

# 19-3 React Lanes 模型常用工具函数

## 基本运算函数

```
JavaScript
// 是否是transitionLanes
export function isTransitionLane(lane: Lane): boolean {
 return (lane & TransitionLanes) !== NoLanes;
}
// 获取优先级最高的lane
// 因为在 lane 的值中,值越小,代表的优先级越高。即
// 获取最低位的1,如4194240&-4194240就是64
// 负数原码转换为补码的方法:符号位保持1不变,数值位按位求反,末位加1
export function getHighestPriorityLane(lanes: Lanes): Lane {
 return lanes & -lanes;
// 是否包含某个lane或者某些lane(lanes)
export function includesSomeLane(a: Lanes | Lane, b: Lanes | Lane): bo
 return (a & b) !== NoLanes;
}
// set是否包含subset,和 includesSomeLane 不同,includesSomeLane检查的是a和
```

```
// 而这里的 isSubsetOfLanes 检查的是 subset 是否是 set 的子集
export function isSubsetOfLanes(set: Lanes, subset: Lanes | Lane): boo
  return (set & subset) === subset;
// 合并两个lane或者lanes
export function mergeLanes(a: Lanes | Lane, b: Lanes | Lane): Lanes {
 return a | b;
}
// 移除某个lane或者lanes,比如执行完节点的 Update 操作之后,则需要移动 fiber.fi
export function removeLanes(set: Lanes, subset: Lanes | Lane): Lanes {
 return set & ~subset;
// 与 includesSomeLane 不同, includesSomeLane返回的是是否有交叉,即结果是boo
// intersectLanes 返回交叉的lanes
export function intersectLanes(a: Lanes | Lane, b: Lanes | Lane): Lane
 return a & b;
}
// 返回优先级较高的lane。如果 a < b, 则说明a的优先级高于b, 因为lane越小, 优先级是
export function higherPriorityLane(a: Lane, b: Lane): Lane {
 return a !== NoLane && a < b ? a : b;
}
// 其实就是返回比特位上最右边1的位置下标,(从左边往右边数,从0开始)
// 这个常函数用在获取一个lanes上优先级最高的lane,如这里返回值为index,那么1<<ir
function pickArbitraryLaneIndex(lanes: Lanes) {
  return 31 - clz32(lanes);
}
// 返回比特位上最右边1的位置下标,(从左边往右边数,从0开始)
function laneToIndex(lane: Lane) {
 return pickArbitraryLaneIndex(lane);
}
```

## 检查饿死现象

#### FiberRoot

FiberRoot 上有个属性值 expirationTimes ,用于记录的过期时间,其值类型定义:

```
avaScript
export type LaneMap<T> = Array<T>;
expirationTimes: LaneMap<number>, •
```

#### 初始化的时候:

```
DebugReact > src > react > packages > react-reconciler > src > JS ReactFiberRoot.js
       function FiberRootNode(
 48
 49
         this: $FlowFixMe,
 50
         containerInfo: any,
 51
         // $FlowFixMe[missing-local-annot]
 52
         tag,
         hydrate: any,
 53
 54
         identifierPrefix: any,
        onRecoverableError: any,
 55
         formState: ReactFormState<any, any> | null,
 56
 57
       ) {
 58
        this.tag = tag;
 59
         this.containerInfo = containerInfo;
 60
        this.pendingChildren = null;
        this.current = null;
 61
        this.pingCache = null;
 62
 63
        this.finishedWork = null;
        this.timeoutHandle = noTimeout;
 64
        this.cancelPendingCommit = null;
 65
 66
        this.context = null;
         this.pendingContext = null;
 67
        this.next = null;
 68
 69
         this.callbackNode = null:
       Pthis.callbackPriority = NoLane:
 70
 71
         this.expirationTimes = createLaneMap(NoTimestamp);
```

#### 初始化函数:

react/packages/react-reconciler/src/ReactFiberLane.js

JavaScript

```
export const NoTimestamp = -1;

export function createLaneMap<T>(initial: T): LaneMap<T> {
    // Intentionally pushing one by one.
    // https://v8.dev/blog/elements-kinds#avoid-creating-holes
    const laneMap = [];
    for (let i = 0; i < TotalLanes; i++) {
        laneMap.push(initial);
    }
    return laneMap;
}</pre>
```

