CS 430 Lecture 27 Activities

Shortest Path Problem

How to find the shortest route between two points on a map.

Input

- Directed graph G = (V, E)
- Weight function $w: E \to \mathbf{R}$

Weight of path

$$p = \langle v_0, v_1, \dots, v_k \rangle$$

$$= \sum_{i=1}^k w(v_{i-1}, v_i)$$

$$= \text{sum of edge weights on path } p.$$

Shortest-path weight u to v

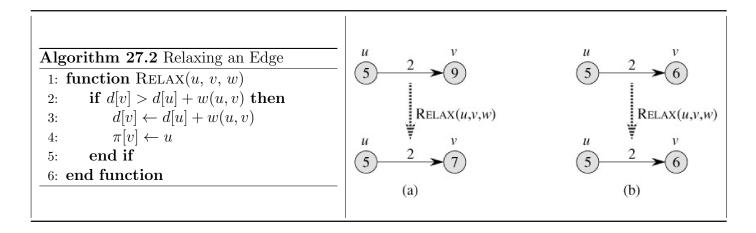
$$\delta(u,v) = \begin{cases} \min\{w(p) : u \leadsto^p v & \text{if there exists a path } u \leadsto v, \} \\ \infty & \text{otherwise.} \end{cases}$$

Shortest path u to v is any path p such that $w(p) = \delta(u, v)$. Variants

- Single-source: Find shortest paths from a given source vertex $s \in V$ to every vertex $v \in V$.
- Single-destination: Find shortest paths to a given destination vertex.
- Single-pair: Find shortest path from u to v. No way known that's better in worst case than solving single-source.
- All-pairs: Find shortest path from u to v for all $u, v \in V$. We'll see algorithms for all-pairs in the next chapter.

Negative-weight edges – OK, as long as no negative-weight cycles are reachable from the source.

- If we have a negative-weight cycle, just keep going around it, and get $w(s, v) = -\infty$ for all v on the cycle.
- But OK if the negative-weight cycle is not reachable form the source.
- Some algorithms work only if there are no negative-weight edges in the graph.



1. What would the brute force approach be to solve the shortest path problem, and what is its run time?

1 Path of 1 edge
$$|V| - 2$$
 Paths of 2 edges $(|V| - 2)(|V| - 3)$ Paths of 3 edges $|V|$! Paths of V edges

2. Prove optimal substructure for the shortest path problem. Since shortest paths contain shortest subpaths (optimal solution to subproblem must in in optimal answer to problem.) $G\{V, E\}$, weight function on edge given source v, find shortest path to u

Output of single-source shortest-path algorithm For each vertex $v \in V$:

- $d[v] = \delta(s, v)$, Initially, $d[v] = \infty$; reduces as algorithms progress. But always maintain $d[v] \leftarrow \delta(s, v)$. Call d[v] a shortest-path estimate.
- $\pi[v] = \text{predecessor of } v \text{ on a shortest path from } s.$ If no predecessor, $\pi[v] = NIL$, π induces a tree–shortest-path tree.

Initialization – All the shortest-paths algorithms start with Init-Single-Source.

Algorithm 27.1 Single Source Initialization

```
1: function INIT-SINGLE-SOURCE(V,s)

2: for all v \in V do

3: d[v] \leftarrow \infty

4: \pi[v] \leftarrow \text{NIL}

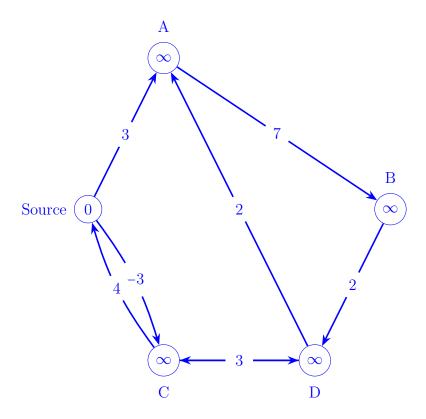
5: end for

6: d[s] \leftarrow 0

7: end function
```

Relaxing an edge (u, v) - Can we improve the shortest-path estimate (best seen so far) from the source s to v be going through u and taking edge (u, v)?

The algorithms differ in the order and how many times they relax each edge.



Shortest Path Algorithm - Bellman-Ford

The most straightforward of the "relax an edge" algorithms. Relaxes the edges in a fixed order (any fixed order) |V| - 1 times. Not a greedy algorithm.

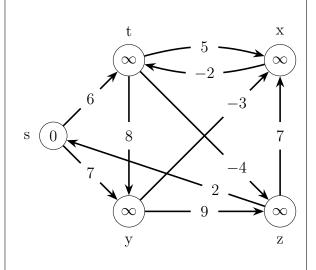
- Allows negative-weight edges.
- Computers d[v] and $\pi[v]$ for all $v \in V$.
- Returns TRUE if no negative-weight cycles are reachable from s, FALSE otherwise.
- 3. Execute Bellman-Ford on the above graph from source s for this edge order (t, x), (t, y), (t, z), (x, t), (y, x), (y, z), (z, x), (z, s), (s, t), (s, y). Update the d[v] and $\pi[v]$ values for each iteration.

¹Works on any graph with no negative cycles, and the algorithm finds the negative cycles.

 $^{^{2}}$ Most # of edges on short path.

Algorithm 27.3 Bellman-Form Shortest Path Algorithm $O(|V||E|) = O(|V|^3)$

```
1: function Bellman-Ford(V, E, w, s)
       INIT-SINGLE-SOURCE(V, s)
2:
       for i \leftarrow 1 to |V| - 1 do
3:
          for all edge (u, v) \in E do
4:
              Relax(u, v, w)
5:
          end for
6:
7:
       end for
       for all edge (u, v) \in E do
8:
          ▶ All edges, in any order, same order each time
9:
          if d[v] > d[u] + w(u, v) then
                                              ▶ Must be a
10:
   negative cycle
              return FALSE
11:
12:
          end if
       end for
13:
       return TRUE
14:
15: end function
```



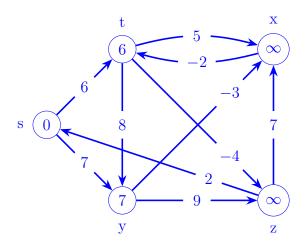


Figure 27.1: Example of the Execution of Bellman-Ford Step 1.

- 4. What is the runtime of Bellman-Ford? $O(|V||E|) = O(|V|^3)$
- 5. Prove Bellman-Ford is correct. Values you get on each pass how quickly it converges depends on order of relaxation. But guaranteed to converged after |V| 1 passes, assume no negative-weight cycles.