MATH 252 - Introduction to Differential Equations Notes

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Contents

Chapter 1

Introduction to Differential Equations

1.1 Terminology and Notation

Differential equation (D.E.) – An equation in which at least one derivative of an unknown function.
Order of the D.E. – The highest order of derivative in the D.E.
Example:

$$4y'' + e^x y' - 3yy' = \sin(x)$$

An example of a partial differential equation is:

$$\frac{\partial T}{\partial x} + x^2 \frac{\partial T}{\partial y} = x + y$$

however, we won't study these in this course.

1.1.1 – Linear vs Non-Linear DE's

Linear D.E. – The dependent variable and all of its derivatives in the D.E. are in separate terms to the 1^{st} power. $y^{(n)}$ or $\frac{d^n y}{dx^n}$ where $n \neq 1$ are non-first power.

$$4y'' + e^x y' - 3yy' = \sin(x)$$

is a non-linear D.E. while

$$4y'' + e^x y' - 3y = \sin(x)$$

is linear.
The general formula of a linear D.E. would look like

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x) = g(x)$$

Solution – a function $\phi(x)$ and an interval I for which the D.E. is satisfied when $y = \phi(x)$ for all x in I.

It may be the case that the natural domain of $\phi(x)$ is larger than I.Example: $y' = -\frac{1}{x^2}$ has a solution $\phi(x) = \frac{1}{x}$ on $I = (0, \infty)$ but the domain of $\phi(x) = (-\infty, 0) \cup (0, \infty)$.Practice:

$$\frac{d^2x}{dt^2} + 16x = 0$$

Show (*Verify* not derive) $x(t) = c_1 \sin(4t)$ is a solution on $(-\infty, \infty)$ where c is any real parameter.

$$\begin{aligned} x &= c_1 \sin(4t) \\ \frac{dx}{dt} &= 4c_1 \cos(4t) \\ \frac{d^2x}{dt^2} &= -16c_1 \sin(4t) \\ \text{LHS} = \frac{d^2x}{dt^2} &+ 16x \\ &= -16c_1 \sin(4t) + 16(c_1 \sin(4t)) \\ &= 0 = \text{RHS} \end{aligned}$$

But the equation $x = c_2 \cos(4t)$ would also be a solution. If you have 2 equations that are both solutions, you could add them together and you would still have a solution. $x = c_1 \sin(4t) + c_2 \cos(4t)$ is a solution for all parameters c_1 and c_2. *In fact, this is the general solution to the D.E.*

The D.E.

$$\frac{dy}{dx} = xy^{\frac{1}{2}}$$

Show $y = \left(\frac{1}{4}x^2 + C\right)^2$ is a one parameter family of solutions

$$\begin{aligned} \text{LHS} = \frac{dy}{dx} &= 2\left(\frac{1}{4}x^2 + C\right) \times \frac{1}{2}x \\ &= x\left(\frac{1}{4}x^2 + C\right) \\ \text{RHS} = xy^{\frac{1}{2}} &= x\left(\left(\frac{1}{4}x^2 + C\right)^2\right)^{\frac{1}{2}} \\ &= x\left(\frac{1}{4}x^2 + C\right) \\ \text{LHS} &= \text{RHS} \end{aligned}$$

But there is another solution: namely $y(x) = 0$ for all x. This is called the "trivial solution".

1.2 Initial Value Problems (IVP)

1st order IVP is a 1st order D.E. together with one extra condition:

$$\frac{dy}{dx} = f(x, y), y(x_0) = y_0$$

2nd order IVP

$$y'' = f(x, y, y')$$

Initial conditions:

- $y(x_0) = y_0$
- $y'(x_0) = y_1$

1.2.1 – Example

$$y' = y \text{ and } y(0) = 3$$

$y = ce^x$ is a one-parameter family of solutions

$$\frac{d}{dx}(ce^x) = ce^x = y$$

$$\begin{aligned} ce^1 &= -2 \\ c &= -\frac{2}{e} \\ y &= \left(-\frac{2}{e}\right)e^x \\ y &= -2e^{x-1} \end{aligned}$$

1.2.2 – Example

$$\text{D.E.: } y' + 2xy^2 = 0 \text{ and } y(0) = 1$$

Given that you have the solution: $y = \frac{1}{x^2+C}$, Solve:

$$\begin{aligned} -1 &= \frac{1}{(0)^2 + c} \\ -1 &= \frac{1}{c} \\ -1 \times c &= 1 \\ c &= -1 \\ y &= \frac{1}{x^2 - 1}, I = (-1, 1) \end{aligned}$$

1.2.3 – Example

$$\text{D.E.: } y' + 2xy^2 = 0 \text{ and } y(0) = 1$$

Example

$$x'' + 16x = 0 \text{ and } x(\frac{\pi}{2}) = 5 \text{ and } x'(\frac{\pi}{2}) = -4$$

$$\begin{aligned}
x &= c_1 \cos(4t) + c_2 \sin(4t) \\
5 &= c_1 \cos(4t) + c_2 \sin(4t) \\
&= c_1 \cos(2\pi) + c_2 \sin(2\pi) \\
&= c_1(1) + c_2(0) \\
&= c_1 \\
x' &= -4c_1 \sin(4t) + 4c_2 \cos(4t) \\
-4 &= -4c_1 \sin\left(4\left(\frac{\pi}{2}\right)\right) + 4c_2 \cos\left(4\left(\frac{\pi}{2}\right)\right) \\
&= -4c_1 \sin(2\pi) + 4c_2 \cos(2\pi) \\
&= -4c_1(0) + 4c_2(1) \\
&= 4c_2 \\
-1 &= c_2
\end{aligned}$$

Reasonable Question: Given a 1st order IVP, can we say whether a solution *exists* or not and, if a solution exists, is it *unique*.

