

Diffusion and Strategic Interaction on Social Networks



Leeat Yariv

Jerusalem Summer School, June 28, 2016

Questions:

- How do *choices* to invest in education, learn a language, etc., depend on social network structure and location within a network?

Questions:

- How do choices to invest in education, learn a language, etc., depend on social network structure and location within a network?
 - How does network structure impact behavior and welfare?
 - How does relative location in a network impact behavior and welfare?

Questions:

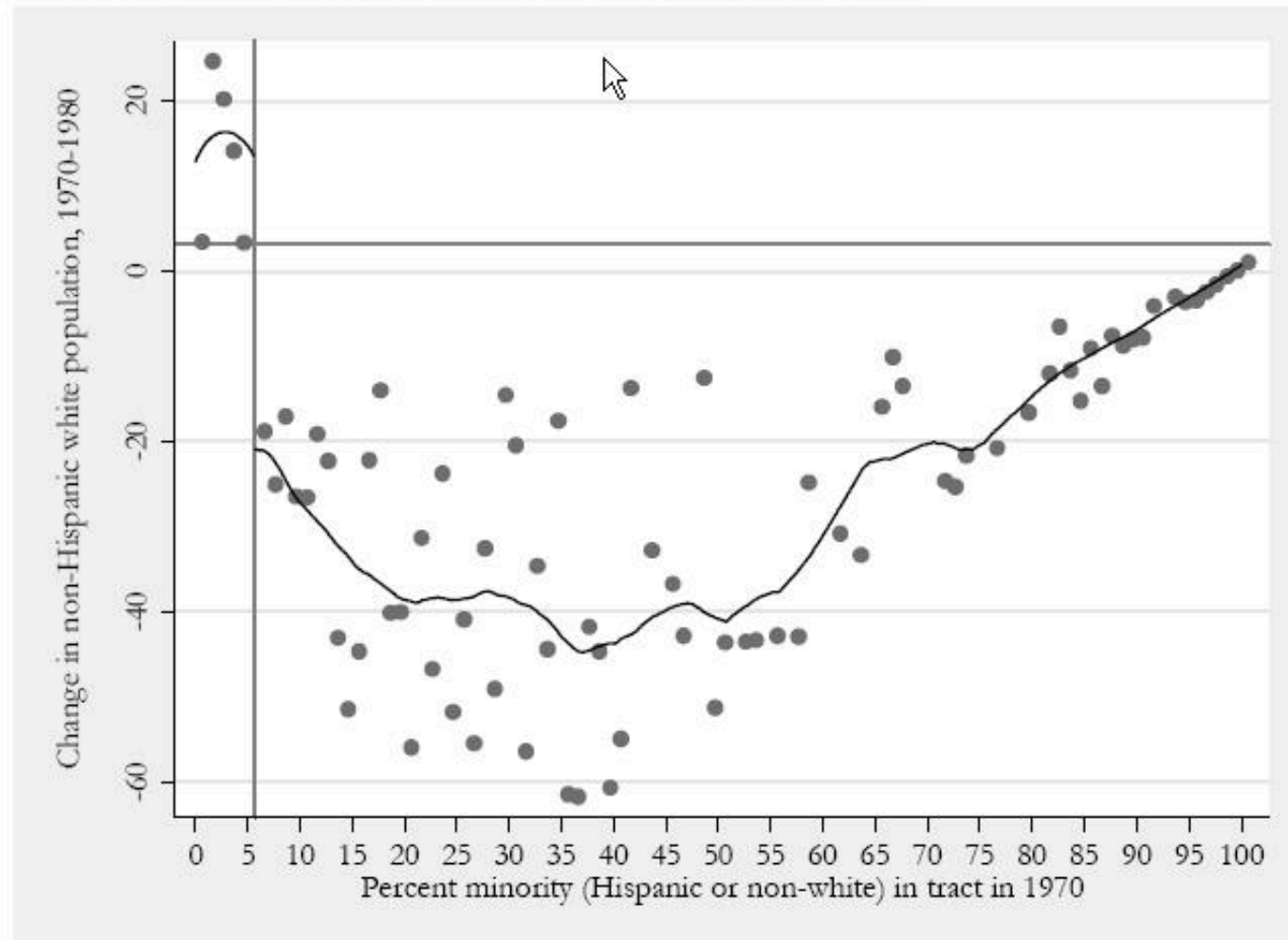
- How do choices to invest in education, learn a language, etc., depend on social network structure and location within a network?
 - How does network structure impact behavior and welfare?
 - How does relative location in a network impact behavior and welfare?
- How does behavior propagate through networks (important for marketing, epidemiology, etc.)?

Choices without Networks: Some History

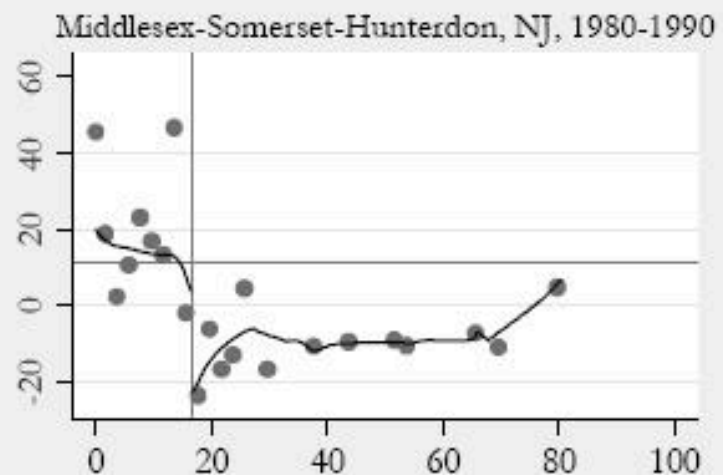
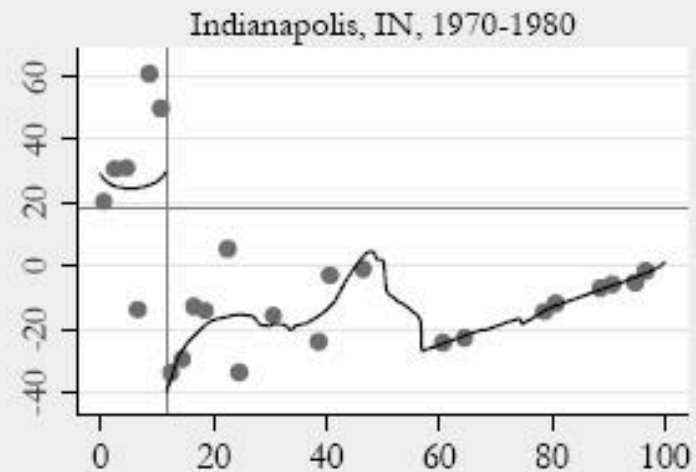
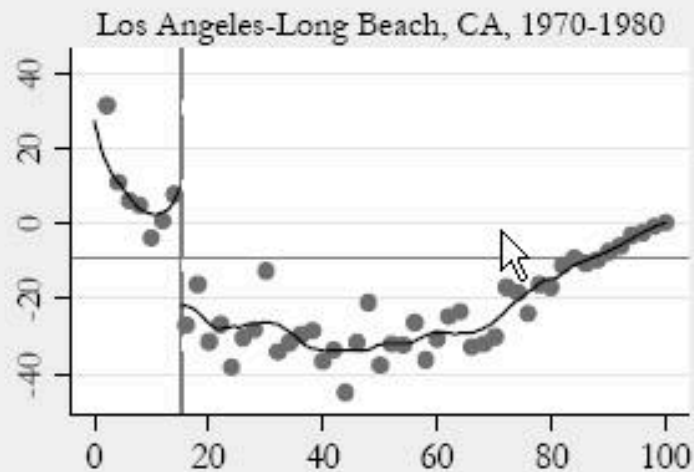
- Morton Grodzins (1957) coined the term *tipping point* when explaining white flight
- **Tipping Point:** A time in which a large number of individuals rapidly and dramatically change behavior

Card, Mas, and Rothstein (2008)

