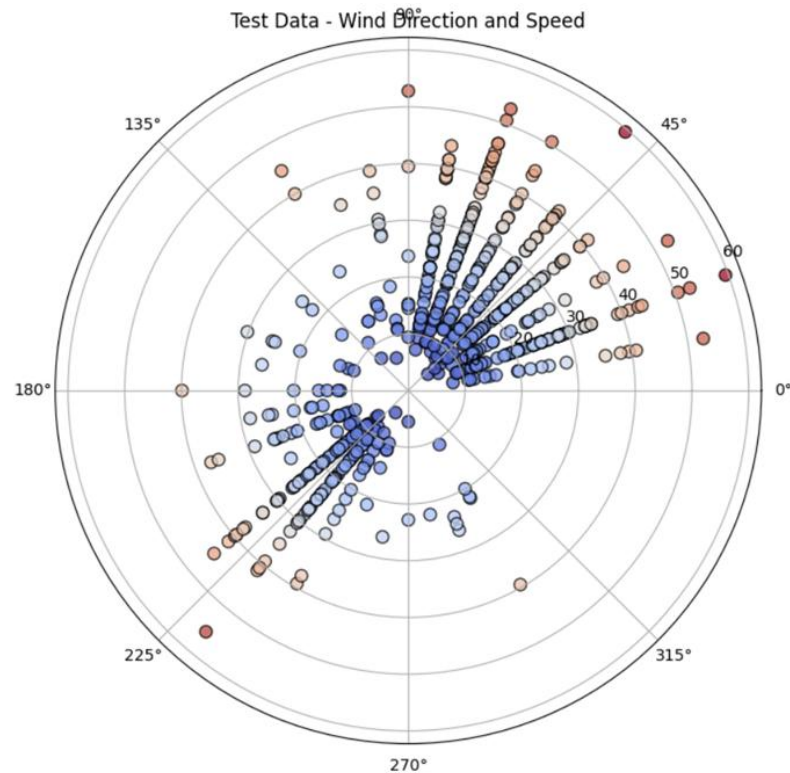
Train Data

Train Data - Wind Direction and Speed

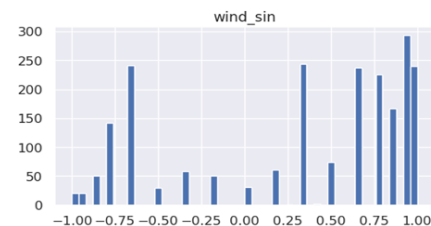
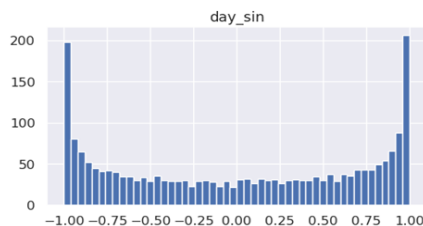
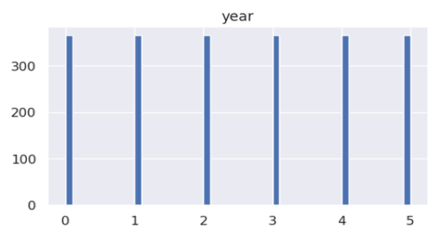
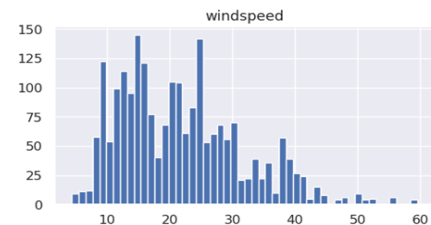
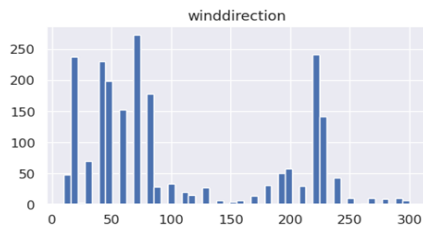
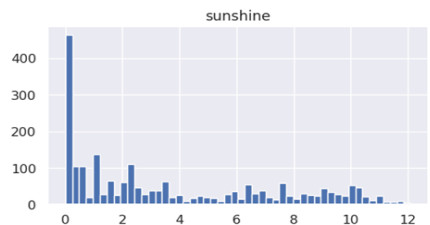
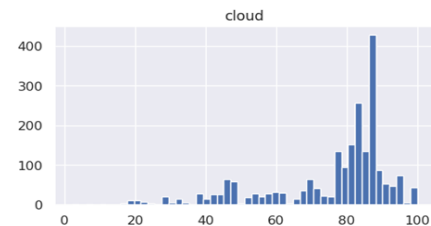
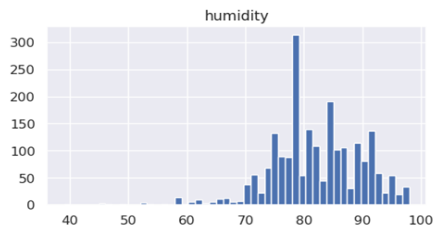
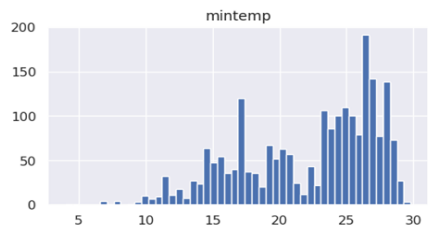
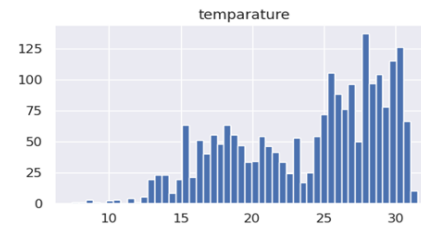
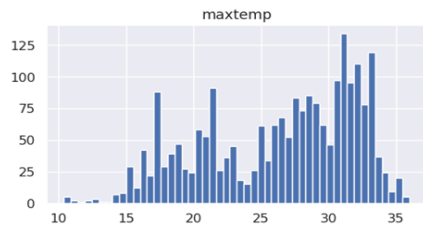
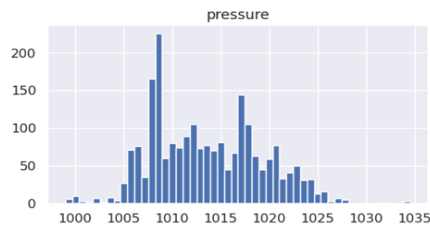