Theorem: Given $y' = f(x, y)$ and $y(x_0) = y_0$, if $f(x, y)$ and $\frac{\partial f}{\partial y}$ are both continuous on a rectangle R containing (x_0, y_0) in its interior, then there exists an interval $I = (x_0 - h, x_0 + h)$ where $h > 0$ such that there exists a unique solution to IVP on I.

1.2.4 – Example

$$y' = xy^{\frac{1}{2}} \text{ and } y(1) = 2$$

- $f(x, y) = xy^{\frac{1}{2}}$ is continuous everywhere its defined $y \geq 0$
- $\frac{\partial f}{\partial y} = x\frac{1}{2}y^{-\frac{1}{2}} = \frac{x}{2y}$ is continuous everywhere its defined $y > 0$

1.2.5 – Example

$$y' = xy^{\frac{1}{2}} \text{ and } y(0) = 0$$

- $f(x, y) = xy^{\frac{1}{2}}$ is continuous for all x and $y \geq 0$
- $\frac{\partial f}{\partial} = \frac{x}{2y}$ is continuous for all x and $y > 0$.
- ***Theorem does not give any conclusion.***

Chapter 2

First-Order Differential Equations

2.1 Solution Curves Without a Solution

Given a 1st order D.E. $y' = f(x, y)$, y' is the slope of the tangent line at any point (x_0, y_0) on a solution curve

2.1.1 – Example

$$y' = f(x, y) = x + y$$

- $f(0, 0)$=0
- $f(1, 0)$=1

2.1.2 – Slope/Direction Fields

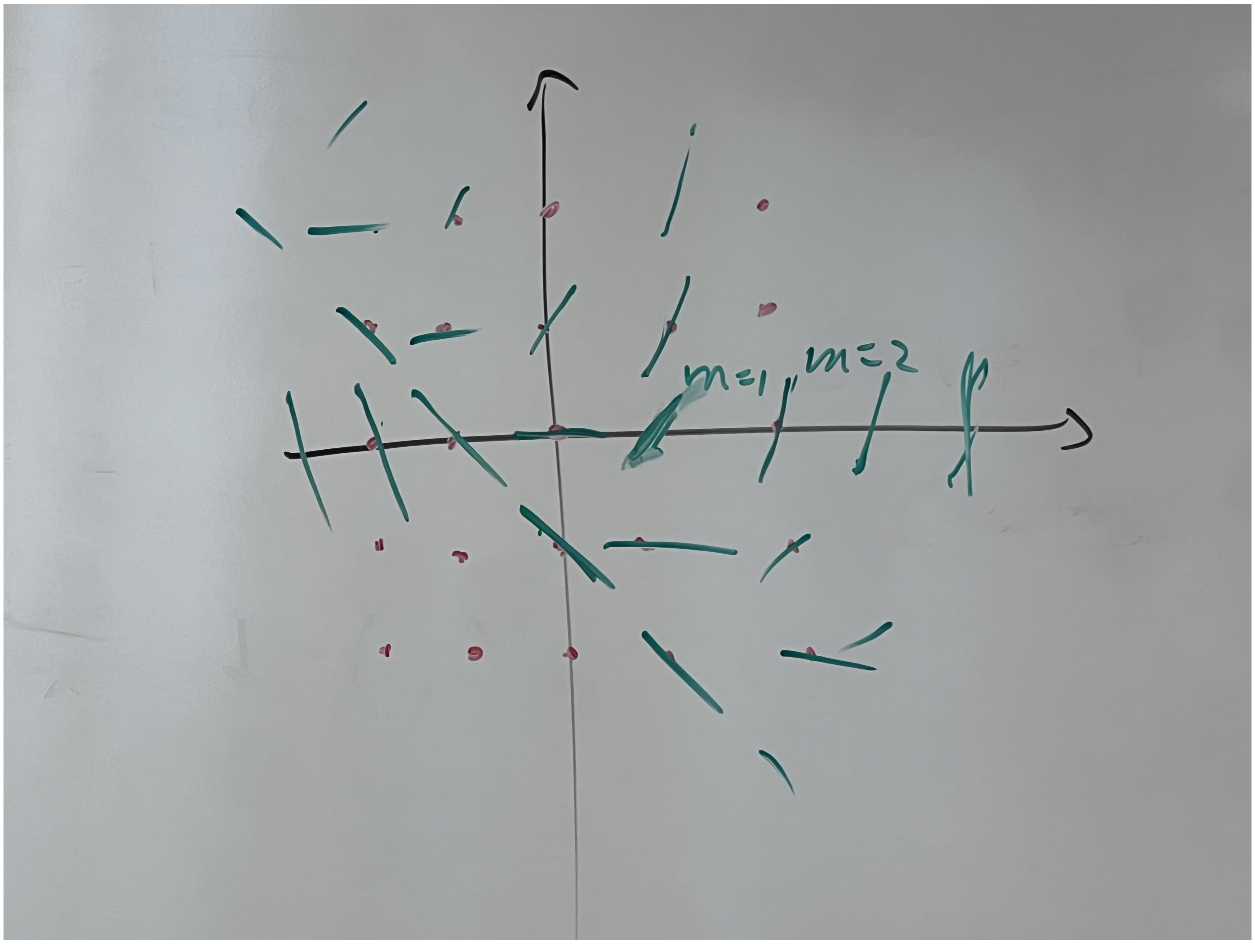

Figure 2.1: The direction field for the previous example

If the function $f(x, y)$ in the D.E. $y' = f(x, y)$ is reasonably simple so that we can solve $f(x, y) = 0$, we can make a "phase portrait diagram". We will also assume $f(x, y)$ only involves the y-variable.