Figure 1: Neighborhood change in Chicago, 1970-1980

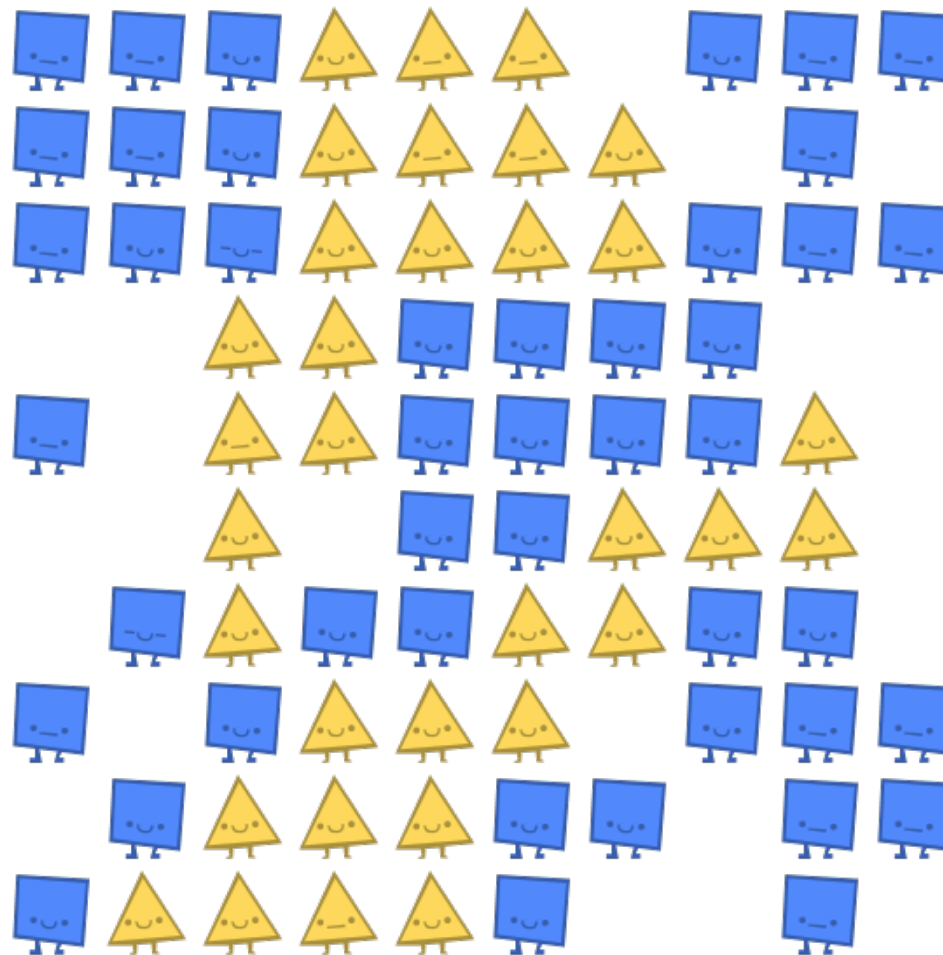


In Other Cities as Well



Schelling (1969, 1971)

□ “A general theory of tipping”



Granovetter (1978): Threshold Models of Collective Behavior

- ▣ N agents, all connected
- ▣ Each chooses an action 0 or 1

Granovetter (1978): Threshold Models of Collective Behavior

- N agents, all connected
- Each chooses an action 0 or 1
- When agent i faces a profile (x_1, x_2, \dots, x_n) ,

$$u_i(x_1, \dots, x_N) = \left[\frac{\sum_{j \neq i} x_j}{N-1} - c_i \right] x_i$$

- c_i is cost of choosing 1, distributed according to a continuous F over $[0,1]$

Granovetter (1978): Threshold Models of Collective Behavior

- N agents, all connected
- Each chooses an action 0 or 1
- When agent i faces a profile (x_1, x_2, \dots, x_n) ,

$$u_i(x_1, \dots, x_N) = \left[\frac{\sum_{j \neq i} x_j}{N-1} - c_i \right] x_i$$

- c_i is cost of choosing 1, distributed according to a continuous F over $[0,1]$
(could be privately or commonly known)
(analogous to random thresholds)

Granovetter (1978)

- ▣ Assume at each stage agents best respond to previous period's action distribution

Granovetter (1978)

- Assume at each stage agents best respond to previous period's action distribution
- Suppose at period t a fraction x^t choose 1
- At period $t+1$, adopt \leftrightarrow

$$\frac{Nx^t - x_i^t}{N-1} \geq c_i$$

- For N large,

$$\frac{Nx^t - x_i^t}{N-1} \approx x^t$$

Equilibrium in Granovetter

- ▣ Approximated transition formula:

$$x^{t+1} \approx F(x^t)$$

- ▣ A fixed point $x^* = F(x^*)$ is an equilibrium

Equilibrium in Granovetter

- Approximated transition formula:

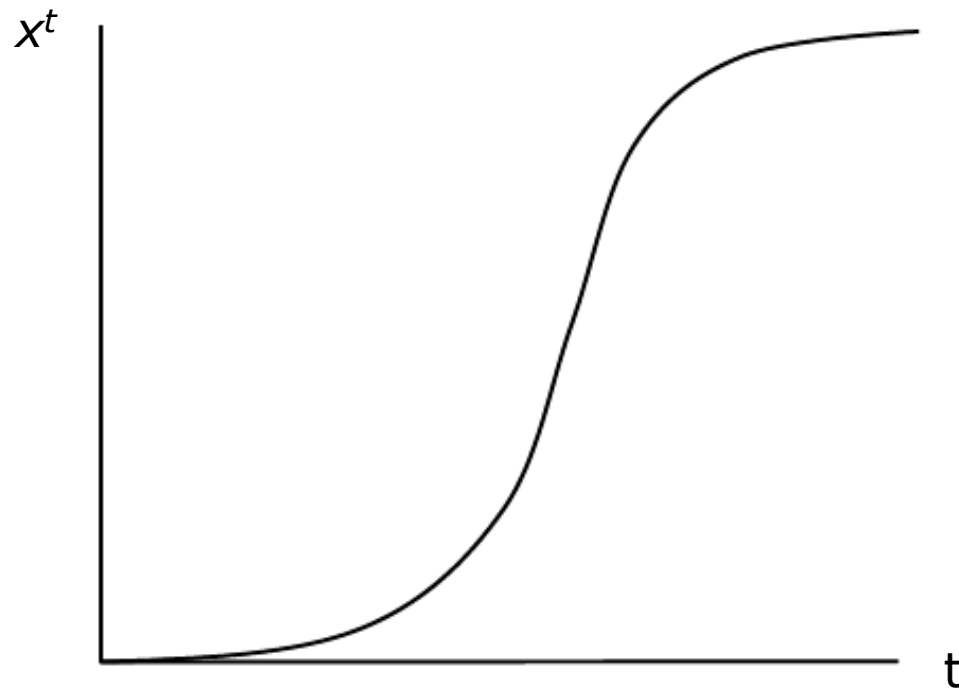
$$x^{t+1} \approx F(x^t)$$

- A fixed point $x^* = F(x^*)$ is an equilibrium
- The shape of F determines which equilibria are tipping points (more formal soon)
- [Contrast with Bass' $F(t)$]

S-shape Adoption in Granovetter (1978)

□ Level of change:

$$\Delta(x^t) = F(x^t) - x^t$$



S-shape Adoption in Granovetter (1978)

- Level of change:

$$\Delta(x^t) = F(x^t) - x^t$$

- Assume F differentiable
- The derivative of $F(x)-x$ is $F'(x)-1$
- S-shape $\rightarrow F'(x) > 1$ up to some point and $F'(x) < 1$ afterwards

Introducing Networks

- ❑ So far, no networks
- ❑ How does network architecture affect diffusion?
- ❑ How does location within a network affect diffusion (recall the adoption of Tetracycline...)?

Example - Experimentation

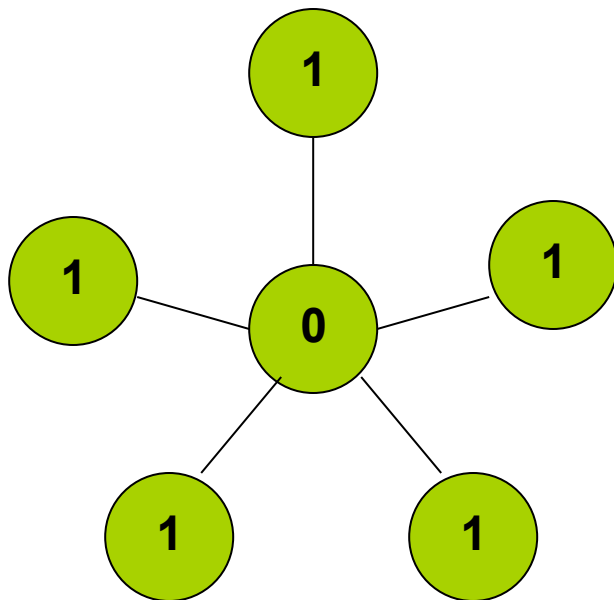
Knowing the Network Structure

- ▣ Suppose you gain 1 if anyone experiments, 0 otherwise, but experimentation is costly (grains, software, etc.)

