

第2章 信号与系统的时域分析

内容回顾

01 奇异信号概念及其性质

02 系统的基本描述方式

03 系统的互联

04 系统的性质

主要内容

CONTENTS

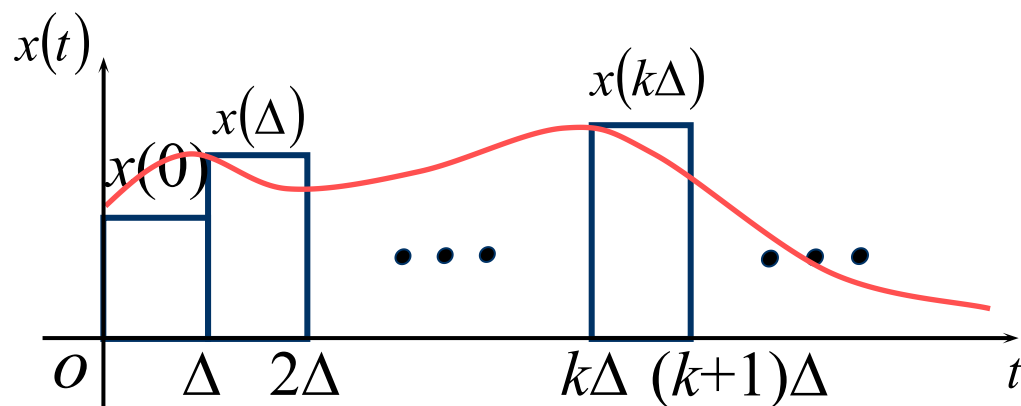
01 理解信号分解的基本思想

02 掌握卷积积分的计算方法及性质

01 时域信号的分解

对子信号的要求

- 完备性: 任意信号都可以分解为该子信号的和;
- 简单性: 容易求得系统对该子信号的响应;
- 相似性: 不同子信号的响应具有内在联系,可以类推。



$$x(t) \approx \hat{x}(t) = \sum_{k=-\infty}^{\infty} x_k(t)$$

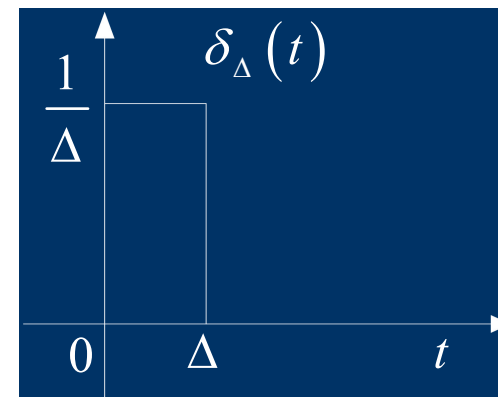
LTI

$$y(t) = \sum_{k=-\infty}^{\infty} y_k(t)$$

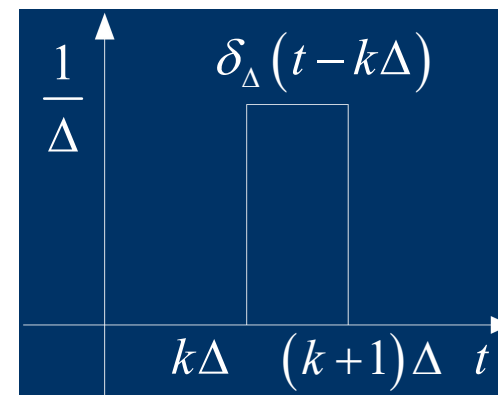


矩形脉冲信号 $\delta_{\Delta}(t)$

$$\delta_{\Delta}(t) = \begin{cases} \frac{1}{\Delta} & 0 < t < \Delta \\ 0 & \text{else} \end{cases}$$



$$\Delta \times \delta_{\Delta}(t - k\Delta) = \begin{cases} 1 & k\Delta < t < (k+1)\Delta \\ 0 & \text{else} \end{cases}$$