Test Data

Test Data - Wind Direction and Speed



EDA - Distribution of Given Features (Train Data)



EDA - Distribution of Given Features (Test Data)

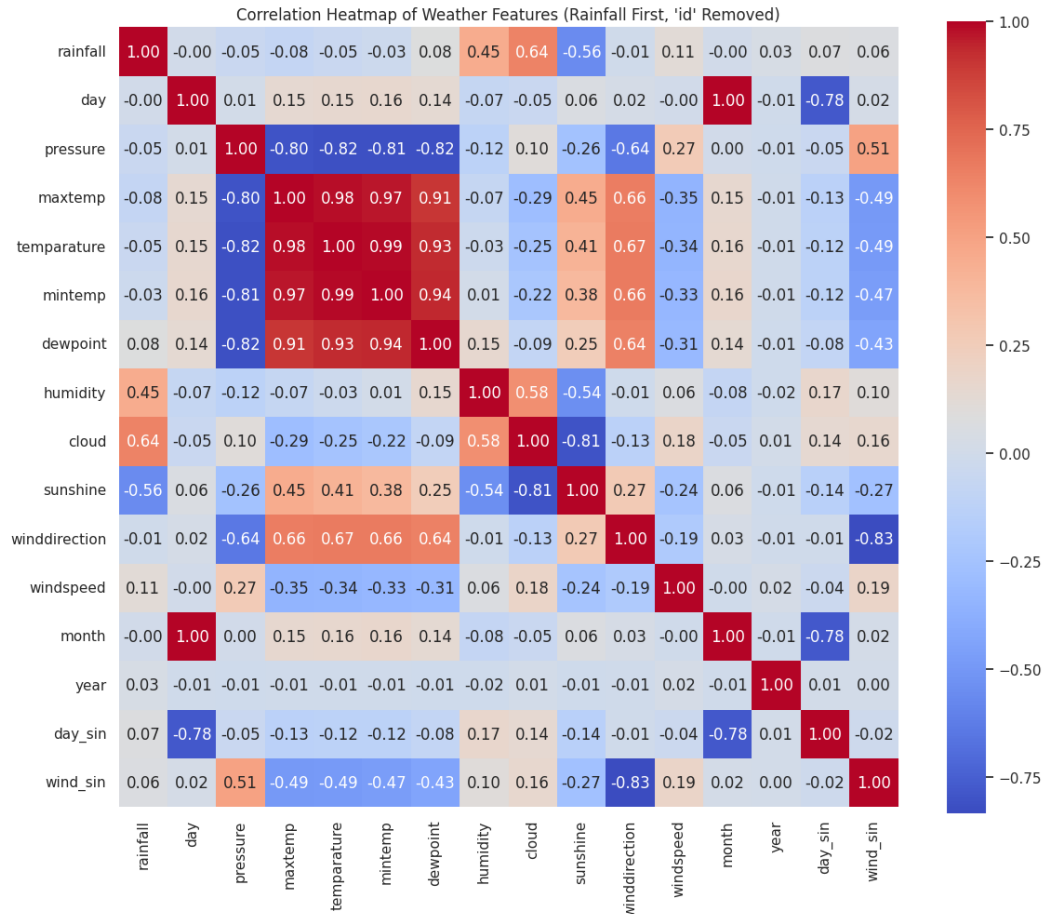


EDA - Data Preprocessing and Transformation

- Input Features: `['day', 'pressure', 'maxtemp', 'temperature', 'mintemp', 'humidity', 'cloud', 'sunshine', 'winddirection', 'windspeed']`
- Additional Features:
 - wind_sin – a sine transformation of the wind direction to encode it cyclically: $2\pi \cdot \text{winddirection} / 360$
 - day_sin – a sine transformation of the day to capture seasonal cycles: $2\pi \cdot \text{day} / 365$
 - year – Synthetic year assigned based on index or grouping.
 - month – Extracted from the synthetic date derived from day

EDA - Linear Relationships

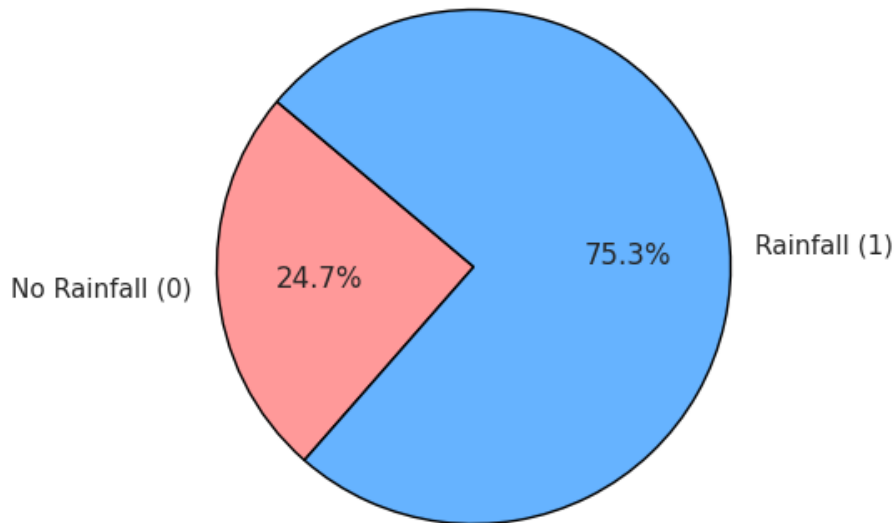
- All Features: ['day', 'pressure', 'maxtemp', 'temperature', 'mintemp', 'humidity', 'cloud', 'sunshine', 'winddirection', 'windspeed', 'month', 'year', 'wind_sin', 'day_sin']
- Relevant Features: ['pressure', 'maxtemp', 'temperature', 'mintemp', 'humidity', 'cloud', 'sunshine', 'winddirection', 'windspeed', 'year', 'day_sin', 'wind_sin']
- Irrelevant Features: ['day', 'month']
- Additional Features to Test: Previous day(s)' Features



Modeling - Baseline

- Train/Val Split
 - 80/20
 - Random / Sequential
- If a model always predicts rainfall = 1, the accuracy is 75.3%
- A basic Logistic Regression model (without feature engineering) improves the accuracy to 86%

Rainfall Distribution (Train Data)



Modeling - Improvement

Model	Validation Accuracy	Test Score
Logistic Regression	0.8837	0.8961
KNN	0.8744	0.8716
Decision Tree	0.8676	0.8556
Random Forest	0.8744	0.8958
XGBoost	0.8721	0.8998
Neural Network	0.8790	0.9014
1D CNN	0.8833	0.8916
2D CNN	0.8787	0.8879
LSTM	0.8767	0.8959
GRU	0.8699	0.8972
Ensemble	—	0.9038

