

Week 9: Multidimensional Change of Variable

MATH697

Sahir Bhatnagar

October 31, 2017

McGill University

First Some Terminology

One-to-one and Onto

© The McGraw-Hill Companies, Inc. all rights reserved.

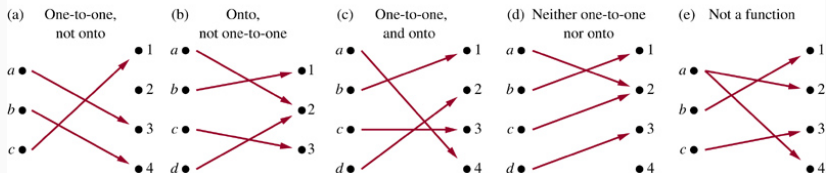


Figure 1

Multidimensional Change of Variable

- **Univariate Transformations:** We previously discussed the problem of starting with a single random variable X , forming some function of X , such as X^2 or e^X , to obtain a new random variable $Y = h(X)$

- **Univariate Transformations:** We previously discussed the problem of starting with a single random variable X , forming some function of X , such as X^2 or e^X , to obtain a new random variable $Y = h(X)$
- **Multivariate Transformations:** We now generalize this scenario by starting with more than a single random variable

- Consider a system having a component that can be replaced just once before the system itself expires.

Introduction

- Consider a system having a component that can be replaced just once before the system itself expires.
- X : lifetime of the original component

Introduction

- Consider a system having a component that can be replaced just once before the system itself expires.
- X : lifetime of the original component
- Y : lifetime of the replacement component

Introduction

- Consider a system having a component that can be replaced just once before the system itself expires.
- X : lifetime of the original component
- Y : lifetime of the replacement component
- Any of the following functions of X and Y may be of interest to an investigator:

Introduction

- Consider a system having a component that can be replaced just once before the system itself expires.
- X : lifetime of the original component
- Y : lifetime of the replacement component
- Any of the following functions of X and Y may be of interest to an investigator:
 1. The total lifetime $X + Y$

Introduction

- Consider a system having a component that can be replaced just once before the system itself expires.
- X : lifetime of the original component
- Y : lifetime of the replacement component
- Any of the following functions of X and Y may be of interest to an investigator:
 1. The total lifetime $X + Y$
 2. The ratio of lifetimes X/Y ; e.g. if the ratio is 2, the original component lasted twice as long as its replacement

- Consider a system having a component that can be replaced just once before the system itself expires.
- X : lifetime of the original component
- Y : lifetime of the replacement component
- Any of the following functions of X and Y may be of interest to an investigator:
 1. The total lifetime $X + Y$
 2. The ratio of lifetimes X/Y ; e.g. if the ratio is 2, the original component lasted twice as long as its replacement
 3. The ratio $X/(X + Y)$; the proportion of system lifetime during which the original component operated

- Given two continuous random variables X and Y , consider forming two new random variables

$$U = g_1(X, Y) \quad V = g_2(X, Y)$$

- Given two **continuous** random variables X and Y , consider forming two new random variables

$$U = g_1(X, Y) \quad V = g_2(X, Y)$$

- We now focus on finding the joint distribution of these two new **continuous** variables (U, V)

Joint Distribution of Two New Random Variables

Recall, $U = g_1(X, Y)$ and $V = g_2(X, Y)$.

Joint Distribution of Two New Random Variables

Recall, $U = g_1(X, Y)$ and $V = g_2(X, Y)$. Let

$f_{X,Y}(x, y)$ = the joint pdf of the two original variables

$f_{U,V}(u, v)$ = the joint pdf of the two new variables

Joint Distribution of Two New Random Variables

Recall, $U = g_1(X, Y)$ and $V = g_2(X, Y)$. Let

$f_{X,Y}(x, y)$ = the joint pdf of the two original variables

$f_{U,V}(u, v)$ = the joint pdf of the two new variables

- $g_1(\cdot)$ and $g_2(\cdot)$ are functions that express the **new variables in terms of the original ones**