Example - Experimentation

- Suppose you gain 1 if anyone experiments, 0 otherwise, but experimentation is costly (grains, software, etc.)
EXPERIMENTATION – 1
NO EXPERIMENTATION - 0

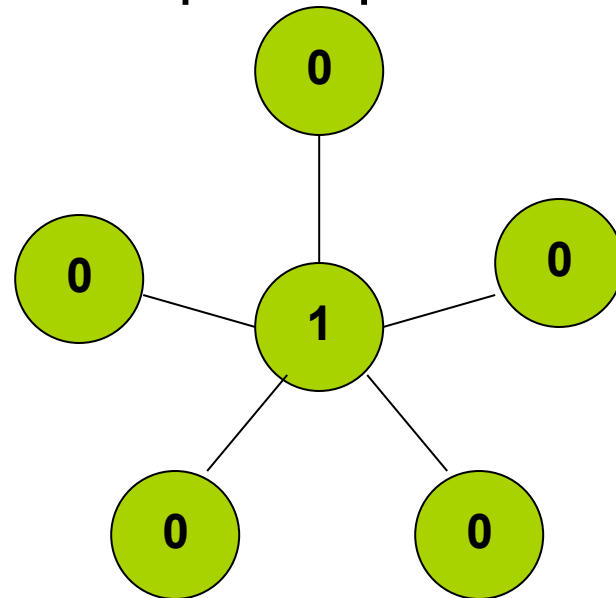
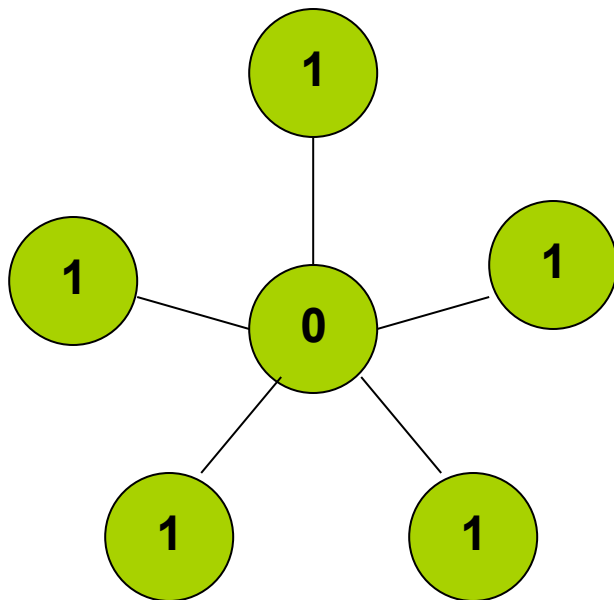
- Network structure known



Example - Experimentation

- Suppose you gain 1 if anyone experiments, 0 otherwise, but experimentation is costly (grains, software, etc.)
EXPERIMENTATION – 1
NO EXPERIMENTATION – 0

- Network structure known – multiple equilibria:





Example – Experimentation (2)

Not knowing the structure

Example – Experimentation (2)

Not knowing the structure

- ▣ Probability p of a link between any two agents (Poisson..)

Example – Experimentation (2)

Not knowing the structure

- ▣ Probability p of a link between any two agents
- ▣ Symmetry

Example – Experimentation (2)

Not knowing the structure

- Probability p of a link between any two agents.
- Symmetry
- Probability that a neighbor experiments independent of own degree (number of neighbors)
 - → Higher degree less willing to choose 1
 - → Threshold equilibrium: low degrees experiment, high degrees do not.

Example – Experimentation (2)

Not knowing the structure

- Probability p of a link between any two agents.
- Symmetry
- Probability that a neighbor experiments independent of own degree (number of neighbors)
 - \rightarrow Higher degree less willing to choose 1
 - \rightarrow Threshold equilibrium: low degrees experiment, high degrees do not.
- Strong dependence on p
 - $p=0 \rightarrow$ all choose 1,
 - $p=1 \rightarrow$ all choose 1 with probability $1 - c^{1/(n-1)}$



General Messages

□ **Information Matters**

General Messages

□ Information Matters

□ **Location Matters**

- Monotonicity with respect to degrees
 - Regarding behavior (complementarities...)
 - Regarding expected benefits (externalities...)

General Messages

- Information Matters
- Location Matters
 - Monotonicity with respect to degrees
 - Regarding behavior (complementarities...)
 - Regarding expected benefits (externalities...)
- **Network Structure Matters**
 - Adding links affects behavior monotonically (complementarities...)
 - Increasing heterogeneity?

Challenge

- ❑ Complexity of networks
- ❑ Tractable way to study behavior outside of simple (regular structures)?

Focus on key characteristics:

- Degree Distribution
- How connected is the network?
 - average degree, FOSD shifts
- How are links distributed across agents?
 - variance, skewness, etc.

Network Games – Payoff Structure

- ▣ Actions in $\{0,1\}$

Network Games – Payoff Structure

- ▣ Actions in $\{0,1\}$
- ▣ **Action 0:** Normalize payoff to 0

Network Games – Payoff Structure

- Actions in $\{0,1\}$
- **Action 0:** Normalize payoff to 0
- **Action 1:** payoffs depend on number of neighbors choosing 1

Network Games – Payoff Structure

- Actions in $\{0,1\}$
- **Action 0**: Normalize payoff to 0
- **Action 1**: payoffs depend on number of neighbors choosing 1
- $v(d,x) - c_i$ payoff from choosing 1 if degree is d and a fraction x of neighbors choose 1
- c_i distributed according to H , with no atoms

Examples (payoff: $v(d,x)-c$)

- ❑ **Average Action:** $v(d,x)=v(d)x= x$
(classic coordination games, choice of technology)
- ❑ **Total Number:** $v(d,x)=v(d)x=dx$
(learn a new language, need partners to use new good or technology, need to hear about it to learn)
- ❑ **Critical Mass:** $v(d,x)=0$ for x up to some M/d and $v(d,x)=1$ above M/d
(uprising, voting, ...)
- ❑ **Decreasing:** $v(d,x)$ declining in d
(information aggregation, lower degree correlated with leaning towards adoption)

Network Games – Information

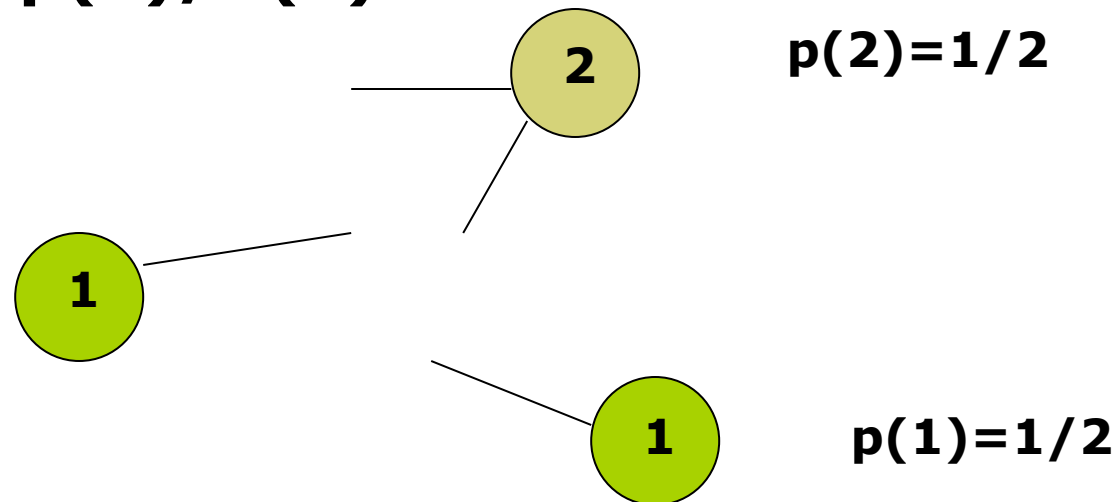
- (today) Incomplete information
 - know only own degree and assume others' types are governed by degree distribution
 - presume no correlation in degree
 - Bayesian equilibrium – as function of degree

Incomplete Information

- g drawn from some set of networks G such that (assuming large population):
 - degrees of neighbors are independent
 - Probability of any node having degree d is $p(d)$
 - probability of given neighbor having degree d is **$P(d) = dp(d)/E(d)$**

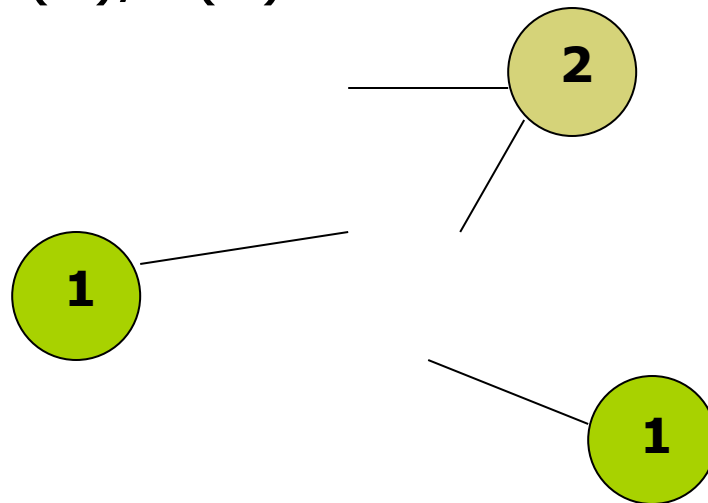
Incomplete Information

- g drawn from some set of networks G such that (assuming large population):
 - degrees of neighbors are independent
 - Probability of any node having degree d is $p(d)$
 - probability of given neighbor having degree d is $P(d) = dp(d)/E(d)$



Incomplete Information

- g drawn from some set of networks G such that (assuming large population):
 - degrees of neighbors are independent
 - Probability of any node having degree d is $p(d)$
 - probability of given neighbor having degree d is $P(d) = dp(d)/E(d)$



Probability of hitting **2** is twice as high as that of hitting **1** → **$P(2)=2/3$** .