### markStarvedLanesAsExpired

这个函数在调度更新的过程中会被调用。

react/packages/react-reconciler/src/ReactFiberRootScheduler.js

```
DebugReact > src > react > packages > react-reconciler > src > J5 ReactFiberRootScheduler.js > 分 scheduleTaskForRootDuringMicrotask
     function scheduleTaskForRootDuringMicrotask(
      root: FiberRoot,
324
      currentTime: number,
325
      ): Lane {
326 // 这个函数总是在microtask中被调用,或者在渲染任务的最后,在我们将控制权交还给主线程之前被调用。它绝对不应该被同步调用
327
       // This function is always called inside a microtask, or at the very end of a
328
       // rendering task right before we yield to the main thread. It should never be
       // called synchronously.
329
330
331
       // TODO: Unless enableDeferRootSchedulingToMicrotask is off. We need to land
332
       // that ASAP to unblock additional features we have planned.
333
334
       // This function also never performs React work synchronously; it should
335
       // only schedule work to be performed later, in a separate task or microtask.
336
337
       // Check if any lanes are being starved by other work. If so, mark them as
338
        // expired so we know to work on those next.
       // 检查是否有任何lanes被其他work饿死。如果是,将它们标记为过期,这样我们就知道下一个要处理的是它们。
339
340
       markStarvedLanesAsExpired(root, currentlime);
```

用处就是检查是否有 lanes 挨饿,如果有,则标记他们过期,以便下次执行。

```
port function markStarvedLanesAsExpired(
  root: FiberRoot,
  currentTime: number,
): void {
  const pendingLanes = root.pendingLanes;
  const suspendedLanes = root.suspendedLanes;
```

```
const pingedLanes = root.pingedLanes;
 const expirationTimes = root.expirationTimes;
 // 遍历pending lanes,并检查是否已经达到它们的过期时间。
 // 如果是,我们就认为这个update挨饿了,并将其标记为已过期,以强制其完成。
 let lanes = enableRetryLaneExpiration
   ? pendingLanes // ? sy
   : pendingLanes & ∼RetryLanes;
 while (lanes > 0) {
   // 下面两行代码的作用是找到Lanes中最低位的1,即优先级最
   const index = pickArbitraryLaneIndex(lanes);
   // 把1左移index位,即得到一个只有第index位为1的子掩码
   const lane = 1 << index;</pre>
   const expirationTime = expirationTimes[index];
   if (expirationTime === NoTimestamp) {
     // 如果这个 pending lane 没有过期时间
     // 如果它没有被挂起且需要更新,我们就认为它是CPU密集型操作。
     // 用当前时间计算出一个新的过期时间给它。
     // CPU bound / IO Bound
     if (
       (lane & suspendedLanes) === NoLanes
       (lane & pingedLanes) !== NoLanes
     ) {
      // 假设timestamps(时间戳)是单调递增的
       expirationTimes[index] = computeExpirationTime(lane, currentTi
     }
   } else if (expirationTime <= currentTime) {</pre>
     // 这个 pending lane 已经过期了
     root.expiredLanes |= lane;
   }
   // 把lane从lanes中移除,计算下一个lane
   lanes &= ~lane;
 }
}
```

### 通过 Lane 计算过期时间

策略和 scheduler 相同,根据优先级判断过期时间,优先级越大,值越小。 react/packages/react-reconciler/src/ReactFiberLane.js

```
JavaScript
function computeExpirationTime(lane: Lane, currentTime: number) {
  switch (lane) {
    case SyncHydrationLane:
    case SyncLane:
    case InputContinuousHydrationLane:
    case InputContinuousLane:
      // 交互行为应该早点被执行,因此过期时间会比较小
      return currentTime + syncLaneExpirationMs; // + 250;
    case DefaultHvdrationLane:
    case DefaultLane:
    case TransitionHydrationLane:
    case TransitionLane1:
    case TransitionLane2:
    case TransitionLane3:
    case TransitionLane4:
    case TransitionLane5:
    case TransitionLane6:
    case TransitionLane7:
    case TransitionLane8:
    case TransitionLane9:
    case TransitionLane10:
    case TransitionLane11:
    case TransitionLane12:
    case TransitionLane13:
    case TransitionLane14:
    case TransitionLane15:
      return currentTime + transitionLaneExpirationMs; // + 5000
    case RetryLane1:
    case RetryLane2:
    case RetryLane3:
    case RetryLane4:
      return enableRetryLaneExpiration
        ? currentTime + retryLaneExpirationMs // + 5000
        : NoTimestamp;
    case SelectiveHydrationLane:
    case IdleHydrationLane:
    case IdleLane:
```