2.1.3 – Example

$$y' = (y + 2)(y - 3)(y - 5)$$
$$f(x, y) = (y + 2)(y - 3)(y - 5)$$

An "equilibrium solution" is a solution where y is a constant. In this example: $y = 3$, $y = 5$, $y = -2$ are each constant functions.

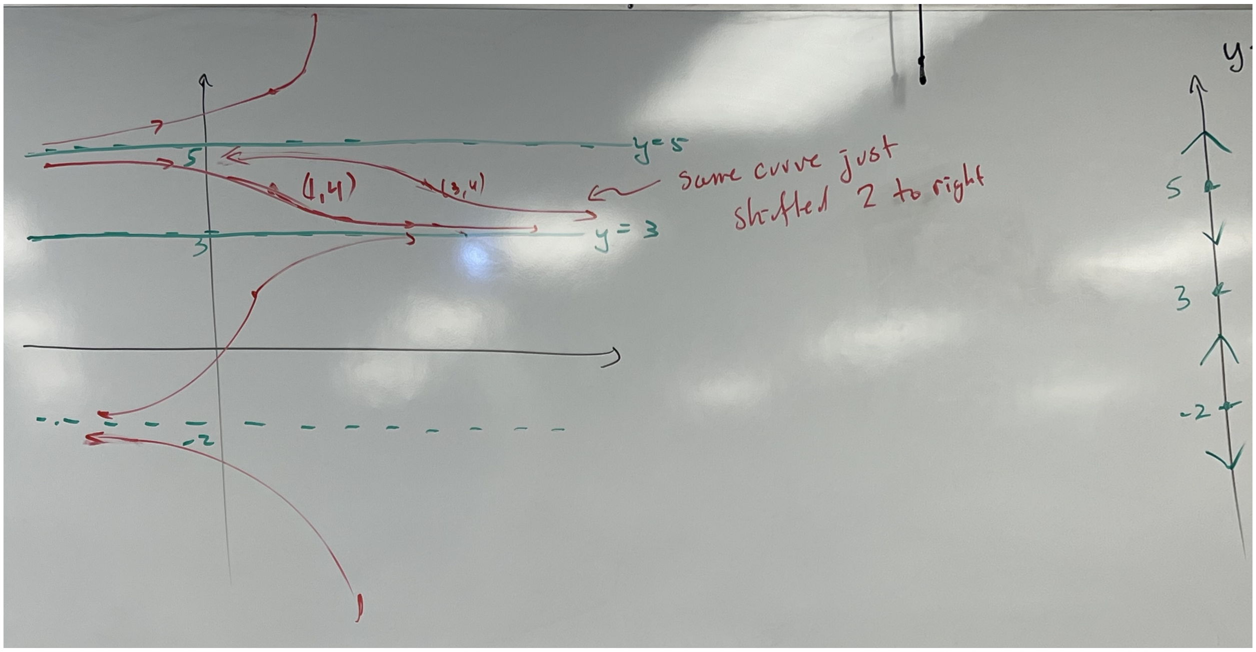

Figure 2.2: The equilibrium solution for the previous example.

The area around $y = 5$ is an unstable equilibrium since the solutions diverge and go in separate directions away from $y = 5$. The area around $y = 3$ is a stable equilibrium because the slopes above and below it converge to $y = 3$. The area around $y = -2$ is semi-stable, since all the slopes around it will converge in one direction, but the point isn't always $y = -2$.

2.2 Separable Differential Equations

Separable D.E.s are DE's $\frac{dy}{dx} = f(x, y)$ where $f(x, y)$ can be factored as $f(x, y) = g(x)h(y)$.

$$\frac{dy}{dx} = (1 + y^2)x^3 \text{ is separable}$$

$$\frac{dy}{dx} = \sin(xy) \text{ is } \textit{not} \text{ separable}$$

$$\frac{dy}{dx} = x^3 y \text{ is } \textit{not} \text{ separable}$$

$$\begin{aligned}
\frac{5}{xy}\frac{dy}{dx} &= \left(x^2 + y\right) e^y \\
\frac{dy}{dx} &= \frac{xy\left(x^2 + y\right) e^y}{5} \\
&= \frac{x\left(x^2 + y\right)}{5} \times ye^y
\end{aligned}$$

2.2.1 – Method of Solution

"Separate the variable" to get $\frac{1}{h(y)}dy = g(x)d$ or $p(y)dy = g(x)dx$ where $p(y) = \frac{1}{h(y)}$.**Integrate both sides**

$$\int p(y)dy = \int g(x)dx \text{ and if possible, solve for } y$$

2.2.2 – Example

$$\begin{aligned}
\frac{dy}{dx} &= \left(1+y^2\right)x^3 \\
\int \frac{1}{1+y^2}dy &= \int x^3 dx \\
\tan^{-1}(y) + C_1 &= \frac{x^4}{4} + C_2 \\
\tan^{-1}(y) &= \frac{x^4}{4} + C_2 - C_1 \\
\tan^{-1}(y) &= \frac{x^4}{4} + C \\
y &= \tan\left(\frac{x^4}{4} + C\right)
\end{aligned}$$