Incomplete Information

- g drawn from some set of networks G such that:
 - degrees of neighbors are independent
 - Probability of any node having degree d is $p(d)$
 - probability of given neighbor having degree d is $P(d) = dp(d)/E(d)$
- type of i is $(d_i(g), c_i)$; space of types T_i

Incomplete Information

- g drawn from some set of networks G such that:
 - degrees of neighbors are independent
 - Probability of any node having degree d is $p(d)$
 - probability of given neighbor having degree d is $P(d) = dp(d)/E(d)$
- type of i is $(d_i(g), c_i)$; space of types T_i
- strategy: $\sigma_i: T_i \rightarrow \Delta(X)$

Equilibrium as a fixed point:

- Adopt if and only if $v(d,x) - c_i \geq 0$
- $H(v(d,x))$ is the percent of degree d types adopting action 1 if x is fraction of random neighbors adopting

Equilibrium as a fixed point:

- Adopt if and only if $v(d, x) - c_i \geq 0$
- $H(v(d, x))$ is the percent of degree d types adopting action 1 if x is fraction of random neighbors adopting
- Equilibrium corresponds to a fixed point:
$$\mathbf{x} = \boldsymbol{\varphi}(\mathbf{x}) = \sum \mathbf{P}(\mathbf{d}) H(\mathbf{v}(\mathbf{d}, \mathbf{x}))$$
$$= \sum \mathbf{d} p(\mathbf{d}) H(\mathbf{v}(\mathbf{d}, \mathbf{x})) / E[\mathbf{d}]$$

Equilibrium as a fixed point:

- $H(v(d,x))$ is the percent of degree d types adopting action 1 if x is fraction of random neighbors adopting
- Equilibrium corresponds to a fixed point:
$$x = \varphi(x) = \sum P(d) H(v(d,x))$$
- **v continuous in $x \rightarrow$ fixed point exists**

Monotone Behavior

Observation 1:

In a game of incomplete information, every symmetric equilibrium is monotone

- ▣ Non-decreasing in degree if $v(d,x)$ is increasing in d
- ▣ Non-increasing in degree if $v(d,x)$ is decreasing in d

Monotone Behavior

Intuition

- Symmetric equilibrium – a random neighbor has probability x of choosing 1, probability $1-x$ of choosing 0

Monotone Behavior

Intuition

- Symmetric equilibrium – a random neighbor has probability x of choosing 1, probability $1-x$ of choosing 0
- Consider agent of degree $d+1$
 - $v(d,x)$ non-decreasing \rightarrow payoff from 1 is $v(d+1,x) \geq v(d,x)$
 - $v(d,x)$ non-increasing \rightarrow payoff from 1 is $v(d+1,x) \leq v(d,x)$

Diffusion

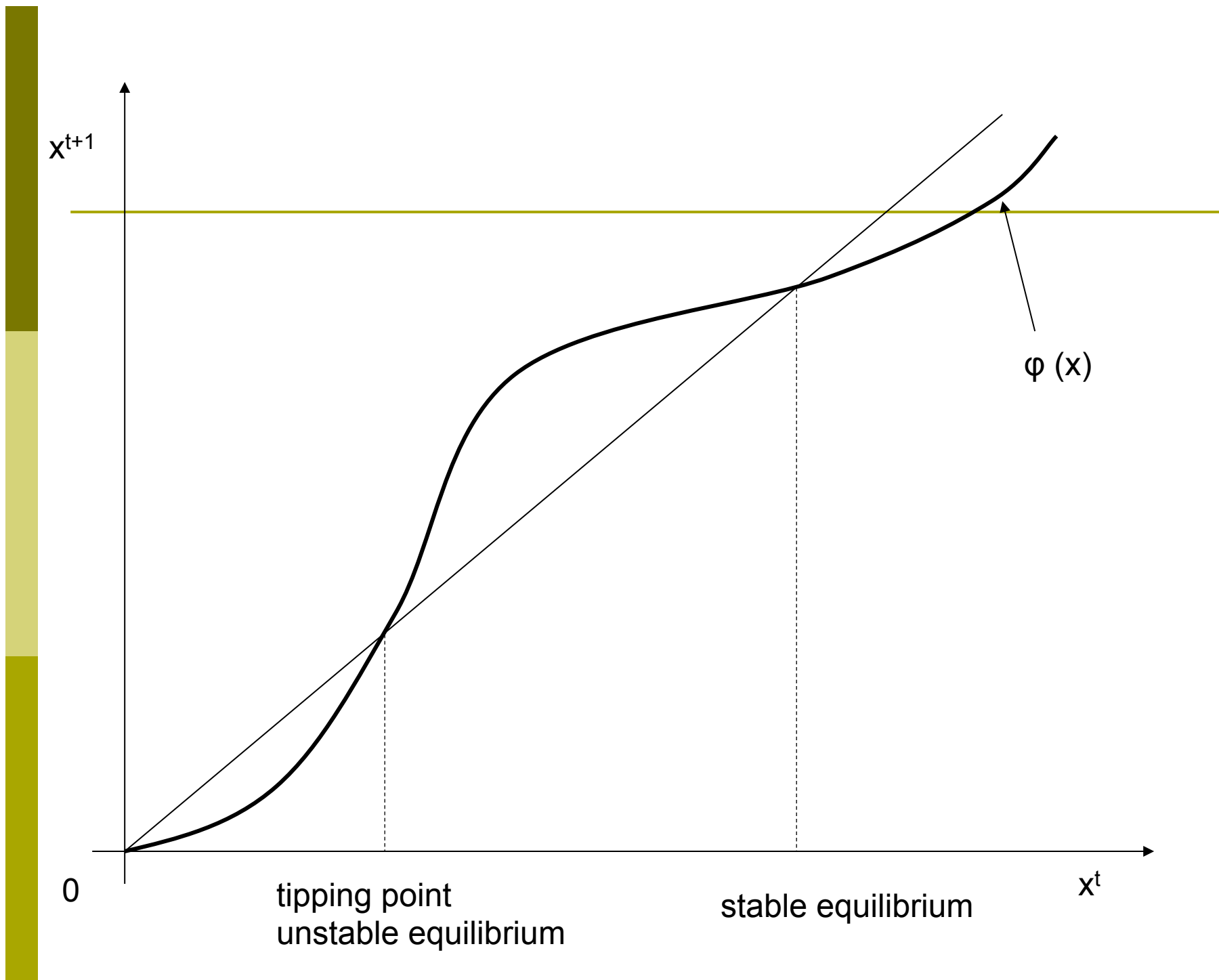
$$\mathbf{x} = \boldsymbol{\varphi}(\mathbf{x}) = \sum \mathbf{P}(\mathbf{d}) \mathbf{H}(\mathbf{v}(\mathbf{d}, \mathbf{x}))$$

