## CS 170 Project Algorithm

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## 1 QIP

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Algorithm 1: Quadratic Integer program for Graph Partitioning with Dynamic Constraints
  Input: i, j, h_{i,j}, s_{i,j} \forall i, j, R, S_{max}
  Output: \{\text{room}_r : [\text{people} \in \text{room}_r]\}
  Initialization:
  \begin{array}{l} e_{i,j_k} \leftarrow \{0,1\}, \ \forall i,j \ \& \ k = \{1,\dots K\} \\ v_{i_k} \leftarrow \{0,1\}, \ \forall i \ \& \ k = \{1,\dots K\} \end{array}
  placements \leftarrow []
  output \leftarrow \{\}
  Objective:
  \max \{e_{i,j_k}*h_{i,j}\}, \ \forall i,j \ \& \ k=\{1,\dots K\}
  Constraints:
  placements \leftarrow split(v_i's, k), \ k = \{1, \dots K\}
  for k in range(K) do
       temp = [];
       \textbf{for } \textit{i in } \textit{range}(N) \textbf{ do}
            if placement[i][k] > 0 then
                  temp = [i];
                  output[k] = temp;
                 return output
            end
       end
  end
```

## 2 ILP

## Algorithm 2: Integer Linear program for Graph Partitioning with Dynamic Constraints

```
Input: i, j, h_{i,j}, s_{i,j} \forall i, j, K, S_{max}
Output: \{\text{room}_r : [\text{people} \in \text{room}_r]\}
Initialization:
e_{i,j_k} \leftarrow \{0,1\}, \ \forall i,j \ \& \ k = \{1,\dots K\}
v_{i_k} \leftarrow \{0,1\}, \ \forall i \ \& \ k = \{1, \dots K\}
placements \leftarrow []
output \leftarrow \{\}
Objective:
\max\{e_{i,j_k} * h_{i,j}\}, \ \forall i,j \ \& \ k = \{1, \dots K\}
Constraints:
\sum_{k=1}^{K} e_{i,j_k} = 1, \ \forall i, j
\sum_{(i,j)} e_{i,j_k} \leq \frac{S_{max}}{K}, \ k = \{1, \dots K\}
e_{i,j_k} \leq v_{i_k} \ \forall i \ \& \ k = \{1, \dots K\}
e_{i,j_k} \leq v_{j_k} \ \forall i \ \& \ k = \{1, \dots K\}
e_{i,j_k} \ge v_{i_k} + v_{j_k} - 1 \ \forall i,j \ \& \ k = \{1, \dots K\}
placements \leftarrow split(v_i's, k), \ k = \{1, ... K\}
for k in range(K) do
      temp = [];
      for i in range(N) do
             if placement[i][k] > 0 then
                   temp = [i];
                    output[k] = temp;
                   return output
             end
      end
end
```