2.2.3 – Example

Problem 12 from the textbook.

$$\sin(3x)dx + 2y\cos^3(3x)dy = 0$$

$$\begin{aligned}
\int -2ydy &= \int \frac{\sin(3x)}{\cos^3(x)}dx \\
&= \int \tan(3x)\sec^2(3x)dx \\
&= \int u\ \frac{1}{3}du \text{ where } u = \tan(3x),\ du = 3\sec^2(3x)dx \\
-2\int ydy &= \frac{1}{3}\int u\ du + C \\
-y^2 &= \frac{u^2}{6} + C \\
&= \frac{\tan^2(3x)}{6} + C
\end{aligned}$$

$$\begin{aligned}
\frac{\tan^2(3x)}{6} + y^2 &= -C \\
\frac{\tan^2(3x)}{6} + y^2 &= C
\end{aligned}$$

Problem 25 from the textbook.

$$x^2\frac{dy}{dx} = y - xy, y(-1) = -1$$

$$\begin{aligned}
x^2\frac{dy}{dx} &= y - xy \\
x^2\frac{dy}{dx} &= y(1-x) \\
\frac{dy}{y} &= \frac{(1-x)}{x^2}dx \\
\int \frac{dy}{y} &= \int \frac{(1-x)}{x^2}dx \\
\int \frac{dy}{y} &= \int \frac{1}{x^2}dx - \int \frac{x}{x^2}dx \\
\int \frac{dy}{y} &= \int \frac{1}{x^2}dx - \int \frac{1}{x}dx \\
\ln|y| + C_1 &= -\frac{1}{x} + C_2 - \ln|x| + C_3 \\
\ln|y| &= -\frac{1}{x} - \ln|x| + C \\
y &= e^{-\frac{1}{x}} \times e^{-\ln|x|} \times e^C \\
y &= e^{-\frac{1}{x}} \times e^{-\ln|x|} \times e^C \\
y &= e^{-\frac{1}{x}} \times \frac{1}{|x|} \times e^C \\
y &= \frac{1}{|x|}e^{C-\frac{1}{x}} \\
-1 &= \frac{1}{|-1|}e^{C-\frac{1}{-1}} \\
-1 &= \frac{1}{1}e^{C-(-1)} \\
-1 &= e^{C+1}
\end{aligned}$$

2.3 First Order Linear Differential Equations

$$\begin{aligned}
a_1(x)\frac{dy}{dx} + a_0(x)y &= g(x) \\
\frac{dy}{dx} + \frac{a_0(x)}{a_1(x)}y &= \frac{g(x)}{a_1(x)}
\end{aligned}$$

$$\left.\frac{dy}{dx} + P(x)y = f(x)\right\} \text{ Standard form of a 1st-order linear DE}$$

We will try to find a function $\mu(x)$ such that by multiplying the D.E. by an integrating factor (I.F.) $\mu(x)$:

$$\mu(x)\frac{dy}{dx} + \mu(x)P(x)y = \mu(x)f(x)$$

such that the LHS is an exact derivative, Observe:

$$\frac{d}{dx}\left(\mu(x)y\right) = \mu(x)\frac{dy}{dx} + \frac{dy}{dx}y$$

from which we see

$$\begin{aligned}
\mu(x)P(x) &= \frac{d\mu}{dx} \\
P(x)dx &= \frac{d\mu}{\mu(x)} \\
\int P(x)dx &= \int \frac{d\mu}{\mu} \\
\int P(x)dx &= \ln\mu \\
\ln\mu &= \int P(x)dx \\
\mu &= e^{\int P(x)dx}
\end{aligned}$$

2.3.1 – Example

$$\begin{aligned}
x\frac{dy}{dx} - 4y &= x^6e^x \\
\text{Standard form: } \frac{dy}{dx} - \frac{4}{x}y &= x^5e^x \\
P(x) &= -\frac{4}{x} \\
\mu &= e^{\int \frac{-4}{x}dx} \\
&= e^{-4\ln x} \\
&= e^{\ln x^{-4}} \\
&= x^{-4} \\
\text{I.F.} = \mu &= x^{-4}
\end{aligned}$$

Now multiply the standard form of the given D.E. by x^{-4}.

$$\begin{aligned}
x^{-4}\frac{dy}{dx} - x^{-4}\frac{4}{x}y &= x^{-4}x^5e^x \\
x^{-4}\frac{dy}{dx} - x^{-4}\frac{4}{x}y &= xe^x \\
\int \frac{d}{dx}\left(x^{-4}y\right) &= \int xe^x \\
x^{-4}y &= \int xe^x
\end{aligned}$$

2.3.2 – Example

$$\left(x^2-9\right)\frac{dy}{dx}+xy=0$$

$$\begin{aligned}
\left(x^2-9\right)\frac{dy}{dx}+xy&=0\\
\frac{dy}{dx}+\frac{x}{x^2-9}y&=0\\
P(x)&=\frac{x}{x^2-9}\\
\int P(x)dx&=\int\frac{x}{x^2-9}dx\\
\int P(x)dx&=\int\frac{1}{u-9}\frac{du}{2}\\
\int P(x)dx&=\frac{1}{2}\int\frac{1}{u-9}du\\
\int P(x)dx&=\frac{1}{2}\ln|u-9|\\
\int P(x)dx&=\frac{1}{2}\ln\left|x^2-9\right|\\
\mu&=e^{\frac{1}{2}\ln|x^2-9|}\\
\mu&=e^{\ln\left|\left(x^2-9\right)^{\frac{1}{2}}\right|}\\
\mu&=\left(x^2-9\right)^{\frac{1}{2}}\\
\mu&=\sqrt{x^2-9}\\
\sqrt{x^2-9}\left(\frac{dy}{dx}+\frac{x}{x^2-9}y\right)&=\sqrt{x^2-9}(0)\\
\sqrt{x^2-9}\frac{dy}{dx}+\frac{x}{\sqrt{x^2-9}}y&=0\\
\int\frac{d}{dx}\left(y\sqrt{x^2-9}\right)&=\int 0\\
y\sqrt{x^2-9}&=C\\
y&=\frac{C}{\sqrt{x^2-9}}
\end{aligned}$$