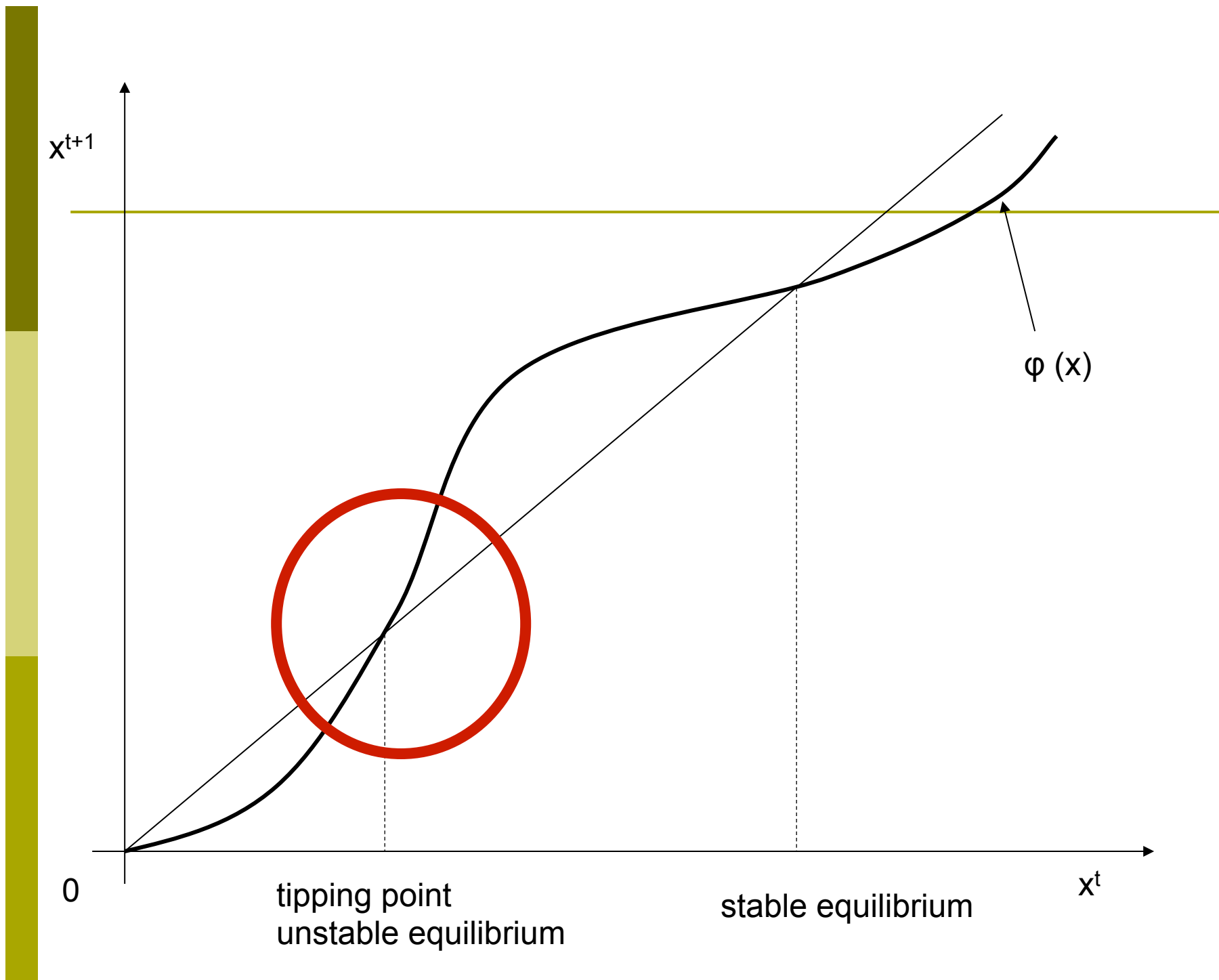
- start with some x^0
- let $x^1 = \boldsymbol{\varphi}(x^0)$, $x^t = \boldsymbol{\varphi}(x^{t-1})$, ...

