

第5章: 5.3

5.3 (1) u_1 正半周期 VD_1, VD_2 导通 VD_3, VD_4 截止

$$\begin{cases} V_{D1} = u_1 - u_o \\ V_{D2} = -(u_1 - u_o) \end{cases} \quad \begin{cases} i_1 = g(u_1 - u_o) \\ i_2 = -g(u_1 - u_o) \end{cases}$$

$$u_{o正} = i_o R_L = R_L(i_1 - i_2) = 2gR_L(u_1 - u_o) \cdot k^+$$

u_1 负半周期 VD_3, VD_4 导通

$$\begin{cases} i_3 = g(-u_1 - u_o) \\ i_4 = g(u_1 + u_o) \end{cases}$$

$$u_{o负} = R_L(i_3 - i_4) = -2gR_L(u_1 + u_o)k^-$$

$$u_o = u_{o正} + u_{o负}$$

$$= 2gR_L u_1 (k^+ - k^-) - 2gR_L u_o (k^+ + k^-)$$

$$\therefore u_o = \frac{2gR_L(k^+ - k^-)}{1 + 2gR_L} \quad (\because k^+ + k^- = 1)$$

(2) $u_{o正} = 2g_1 R_L(u_1 - u_o)k^+$

$$u_{o负} = -2g_2 R_L(u_1 + u_o)k^-$$

$$u_o = u_{o正} + u_{o负}$$

$$= 2g_1 R_L(u_1 - u_o)k^+ - 2g_2 R_L(u_1 + u_o)k^-$$

$$= 2R_L(g_1 k^+ - g_2 k^-)u_1 - 2R_L(g_1 k^+ + g_2 k^-)u_o$$

$$u_o = \frac{2R_L(g_1 k^+ - g_2 k^-)}{1 + 2R_L(g_1 k^+ + g_2 k^-)} u_1$$

$$VD_1: u_1 + u_2 - u_o$$

$$VD_2: u_1 - u_2 + u_o$$

$$VD_3: -(u_1 + u_2 + u_o)$$

$$VD_4: -(u_1 - u_2 - u_o)$$

(3) u_2 正半周期 VD_1 和 VD_4 导通

$$\begin{cases} V_{D1} = u_1 + u_2 - u_o \\ V_{D4} = -(u_1 - u_2 - u_o) \end{cases} \quad \begin{cases} i_1 = g(u_1 + u_2 - u_o) \\ i_4 = -g(u_1 - u_2 - u_o) \end{cases}$$

$$u_{o正} = R_L(i_1 - i_4) = 2gR_L(u_1 - u_o)k^+$$

u_2 负半周期 VD_3 和 VD_2 导通

$$\begin{cases} i_2 = g(u_1 - u_2 + u_o) \\ i_3 = g(-u_o - u_1 - u_2) \end{cases}$$

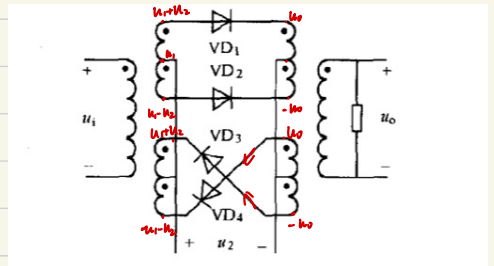
电流方向一致

$$u_{o负} = R_L(i_3 - i_2) = -2gR_L(u_o + u_1)k^-$$

$$u_o = u_{o正} + u_{o负} = 2gR_L(u_1 - u_o)k^+ - 2gR_L(u_o + u_1)k^-$$

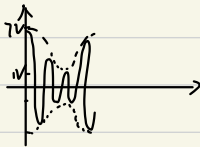
$$= 2gR_L(k^+ - k^-)u_1 - 2gR_L(k^+ + k^-)u_o$$

$$u_o = \frac{2gR_L(k^+ - k^-)}{1 + 2gR_L} u_1$$



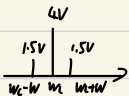
第六章: 6.1 6.3 6.8 6.13 6.15

6.1 (1) $U_{max} = 4 \times (1 + 0.75) = 7V$ $U_{min} = 4 \times (1 - 0.75) = 1V$



(2) $u_{Am}(t) = 4 \cos(22\pi \times 10^7 t) + 1.5 \cos[(22\pi \times 10^7 - 22\pi \times 10^4)t] + 1.5 \cos[(22\pi \times 10^7 + 22\pi \times 10^4)t]$

$\therefore \omega_c = 22\pi \times 10^7 \text{ rad/s}$ $\omega = 22\pi \times 10^4 \text{ rad/s}$



(3) $B = \frac{2W}{2\pi} = 20 \text{ kHz}$

(4) $\eta = \frac{P_m}{P_c + P_m} = \frac{\frac{m^2 \sqrt{1-\alpha^2}}{1 + m^2 \frac{1-\alpha^2}{3\alpha^2}}}{\frac{1}{1 + \frac{m^2}{3\alpha^2}} \times \frac{1}{2}} \approx 22\%$

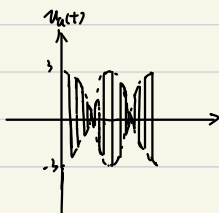
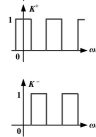
6.3 $u_{Am}(t) = 8(1 + \frac{1}{8} \cos(22\pi \times 10^3 t) + \frac{3}{8} \cos(22\pi \times 10^4 t) + \frac{1}{8} \cos(22\pi \times 10^5 t)) \cos(22\pi \times 10^6 t)$