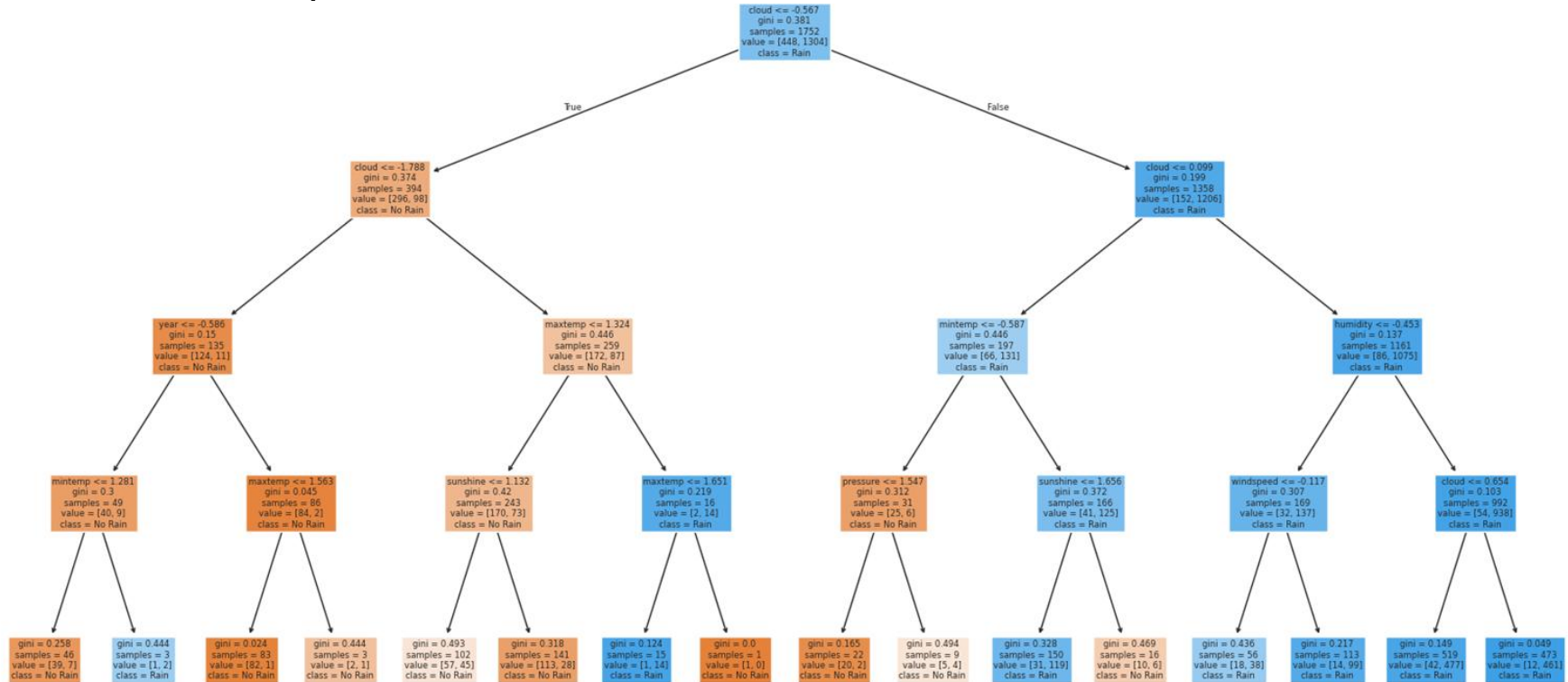
Experiments

- Classic Models:
 - Logistic Regression, Decision Tree, Random Forest, XGBoost, KNN
- Neural Net Models:
 - NN, 1D CNN, 2D CNN, LSTM, GRU
- Ensemble:
 - Weighted average of different models

