

# Chapter 1

## Introduction to Differential Equations

### 1.1 Terminology and Notation

**Differential equation (D.E.)** – An equation in which at least one derivative of an unknown function.

**Order of the D.E.** – The highest order of derivative in the D.E.

#### 1.1.1 – Example

$$4y'' + e^x y' - 3yy' = \sin(x)$$

An example of a partial differential equation is:

$$\frac{\partial T}{\partial x} + x^2 \frac{\partial T}{\partial y} = x + y$$

however, we won't study these in this course.

#### 1.1.2 – Linear vs Non-Linear DE's

**Linear D.E.** – The dependent variable and all of its derivatives in the D.E. are in separate terms to the 1<sup>st</sup> power.  $y^{(n)}$  or  $\frac{d^n y}{dx^n}$  where  $n \neq 1$  are non-first power.

$$4y'' + e^x y' - 3yy' = \sin(x)$$

is a non-linear D.E. while

$$4y'' + e^x y' - 3y = \sin(x)$$

is linear.

The general formula of a linear D.E. would look like

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = g(x)$$

**Solution** – a function  $\phi(x)$  and an interval  $I$  for which the D.E. is satisfied when  $y = \phi(x)$  for all  $x$  in  $I$ .

It may be the case that the natural domain of  $\phi(x)$  is larger than  $I$ .

### 1.1.3 – Example

$y' = -\frac{1}{x^2}$  has a solution  $\phi(x) = \frac{1}{x}$  on  $I = (0, \infty)$  but the domain of  $\phi(x) = (-\infty, 0) \cup (0, \infty)$ .

Practice:

$$\frac{d^2x}{dt^2} + 16x = 0$$

Show (*Verify* not derive)  $x(t) = c_1 \sin(4t)$  is a solution on  $(-\infty, \infty)$  where  $c$  is any real parameter.

$$\begin{aligned} x &= c_1 \sin(4t) \\ \frac{dx}{dt} &= 4c_1 \cos(4t) \\ \frac{d^2x}{dt^2} &= -16c_1 \sin(4t) \\ \text{LHS} &= \frac{d^2x}{dt^2} + 16x \\ &= -16c_1 \sin(4t) + 16(c_1 \sin(4t)) \\ &= 0 = \text{RHS} \end{aligned}$$

But the equation  $x = c_2 \cos(4t)$  would also be a solution. If you have 2 equations that are both solutions, you could add them together and you would still have a solution.  $x = c_1 \sin(4t) + c_2 \cos(4t)$  is a solution for all parameters  $c_1$  and  $c_2$ . *In fact, this is the general solution to the D.E.*

The D.E.

$$\frac{dy}{dx} = xy^{\frac{1}{2}}$$

Show  $y = \left(\frac{1}{4}x^2 + C\right)^2$  is a one parameter family of solutions

$$\begin{aligned} \text{LHS} &= \frac{dy}{dx} = 2 \left( \frac{1}{4}x^2 + C \right) \times \frac{1}{2}x \\ &= x \left( \frac{1}{4}x^2 + C \right) \\ \text{RHS} &= xy^{\frac{1}{2}} = x \left( \left( \frac{1}{4}x^2 + C \right)^2 \right)^{\frac{1}{2}} \\ &= x \left( \frac{1}{4}x^2 + C \right) \\ \text{LHS} &= \text{RHS} \end{aligned}$$

But there is another solution: namely  $y(x) = 0$  for all  $x$ . This is called the “trivial solution”.