2.4 Exact Equations

1st Order D.E. in differential form

$$M(x,y)dx+N(x,y)dy=0$$

Given a function

$$z=f(x,y)$$

, the total differential, dz, is defined as

$$dx = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

2.4.1 – Method

See if whe can find a function $f(x, y)$ such that

$$\frac{\partial f}{\partial x} = M, \frac{\partial f}{\partial y} = N$$

If we can do this, then the D.E. is equivalent to

$$df = 0 \Rightarrow f(x, y) = c$$

is an implicit solution of D.E.Assume that M and N have continuous 1st order partials (assuming f exists)

$$\left.\begin{array}{lll} My & = \frac{\partial}{\partial y}\frac{\partial f}{\partial x} dy = & f_{xy} \\ Nx & = \frac{\partial}{\partial x}\frac{\partial f}{\partial Y} dy = & f_{yx} \end{array}\right\} \text{Theorem tells use these are equal}$$

This provides a quick test to check if the D.E. is exact or not.

2.4.2 – Example

$$2xydx + \left(x^2 - 1\right) dy = 0$$
$$M(x, y) = 2xyN(x, y) = x^2 - 1$$

To check if the D.E. is exact

$$M_y = 2x = N_x$$

We now know there exists a function $f(x, y)$ with

$$\begin{array}{ll} \frac{\partial f}{\partial x} = M = & 2xy \\ \frac{\partial f}{\partial y} = N = & x^2 - 1 \end{array}$$

$$
\begin{aligned}
f_M(x,y) &= \int \frac{\partial f}{\partial x} dx \\
&= \int 2xy dx \\
&= x^2y + \phi(y) \\
\frac{\partial f}{\partial y}\left(x^2y+\phi(y)\right) &= x^2 - 1 \text{ required to equal } N \\
x^2 + \phi'(y) &= x^2 - 1 \\
\phi'(y) &= -1 \\
\phi(y) &= \int -1 dy \\
&= -y \\
f(x,y) &= x^2y - y \\
d\left(f(x,y)\right) &= 0 \\
f(x,y) &= c \\
x^2y - y &= c \text{ is an implicit solution of the D.E.}
\end{aligned}
$$

Note: the f_M format is just there to show which partial equation was integrated. It was made by me and, as far as I know, not standardly known.

2.4.3 – Example

$$
\begin{aligned}
\left(e^{2y} - y\cos(xy)\right)dx + (2xe^{2y} - x\cos(xy) + 2y)dy &= 0 \\
M_y &= N_x \\
\frac{\partial}{\partial y}\left(e^{2y} - y\cos(xy)\right) &= \frac{\partial}{\partial x}\left(2xe^{2y} - x\cos(xy) + 2y\right) \\
2e^{2y} - [\cos(xy) - y\sin(xy)\times x] &= 2e^{2y} - (\cos(xy) - x\sin(xy)\times y) + 0 \\
2e^{2y} - \cos(xy) + xy\sin(xy) &= 2e^{2y} - \cos(xy) + xy\sin(xy)
\end{aligned}
$$

$$
\begin{aligned}
\frac{\partial f}{\partial x} &= M = e^{2y} - y\cos(xy) \\
\frac{\partial f}{\partial y} &= N = 2xe^{2y} - x\cos(xy) + 2y \\
f_N(x,y) &= \int \frac{\partial f}{\partial y} dy \\
&= \int \left(2xe^{2y} - x\cos(xy) + 2y\right) dy \\
&= \frac{2xe^{2y}}{2} - \frac{x\sin(xy)}{x} + 2\times\frac{y^2}{2} + \phi(x) \\
&= xe^{2y} - \sin(xy) + y^2 + \phi(x)
\end{aligned}
$$

Take the ∂x of this and equate with M:

$$\begin{aligned} M &= \frac{\partial}{\partial x}\left(xe^{2y} - \sin(xy) + y^2 + \phi(x)\right) \\ e^{2y} - y\cos(xy) &= e^{2y} - y\cos(xy) + 0 + \phi'(x) \\ 0 &= \phi'(x) \\ \phi(x) &= c \end{aligned}$$

So $f(x, y) = c_2$ is the solution

$$xe^{2y} - \sin(xy) + y^2 = c$$

$$dx = \frac{\partial z}{\partial x}dx + \frac{\partial z}{\partial y}dy$$

2.4.4 – What can you do if $M_y \neq N_x$

Sometimes you can multiply the DE by an integrating factor $\mu(x, y)$ to get an exact DE.If

$$\frac{M_y - N_x}{N}$$

is a function of only x, then

$$\mu = e^{\int \frac{M_y - N_x}{N}dx}$$

will be an I.F.
If

$$\frac{N_x - M_y}{M}$$

is a function of only y, then

$$\mu = e^{\int \frac{N_x - M_y}{M}dy}$$

will be an I.F.

