Contents

Find conservation laws, if possible. i.e. combination of variables that are constant in time. One method: Combine ODE's so

$$\frac{d}{dt}(+\dots+) = 0$$
$$+\dots+ = \text{constant}$$

$$\begin{cases}
\frac{dA}{dt} = -k_1 A x, & A(0) = A_0 \\
\frac{dx}{dt} = -k_1 A x - k_2 z x & x(0) = x_0 \\
\frac{dz}{dt} = k_1 A x - k_2 x z & z(0) = 0 \\
\frac{dp}{dt} = k_2 x z & p(0) = 0
\end{cases}$$
(1)

$$\frac{dA}{dt} + \frac{dp}{dt} + \frac{dz}{dt} = \frac{d}{dt}(A + P + Z)$$

$$= 0A(t) + P(t) + Z(t) = \text{constant for all time}$$

What is the constant? Set t = 0, $A(0) = A_0$, z(0) = 0, p(0) = 0:

$$A(t) + P(t) + Z(t) = A_0$$

 $P(t) = A_0 - A(t) - Z(t)$

Eliminate P from (??)

$$\begin{cases}
\frac{dA}{dt} = -k_1 A x, & A(0) = A_0 \\
\frac{dx}{dt} = -k_1 A x - k_2 z x & x(0) = x_0 \\
\frac{dz}{dt} = k_1 A x - k_2 x z & z(0) = 0
\end{cases}$$
(2)

Look for other conservation laws

$$\frac{d}{dt}(2A - x + z) = 0$$

$$2A(t) - x(t) + z(t) = \text{constant for all time}$$

$$2A(t) - x(t) + z(t) = 2A_0 - x_0$$

$$x(t) = 2A(t) + z(t) - 2A_0 + x_0$$

2 equations and 2 unknowns

Example 1 Simple reaction modeling

Reversible conformational change 1st order

$$\begin{cases} \frac{dA}{dt} = -k_1 A + k_{-1} B, & A(0) = A_0\\ \frac{dB}{dt} = k_1 B - k_{-1} B, & B(0) = B_0 \end{cases}$$
 (3)

What to do? By luck, first order reactions have linear systems with constant coefficients:

$$\frac{d}{dt}\left(\left[\begin{array}{c}A\\B\end{array}\right]\right) = M\left[\begin{array}{c}A\\B\end{array}\right]$$

Assume: $\begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{\lambda t}$ which leads to the eigenvalue problem

$$0 = \begin{vmatrix} -k_1 - \lambda & k_{-1} \\ k_1 & -k_{-1} - \lambda \end{vmatrix}$$
$$= (-k_1 - \lambda)(-k_{-1} - \lambda) - (k_{-1})(k_1)$$
$$\lambda_1 = 0 \qquad \lambda_2 = -(k_1 + k_{-1})$$

If reactions are more complicated (nonlinear systems): find conservative laws

Example 2 Dimerization of 2 monomers

Kinetic equations:

$$\frac{dA}{dt} = -2k_1A^2 + 2k_{-1}C \qquad A(0) = A_0
\frac{dC}{dt} = -k_{-1}C + k_1A^2 \qquad C(0) = 0$$
(4)

Given $[A] = \frac{M}{L^3}$, $[C] = \frac{M}{L^3}$, $[A_0] = \frac{M}{L^3}$, [t] = T: find k:

$$\left[\frac{dA}{dt} \right] = \left[-2k_1 A^2 \right] + \left[2k_{-1}C \right]
 \frac{ML^{-3}}{T} = \left[k_1 \right] \left[A^2 \right] + \left[k_{-1} \right] \left[C \right]
 \frac{ML}{L^3 T} = \left[k_1 \right] \left(\frac{M}{L^3} \right)^2 + \left[k_{-1} \right] \left(\frac{M}{L^3} \right)^2
 \frac{ML}{L^3 T} = \left[k_1 \right] \frac{M^2}{L^6} + \left[k_{-1} \right] \frac{M^2}{L^6}
 \frac{ML}{L^3 T} = \left[k_1 \right] \frac{M^2}{L^6} \qquad \frac{ML}{L^3 T} = \left[k_{-1} \right] \frac{M^2}{L^6}
 A = f(t, k_1, k_{-1}, A_0) \qquad C = g(t, k_1, k_{-1}, A_0)$$

$$[A] = [t]^{a} [k_{1}]^{b} [k_{-1}]^{c} [A_{0}]^{d}$$

$$\frac{M}{L^{3}} = T^{a} (L^{3} M^{-1} T^{-1})^{b} T^{-1c} (M L^{-3})^{d}$$

$$M L^{-3} = T^{a} L^{3b} M^{-b} T^{-b} T^{-c} M^{d} L^{-3d}$$

$$M^{1} L^{-3} T^{0} = M^{-b+d} L^{3b-3d} T^{a-b-c}$$

$$\begin{bmatrix} 1 & -1 & -1 & 0 \\ 0 & 3 & 0 & -3 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

$$\frac{dA}{dt} + 2 \frac{dC}{dt} = 0$$

$$A(t) + 2C(t) = A_{0} + 0$$

Leonor Michaelis - Maud Menton Kinetics

MM Kinetics – rate is used frequently instead of 1st order kx terms. Where does it come from?

Prototype in biological setting. How do bacteria consume organic substances (e.g. glucose)?

$$c + x_0 \stackrel{\longleftarrow}{\longrightarrow}_{k_1}^{k_{-1}} x_1$$
$$x_1 \stackrel{\longrightarrow}{\longrightarrow}^{k_2} p + x_0$$