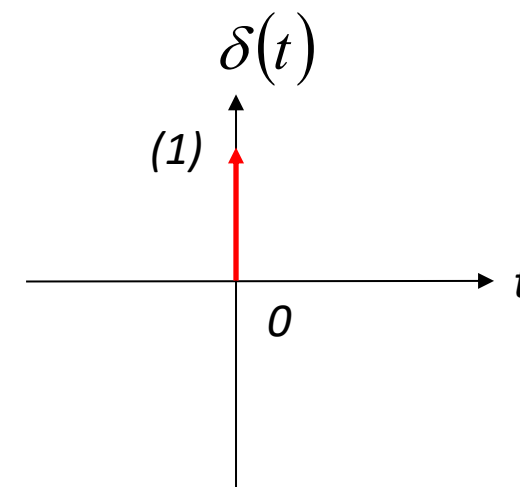
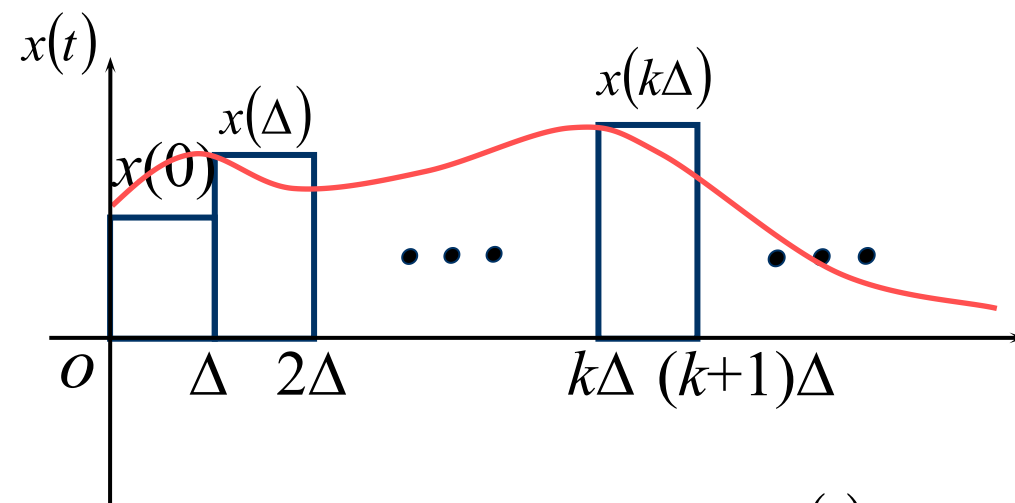
近似函数: $\hat{x}(t) = \sum_{k=-\infty}^{\infty} x(k\Delta) \delta_{\Delta}(t - k\Delta) \times \Delta$



当 $\Delta \rightarrow 0$ 时, $\hat{x}(t) \rightarrow x(t)$, $\delta_{\Delta}(t) \rightarrow \delta(t)$, $\Delta \rightarrow d\tau$, $k\Delta \rightarrow \tau$



$$x(t) = \lim_{\Delta \rightarrow 0} \hat{x}(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$



$$\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0) \quad x(t) \text{ 在 } t_0 \text{ 连续}$$



变量代换: $t \rightarrow \tau, t_0 \rightarrow t$

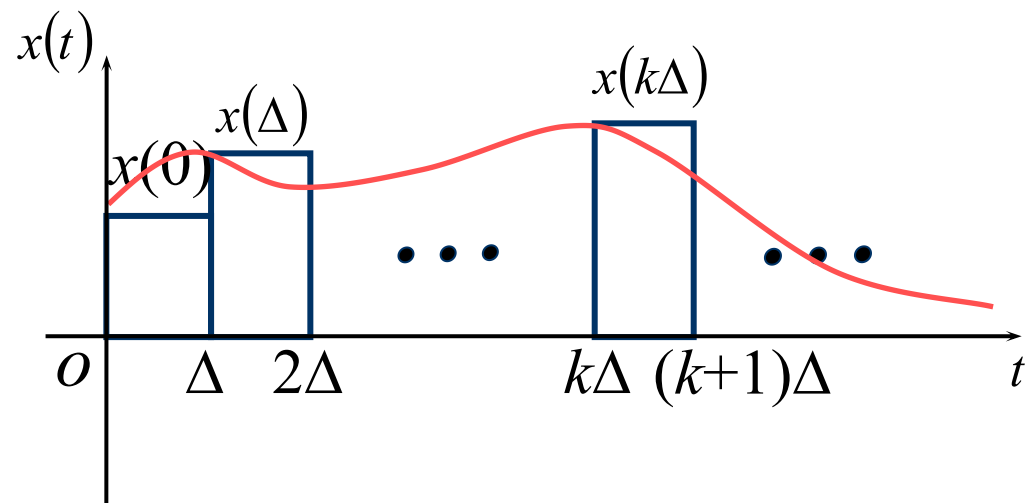
$$\int_{-\infty}^{\infty} x(\tau) \delta(\tau - t) d\tau = x(t)$$