Hyperparameter Choices – Decision Trees

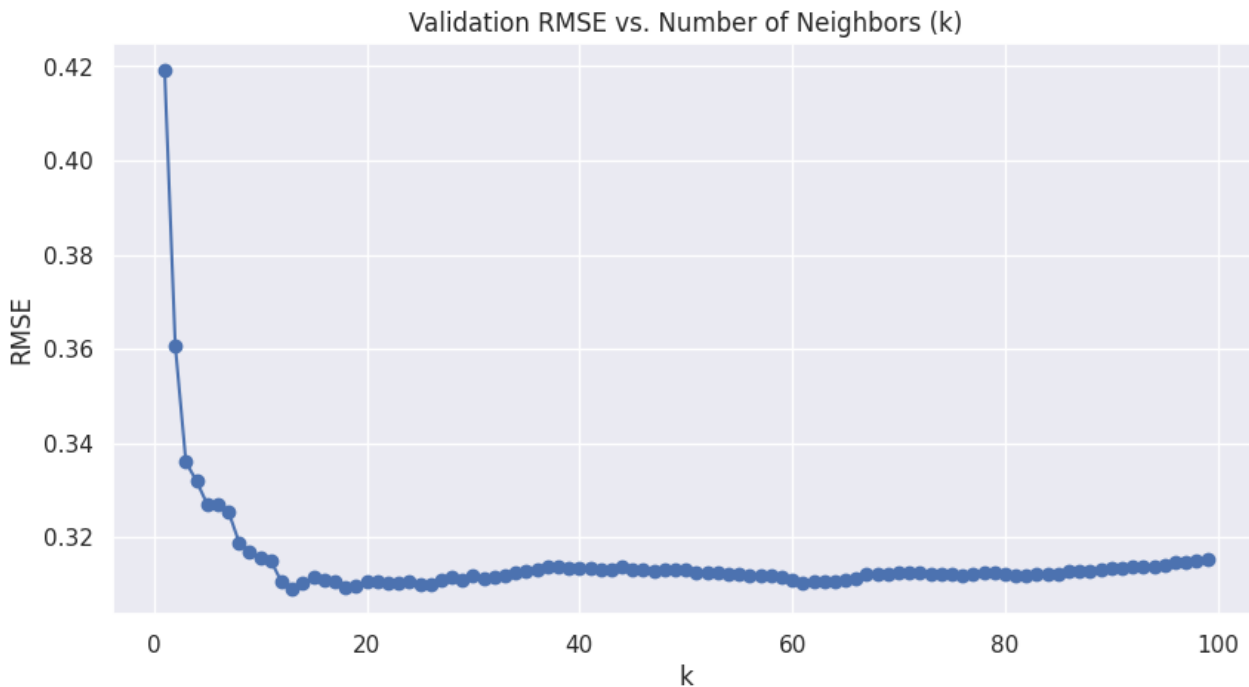
Decision Tree

- Max_depth = 4



