

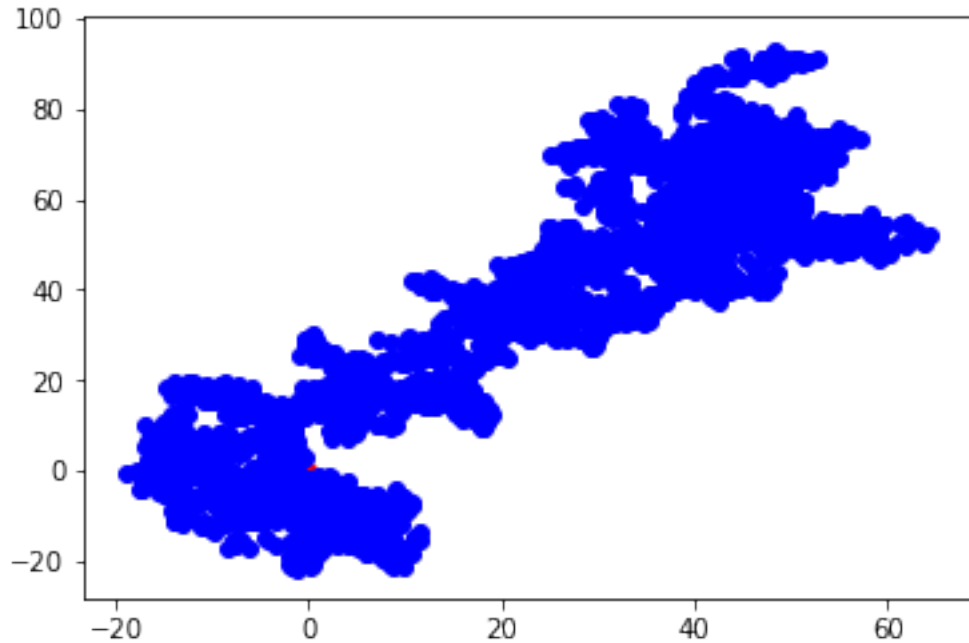
# CogSci131 HW1

Summer, 2019

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In [25]: %matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
from math import*

In [43]: #1a. Suppose that an ant wandered randomly by taking steps (x,y), one per second, where
#come from a normal distribution with a mean of 0 and a standard deviation of 1.0mm (
#Plot a trace of the ant's path over the course of an hour.
x=0
y=0
plt.scatter(0,0, color='red')
for i in range(1,3600): #3600s for an hour
    right=np.random.normal(0,1,1)
    up=np.random.normal(0,1,1)
    x+=right
    y+=up
    plt.scatter(x,y,color='blue')

plt.show()
```



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In [13]: #1b. Lets think about why ants need to perform path integration. Suppose that instead
#Is this a good strategy? Why or why not?
#denote start point as (0,0), record food location. keep wandering, check if currnet
def homerun1():
    x=0
    y=0
    for i in range(1,3601): #left include right exclude
        right=np.random.normal(0,1,1)
        up=np.random.normal(0,1,1)
        x+=right#one step in x direction
        y+=up#one step in y direction. x,y denotes food location
    time_back=1
    while(time_back<=3600):
        right=np.random.normal(0,1,1)
        up=np.random.normal(0,1,1)
        x+=right
        y+=up
        if x**2+y**2 < 100:
            return True
        else:
            time_back+=1

count=0
for i in range(1,1001):
    if homerun1()==True:
        count+=1
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prob=count/1000
print(prob)

```

*#no, this is not a good strategy, because the probability of returning to within a ran*

0.205

In [49]: *#1c. what is the random closest distance to the nest?*

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min_dis=[]
for i in range(1,1001):
    for j in range(1,3601): #left include right exclude
        x=0
        y=0
        right=np.random.normal(0,1,1)
        up=np.random.normal(0,1,1)
        x+=right
        y+=up
    distance=[]
    for k in range (1,3601):
        right=np.random.normal(0,1,1)
        up=np.random.normal(0,1,1)
        x+=right
        y+=up
        distance.append(sqrt(x**2+y**2))
    min_dis.append(min(distance))

avg=np.mean(min_dis)
avg

```

Out [49]: 0.7452743539145392

In [59]: *#2. show a range of s values to show what is going on. First we use a fixed S as the*

```

X=0
Y=0
x=0
y=0
mean_dis=[]
for s in range(1, 10001, 100):
    s = s*10**(-4)
    distance=[]
    for i in range(1,101) :
        for j in range(1,3601):
            right=np.random.normal(0,1,1)
            up=np.random.normal(0,1,1)

```

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ex=np.random.normal(0,s,1)
ey=np.random.normal(0,s,1)
x+=right #actual location
X=X+right+ex #memorizede location
y+=up
Y=Y+up+ey
distance.append(sqrt((X-x)**2+(Y-y)**2))
mean_dis.append(np.mean(distance))