Joint Distribution of Two New Random Variables

Recall, $U = g_1(X, Y)$ and $V = g_2(X, Y)$. Let

$f_{X,Y}(x, y)$ = the joint pdf of the two original variables

$f_{U,V}(u, v)$ = the joint pdf of the two new variables

- $g_1(\cdot)$ and $g_2(\cdot)$ are functions that express the **new variables in terms of the original ones**
- The general result presumes that these functions can be inverted to solve for the original variables in terms of the new ones:

$$X = h_1(U, V) \quad Y = h_2(U, V)$$

Joint Distribution of Two New Random Variables

- For example, if

$$u = g_1(x, y) = x + y \quad v = g_2(x, y) = x - y$$

then

$$x = h_1(u, v) = \frac{1}{2}(u + v) \quad y = h_2(u, v) = \frac{1}{2}(u - v)$$

Joint Distribution of Two New Random Variables

- For example, if

$$u = g_1(x, y) = x + y \quad v = g_2(x, y) = x - y$$

then

$$x = h_1(u, v) = \frac{1}{2}(u + v) \quad y = h_2(u, v) = \frac{1}{2}(u - v)$$

- $\mathcal{A} = \{(x, y) : f(x, y) > 0\}$ is the region of positive density for the original variables

Joint Distribution of Two New Random Variables

- For example, if

$$u = g_1(x, y) = x + y \quad v = g_2(x, y) = x - y$$

then

$$x = h_1(u, v) = \frac{1}{2}(u + v) \quad y = h_2(u, v) = \frac{1}{2}(u - v)$$

- $\mathcal{A} = \{(x, y) : f(x, y) > 0\}$ is the region of positive density for the original variables
- $\mathcal{B} = \{(u, v) : u = g_1(x, y), v = g_2(x, y) \text{ for some } (x, y) \in \mathcal{A}\}$ is the region of positive density for the new variables

Joint Distribution of Two New Random Variables

- For example, if

$$u = g_1(x, y) = x + y \quad v = g_2(x, y) = x - y$$

then

$$x = h_1(u, v) = \frac{1}{2}(u + v) \quad y = h_2(u, v) = \frac{1}{2}(u - v)$$

- $\mathcal{A} = \{(x, y) : f(x, y) > 0\}$ is the region of positive density for the original variables
- $\mathcal{B} = \{(u, v) : u = g_1(x, y), v = g_2(x, y) \text{ for some } (x, y) \in \mathcal{A}\}$ is the region of positive density for the new variables
- \mathcal{B} is the **image** of \mathcal{A} under the transformation

Joint Distribution of Two New Random Variables

- Suppose that the partial derivative of each $h_i(u, v)$ with respect to both u and v exists for every pair (u, v) in \mathcal{B} and is continuous

Joint Distribution of Two New Random Variables

- Suppose that the partial derivative of each $h_i(u, v)$ with respect to both u and v exists for every pair (u, v) in \mathcal{B} and is continuous
- Define the **Jacobian** as

$$\begin{aligned}\mathcal{J} &= \det \begin{bmatrix} \frac{\partial h_1(u, v)}{\partial u} & \frac{\partial h_1(u, v)}{\partial v} \\ \frac{\partial h_2(u, v)}{\partial u} & \frac{\partial h_2(u, v)}{\partial v} \end{bmatrix} \\ &= \frac{\partial h_1(u, v)}{\partial u} \frac{\partial h_2(u, v)}{\partial v} - \frac{\partial h_1(u, v)}{\partial v} \frac{\partial h_2(u, v)}{\partial u}\end{aligned}$$

Joint Distribution of Two New Random Variables

- Suppose that the partial derivative of each $h_i(u, v)$ with respect to both u and v exists for every pair (u, v) in \mathcal{B} and is continuous
- Define the **Jacobian** as

$$\begin{aligned}\mathcal{J} &= \det \begin{bmatrix} \frac{\partial h_1(u, v)}{\partial u} & \frac{\partial h_1(u, v)}{\partial v} \\ \frac{\partial h_2(u, v)}{\partial u} & \frac{\partial h_2(u, v)}{\partial v} \end{bmatrix} \\ &= \frac{\partial h_1(u, v)}{\partial u} \frac{\partial h_2(u, v)}{\partial v} - \frac{\partial h_1(u, v)}{\partial v} \frac{\partial h_2(u, v)}{\partial u}\end{aligned}$$

- Then

$$f_{u, v}(u, v) = \begin{cases} f_{X, Y}(h_1(u, v), h_2(u, v)) \times |\mathcal{J}| & u, v \in \mathcal{B} \\ 0 & \text{else} \end{cases}$$

Multivariate Transformations

Theorem 1 (Multivariate Transformations (2 random variables))

