CS 430 Lecture 25 Activities

Opening Questions

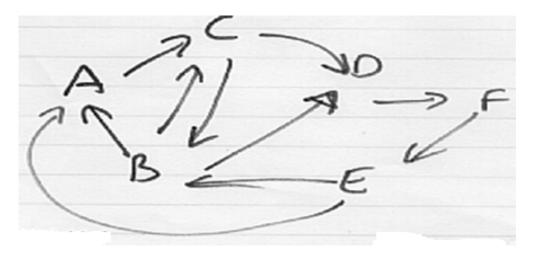
- 1. What is the runtime of breadth first search (if you restart the search from a new source if everything was not visited from the first source)?
- 2. Does a breadth-first search always reach all vertices?
- 3. How can you use a breadth-first search to find the shortest path (minimum number of edges) from a given source vertex to all other vertices?
- 4. If you look at the predecessor edges which were used to connect to an unvisited vertex, what do these predecessor edges form? Is it unique for a graph?

Depth-First Search

https://www.reddit.com/r/dataisbeautiful/comments/7b7aa0/visualizing_the_depthfirst_search_recursive/?st=J90UDR00&sh=5b671c59

As we visit a vertex, we try to move to a new adjacent vertex that hasn't yet been visited, until there is nowhere else to go, then backtrack. Uses a stack and some way to mark a vertex as visited (white initially, gray when first visited and put in stack, black when out of stack), label a vertex with a counter for first time seen, and another counter for last time seen (we will see why later), and label a vertex with how its predecessor vertex was during the traversal.

1. Perform a depth-first search on this graph.



	Algorithm 25.2 Depth First Search Visit	
Algorithm 25.1 Depth-First Search	1:	function DFS-Visit (u)
1: function $DFS(G)$	2:	$Color(u) \leftarrow GRAY \qquad \triangleright White vertex u has just$
2: for all vertex $u \in V[G]$ do		been discovered.
3: $Color(u) \leftarrow WHITE$	3:	$time \leftarrow time + 1$
4: $\pi(u) \leftarrow \text{NIL}$	4:	$D(u) \leftarrow time$
5: end for	5:	for all $v \in AdJ(u)$ do \triangleright Explore edge (u, v) .
6: $time \leftarrow 0$	6:	if $COLOR(v) == WHITE$ then
7: for all vertex $u \in V[G]$ do	7:	$\pi(v) \leftarrow u$
8: if $Color(u) == WHITE$	8:	DFS- $Visit(v)$
then DFS-VISIT (u)	9:	end if
9: end if	10:	end for
10: end for	11:	$Color(u) \leftarrow BLACK \triangleright Blacken u$; it is finished.
11: end function	12:	$F(u) \leftarrow time \leftarrow time + 1$
	13: end function	

2. What is the runtime for <u>depth</u>-first search (if you restart the search from a new source if everything was not visited from the first source)?

Another interesting property of depth-first search is that the search can be used to classify the edges of graph G based on how they are traversed.

- Tree edges are edges in the depth-first forest G_{π} . Edge (u, v) is a tree edge if v was first discovered by exploring edge (u, v).
- Back edges are those edges (u, v) connecting a vertex u to an ancestor v in a depth-first tree. Self-loops, which may occur in directed graphs, are considered to be back edges.
- Forward edges are those non-tree edges (u, v) connecting a vertex u to a descendant v in a depth-first tree.
- <u>Cross edges</u> are all other edges. They can go between vertices in the same depth-first tree, as long as one vertex is not an ancestor of the other, or they can go between vertices in different depth-first trees.
- 3. If a graph has no back edges when completing a depth first search, what does that tell us about the graph?

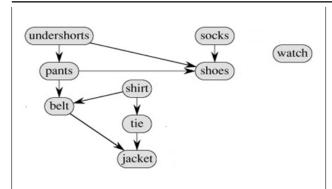
Demo of BFS/DFS: https://www3.cs.stonybrook.edu/~skiena/combinatorica/animations/search.html

Topological Sort (a DFS application)

• A topological sort of a directed acyclic graph¹, G = (V, E) is a linear ordering of all its vertices such that if G contains an edge (u, v), then u appears before v in the ordering. (If the graph is not acyclic, then no linear ordering is possible.)

¹sometimes known as a dag

- A topological sort of a graph can be viewed as an ordering of its vertices along a horizontal line so that all directed edges from left to right. Topological sorting is thus different from the usual kind of "sorting" studied earlier.
- Directed acyclic graphs are used in many applications to indicate precedence among events.
- A depth-first search can be used to perform a topological sort of a dag.
- 4. Perform a topological sort on this graph.



Algorithm 25.3 Topological Sort

- 1: function Topological-sort(G)
- 2: DFS(G) to compute finishing times F(v) for each vertex v.
- 3: As each vertex is finished, insert it onto the front of a linked list.
- 4: **return** the linked list of vertices
- 5: end function
- 5. Why does the topological sort work? What is its runtime?

The Parenthesis Theorem

The parenthesis theorem tells us that, for two vertices $u, v \in V$, it cannot be the case the d[u] < d[v] < f[u] < f[v]; that is, the intervals [d[u], f[u]] and [d[v], f[v]] are either disjoint or nested. This is a simple consequence of the depth-first nature of DFS. If the algorithm discovers u and then discovers v, it cannot later back out of u without backing out of v.

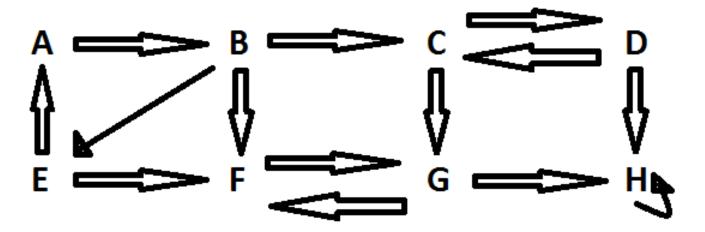
Strongly Connected Components (a DFS application)

A graph is said to be strongly connected if every vertex is reachable from every other vertex. The strongly connected components of an arbitrary directed graph from a partition into subgraphs that are themselves strongly connected. It is possible to test the strong connectivity of a graph, or to find its strongly connected components, in linear time.

Algorithm 25.4 Strongly Connected Components

- 1: function Strongly-Connected-Components(G)
- 2: Call DFS(G) to compute finishing times f[u] for each vertex u.
- 3: Compute G^T (the transpose of the graph).
- 4: Call DFS(G^T), but in the main loop of DFS, consider the vertices in order of decreasing f[u] (as computed in line 1).
- 5: Output the vertices of each tree in the depth-first forest formed in line 3 as a separate strongly connected component.
- 6: end function

6. Find the strongly connected components.



- 7. Discuss: G and G^T will have the same strongly connected components.
- 8. Discuss: The component with the latest finish time vertex will have no edges in the transpose to any other component.