$$\delta(t - \tau) = \delta(\tau - t)$$

$$\int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau = x(t)$$

任意连续时间信号，
均可以**分解**成一系列不同加权的单位冲激信号之和。

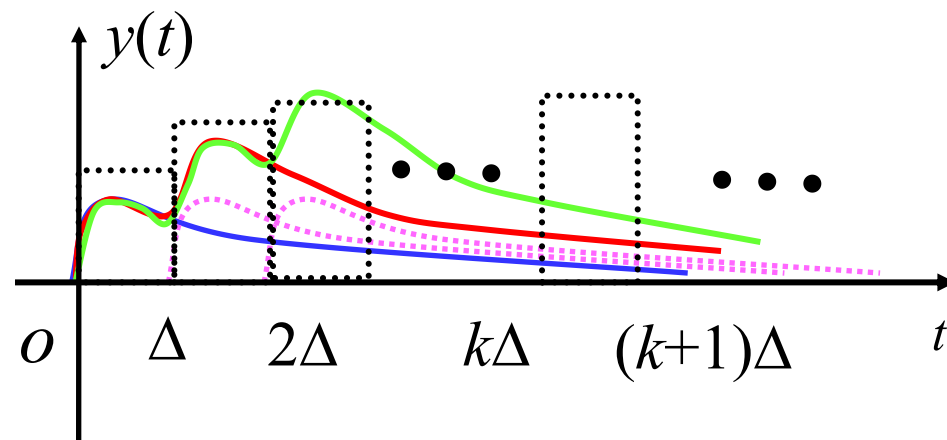


$$\hat{x}(t) = \sum_{k=-\infty}^{\infty} x(k\Delta) \delta_{\Delta}(t - k\Delta) \times \Delta$$

假设：对于LTI系统，单位矩形脉冲信号 $\delta_{\Delta}(t)$ 的输出为 $h_{\Delta}(t)$

$$\hat{x}(t) \rightarrow \hat{y}(t)$$

$$\text{则 } \hat{y}(t) = \sum_{k=-\infty}^{\infty} x(k\Delta) h_{\Delta}(t - k\Delta) \times \Delta$$



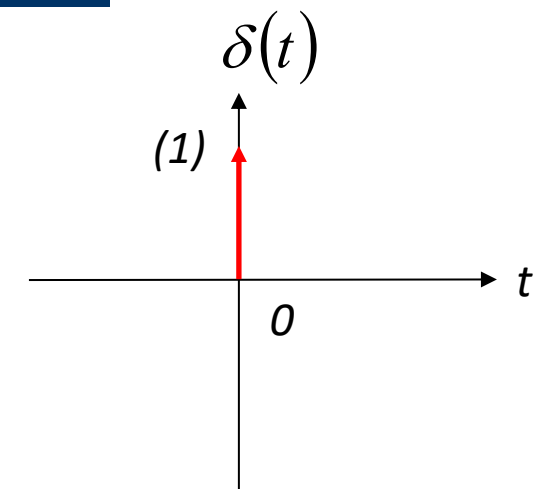
$$\hat{x}(t) = \sum_{k=-\infty}^{\infty} x(k\Delta) \delta_{\Delta}(t-k\Delta) \times \Delta \longrightarrow \hat{y}(t) = \sum_{k=-\infty}^{\infty} x(k\Delta) h_{\Delta}(t-k\Delta) \times \Delta$$

当 $\Delta \rightarrow 0$ 时, $\hat{x}(t) \rightarrow x(t)$, $\delta_{\Delta}(t) \rightarrow \delta(t)$, $\Delta \rightarrow d\tau$, $k\Delta \rightarrow \tau$

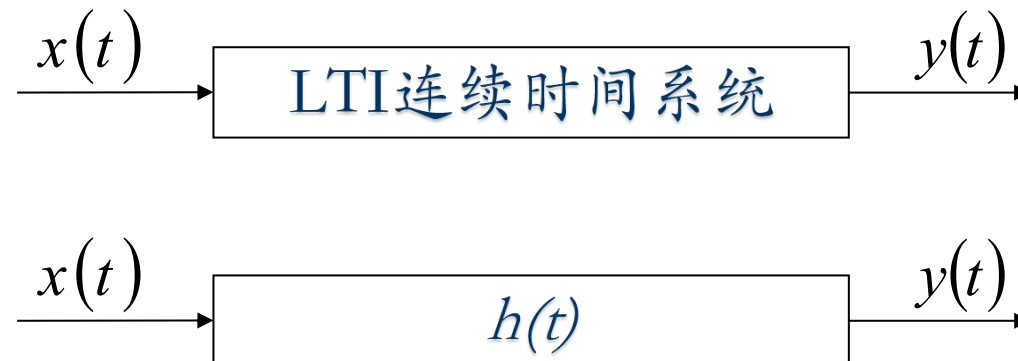
输入信号: $x(t) = \lim_{\Delta \rightarrow 0} \hat{x}(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$
 输出信号: $y(t) = \lim_{\Delta \rightarrow 0} \hat{y}(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$