Let X and Y be jointly continuous, with PDF $f_{X,Y}(x, y)$ on the set $\mathcal{A} = \{(x, y) : f_{X,Y}(x, y) > 0\}$. Let $U = g_1(X, Y)$ and $V = g_2(X, Y)$ on the set $\mathcal{B} = \{(u, v) : u = g_1(x, y), v = g_2(x, y) \text{ for some } (x, y) \in \mathcal{A}\}$, where $g_1, g_2 : \mathbb{R}^2 \rightarrow \mathbb{R}$ are differentiable functions. Assume g_1, g_2 is one-to-one on \mathcal{A} , i.e., we can solve the equations $u = g_1(x, y), v = g_2(x, y)$ for x and y denoted by $x = h_1(u, v)$ and $y = h_2(u, v)$. Then U and V are also jointly continuous with PDF

$$f_{U,V}(u, v) = \begin{cases} f_{X,Y}(h_1(u, v), h_2(u, v)) \times |\mathcal{J}| & u, v \in \mathcal{B} \\ 0 & \text{else} \end{cases} \quad (1)$$

where

$$\mathcal{J} = \det \begin{bmatrix} \frac{\partial h_1(u, v)}{\partial u} & \frac{\partial h_1(u, v)}{\partial v} \\ \frac{\partial h_2(u, v)}{\partial u} & \frac{\partial h_2(u, v)}{\partial v} \end{bmatrix}$$

Multivariate Transformation Example

Example 2 (Uniform Square Transformation)

Let X and Y be independent $Uniform(0, 1)$ random variables. Consider the two random variables $U = X + Y$ and $V = X - Y$.

1. Determine the joint PDF of U and V
2. What is the marginal PDF of U and marginal PDF of V ?

Multivariate Transformation Example

Example 3 (Distribution of the product of beta variables)

Let $X \sim \text{Beta}(\alpha, \beta)$ and $Y \sim \text{Beta}(\alpha + \beta, \gamma)$ be independent random variables. The joint PDF of (X, Y) is

$$f_{X,Y}(x, y) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} x^{\alpha-1} (1-x)^{\beta-1} \frac{\Gamma(\alpha + \beta + \gamma)}{\Gamma(\alpha + \beta)\Gamma(\gamma)} y^{\alpha+\beta-1} (1-y)^{\gamma-1}$$

on the set $\mathcal{A} = \{(x, y) : 0 < x < 1, 0 < y < 1\}$ and 0 elsewhere. Consider the transformation $U = XY$ and $V = X$

1. Determine the joint PDF of U and V
2. What is the marginal PDF of U and marginal PDF of V ?

Multivariate Transformation Example

Example 4 (Sum and difference of normal variables)

Let $X \sim N(0, 1)$ and $Y \sim N(0, 1)$ be independent standard normal random variables. The joint PDF of (X, Y) is

$$f_{X,Y}(x, y) = \frac{1}{2\pi} \exp\{-x^2/2\} \exp\{-y^2/2\}$$

on the set $\mathcal{A} = \{(x, y) : -\infty < x < \infty, -\infty < y < \infty\}$.

Consider the transformation $U = X + Y$ and $V = X - Y$

1. Determine the joint PDF of U and V
2. What is the marginal PDF of U and marginal PDF of V ?

When the transformation is not one-to-one

- In many situations, the transformation of interest is not one-to-one

When the transformation is not one-to-one

- In many situations, the transformation of interest is not one-to-one
- Let $\mathcal{A} = \{(x, y) : f_{x,y}(x, y) > 0\}$

When the transformation is not one-to-one

- In many situations, the transformation of interest is not one-to-one
- Let $\mathcal{A} = \{(x, y) : f_{x,y}(x, y) > 0\}$
- Suppose $\mathcal{A}_0, \mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_k$ form a partition of \mathcal{A} with the following properties:

When the transformation is not one-to-one

- In many situations, the transformation of interest is not one-to-one
- Let $\mathcal{A} = \{(x, y) : f_{X,Y}(x, y) > 0\}$
- Suppose $\mathcal{A}_0, \mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_k$ form a partition of \mathcal{A} with the following properties:
 - The set \mathcal{A}_0 , which may be empty, satisfies $P((X, Y) \in \mathcal{A}_0) = 0$

When the transformation is not one-to-one

- In many situations, the transformation of interest is not one-to-one
- Let $\mathcal{A} = \{(x, y) : f_{X,Y}(x, y) > 0\}$
- Suppose $\mathcal{A}_0, \mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_k$ form a partition of \mathcal{A} with the following properties:
 - The set \mathcal{A}_0 , which may be empty, satisfies $P((X, Y) \in \mathcal{A}_0) = 0$
 - The transformation $U = g_1(X, Y)$ and $V = g_2(X, Y)$ is a one-to-one transformation from \mathcal{A}_i onto \mathcal{B} for each $i = 1, 2, \dots, k$

