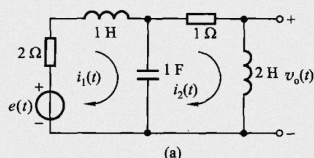


HW1: 2-1(a), 2-4(1), 2-7

HW2: 卷积 2-13(2)(3), 2-14,
2-15(1)(3), 2-18(a)(c), 2-20

信号作业2

2-1 对题图2-1所示电路图分别列写求电压 $v_o(t)$ 的微分方程表示。



$$\begin{aligned} \dot{i}_L(t) &= \frac{1}{L_2} \int_{-\infty}^t v_o(\tau) d\tau & \dot{i}_C(t) &= \dot{i}_1(t) - \dot{i}_2(t) \\ u_C(t) &= v_o(t) + \dot{i}_2(t) \cdot L_2 \\ L_1 \frac{d}{dt} \dot{i}_1(t) &= e(t) - 2\dot{i}_1(t) - v_o(t) - \dot{i}_L(t) \end{aligned}$$

2-4 已知系统相应的齐次方程及其对应的0⁻状态条件,求系统的零输入响应。

(1) $\frac{d^2}{dt^2} r(t) + 2 \frac{d}{dt} r(t) + 2r(t) = 0$ 给定: $r(0_+) = 1, r'(0_+) = 2$

$$r^2 + 2r + 2 = 0$$

$$r_1 = -1 - i, \quad r_2 = -1 + i$$

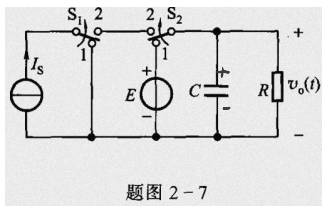
$$\therefore r(t) = e^{-t} (C_1 \cos t + C_2 \sin t) \quad r(0) = C_1 = 1$$

$$r'(t) = e^{-t} (-\sin t + C_2 \cos t - \cos t - C_2 \sin t)$$

$$r'(0) = C_2 - 1 = 2 \quad C_2 = 3$$

$$\therefore r(t) = e^{-t} (\cos t + 3 \sin t)$$

2-7



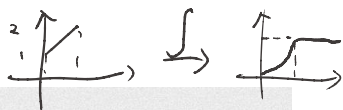
零输入: $v_o(t) = RC \frac{dv_c}{dt}$
 $v_c(0) = E$

零状态: $v_o(t) = I_s R$

2-13

(2) $f_1(t) = \delta(t)$, $f_2(t) = \cos(\omega t + 45^\circ)$

(3) $f_1(t) = (1+t)[u(t) - u(t-1)]$, $f_2(t) = u(t-1) - u(t-2)$



(2) $f_1 * f_2 = f_2 = \cos(\omega t + 45^\circ)$ (性质)

(3) $f_1 * f_2 = f_1 * u(t-1) - f_1 * u(t-2)$

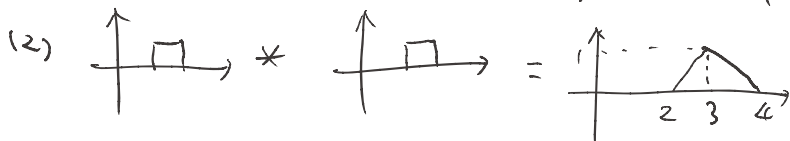
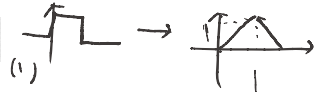
$$= \int_{-\infty}^{t-1} f_1(\tau) d\tau - \int_{-\infty}^{t-2} f_1(\tau) d\tau$$

$$= \int_{t-2}^{t-1} f_1(\tau) d\tau$$

$$= \int_{t-2}^{t-1} (1+\tau) u(\tau) d\tau - \int_{t-2}^{t-1} (1+\tau) u(\tau-1) d\tau$$

$$= \left(\frac{1}{2} \tau^2 + \tau \right) u(\tau) \Big|_{t-2}^{t-1} - \left(\frac{1}{2} \tau^2 + \tau - \frac{3}{2} \right) u(\tau-1) \Big|_{t-2}^{t-1}$$

