

# January 10, 2024 Notes

# Intelligent (Autonomous) Agents

## Agent

An **agent** is just **something that acts** (from the Latin agere, to do).

Of course, we would prefer “acting” to be:

- autonomous
- situated in some environment (that could be really complex)
- adaptive
- create and goal-oriented

## Rational Agent

A **rational agent** is one that acts **to achieve the best outcome**, or when there is uncertainty, **the best expected outcome**<sup>1</sup>.

## AI: Constructing Agents

You can say that: AI is focused on the **study and construction of agents that do the right thing**.

## Percepts and Percept Sequences

**Percept** – content/information that agent’s sensors are perceiving / capturing **currently**

**Percept Sequence** – a **complete history** of **everything that agent has ever perceived**

- any practical issues that you can see here?
- what can a percept sequence be used for?

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<sup>1</sup>no worries, we will make it a little less vague soon

# Percepts, Knowledge, Actions, States

- Agent's choice of action / decision at any given moment:
  - CAN depend on:
    - \* built-in **knowledge**
    - \* entire **percept sequence**
  - CANNOT depend anything it hasn't perceived
- Agent's action CAN change the **environment state**

Knowledge is power, right?

## Agent Function/Program

Specifying an action choice for every possible percept sequence would define an agent

- Action  $\leftrightarrow$  percept sequence **mapping** IS the agent **function**.
- Agent **function** describes agent **behavior**.
- Agent **function** is an **abstract concept**.
- Agent **program** implements agent **function**.

## Vacuum Cleaner Agent Example

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### Algorithm 1.1 Vacuum Cleaner Agent Example

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1: function TABLE-DRIVEN-AGENT(percept) returns an action
2:   percepts: a sequence, initially empty
3:   table, a table of actions, indexed by percept sequences, initially fully specified
4:   append percept to the end of percepts
5:   action  $\leftarrow$  LOOKUP(percepts, table)
6:   return action
7: end function
8:
9: function REFLEX-VACUUM-AGENT([location, status]) returns an action
10:  if status = Dirty then return Suck
11:  else if location = A then return Right
12:  else if location = B then return Left
13:  end if
14: end function

```

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# Actions Have Consequences

- An agent can act upon its environment, but **how do we know if the end result is “right”?**
- After all, **actions have consequences**: either good or bad.
- Recall that **agent actions change environment state!**
- If state changes are desirable, and agent performs well.
- Performance measure evaluates state changes.

# Performance Measure

## A Tip

It is better to **design performance measures according to what one actually wants to be achieved in the environment**, rather than according to how one thinks the agent should behave.

## A Warning

If it is difficult to specify the performance measure, agents may end up optimizing a wrong objective. Handle uncertainty well in such cases.

# Rationality

Rational decisions at the moment depend on:

- The **performance measure** that defines success criteria
- The agent's **prior knowledge** of the environment
- The **actions** that the agent can perform
- The agent's **percept sequence** so far

# Rational Agent

For each possible percept sequence, a rational agent should **select an action that is expected to maximize its performance measure**, given the **evidence provided by the percept sequence** and whatever **built-in knowledge** the agent has.

# Rationality in Reality

- An omniscient agent will ALWAYS know the final outcome of its action. Impossible in reality. That would be perfection.
- Rationality maximizes what is EXPECTED to happen.
- Perfection maximizes what WILL happen.
- Performance can be improved by **information gathering and learning**.

# Designing the Agent for the Task

## Analyze the Problem

### Task Environment — PEAS

In order to start the agent design process, we need to specify/define:

- The Performance measure
- The Environment in which the agent will operate
- The Actuators that the agent will use to affect the environment
- The Sensors

### Task Environment Properties

Key dimensions by which task environments can be categorized:

- Fully vs partially observable (can be unobservable too)
- Single agent vs multi-agent
  - multi-agent: competitive vs. co-operative
- Deterministic vs. non-deterministic (stochastic)
- Episodic vs. sequential
  - Sequential requires planning ahead
- Static vs. dynamic
- Discrete vs. continuous
- Known vs. unknown (to the agent)

## Select Agent Architecture

$$\text{Agent} = \text{Architecture} + \text{Program}$$

### Typical Agent Architectures

- Simple reflex agent.
- Model-based reflex agent.
- Goal-based reflex agent.
- Utility-based reflex agent.

## Select Internal Representations