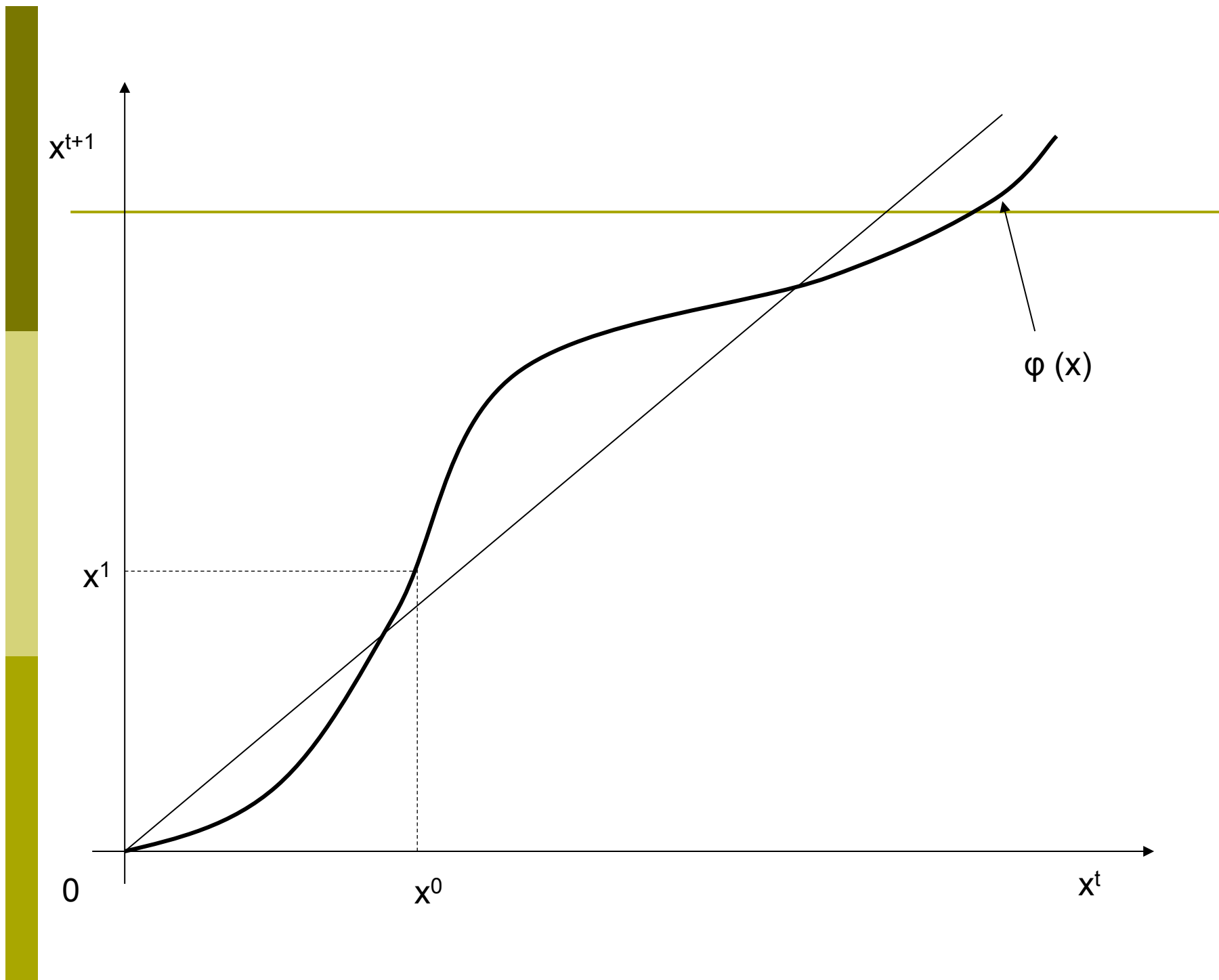
Diffusion

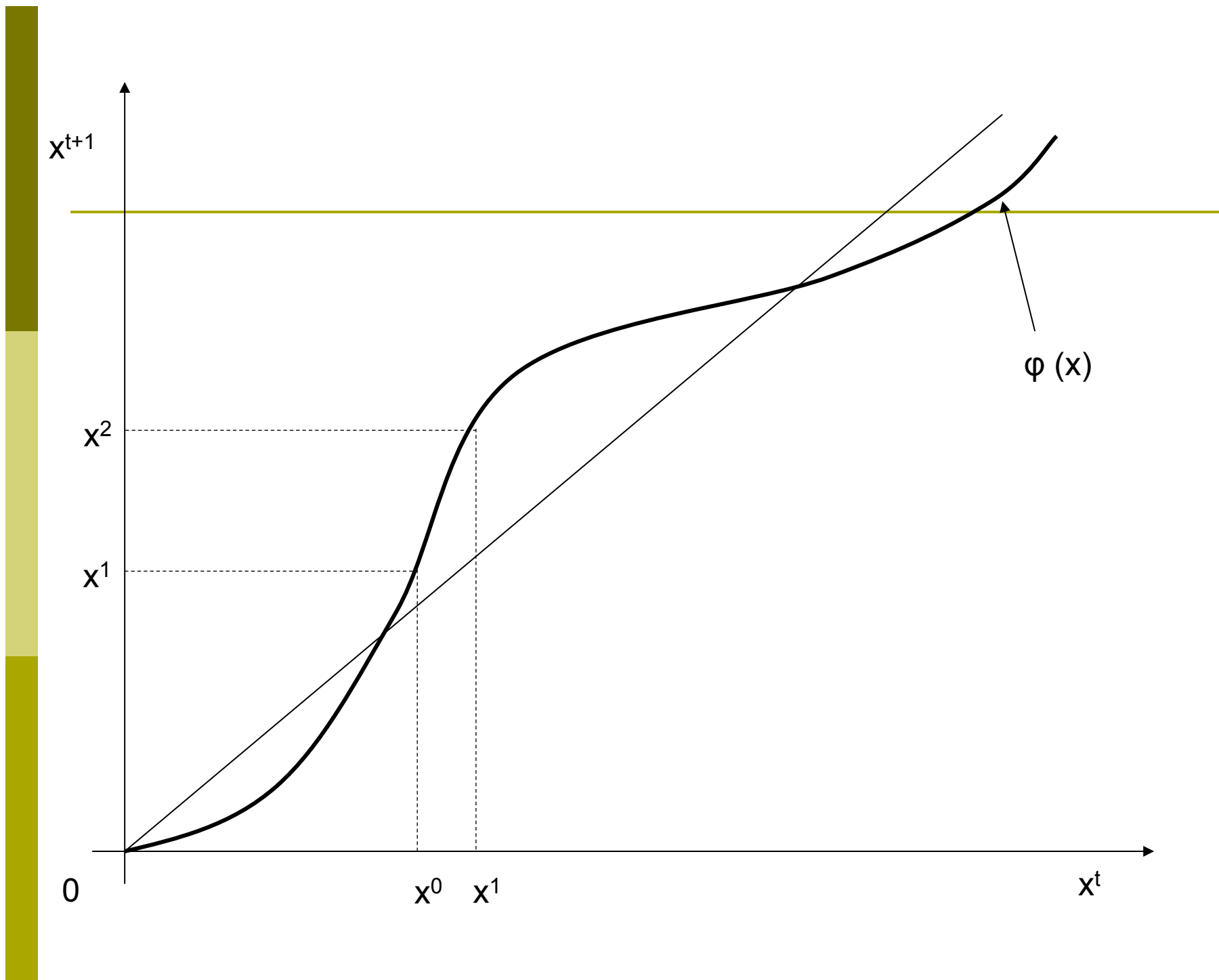
$$\mathbf{x} = \boldsymbol{\varphi}(\mathbf{x}) = \sum \mathbf{P}(\mathbf{d}) \mathbf{H}(\mathbf{v}(\mathbf{d}, \mathbf{x}))$$

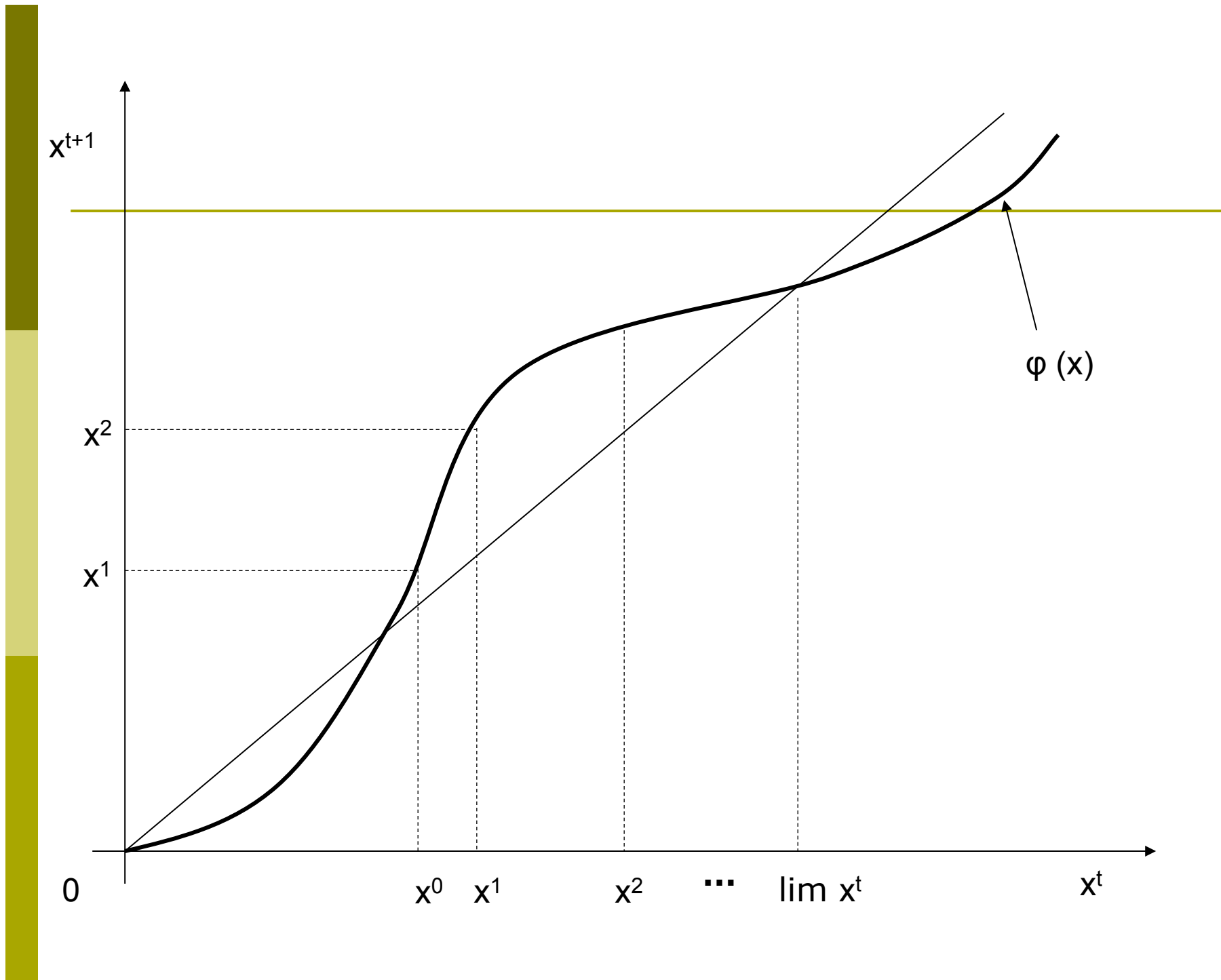
- start with some x^0
- let $x^1 = \varphi(x^0)$, $x^t = \varphi(x^{t-1})$, ...
- **Interpretations**
 - examining equilibrium set with incomplete information
 - Stable equilibria are converged to from above and below
 - looking at diffusion: best response dynamics on “large, well-mixed” social network (mean-field approximation)