2.4.5 – Example

$$xydx + \left(2x^2 + 3y^2 - 20\right)dy = 0$$

$$\begin{aligned} M_y &= x \\ N_x &= 4x \\ M_y &\neq N_x \frac{N_x - M_y}{M} & &= \frac{4x - x}{xy} \\ &= \frac{3x}{xy} \\ &= \frac{3}{y} \text{ is a function of just } y \end{aligned}$$

So:

$$\begin{aligned} \mu &= e^{\int \frac{3}{y} dy} \\ &= e^{3\ln y} \\ &= y^3 \\ xy^4 dx + y^3\left(2x^2 + 3y^2 - 20\right) dy &= 0(y^3) \\ xy^4 dx + \left(2x^2y^3 + 3y^5 - 20y^3\right) dy &= \\ M_y &= N_x \\ 4xy^3 &= 4xy^3 \frac{\partial f}{\partial x} \end{aligned}$$

2.5 Substitution Methods

Taking a D.E. that's not:

- Separable
- 1st Order Linear
- Exact

and making a substitution to turn the new D.E. into one of these**Theorem:** Given a D.E.

$$M(x,y)dx + N(x,y)dy = 0$$

A function $f(x,y)$ is said to be homogenous of order α if $f(tx,ty) = t^\alpha f(x,y)$.

2.5.1 – Example

Given:

$$f(x,y) = x^3 + 5xy^2 - y^3$$

Then:

$$\begin{aligned} f(tx,ty) &= (tx)^3 + 5(tx)(ty)^2 - (ty)^3 \\ &= t^3x^3 + 5t^3xy^2 - t^3y^3 \\ &= t^3\left(x^3 + 5xy^2 - y^3\right) \\ &= t^3 f(x,y) \end{aligned}$$

2.5.2 – Example

$$
\begin{aligned}
f(x,y) &= \frac{x+y}{x^2+y^2} \\
f(tx,ty) &= \frac{tx+ty}{(tx)^2+(ty)^2} \\
f(tx,ty) &= \frac{tx+ty}{x^2t^2+y^2t^2} \\
f(tx,ty) &= \frac{t}{t^2} \times \frac{x+y}{x^2+y^2} \\
f(tx,ty) &= \frac{t}{t^2} f(x,y) \\
f(tx,ty) &= \frac{1}{t} f(x,y)
\end{aligned}
$$

$f(x,y) = \frac{x+y}{x^2+y^2}$ is homogenous of order $\alpha = -1$

2.5.3 – Substitution Rule

If $M(x,y)$ and $N(x,y)$ are homogenous, each of the same order, then $u = \frac{y}{x}$ i.e., $y = ux$ or $v = \frac{x}{y}$ (i.e. $x = vy$) will produce a separable D.E.

2.5.4 – Example

Solve the separable D.E. and then back-substitute

$$(x^2+y^2)dx + (x^2 - xy)dy = 0$$

$$\begin{aligned}
M(x,y) &= x^2+y^2 \quad N = x^2-xy \\
M_y &= 2y \quad N_x = 2x-y \\
M_y &\neq N_x \\
M(tx,ty) &= (tx)^2+(ty)^2 \\
&= t^2x^2+t^2y^2 \\
&= t^2(x^2+y^2) \\
&= t^2M(x,y) \text{ } M \text{ is homogeneous of order 2 and so is } N \\
u &= \frac{y}{x} \\
y &= ux \\
dy &= udx+xdu \\
(x^2+(ux)^2)dx+(x^2-x(ux))(udx+xdu) &= 0 \\
(x^2+u^2x^2)dx+(x^2-ux^2)(udx+xdu) &= 0 \\
(1+u^2)x^2dx+x^2(1-u)(udx+xdu) &= 0 \\
(1+u^2)x^2dx+x^2\left(udx+xdu-u^2dx-uxdu\right) &= 0 \\
x^2\left(1dx+u^2dx+udx+xdu-u^2dx-uxdu\right) &= 0 \\
x^2\left(1dx+u^2dx-u^2dx+udx+xdu-uxdu\right) &= 0 \\
x^2\left(1dx+udx+xdu-uxdu\right) &= 0 \\
x^2(1+u)dx+x^3(1-u)du &= 0 \\
\int \frac{1}{x}dx &= \int -\frac{1-u}{1+u}du \\
&= \int \frac{u-1}{u+1}du \\
&= \int \frac{u+(1-2)}{u+1}du \\
&= \int \left(\frac{u+1}{u+1}-\frac{2}{u+1}\right)du \\
&= \int \left(1-\frac{2}{u+1}\right)du \\
\ln|x| &= \int \left(1-\frac{2}{u+1}\right)du \\
&= u-2\ln|u+1|+C \\
\ln|x| &= \frac{y}{x}-2\ln\left|\frac{y}{x}+1\right|+C
\end{aligned}$$

Theorem: An equation of the form

$$\frac{dy}{dx}+P(x)y=f(x)y^n$$

where $n \neq 0,1$ is called a Bernoulli Equation. The substitution

$$u=y^{1-n}$$

will transform the D.E. into a 1st order linear.