Hyperparameter Choices - KNN

- $K = 15$

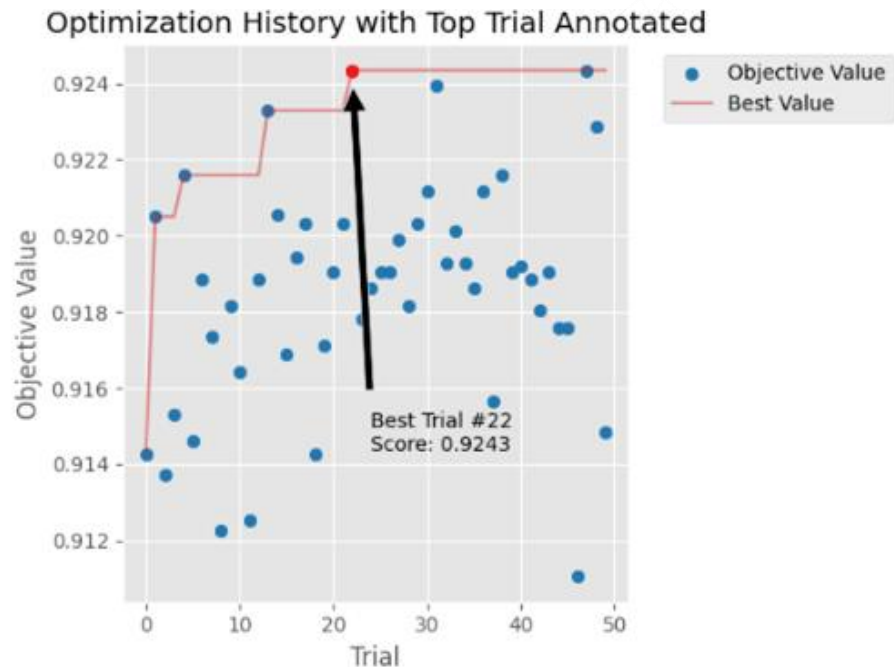
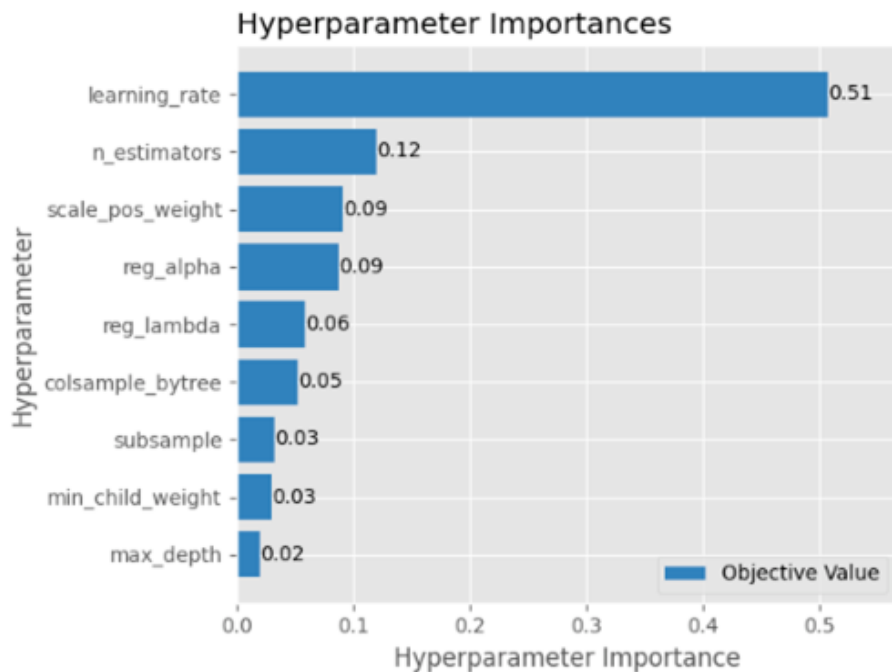