```

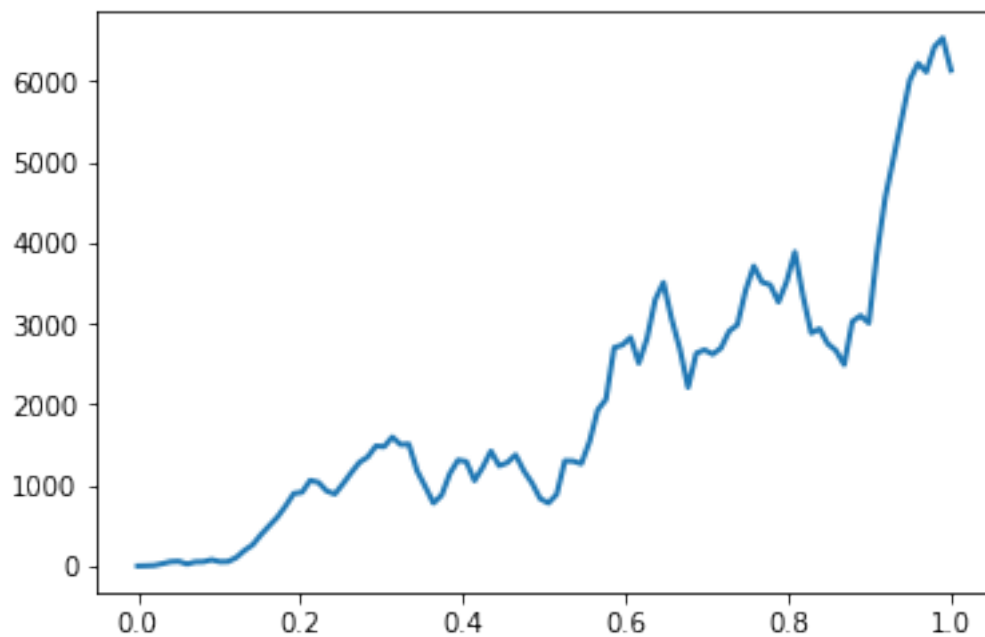
mean\_dis

```

x=np.linspace(0.0001,1,100)
y=mean_dis
plt.plot(x, y, linewidth=2.0)
plt.show()

```

*#conclusion: as s becomes greater, the mean distance from the ants to the nest become*



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In [60]: #3a.
X=0
Y=0
x=0
y=0
mean_dis=[]
mean_energy=[]
for s in range(1, 10001, 100):

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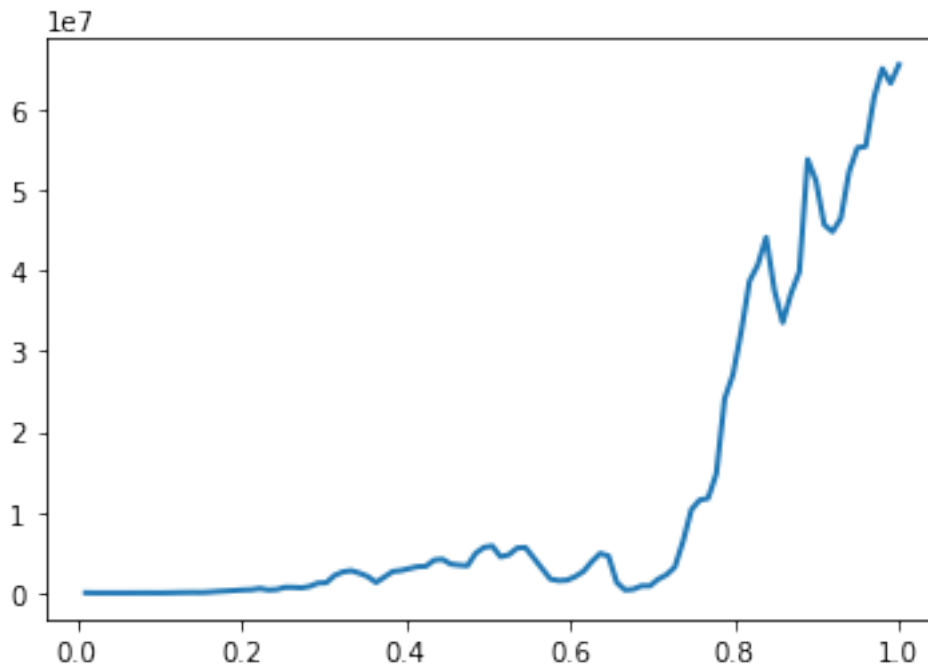
s = s*10**(-4)
distance=[]
energy=[]
for i in range(1,101) :
    for j in range(1,3601):
        right=np.random.normal(0,1,1)
        up=np.random.normal(0,1,1)
        ex=np.random.normal(0,s,1)
        ey=np.random.normal(0,s,1)
        x+=right #actual location
        X=X+right+ex #memorizede location
        y+=up
        Y=Y+up+ey
        distance.append(sqrt((X-x)**2+(Y-y)**2))
        energy.append(((X-x)**2+(Y-y)**2)+np.exp(0.1/s))
    mean_dis.append(np.mean(distance))
    mean_energy.append(np.mean(energy))

```

```

mean_energy
x=np.linspace(0.0001,1,100)
y=mean_energy
plt.plot(x, y, linewidth=2.0)
plt.show()
#conclusion: the minimum acheives at when s is relatively small but not the smallest.

```



In [ ]: #3b.

*#Evolutionary significance*

*#Supposing that s1 is the sd which acheives minimum energy consumption. And suppose th*

*#will acheive minimal energy consumption while searching food, thus have a higher chan*

*#offsprings. In the long run, in the ant colony, number of ants with s1 as their food*

*#will evolve into the direction that acheives minimum energy consumption( food searcd*