When the transformation is not one-to-one

- In many situations, the transformation of interest is not one-to-one
- Let $\mathcal{A} = \{(x, y) : f_{X,Y}(x, y) > 0\}$
- Suppose $\mathcal{A}_0, \mathcal{A}_1, \mathcal{A}_2, \dots, \mathcal{A}_k$ form a partition of \mathcal{A} with the following properties:
 - The set \mathcal{A}_0 , which may be empty, satisfies $P((X, Y) \in \mathcal{A}_0) = 0$
 - The transformation $U = g_1(X, Y)$ and $V = g_2(X, Y)$ is a one-to-one transformation from \mathcal{A}_i onto \mathcal{B} for each $i = 1, 2, \dots, k$
- Then for each i , the inverse functions from \mathcal{B} to \mathcal{A} can be found.

When the transformation is not one-to-one

- Denote the i th inverse by $x = h_{1i}(u, v)$ and $y = h_{2i}(u, v)$

When the transformation is not one-to-one

- Denote the i th inverse by $x = h_{1i}(u, v)$ and $y = h_{2i}(u, v)$
- This i th inverse gives, for $(u, v) \in \mathcal{B}$, the unique $(x, y) \in \mathcal{A}_i$ such that $(u, v) = (g_1(x, y), g_2(x, y))$.

When the transformation is not one-to-one

- Denote the i th inverse by $x = h_{1i}(u, v)$ and $y = h_{2i}(u, v)$
- This i th inverse gives, for $(u, v) \in \mathcal{B}$, the unique $(x, y) \in \mathcal{A}_i$ such that $(u, v) = (g_1(x, y), g_2(x, y))$.
- Let \mathcal{J}_i denote the Jacobian computed from the i th inverse, then

$$f_{U,V}(u, v) = \sum_{i=1}^k f_{X,Y}(h_{1i}(u, v), h_{2i}(u, v)) |\mathcal{J}_i| \quad (2)$$

Multivariate Transformation Example

Example 5 (Distribution of the ratio of normal variables)

Let $X \sim N(0, 1)$ and $Y \sim N(0, 1)$ be independent standard normal random variables. The joint PDF of (X, Y) is

$$f_{X,Y}(x, y) = \frac{1}{2\pi} \exp\{-x^2/2\} \exp\{-y^2/2\}$$

on the set $\mathcal{A} = \{(x, y) : -\infty < x < \infty, -\infty < y < \infty\}$.

Consider the transformation $U = X/Y$ and $V = |Y|$. Note that this transformation is not one-to-one since the points (x, y) and $(-x, -y)$ are both mapped into the same (u, v) point. But if we restrict consideration to either positive or negative values of y , then the transformation is one-to-one.

1. Determine the joint PDF of U and V
2. What is the marginal PDF of U ?

Hierarchical Models and Mixture Distributions

- In the cases we have seen thus far, a random variable (RV) has a single distribution, possibly depending on parameters

- In the cases we have seen thus far, a random variable (RV) has a single distribution, possibly depending on parameters
- While in general, a RV can only have one distribution, it is often easier to model a situation by thinking of things in a hierarchy

- In the cases we have seen thus far, a random variable (RV) has a single distribution, possibly depending on parameters
- While in general, a RV can only have one distribution, it is often easier to model a situation by thinking of things in a hierarchy
- Perhaps the most classic hierarchical model is given in the following example

Example 6 (Binomial-Poisson hierarchy (revisited))

An chicken lays a large number of eggs, each surviving with probability p . On the average, how many eggs will survive? The large number of eggs laid is a random variable, often taken to be $Poisson(\lambda)$. Furthermore, if we assume that each egg's survival is independent, then we have Bernoulli trials. Therefore, if we let X =number of survivors and N =number of eggs laid, we have

$$X|N \sim \text{Binomial}(N, p) \quad \text{and} \quad N \sim \text{Poisson}(\lambda)$$

a hierarchical model.