Hyperparameter Choices - XGBoost

```
def objective(trial):  
    params = {  
        "n_estimators": trial.suggest_int("n_estimators", 100, 1000),  
        "max_depth": trial.suggest_int("max_depth", 3, 10),  
        "learning_rate": trial.suggest_float("learning_rate", 0.01, 0.3, log=True),  
        "subsample": trial.suggest_float("subsample", 0.6, 1.0),  
        "colsample_bytree": trial.suggest_float("colsample_bytree", 0.6, 1.0),  
        "reg_alpha": trial.suggest_float("reg_alpha", 0.0, 1.0),  
        "reg_lambda": trial.suggest_float("reg_lambda", 0.0, 10.0),  
        "min_child_weight": trial.suggest_int("min_child_weight", 1, 10),  
        "scale_pos_weight": trial.suggest_float("scale_pos_weight", 1.0, 10.0),  
    }
```

```
model_xgb = XGBClassifier(  
    n_estimators=300,  
    learning_rate=0.05,  
    max_depth=6,  
    subsample=0.8,  
    colsample_bytree=0.8,  
    scale_pos_weight=3, # if rainfall is imbalanced  
    random_state=42  
)
```

Hyperparameter Choices - XGBoost



Hyperparameter Choices - 1D CNN

```
def create_cnn_model(trial):  
    model = Sequential()  
  
    # Hyperparameters to tune  
    num_filters = trial.suggest_categorical("num_filters", [32, 64, 128])  
    kernel_size = trial.suggest_categorical("kernel_size", [3, 4, 5, 7])  
    dropout_rate = trial.suggest_float("dropout_rate", 0.2, 0.5)  
    dense_units = trial.suggest_int("dense_units", 32, 128)  
    learning_rate = trial.suggest_float("learning_rate", 1e-4, 1e-2, log=True)
```


Hyperparameter Choices - 2D CNN

```
def create_2dcnn_model(trial):  
    model = Sequential()  
  
    # Trial-controlled hyperparameters  
    filters = trial.suggest_categorical('filters', [32, 64, 128])  
    kernel_size = trial.suggest_categorical('kernel_size', [3, 5])  
    pool_size = 1  
    dropout_rate = trial.suggest_float('dropout_rate', 0.2, 0.5)  
    dense_units = trial.suggest_int('dense_units', 64, 256)  
    learning_rate = trial.suggest_float('learning_rate', 1e-4, 1e-2, log=True)
```

Hyperparameter Choices – 1D CNN, 2D CNN

- 2D CNNs are not better than 1D CNNs
- Deeper CNNs are not better than shallower CNNs