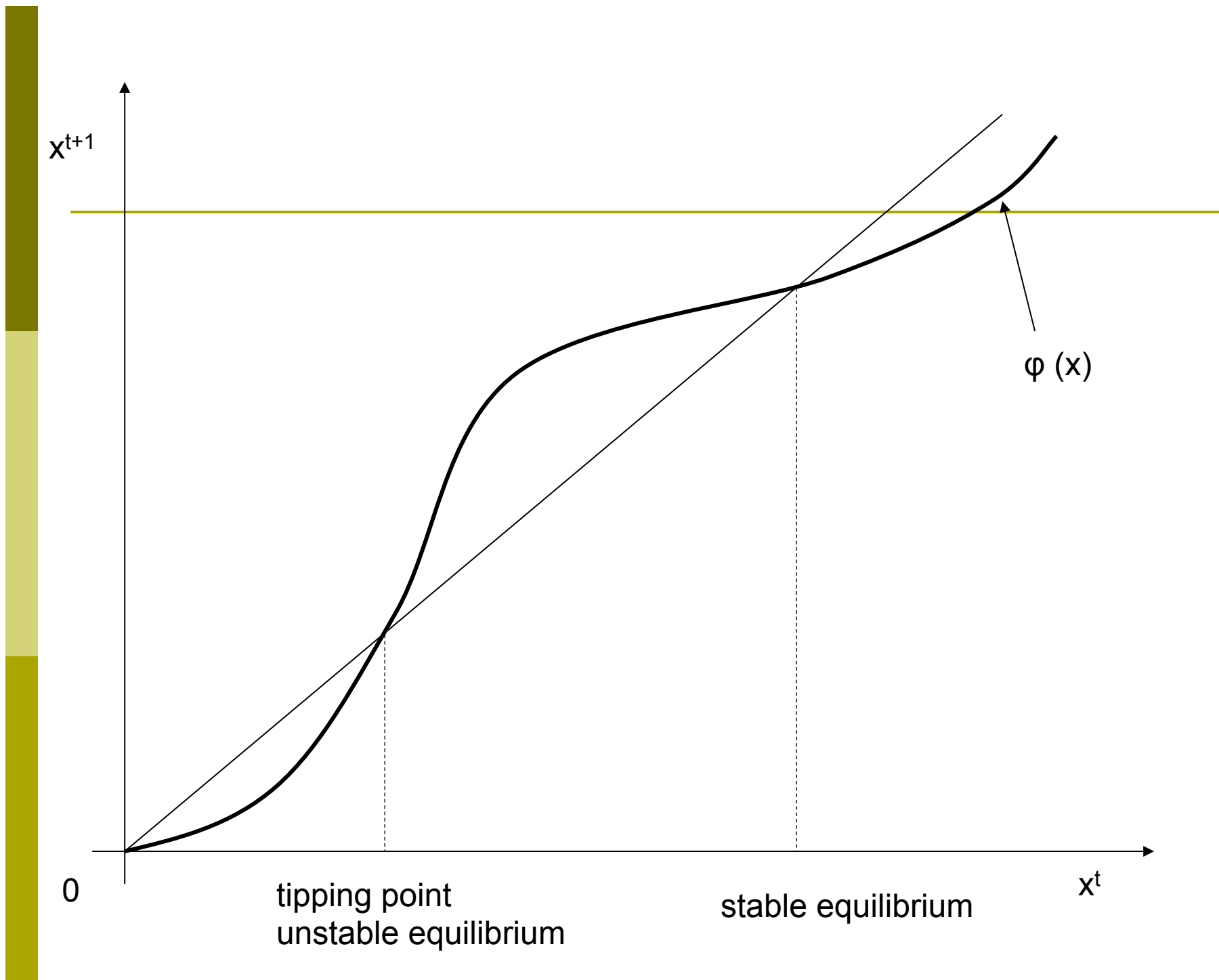






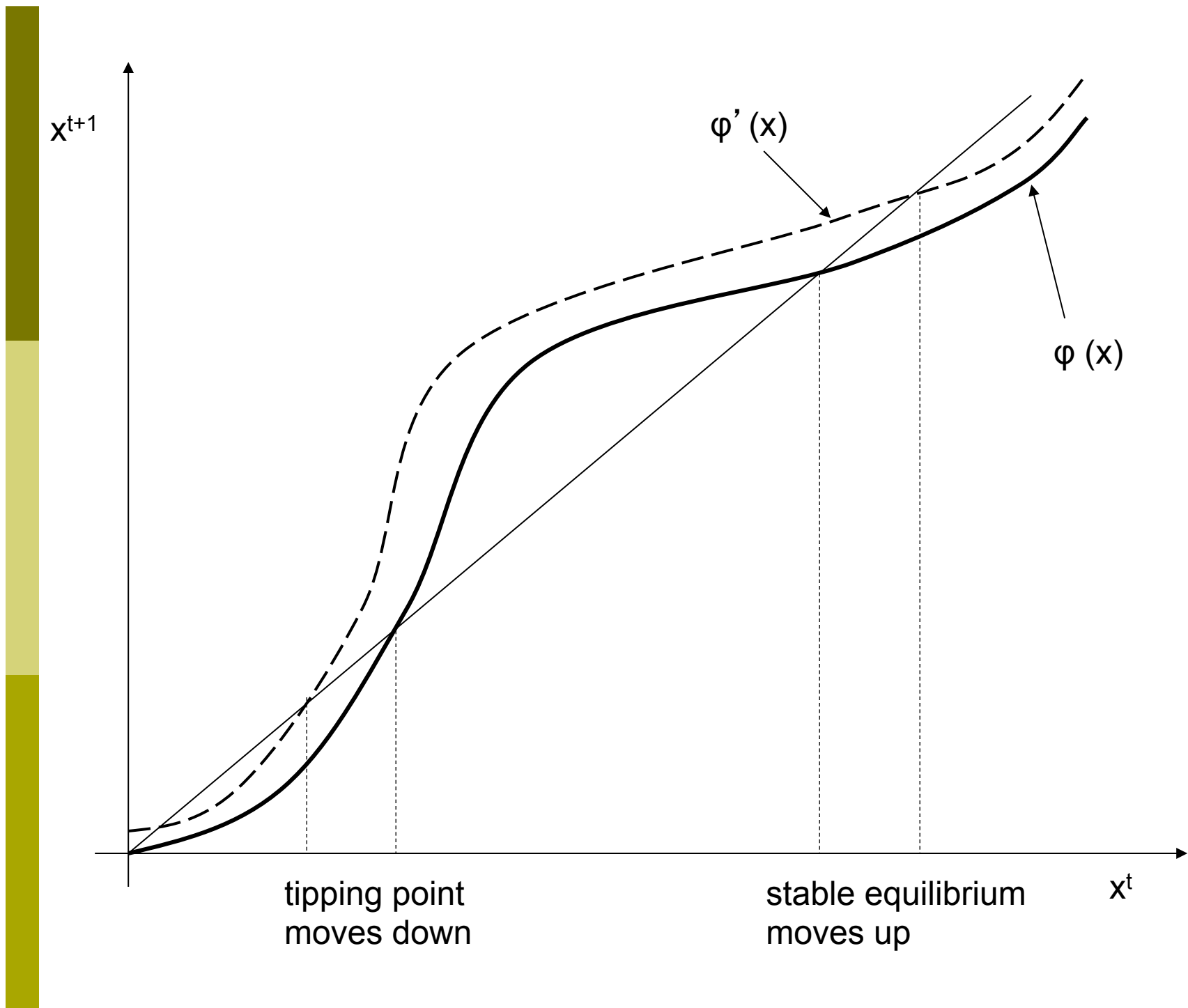






How can we relate structure (network or payoff) to diffusion?

- Concentrate on “regular” environments – no tangencies
- Tipping and stable points alternate
- Keep track of how φ shifts with changes



Adding Links

- Consider a FOSD shift in distribution $P(d)$
 - More weight on higher degrees
 - $v(d,x)$ non-decreasing in $d \rightarrow$ Higher expectations of higher actions (Observation 1)
 - More likely to take higher action

Adding Links

- Consider a FOSD shift in distribution $P(d)$
 - More weight on higher degrees
 - $v(d,x)$ non-decreasing in $d \rightarrow$ Higher expectations of higher actions (Observation 1)
 - More likely to take higher action

- If $v(d,x)$ is non-decreasing in d , then this leads to a point-wise increase of
$$\varphi(x) = \sum P(d) H(v(d,x))$$

Adding Links

- Consider a FOSD shift in distribution $P(d)$
 - More weight on higher degrees
 - $v(d,x)$ non-decreasing in $d \rightarrow$ Higher expectations of higher actions (Observation 1)
 - More likely to take higher action
- If $v(d,x)$ is non-decreasing in d , then this leads to a point-wise increase of
$$\varphi(x) = \sum P(d) H(v(d,x))$$
- Lowers tipping points, raises stable equilibria

Adding Links

- Consider a FOSD shift in distribution $P(d)$
 - More weight on higher degrees
 - $v(d,x)$ non-decreasing in $d \rightarrow$ Higher expectations of higher actions (Observation 1)
 - More likely to take higher action
- If $v(d,x)$ is non-decreasing in d , then this leads to a point-wise increase of
$$\varphi(x) = \sum P(d) H(v(d,x))$$
- Lowers tipping points, raises stable equilibria
- Does not translate to FOSD shifts in $p(d)$

Adding Links – Welfare

- Suppose $v(d,x)$ non-decreasing in x
- \rightarrow FOSD shift in P increases payoffs for all agents corresponding to stable equilibria
- \rightarrow Higher welfare

Adding Links – Welfare

- Suppose $v(d,x)$ non-decreasing in x
- \rightarrow FOSD shift in P increases payoffs for all agents corresponding to stable equilibria
- \rightarrow Higher welfare
- In general, monotonicity with respect to x (externalities) is important for welfare

Raising Costs

- Raising of costs of adoption of action 1 (FOSD shift of H) lowers $\varphi(x)$ pointwise
 - raises tipping points, lowers stable equilibria

Increasing Variance of Degrees

- $v(d,x)$ increasing convex in d , H convex
 - e.g., $v(d,x)=dx$, H uniform $[0,C]$ (with high C)
- p' is MPS of p implies $\varphi(x)$ is pointwise higher under p'
- Roughly, increasing variance leads to lower tipping points and higher stable equilibria
- Fixing means,
$$\varphi^{\text{power}}(\mathbf{x}) \geq \varphi^{\text{Poisson}}(\mathbf{x}) \geq \varphi^{\text{regular}}(\mathbf{x})$$

Can we relate the payoff structure to equilibrium?

- Assume $v(d,x)=v(d)x$
- Vary $v(d)$
- If we can influence v , whom should we target to shift equilibrium?