- We showed in Example 25 (Week 7), that the marginal distribution of X is $Poisson(\lambda p)$ with Y playing no part at all

- Introducing Y into the hierarchy was mainly to aid our understanding of the model

Introduction

- Introducing Y into the hierarchy was mainly to aid our understanding of the model
- The answer to the original question is easy to compute $E(X) = \lambda p$. So on average λp eggs will survive

- Introducing Y into the hierarchy was mainly to aid our understanding of the model
- The answer to the original question is easy to compute $E(X) = \lambda p$. So on average λp eggs will survive
- If we were interested only in this mean and did not need the distribution, we could have used properties of **conditional expectation**

Introduction

- Introducing Y into the hierarchy was mainly to aid our understanding of the model
- The answer to the original question is easy to compute $E(X) = \lambda p$. So on average λp eggs will survive
- If we were interested only in this mean and did not need the distribution, we could have used properties of **conditional expectation**
- Sometimes, **calculations can be greatly simplified** by using the following theorem. Recall that $E(X|y)$ is a function of y and $E(X|Y)$ is a random variable whose value depends on the value of Y

Theorem 7 (Conditional Expectation)

If X and Y are any two random variables, then

$$E(X) = E(E(X|Y)) \quad (3)$$

provided that the expectations exist

Proof: on board

Mixture Distribution

- The term *mixture distribution* in the title of this section refers to a distribution arising from a hierarchical structure.

Mixture Distribution

- The term *mixture distribution* in the title of this section refers to a distribution arising from a hierarchical structure.

Mixture Distribution

- The term *mixture distribution* in the title of this section refers to a distribution arising from a hierarchical structure.

Definition 8 (Mixture Distribution)

A random variable X is said to have a mixture distribution if the distribution of X depends on a quantity that also has a distribution

Mixture Distribution

- The term *mixture distribution* in the title of this section refers to a distribution arising from a hierarchical structure.

Definition 8 (Mixture Distribution)

A random variable X is said to have a mixture distribution if the distribution of X depends on a quantity that also has a distribution

- Thus in Example 6, the $Poisson(\lambda p)$ distribution is a mixture distribution since it is the result of combining a $Binomial(N, p)$ with a $Poisson(\lambda)$.

Mixture Distribution

- The term *mixture distribution* in the title of this section refers to a distribution arising from a hierarchical structure.

Definition 8 (Mixture Distribution)

A random variable X is said to have a mixture distribution if the distribution of X depends on a quantity that also has a distribution

- Thus in Example 6, the $Poisson(\lambda p)$ distribution is a mixture distribution since it is the result of combining a $Binomial(N, p)$ with a $Poisson(\lambda)$.
- In general we can say that hierarchical models lead to mixture distributions

Example 9 (Binomial-Poisson-Exponential hierarchy)

Consider a generalization of Example 6 where instead of one mother chicken, there are a large number of mothers, and one mother is chosen at random. We are still interested in **knowing the average number of survivors**, but it is no longer clear that the number of eggs laid follows the same Poisson distribution for each mother. The following three stage hierarchy may be more appropriate. Let X = number of survivors. Then

$$X|N \sim \text{Binomial}(N, p)$$

$$N|\Lambda \sim \text{Poisson}(\Lambda)$$

$$\Lambda \sim \text{Exponential}(\beta)$$

where the last stage of hierarchy accounts for the variability across different mothers.

Theorem 10 (Conditional Variance)

For any two random variables X and Y

$$\text{Var}(X) = E(\text{Var}(E|Y)) + \text{Var}(E(X|Y)) \quad (4)$$

Proof: on board

Example 11 (Beta-binomial hierarchy)

One generalization of the binomial is to allow the success probability to vary according to a distribution. A standard model for this situation is

$$X|P \sim \text{Binomial}(n, P)$$

$$P \sim \text{beta}(\alpha, \beta)$$

Session Info

```
devtools::session_info()
```

```
## setting value
## version R version 3.4.1 (2017-06-30)
## system x86_64, linux-gnu
## ui X11
## language en_US
## collate en_US.UTF-8
## tz Canada/Eastern
## date 2017-11-06
##
## package * version date source
## abind 1.4-5 2016-07-21 cran (@1.4-5)
## arm 1.9-3 2016-11-27 cran (@1.9-3)
## assertthat 0.2.0 2017-04-11 CRAN (R 3.4.1)
## backports 1.1.0 2017-05-22 cran (@1.1.0)
## base * 3.4.1 2017-07-08 local
## bindr 0.1 2016-11-13 CRAN (R 3.4.1)
## bindrcpp 0.2 2017-06-17 CRAN (R 3.4.1)
## blme 1.0-4 2015-06-14 cran (@1.0-4)
## broom 0.4.2 2017-02-13 CRAN (R 3.4.1)
```