2.5.5 – Example

$$x\frac{dy}{dx} + y = x^2y^2$$
$$\frac{dy}{dx} + \frac{y}{x} = xy^2$$

is a Bernoulli equation with $n = 2$.

$$
\begin{aligned}
u &= y^{1-2} \\
&= y^{-1} \\
&= \frac{1}{y} \\
\frac{du}{dx} &= \frac{du}{dy} \times \frac{dy}{dx} \\
&= -1y^{-2}\frac{dy}{dx} \\
&= -\frac{1}{y^2}\frac{dy}{dx} \\
-y^{-2}\frac{dy}{dx} + -y^{-2} \times \frac{y}{x} &= -y^{-2} \times xy^2 \\
-y^{-2}\frac{dy}{dx} + -\frac{1}{x}y^{-1} &= -x \\
\frac{du}{dx} - \frac{1}{x}u = -x & \\
\text{I.F.} = \mu &= e^{P(x)dx} \\
&= e^{-\int \frac{1}{x}dx} \\
&= e^{-\ln|x|} \\
&= e^{\ln|x^{-1}|} \\
&= x^{-1} \\
\frac{1}{x}\frac{du}{dx} - \frac{1}{x^2}u &= -1 \\
\frac{d}{dx}\left(\frac{1}{x}u\right) &= -1 \\
\int \frac{d}{dx}\left(\frac{1}{x}u\right) &= \int -1dx \\
\frac{1}{x}u &= \int -1dx \\
\frac{1}{x}u &= -x + C \\
\frac{1}{x} \times 1y &= -x + C \\
\frac{1}{x(-x+C)} &= y \\
y &= \frac{1}{Cx - x^2}
\end{aligned}
$$

Theorem: If the D.E. can be expressed as

$$\frac{dy}{dx} = f(Ax + by + C)$$

for particular numbers A, B, C, then let

$$u = Ax + By + C$$

to get a separable D.E.

2.5.6 – Example

$$\frac{dy}{dx} = (-2x + y)^2 - 7, y(0) = 0$$

$$\begin{aligned}
u &= -2x + y \\
\frac{du}{dx} &= \frac{dy}{dx} \times \frac{du}{dy} \\
&= -2 + \frac{dy}{dx} \\
\frac{du}{dx} + 2 &= \frac{dy}{dx} \\
\frac{du}{dx} + 2 &= u^2 - 7 \\
\frac{du}{dx} &= u^2 - 9 \\
\frac{du}{u^2 - 9} &= dx \\
\int \frac{du}{u^2 - 9} &= \int dx \\
\int \frac{du}{(u+3)(u+9)} &= x + C \\
\int \frac{du}{(u+3)(u+9)} &= x + C
\end{aligned}$$

Chapter 3

Modeling using DE

3.1 Linear DE Modeling

3.1.1 – Standard Problems

1) Population Growth (or decline)
2) Radioactive Decay
3) Newton's Law of Cooling
4) Mixture Problems

3.1.2 – Population Model

Assume the rate of population change is proportional to the size of the population

$$P(t) = \text{ population at time } t$$

$$\frac{dP}{dt} = kP$$

$$\frac{\frac{dP}{dt}}{P} = k \text{ is the relative growth rate of the population}$$

$$
\begin{aligned}
\frac{dP}{dt} &= kP \\
\frac{dP}{P} &= kdt \\
\int \frac{dP}{P} &= \int kdt \\
ln|P| &= kt + C \\
|P| &= e^{kt+C} \\
|P| &= e^{kt}e^{C} \\
|P| &= Ae^{kt} \text{ where } A > 0 \\
P &= \pm Ae^{kt} \\
P &= Be^{kt} \text{ where } B \neq 0 \\
P &= De^{kt} \text{ where } D \text{ can be any real number}
\end{aligned}
$$

The constant can become any number because 0 would be a valid rate of population change, it means that the population size isn't changing.

3.1.3 – Example

If, initially at 2 p.m., there are 1,000 bacteria on a petri dish and at 4 p.m., there are 2,000 bacteria. Assuming constant relative growth rate, how many bacteria are there at 5 p.m.?

$P(t) =$ population t hours after 2 p.m.

$$
\begin{aligned}
P(t) &= Ae^{kt} \\
1000 &= Ae^{(0)k} \\
1000 &= Ae^{0} \\
1000 &= A(1) \\
A &= 1000 \\
P(2) &= 2000 \\
P(2) &= 1000e^{2k} \\
2000 &= 1000e^{2k} \\
2 &= e^{2k} \\
\ln(2) &= 2k \\
k &= \frac{\ln(2)}{2} \\
P(t) &= 1000e^{\frac{\ln(2)}{2}t} \\
P(3) &= 1000e^{\frac{\ln(2)}{2}(3)} \\
&= 1000e^{1.5\ln(2)} \\
&= 1000e^{\ln(2^{1.5})} \\
&= 1000(2^{1.5}) \\
&= 2000(\sqrt{2}) \\
P(3) &\approx 2828.427(\sqrt{2}) \\
P(t) &= 1000e^{\frac{t}{2}\ln(2)} \\
&= 1000e^{\frac{t}{2}\ln(2)} \\
&= 1000e^{\ln(2^{\frac{t}{2}})} \\
&= 1000 \times 2^{\frac{t}{2}}
\end{aligned}
$$