卷积积分: $y(t) = x(t) * h(t)$



系统抽象表示



系统解析表示

$$y(t) = x(t) * h(t)$$

卷积积分? $h(t)=?$

02 卷积积分

定义

$$f_1(t) * f_2(t) = \int_{-\infty}^{\infty} f_1(\tau) f_2(t - \tau) d\tau$$

因果系统中的定义

$$y(t) = \int_0^t x(\tau) h(t - \tau) d\tau = x(t) * h(t)$$

τ 为积分变量（激励作用时刻）

t 为参变量（观察响应时刻）

解析法：直接根据卷积定义基于积分运算规则计算。

已知：某因果线性时不变系统

$$x(t) = e^{-t}u(t) \quad h(t) = e^{-2t}u(t) \quad \text{求: } y(t)$$

$$\begin{aligned} y(t) &= x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} e^{-\tau} u(\tau) e^{-2(t-\tau)} u(t-\tau) d\tau \\ &= \int_0^t e^{-\tau} e^{-2(t-\tau)} d\tau = e^{-2t} \int_0^t e^{\tau} d\tau \\ &= e^{-2t} e^{\tau} \Big|_0^t = u(t) (e^{-t} - e^{-2t}) \end{aligned}$$

1、变换：改变图形中的横坐标，自变量由 t 变为 τ ；

2、反转：将其中一个信号反转；

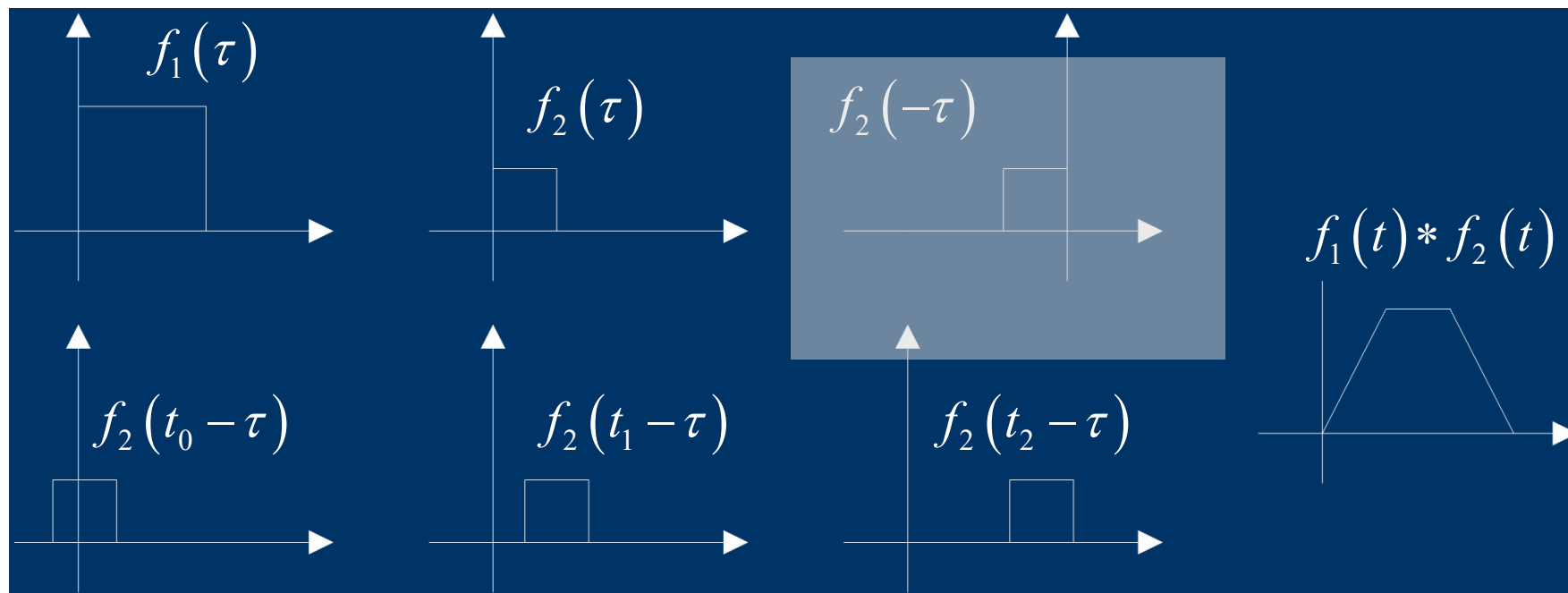
3、平移：反转后的信号随参变量 t 平移，得到 $h(t-\tau)$ ；
(若 $t > 0$ ，则右向平移，若 $t < 0$ ，则左向平移)