Best 1D CNN

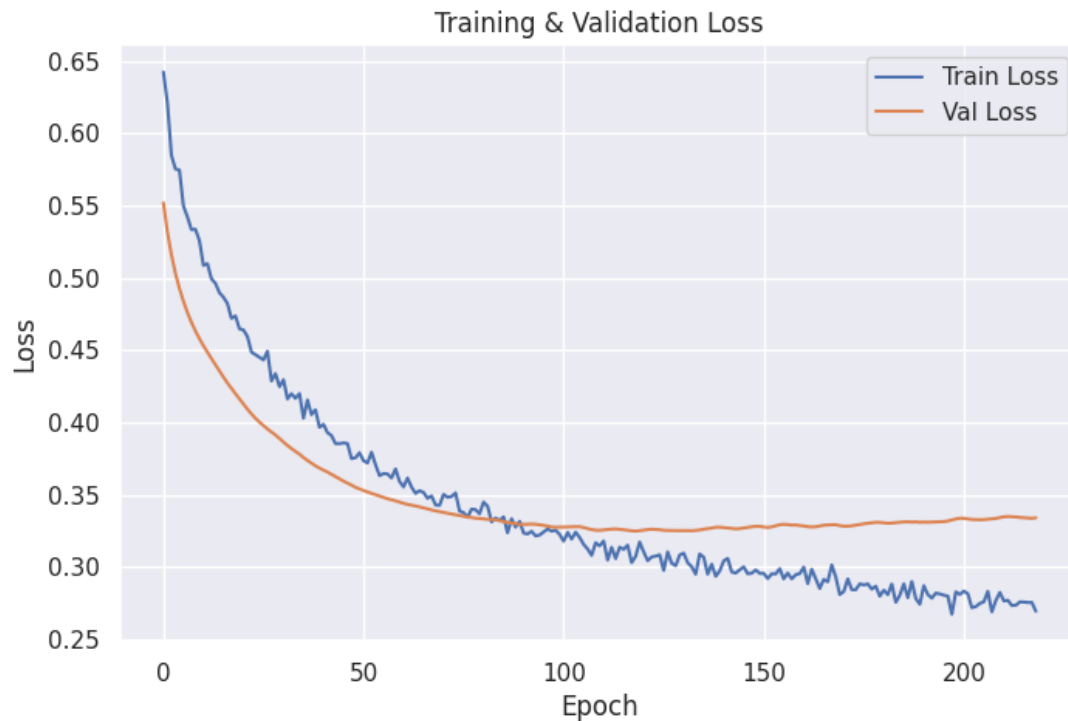
- Filter = 128.
- Kernel_size = 4.
- Stride = 1
- Learning_rate = 0.0005.
- Activation = 'relu'
- Dropout rate = 0.5

Layer (type)	Output Shape	Param #
conv1d_1 (Conv1D)	(None, 8, 128)	6,272
max_pooling1d (MaxPooling1D)	(None, 4, 128)	0
dropout (Dropout)	(None, 4, 128)	0
flatten (Flatten)	(None, 512)	0
dense (Dense)	(None, 1)	513

Total params: 6,785 (26.50 KB)
Trainable params: 6,785 (26.50 KB)
Non-trainable params: 0 (0.00 B)

Hyperparameter Choices – 1D CNN

- Early_stopping
- Patience = 100
- Epochs = 300
- Batch_size 1024

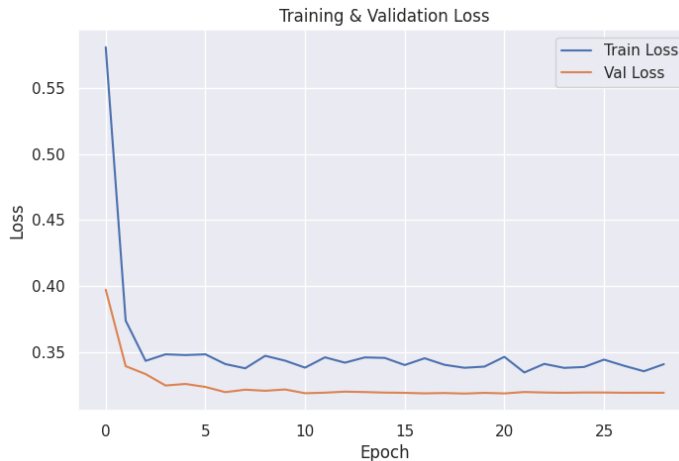


Hyperparameter Choices - LSTM

```
def create_lstm_model(trial):  
    model = Sequential()  
  
    units_1 = trial.suggest_int("units_1", 64, 256)  
    units_2 = trial.suggest_int("units_2", 32, 128)  
    dropout = trial.suggest_float("dropout", 0.2, 0.5)  
    bidirectional = trial.suggest_categorical("bidirectional", [True, False])  
  
    layer_1 = LSTM(units_1, return_sequences=True, dropout=dropout)  
    if bidirectional:  
        model.add(Bidirectional(layer_1))  
    else:  
        model.add(layer_1)  
  
    model.add(LSTM(units_2, dropout=dropout))  
    model.add(Dense(1, activation='sigmoid'))  
  
    learning_rate = trial.suggest_float("learning_rate", 1e-4, 1e-2, log=True)  
    optimizer = tf.keras.optimizers.Adam(learning_rate=learning_rate)  
  
    model.compile(optimizer=optimizer, loss='binary_crossentropy', metrics=['accuracy'])  
  
    return model
```

Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 1, 64)	19,712
dropout_2 (Dropout)	(None, 1, 64)	0
lstm_1 (LSTM)	(None, 64)	33,824
dropout_3 (Dropout)	(None, 64)	0
dense_2 (Dense)	(None, 128)	8,320
dropout_4 (Dropout)	(None, 128)	0
dense_3 (Dense)	(None, 1)	129

Total params: 183,557 (717.02 KB)
Trainable params: 61,185 (239.00 KB)
Non-trainable params: 0 (0.00 B)
Optimizer params: 121,372 (478.02 KB)