3.1.4 – Radioactive Decay

$$m(t) = m_0 e^{kt} \text{ where } k < 0$$

The Half-Life is the amount of time it takes for half of the original amount to remain:

$$\frac{1}{2}A_0 = A_0 e^{kt} \Rightarrow \frac{1}{2} = e^{kt}$$

3.1.5 – Mixture Problems

Setup

Initially, the container has 200 gallons of brine solution (salt-water) of concentration $\frac{10 \text{ lbs}}{200 \text{ gallons}} = 0.05\frac{\text{lbs}}{\text{gallon}}$. A solution of $\frac{5 \text{ lbs}}{200 \text{ gallons}} 0.025\frac{\text{lbs}}{\text{gallon}}$ is poured into the initial container at a rate of $\frac{4 \text{ gallons}}{\text{min}}$. How many pounds of salt are there in the container after 2 hours.
Let $y(t) = \#$ lbs of salt t minutes after the precess starts$\frac{dy}{dt}$ = The rate of change of # lbs of salt

$$\begin{aligned}
\frac{dy}{dt} &= \left.0.025\frac{\text{lbs}}{\text{gal}} \times 4\frac{\text{gal}}{\text{min}}\right\}\text{rate in} \\
&\quad \left.- \frac{y(t)\text{lbs}}{200\text{gal}} \times 4\frac{\text{gal}}{\text{min}}\right\}\text{rate out} \\
&= (0.025)4\frac{\text{lbs}}{\text{min}} - \frac{4y(t)}{200}\frac{\text{lbs}}{\text{min}} \\
&= 0.1\frac{\text{lbs}}{\text{min}} - \frac{y(t)}{50}\frac{\text{lbs}}{\text{min}} \\
&= 0.1 - \frac{y(t)}{50} \\
\frac{dy}{dt} + \frac{1}{50}y &= 0.1 \\
\mu &= e^{\int P(t)dt} \\
&= e^{\int \frac{1}{50}dt} \\
&= e^{\frac{t}{50}} \\
e^{\frac{t}{50}}\left(\frac{dy}{dt}\right) + e^{\frac{t}{50}}\left(\frac{1}{50}y\right) &= e^{\frac{t}{50}}(0.1) \\
\frac{d}{dt}\left(e^{\frac{t}{50}}y\right) &= e^{\frac{t}{50}}(0.1) \\
\int \frac{d}{dt}\left(e^{\frac{t}{50}}y\right) &= \int \frac{1}{10}e^{\frac{t}{50}} \\
e^{\frac{t}{50}}y &= \frac{1}{10} \times \frac{e^{\frac{t}{50}}}{\frac{1}{50}} + C \\
e^{\frac{t}{50}}y &= 5e^{\frac{t}{50}} + C \\
y &= 5 + Ce^{-\frac{t}{50}} \\
&= 5 + Ce^{-0.02t} \\
y(120) &= 5 + Ce^{-0.02(120)} \\
&= 5 + Ce^{-2.4}
\end{aligned}$$

Chapter 4

Higher Order Differential Equations

An nth order DE is linear if it had the form

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + a_{n-2}(x)\frac{d^{n-2}y}{dx^{n-2}} + \cdots + a_1(x)\frac{dy}{dx} + a_0y = g(x)$$

Theorem: If all the coefficient functions are continuous and $a_n(x)$ is not 0 on an interval I and $g(x)$ is continuous, then any initial value problem

$$DE + y(x_0) = y_0$$

has a unique solution on the interval I if $g(x) = 0$. i.e.

$$a_n(x)y^{(n)} + \cdots + a_0(x)y = 0$$

then the DE is said to be homogeneous.

4.0.1 – Example

$$y'' - 3y' - 4y = 0$$

Show $y_1 = e^{4x}$ is a solution and $y_2 = e^{-x}$ is a solution.

$$y_1 = e^{4x}$$

$$y_1' = 4e^{4x}$$

$$y_1'' = 16e^{4x}$$

$$\begin{aligned} 16e^{4x} - 3(4e^{4x}) - 4e^{4x} &= 0 \\ 16e^{4x} - 12e^{4x} - 4e^{4x} &= 0 \\ e^{4x}(16 - 12 - 4) &= 0 \\ e^{4x}(0) &= 0 \\ 0 &= 0 \end{aligned}$$

$$y_3 = 6y_1 = 6e^{4x}$$

$$y_3' = 6y_1' = 24e^{4x}$$

$$y_3'' = 6y_1'' = 96e^{4x}$$

$$\begin{aligned}
96e^{4x} - 3(24e^{4x}) - 4(6e^{4x}) &= 0 \\
96e^{4x} - 72e^{4x} - 24e^{4x} &= 0 \\
e^{4x}(96 - 72 - 24) &= 0 \\
e^{4x}(0) &= 0 \\
0 &= 0
\end{aligned}$$

Theorem: Superposition Principle: if $y_1, y_2, \ldots, y_m$ are each solutions of an nth order Linear, homongenous DE, then $c_1y_1 + c_2y_2 + \cdots + c_my_m$ will also be a solution for any constants $c_1, c_2, \ldots, c_m$.
Our goal is to express the general solution in as concise a way as possible.
Linear combination – a colelction of solutions $y_1, y_2, \ldots, y_m$ is linearly independent is if the only way $c_1y_1+c_2y_2+\cdots+c_my_m = 0$ is iff (if and only if) all of the constants $c_1, c_2, \ldots, c_m = 0$. Otherwise we say $y_1, y_2, \ldots, y_m$ are linearly dependent.**Theorem:** If the DE is an nth order Linear Homogeneous equation then there will exist a collection of n linearly independent solutions $y_1, y_2, \ldots, y_n$ and the general solution will be $y_c = c_1y_1 + c_2y_2 + \cdots + c_ny_n$One way to check for linear independence is to compile the Wronskian

$$W(y_1, y_2, \ldots, y_n) = \det \begin{bmatrix} y_1 & y_2 & \cdots & y_n \\ y_1' & y_2' & \cdots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \cdots & y_n^{(n-1)} \end{bmatrix}$$