4、相乘：将 $x(\tau)$ 与 $h(t-\tau)$ 相乘；

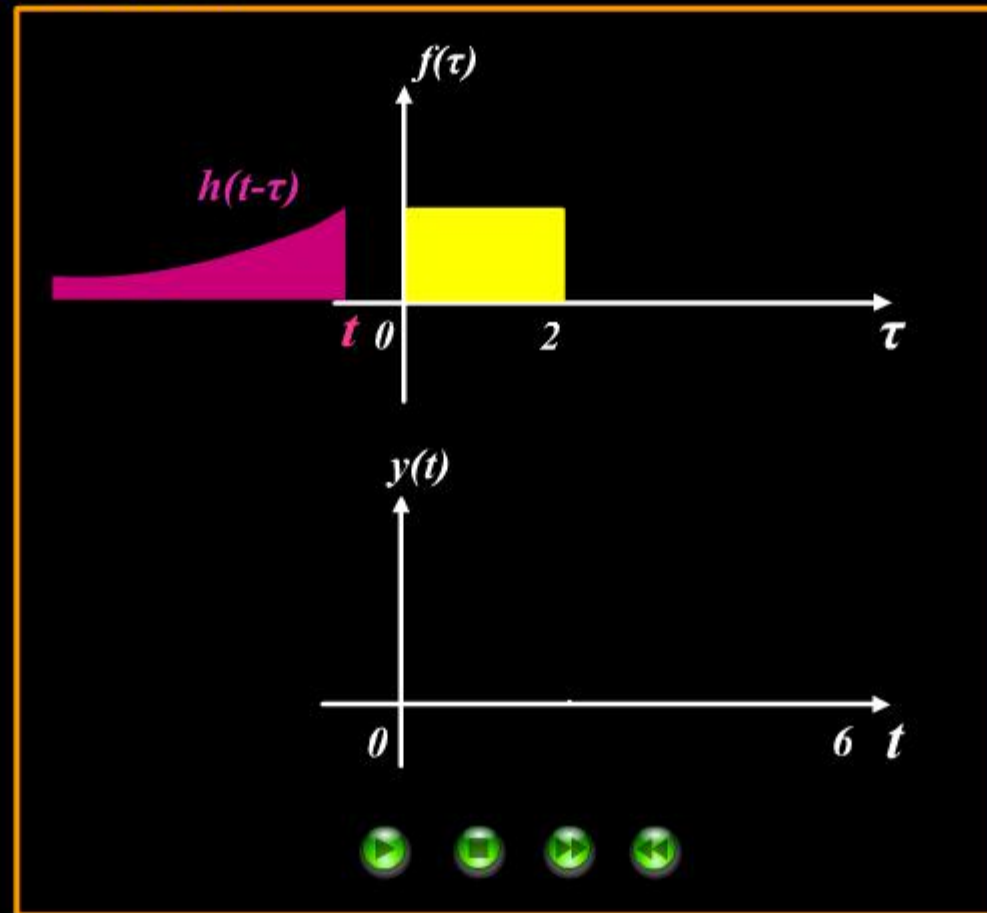
5、积分： $x(\tau)$ 与 $h(t-\tau)$ 乘积曲线下的面积即为 t 时刻的卷积值。

$$f_1(t) = 2[u(t) - u(t-2)], \quad f_2(t) = u(t) - u(t-1)$$

求 $f_1(t) * f_2(t)$



连续卷积



03 卷积之性质

理解基础上善于应用

$$x(t) * h(t) = h(t) * x(t)$$

$$\begin{aligned} x(t) * h(t) &= \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau \\ &= \int_{\infty}^{-\infty} x(t - \lambda) h(\lambda) d(-\lambda) \\ &= \int_{-\infty}^{\infty} h(\lambda) x(t - \lambda) d\lambda = h(t) * x(t) \end{aligned}$$

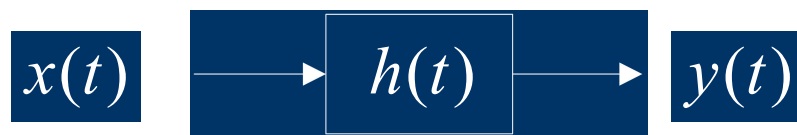
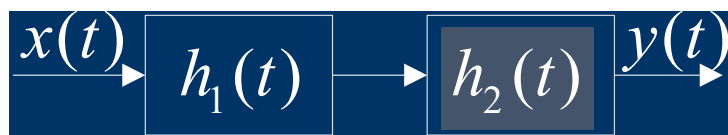
$$\left[x(t) * h_1(t) \right] * h_2(t) = x(t) * \left[h_1(t) * h_2(t) \right]$$

$$\begin{aligned} \left[x(t) * h_1(t) \right] * h_2(t) &= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} x(\tau) h_1(\lambda - \tau) d\tau \right] h_2(t - \lambda) d\lambda \\ &= \int_{-\infty}^{\infty} x(\tau) \left[\int_{-\infty}^{\infty} h_1(\lambda - \tau) h_2(t - \lambda) d\lambda \right] d\tau \\ &= \int_{-\infty}^{\infty} x(\tau) \left[\int_{-\infty}^{\infty} h_1(\rho) h_2(t - \tau - \rho) d\rho \right] d\tau \\ &= \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau = x(t) * h(t) \end{aligned}$$

