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0.1 Definition

- In a supervised learning problem, given the input variables X and outputs Y , the goal of linear regression is to learn a function that can predict an output given an input.
- We find the best line (linear function $y = f(X)$) to explain the data.

0.2 Examples

Predicting a continuous outcome variable

- Predicting a company's future stock price using its profit and other financial information.
- Predicting annual rainfall based on local flora and fauna.
- Predicting distance from a traffic light using LIDAR measurements.

0.3 Simplest Linear Regression

- x is an input feature.
- y is the value we're trying to predict.
- The regression model is:

$$y = w_1x + w_0$$

- Two parameters to estimate –
 - the slope of the line w_1 ,
 - the y -intercept w_0 .
- We basically want to find $\{w_0, w_1\}$ that minimize deviations from the predictor line.

$$\begin{aligned} \min \sum_{i=1,2,\dots,n} (y_i - \hat{y}_i)^2 \\ = \min_{w_0, w_1} \sum_{i=1,2,\dots,n} (y_i - w_1x_i - w_0)^2 \end{aligned}$$

0.4 Linear Regression Function Model

Function $f: X \rightarrow Y$ is a linear combination of input components

$$f(x) = w_0 + w_1x_1 + w_2x_2 + \dots + w_dx_d = w_0 + \sum_{j=1}^d w_jx_j$$

w_0, w_1, \dots, w_d are the parameters (weights)

0.5 Error

- Error function measures how much our predictions deviate from the desired answers.
- Mean-squared error (MSE):

$$\begin{aligned} J_n &= \frac{1}{2n} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2 \\ &= \frac{1}{2n} \sum_{i=1}^n (y_i - \mathbf{w}^T \mathbf{x}_i)^2 \end{aligned} \tag{1}$$

- Learning: We want to find the weights minimizing the error.
- In (1), $y_i - \mathbf{w}^T \mathbf{x}_i$ is the residual and

0.6 Optimization

- For the optimal set of parameters, **derivatives** of the **error** with respect to each **parameter** must be 0.

$$\begin{aligned}\frac{\partial}{\partial w_j} J_n(\mathbf{w}) &= -\frac{1}{n} \sum_{i=1}^n (y_i - w_0 x_{i0} - w_1 x_{i1} - \cdots - w_d x_{id}) x_{ij} \\ &= 0\end{aligned}$$

- Vector of derivatives:

$$\begin{aligned}\nabla_w &= -\frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{w}^T \mathbf{x}_i) \mathbf{x}_i \\ &= \mathbf{0}\end{aligned}$$

- By rearranging the terms, we get a system of linear equations with $d + 1$ unknowns.

$$w_0 \sum_{i=1}^n x_{i0} \cdot x_{ij} + w_1 \sum_{i=1}^n x_{i1} \cdot x_{ij} + \cdots + w_d \sum_{i=1}^n x_{id} \cdot x_{ij} + \sum_{i=1}^n y_i \cdot x_{ij}$$

- Can also be solved through matrix inversion if the matrix is not singular.

$$\mathbf{A}\mathbf{w} = \mathbf{b} \Rightarrow \mathbf{w} = \mathbf{A}^{-1}\mathbf{b}$$

0.7 Linear Regression as a System of Linear Equations

The **linear regression model** is akin to a **system of linear equations**. Assuming n training examples with $d + 1$ **features** each –

$$\begin{aligned}\text{1}^{\text{st}} \text{ training example: } & y_1 = w_0 + x_{11}w_1 + x_{12}w_2 + \cdots + x_{1d}w_d \\ \text{2}^{\text{nd}} \text{ training example: } & y_2 = w_0 + x_{21}w_1 + x_{22}w_2 + \cdots + x_{2d}w_d \\ & \vdots \\ \text{\textcolor{red}{n}}^{\text{th}} \text{ training example: } & y_n = w_0 + x_{n1}w_1 + x_{n2}w_2 + \cdots + x_{nd}w_d\end{aligned}$$