## getNextLanes

// 获取下一个 pending lanes

```
const nonIdleUnblockedLanes = nonIdlePendingLanes & ~suspendedLane
  if (nonIdleUnblockedLanes !== NoLanes) {
   // 获取非idle非suspended的lanes的最高优先级,返回值是个lanes,也包括单个
   nextLanes = getHighestPriorityLanes(nonIdleUnblockedLanes);
 } else {
   const nonIdlePingedLanes = nonIdlePendingLanes & pingedLanes;
   if (nonIdlePingedLanes !== NoLanes) {
     nextLanes = getHighestPriorityLanes(nonIdlePingedLanes);
   }
 }
} else {
 // 只剩下了idle work
  const unblockedLanes = pendingLanes & ~suspendedLanes;
  if (unblockedLanes !== NoLanes) {
   nextLanes = getHighestPriorityLanes(unblockedLanes);
  } else {
   if (pingedLanes !== NoLanes) {
     nextLanes = getHighestPriorityLanes(pingedLanes);
   }
}
if (nextLanes === NoLanes) {
  return NoLanes;
}
// 如果我们已经在render阶段中,切换lanes会中断当前渲染进程,导致丢失进度。
// 只有当新Lanes的优先级更高时,我们才应该这样做。
if (
  wipLanes !== NoLanes &&
  wipLanes !== nextLanes &&
  // 如果我们已经延迟暂停了,那么中断是可以的。不必等到root完成。
  (wipLanes & suspendedLanes) === NoLanes
) {
  const nextLane = getHighestPriorityLane(nextLanes);
  const wipLane = getHighestPriorityLane(wipLanes);
  if (
   // Tests whether the next lane is equal or lower priority than t
   // one. This works because the bits decrease in priority as you
   nextLane >= wipLane ||
   // Default priority updates不应中断transition。default updates和tr
    (nextLane === DefaultLane && (wipLane & TransitionLanes) !== NoL
```

```
) {
    // 继续完成正在进行中的树。不中断。
    return wipLanes;
}

return nextLanes;
}
```

## **getHighestPriorityLanes**

获取优先级最高的 lanes。其实也包括单个 lane,只是从类型上来说,lane 也算 lanes。

```
JavaScript
function getHighestPriorityLanes(lanes: Lanes | Lane): Lanes {
  if (enableUnifiedSyncLane) {
    const pendingSyncLanes = lanes & SyncUpdateLanes;
    if (pendingSyncLanes !== 0) {
      // ? sy
      // 将DefaultLane、SyncLane和ContinuousLane统一为SyncLane,并在根上使
      // https://github.com/facebook/react/pull/25524
      return pendingSyncLanes;
  switch (getHighestPriorityLane(lanes)) {
    case SyncHydrationLane:
      return SyncHydrationLane;
    case SyncLane:
      return SyncLane;
    case InputContinuousHydrationLane:
      return InputContinuousHydrationLane;
    case InputContinuousLane:
      return InputContinuousLane;
    case DefaultHydrationLane:
      return DefaultHydrationLane;
    case DefaultLane:
```

```
return DefaultLane;
case TransitionHydrationLane:
  return TransitionHydrationLane;
case TransitionLane1:
case TransitionLane2:
case TransitionLane3:
case TransitionLane4:
case TransitionLane5:
case TransitionLane6:
case TransitionLane7:
case TransitionLane8:
case TransitionLane9:
case TransitionLane10:
case TransitionLane11:
case TransitionLane12:
case TransitionLane13:
case TransitionLane14:
case TransitionLane15:
  return lanes & TransitionLanes;
case RetryLane1:
case RetryLane2:
case RetryLane3:
case RetryLane4:
  return lanes & RetryLanes;
case SelectiveHydrationLane:
  return SelectiveHydrationLane;
case IdleHydrationLane:
  return IdleHydrationLane;
case IdleLane:
  return IdleLane:
case OffscreenLane:
  return OffscreenLane;
case DeferredLane:
  // This shouldn't be reachable because deferred work is always e
 // with something else.
  return NoLanes;
default:
  if (__DEV__) {
    console.error(
      'Should have found matching lanes. This is a bug in React.',
   );
```

```
}
// This shouldn't be reachable, but as a fallback, return the en
return lanes;
}
```