$$h(t - \tau) = \int_{-\infty}^{\infty} h_1(\rho) h_2(t - \tau - \rho) d\rho$$

$$\Downarrow$$

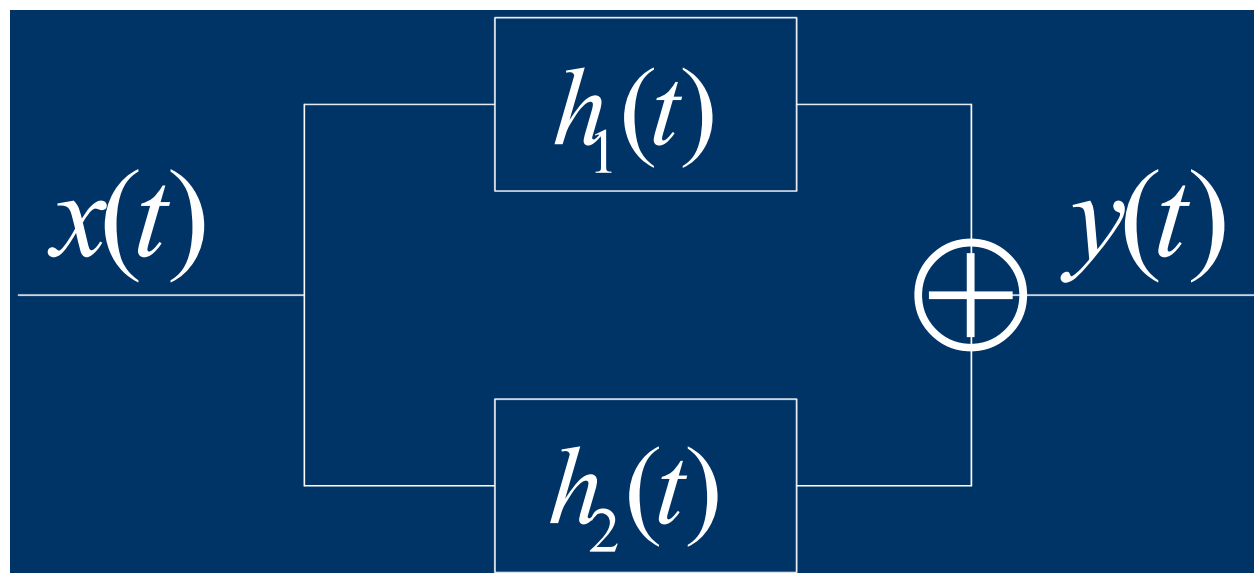
$$h(t) = \int_{-\infty}^{\infty} h_1(\rho) h_2(t - \rho) d\rho = h_1(t) * h_2(t)$$



- 串联系统的冲激响应，**等于**各子系统冲激响应之卷积
- 串联系统与子系统次序无关

$$x(t) * [h_1(t) + h_2(t)] = x(t) * h_1(t) + x(t) * h_2(t)$$

$$\begin{aligned} x(t) * [h_1(t) + h_2(t)] &= \int_{-\infty}^{\infty} x(\tau) [h_1(t - \tau) + h_2(t - \tau)] d\tau \\ &= \int_{-\infty}^{\infty} x(\tau) h_1(t - \tau) d\tau + \int_{-\infty}^{\infty} x(\tau) h_2(t - \tau) d\tau \\ &= x(t) * h_1(t) + x(t) * h_2(t) \end{aligned}$$



并联系统等效单位冲激响应： $h(t) = h_1(t) + h_2(t) + \dots$

一个并联系统的冲激响应等于各个子系统冲激响应之和

$$\frac{d}{dt} [x(t) * h(t)] = \frac{dx(t)}{dt} * h(t) = x(t) * \frac{dh(t)}{dt}$$

$$\begin{aligned} \frac{d}{dt} [x(t) * h(t)] &= \frac{d}{dt} \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau \\ &= \int_{-\infty}^{\infty} x(\tau) \frac{d}{dt} h(t - \tau) d\tau \\ &= x(t) * \frac{d}{dt} h(t) \end{aligned}$$

$$\begin{aligned}\int_{-\infty}^t [x(\lambda) * h(\lambda)] d\lambda &= \left[\int_{-\infty}^t x(\lambda) d\lambda \right] * h(t) \\ &= x(t) * \left[\int_{-\infty}^t h(\lambda) d\lambda \right]\end{aligned}$$

$$\begin{aligned}\int_{-\infty}^t [x(\lambda) * h(\lambda)] d\lambda &= \int_{-\infty}^t \left[\int_{-\infty}^{\infty} x(\tau) h(\lambda - \tau) d\tau \right] d\lambda \\ &= \int_{-\infty}^{\infty} x(\tau) \left[\int_{-\infty}^t h(\lambda - \tau) d\lambda \right] d\tau \\ &= \int_{-\infty}^{\infty} x(\tau) \left[\int_{-\infty}^{t-\tau} h(\lambda) d\lambda \right] d\tau \\ &= x(t) * \left[\int_{-\infty}^t h(\lambda) d\lambda \right]\end{aligned}$$

$$y(t) = x(t) * h(t)$$

$$= \frac{dx(t)}{dt} * \left[\int_{-\infty}^t h(\lambda) d\lambda \right]$$

$$x(-\infty) = 0 \text{ 或 } h_{-1}(\infty) = 0$$

$$= \left[\int_{-\infty}^t x(\lambda) d\lambda \right] * \frac{dh(t)}{dt}$$

$$h(-\infty) = 0 \text{ 或 } x_{-1}(\infty) = 0$$

信号与冲激函数的卷积

$$\begin{aligned}x(t) * \delta(t) &= \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau \\&= \int_{-\infty}^{\infty} x(\tau) \delta(\tau - t) d\tau \\&= x(t)\end{aligned}$$