0.8 Solving Linear Regression

0.8.1 Using Matrices

- $J_n(\mathbf{w})$ can be rewritten in terms of data **matrices** X and **vectors**:

$$J_n(\mathbf{w}) = \frac{1}{2}(\cdots)$$

0.8.2 Using Gradient Descent

- Linear regression problem comes down to the problem of solving a set of linear equations:

$$\begin{aligned}\mathbf{w} &\leftarrow \mathbf{w} - \eta \cdot \nabla_{\mathbf{w}} J_n(\mathbf{w}) \\ \nabla J_n(\mathbf{w}) &= -\mathbf{X}^T(\mathbf{y} - \mathbf{X}\mathbf{w}) \\ \mathbf{w} &\leftarrow \mathbf{w} - \eta \cdot \mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{y})\end{aligned}$$

0.9 Linear Regression

- The **error function** defined for the whole dataset for the linear regression is:

$$J_n = \frac{1}{2n} \sum_{i=1}^n (y_i - f(\mathbf{x}_i))^2$$

- Online Gradient Descent**: use the **most recent sample** at each iteration. Instead of MSE for all data points, it uses **MSE** for an **individual sample**.

$$\begin{aligned}J_{online} &= Error_i(\mathbf{w}) \\ &= \frac{1}{2} (y_i - f(\mathbf{x}_i))^2 \\ \mathbf{w} &\leftarrow \mathbf{w} - \eta \dots\end{aligned}$$

0.10 Input Normalization

- Makes the **data** very roughly on the **same scale**.
- Can make a huge difference in **online learning**.
- For **inputs** with a **large magnitude**, the **change** in the **weight** is **huge**.
- Solution**: Make all inputs vary in the same range.
- New output:

$$\hat{x}_{ij} = \frac{x_{ij} - \bar{x}_j}{\sigma_j}$$

0.11 L1/L2 Regularization

Using **L1/L2 Regularization**, we can rewrite our loss function as:

$$\begin{aligned}L_{lasso} &= \frac{1}{2n} \sum_{i=1}^n (y_i - f(\mathbf{w}^T \mathbf{x}_i))^2 + \lambda \|\mathbf{w}\|_1 \\ L_{ridge} &= \frac{1}{2n} \sum_{i=1}^n (y_i - f(\mathbf{w}^T \mathbf{x}_i))^2 + \lambda \|\mathbf{w}\|_2^2\end{aligned}$$

0.12 Other Ways to Control Overfitting

Early-stopping : stopping training when a monitored matrix has stopped improving.

Bagging : learning multiple models in parallel and applying majority voting to choose final predictor.

Dropout : in each iteration, don't update some of the weights.

Injecting noise in the inputs.

0.13 Bias-Variance Tradeoff

- **Bias** captures the **inherent error** present in the model. The **bias error** originates from **erroneous assumption(s)** in the **learning algorithms**.
- **Bias** is the **contrast** between the **mean prediction** of our model and the **correct prediction**.
- **Variance** captures how much the **model changes** if it is **trained** on a **different training set**.
- **Variance** is the variation or spread of **model prediction** values across **different data samples**.
- **Underfitting** happens when a **model unable to capture** the underlying **pattern** of the data. Such models usually have **high bias** and **low variance**.
- It usually happens when there is much fewer amount of **data** to build an accurate model or when a **linear model** is used to **learn non-linear data**.
- **Overfitting** happens when our **model captures the noise** along with the underlying pattern in **data**.
- ...

Bias:

$$(y - \hat{y}) \tag{2}$$

Variance:

$$\frac{1}{k-1} \sum_{j=1}^{k-1} (\hat{y}_j - \hat{y})^2 \tag{3}$$

Total Error:

$$TE = Bias^2 + Variance = (y - \hat{y})^2 + \frac{1}{k-1} \sum_{j=1}^{k-1} (\hat{y}_j - \hat{y})^2 \tag{4}$$

$$\text{Expected Loss} = \text{Total Error} = \text{Bias}^2 + \text{Variance}$$