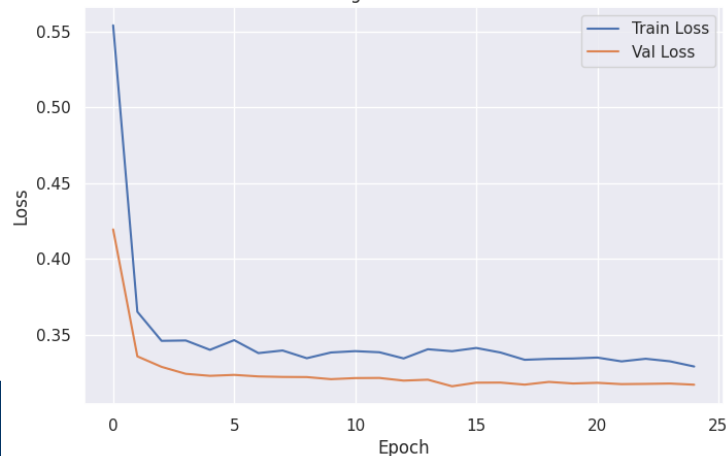
Hyperparameter Choices - GRU

```
def create_model(trial):
    model = Sequential()
    units_1 = trial.suggest_int("units_1", 64, 256)
    units_2 = trial.suggest_int("units_2", 32, 128)
    dropout = trial.suggest_float("dropout", 0.2, 0.5)
    bidirectional = trial.suggest_categorical("bidirectional", [True, False])
    layer_1 = GRU(units_1, return_sequences=True, dropout=dropout)
    if bidirectional:
        model.add(Bidirectional(layer_1))
    else:
        model.add(layer_1)
    model.add(GRU(units_2, dropout=dropout, return_sequences=False))
    model.add(Dense(1, activation='sigmoid'))
    learning_rate = trial.suggest_float("learning_rate", 1e-4, 1e-2, log=True)
    optimizer = tf.keras.optimizers.Adam(learning_rate=learning_rate)
    model.compile(optimizer=optimizer, loss='binary_crossentropy', metrics=['accuracy'])
    return model
```

Layer (type)	Output Shape	Param #
gru (GRU)	(None, 1, 64)	14,976
gru_1 (GRU)	(None, 32)	9,408
dropout_5 (Dropout)	(None, 32)	0
dense_4 (Dense)	(None, 1)	33

Total params: 73,253 (286.15 KB)
Trainable params: 24,417 (95.38 KB)
Non-trainable params: 0 (0.00 B)
Optimizer params: 48,836 (190.77 KB)

Training & Validation Loss



Ensemble – Different Combinations of Models

- KNN worsened ensemble accuracy.
- LSTM and GRU also did not improve ensemble accuracy.
- A weighted average of lr, decision tree, Xgboost, NN, and CNNs results in the best score

Future Work

Incorporation of Additional Data Source

- Use satellite imagery, radar data, or real-time weather station feeds to improve prediction accuracy
- Incorporate topographical and elevation data to account for geographical rainfall patterns

Temporal and Spatial Modeling




- Extend the model to spatio-temporal predictions (e.g., where and when it will rain)
- Use recurrent neural networks (RNNs) or transformers for time-series forecasting.

Fairness

- Distribution Bias, Omitted Variable Bias, Evaluation Bias, Generalization Bias

Conclusion

- Feature engineering, particularly time-based encoding and wind direction transformation, improved all models.
- Neural models outperform simpler models on this task.
- CNNs and recurrent architectures handle sequential dependencies well.
- More complicated models are not necessarily better.
- Ensemble modeling achieved near-top leaderboard performance on Kaggle (rank 21/4382).

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 submission_ensemble.csv Complete (after deadline) · Lynne Wang · 7d ago				0.90376

References

- Kaggle : <https://www.kaggle.com/competitions/playground-series-s5e3/overview>
- Image: <https://www.youtube.com/watch?v=Pn5NTfeKJzY>
- <https://www.pivotalweather.com>

Contributions

- Mridul Jain: EDA, data pre-processing, lr, tree, xgboost, lstm, gru models building and tuning, slides preparation.
- Lynne Wang: EDA, data pre-processing, lr, tree, xgboost, nn, cnn, knn models building and tuning, slides preparation.
- Deepak Kumar Srivastava: EDA, data pre-processing, lr, tree, xgboost, nn, lstm models building and tuning, slides preparation.
- Naresh Kumar Chinnathambi Kailasam: EDA, data pre-processing, lr, tree, xgboost, nn, lstm models building and tuning, slides preparation.
- https://github.com/lwang9/mids-w207-final_project_team2