$P = \frac{1}{2} \times 8^2 + \frac{1}{2} \times (\frac{1}{8})^2 + (\frac{3}{8})^2 + (\frac{1}{8})^2 \times 8^2 \times \frac{1}{2} = 34.75 \text{ W}$

6.8 (1) $u_a(t) = S(t) [K^+(u_r t) - K^-(u_r t)]$

K^+ 、 K^- 为开关函数，如右图所示

$$\begin{cases} K^+(\omega_s t) = \frac{1}{2} + \frac{2}{\pi} \cos \omega_s t - \frac{2}{3\pi} \cos 3\omega_s t + \dots + (-1)^{n-1} \frac{2}{(2n-1)\pi} \cos(2n-1)\omega_s t \\ K^-(\omega_s t) = \frac{1}{2} - \frac{2}{\pi} \cos \omega_s t + \frac{2}{3\pi} \cos 3\omega_s t - \dots + (-1)^n \frac{2}{(2n-1)\pi} \cos(2n-1)\omega_s t \end{cases}$$



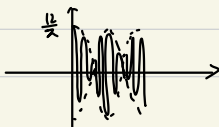
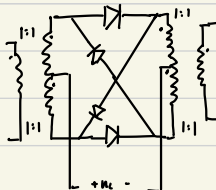
$u_o(t) = u_a(t) * h(t)$

由于 $\omega_s \gg \omega_{max}$ 且 $BW \gg 2\omega_{max}$

$= \frac{1}{\pi} \cos(u_{Am} t) \cos(\omega_c t)$ $H(j\omega)$ 滤波器只保留 $\cos u_{Am} t$ 成分

$= \frac{1}{\pi} [\cos(\omega_{max} + \omega_c)t + \cos(\omega_c - \omega_{max})t]$

(2)



6.13 $u(t) = S_1(t) \cos \omega t - S_2(t) \sin \omega t$

$$y_1(t) = u(t) \cos \omega t = S_1(t) \cos^2 \omega t - S_2(t) \sin \omega t \cos \omega t$$

$$= \frac{1}{2} S_1(t) + \frac{1}{2} \cos 2\omega t - \frac{1}{2} S_2(t) \sin 2\omega t$$

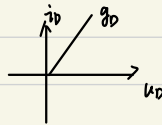
低通后 $u_{o1}(t) = \frac{1}{2} S_1(t)$

$$y_2(t) = u(t) \sin \omega t = S_1(t) \sin \omega t - S_2(t) \sin^2 \omega t$$

$$= \frac{1}{2} S_1(t) - \frac{1}{2} S_1(t) \sin 2\omega t - \frac{1}{2} S_2(t) \cos 2\omega t$$

低通后 $u_{o2}(t) = \frac{1}{2} S_2(t)$

6.15 (1) 对于二极管有: $i_D = \begin{cases} g_D u_D & u_D > 0 \\ 0 & u_D < 0 \end{cases}$



$$u_D = u_i - u_o$$

$$\cos \varphi = \frac{u_o}{u_m} \quad u_m \sin \omega t \text{ 为输入电压幅度}$$

$$I_o = I_p \cos \varphi = g_D (u_m - u_o) \cos \varphi = g_D u_m \frac{\sin \varphi - \varphi \cos \varphi}{\pi}$$

$$\text{且 } u_o = I_o R$$

$$\text{联立得: } \frac{u_o}{R} = g_D u_m \frac{\sin \varphi - \varphi \cos \varphi}{\pi} \Rightarrow \cos \varphi = g_D R \frac{\sin \varphi - \varphi \cos \varphi}{\pi}$$

$$\Rightarrow \frac{\pi}{g_D R} = \tan \varphi - \varphi$$

$$\text{当 } g_D \text{ 和 } R \text{ 足够大时 } \tan \varphi \approx \varphi + \frac{\varphi^3}{3} \quad (\text{泰勒级数展开})$$

$$\therefore \varphi = \sqrt[3]{\frac{3\pi}{g_D R}}$$

(2) $k_D = \frac{u_o}{u_m} = \cos \varphi$

∵ 不失真 则 $k=1$

$$\tau = R_0 C_0$$

$$\text{不失真条件为 } \left| \frac{du(t)}{dt} \right| \geq \left| \frac{dv(t)}{dt} \right|$$

$$\therefore b(t) = U_i (1 + m \cos \Omega_m t)$$

$$\frac{db(t)}{dt} = -U_i m \Omega_m \sin \Omega_m t$$

对于某一峰值时刻 t_1 $u(t) = U_i (1 + m \cos \Omega_m t) \cos \omega t e^{-\frac{t}{\tau}}$ RC电路的阶跃响应

$$\tau = R_0 C_0 \quad \text{则 } \left| \frac{du(t)}{dt} \right|_{t=t_1} = \frac{U_i \cos \varphi}{\tau} (1 + m \cos \Omega_m t_1)$$

$$\text{而 } \left| \frac{dv(t)}{dt} \right|_{t=t_1} = U_i m \Omega_m \sin \Omega_m t_1$$

$$\therefore \frac{U_i \cos \varphi}{\tau} (1 + m \cos \Omega_m t_1) \geq U_i m \Omega_m \sin \Omega_m t_1$$

$$\Rightarrow \cos \varphi - m \sqrt{\cos^2 \varphi + \tau^2 \Omega_m^2} > 0 \Rightarrow m \leq \left[1 + \left(\frac{\tau^2 \Omega_m^2}{\cos^2 \varphi} \right)^2 \right]^{-\frac{1}{2}}$$