信号与冲激函数的卷积-时移

$$\begin{aligned}x(t) * \delta(t - t_0) &= \int_{-\infty}^{\infty} x(\tau) \delta(t - t_0 - \tau) d\tau \\ &= x(t - t_0)\end{aligned}$$

$$\begin{aligned}x(t - t_1) * \delta(t - t_2) &= \int_{-\infty}^{\infty} x(\tau - t_1) \delta(t - \tau - t_2) d\tau \\ &= x(t - t_1 - t_2)\end{aligned}$$

若: $x(t) * h(t) = y(t)$

则: $x(t - t_1) * h(t - t_2) = y(t - t_1 - t_2)$

信号与阶跃函数的卷积

$$\begin{aligned}x(t) * u(t) &= x(t) * \int_{-\infty}^t \delta(\tau) d\tau \\&= \int_{-\infty}^t x(\tau) d\tau * \delta(t) \\&= \int_{-\infty}^t x(\tau) d\tau\end{aligned}$$


$$u(t) * u(t) = tu(t)$$



例

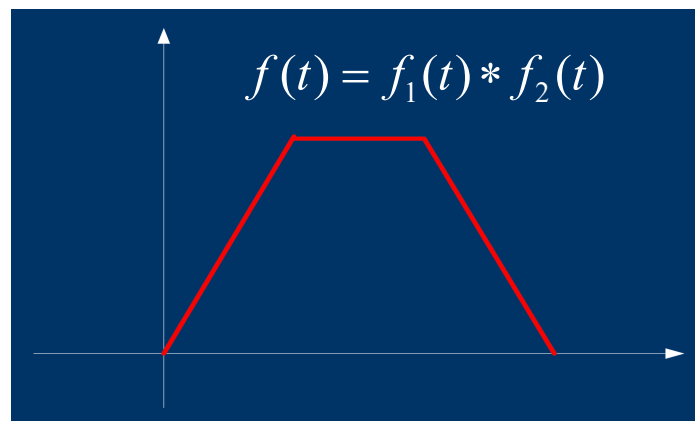
$$f_1(t) = 2[u(t) - u(t-2)], \quad f_2(t) = u(t) - u(t-1)$$

$$\text{求 } f(t) = f_1(t) * f_2(t)$$

$$\begin{aligned} & 2[u(t) - u(t-2)] * [u(t) - u(t-1)] \\ &= 2[u(t) * u(t) - u(t) * u(t-1) - u(t-2) * u(t) + u(t-2) * u(t-1)] \end{aligned}$$

$$= 2[tu(t) - (t-1)u(t-1) - (t-2)u(t-2) + (t-3)u(t-3)]$$

$$\begin{cases} t \leq 0 & f(t) = 0 \\ 0 < t \leq 1 & f(t) = 2t \\ 1 < t \leq 2 & f(t) = 2 \\ 2 < t \leq 3 & f(t) = 6 - 2t \\ 3 < t & f(t) = 0 \end{cases}$$