2-14 (1) $f(t) = u(t) - u(t-1)$, 求 $s(t) = f(t) * f(t)$;
 (2) $f(t) = u(t-1) - u(t-2)$, 求 $s(t) = f(t) * f(t)$ 。



2-15 已知 $f_1(t) = u(t+1) - u(t-1)$, $f_2(t) = \delta(t+5) + \delta(t-5)$, $f_3(t) = \delta(t + \frac{1}{2}) +$

$\delta(t - \frac{1}{2})$, 画出下列各卷积波形。

(1) $s_1(t) = f_1(t) * f_2(t)$

~~(2) $s_2(t) = f_1(t) * f_2(t) * f_2(t)$~~

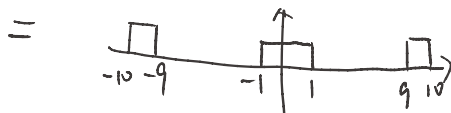
(3) $s_3(t) = \{ [f_1(t) * f_2(t)] [u(t+5) - u(t-5)] \} * f_2(t)$

(1) $S_1(t) = u(t+6) - u(t+4) + u(t-4) - u(t-6)$

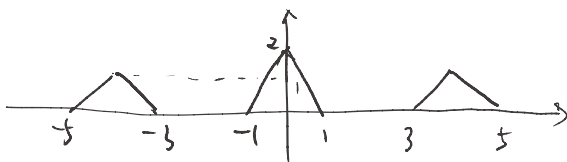
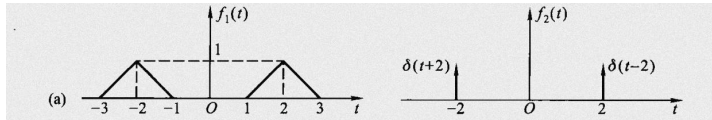


(2) $S_3(t) =$

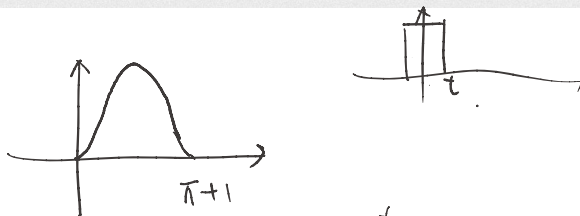
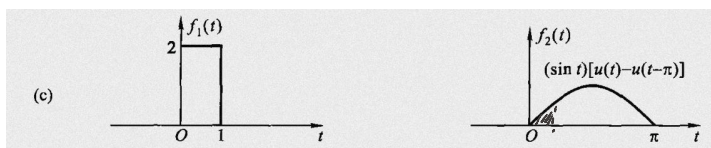
$* f_2(t)$



2-19



$$\begin{aligned} f_1(t) * f_2(t) &= f_1(t) * \delta(t+2) + f_1(t) * \delta(t-2) \\ &= f_1(t+2) + f_1(t-2) \end{aligned}$$



$$\text{对 } t \in (0, 1) \quad f_1(t) * f_2(t) = \int_0^t 2 \sin \tau \, d\tau = 2 - 2 \cos t$$

$$\text{对 } t \in (1, \pi) \quad f_1(t) * f_2(t) = \int_{t-1}^t 2 \sin \tau \, d\tau = -2(\cos t - \cos(t-1))$$

$$\text{对 } t \in (\pi, \pi+1) \quad f_1(t) * f_2(t) = \int_{t-1}^{\pi} 2 \sin \tau \, d\tau = 2 + 2 \cos(t-1)$$

2-20

每个子系统都是 LTI.

$$h(t) = h_1(t) + h_2(t) * h_1(t) * h_3(t)$$

$$= u(t) + \delta(t-1) * u(t) * -\delta(t).$$

$$= u(t) + (-u(t-1)) h(t)$$

$$= u(t) - u(t-1).$$