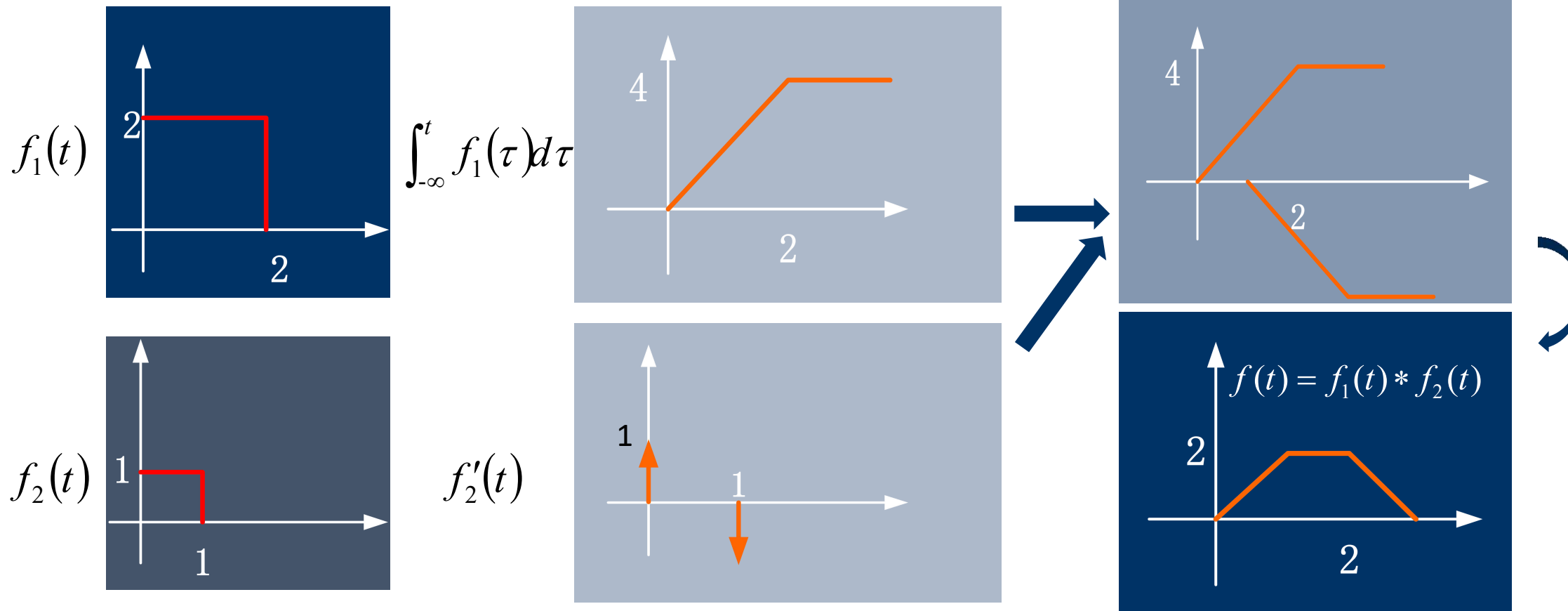




例

$$f_1(t) = 2[u(t) - u(t-2)], \quad f_2(t) = u(t) - u(t-1)$$

求 $f(t) = f_1(t) * f_2(t)$



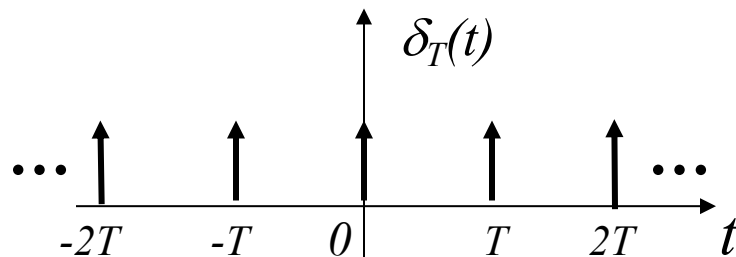
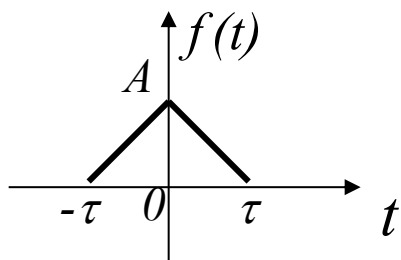


例

$\delta_T(t)$ 为周期为 T 的周期性单位冲激函数序列

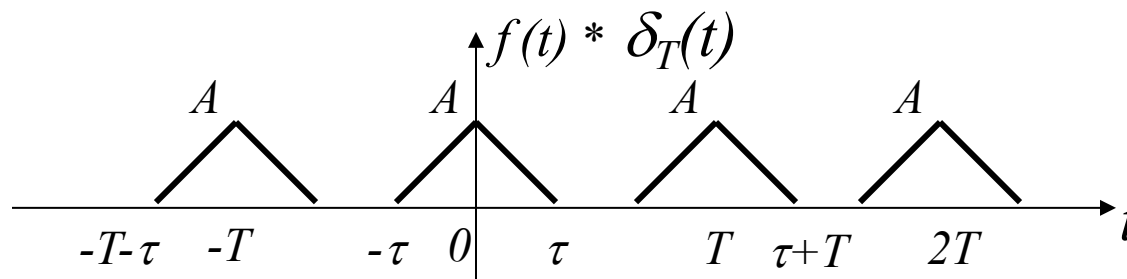
$$\delta_T(t) = \sum_{k=-\infty}^{\infty} \delta(t + kT) = \delta(t) + \delta(t + T) + \delta(t + 2T) + \cdots + \delta(t + kT) + \cdots$$

$f(t)$ 如图所示, 试求 $f(t) * \delta_T(t)$



$$f(t) * \delta(t) = \int_{-\infty}^{\infty} f(\tau) \delta(t - \tau) d\tau$$

$$f(t) * \delta(t - T) = f(t - T)$$



作业

2.4 (a)(c)

2.5 (b)(d)