Proposition: impact of $v(d)$

Consider changing $v(d)$ by rearranging its ordering

Proposition: impact of $v(d)$

Consider changing $v(d)$ by rearranging its ordering

If $p(d)$ increasing, then $v(d)$ increasing raises $\varphi(x)$ pointwise (raises stable equilibria, lowers unstable)
[e.g., p is uniform]

Proposition: impact of $v(d)$

Consider changing $v(d)$ by rearranging its ordering.

If $p(d)d$ increasing, then $v(d)$ increasing raises $\varphi(x)$ pointwise (raises stable equilibria, lowers unstable)
[e.g., p is uniform]

If $p(d)d$ decreasing, then $v(d)$ decreasing raises $\varphi(x)$ pointwise
[e.g., p is power]

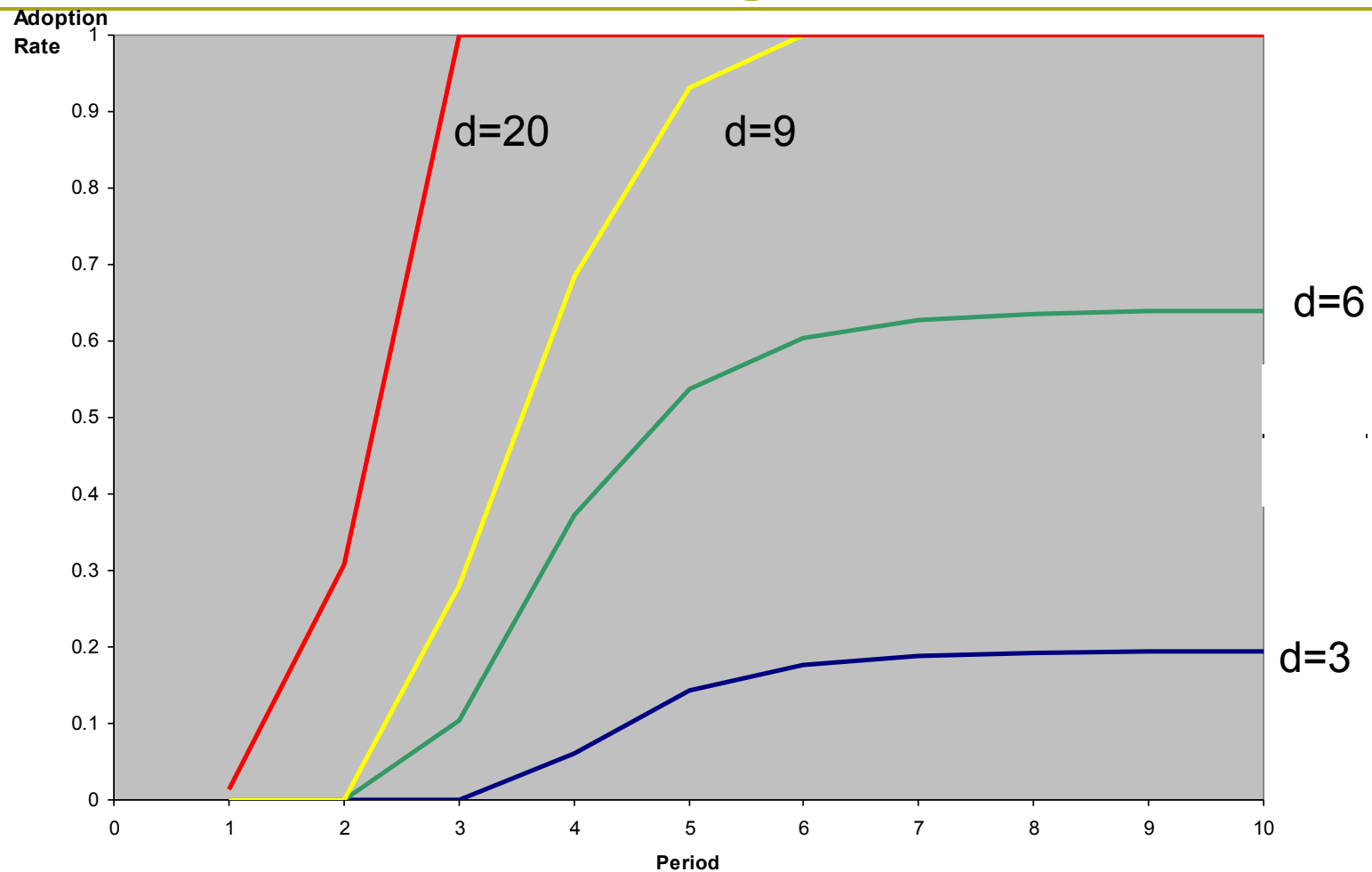
Optimal Targeting

- ❑ Goes against idea of “targeting” high degree nodes
- ❑ Want the most probable neighbors to have the best incentives to adopt

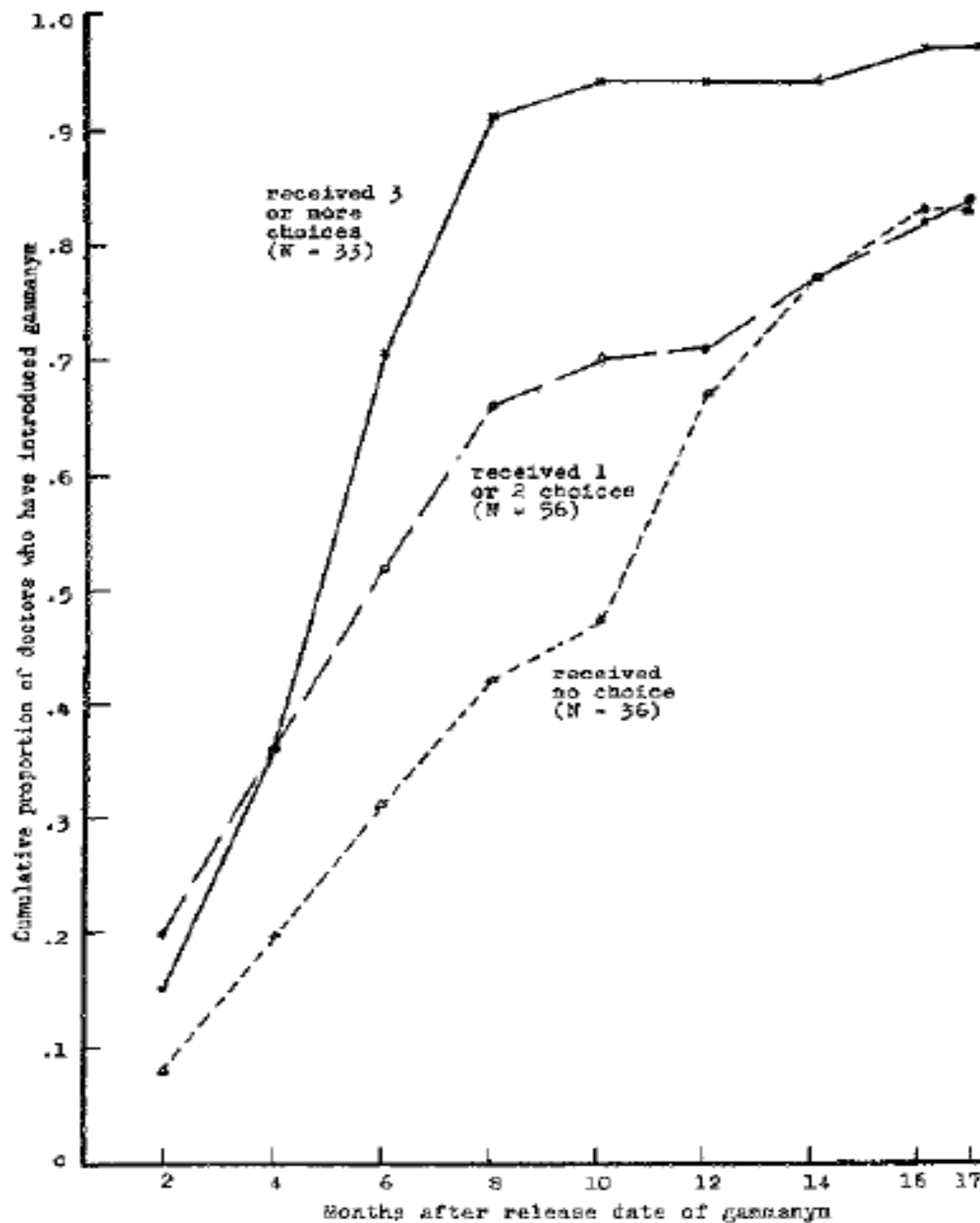
Adoption Across Degrees

- If $v(d,x)$ is increasing in d , then higher d adopt in higher percentage for each x
 - adoption fraction is $H(v(d,x))$ which is increasing
- Patterns over time – depend on concavity of H

Diffusion Across Degrees



fraction adopting over time, power distribution
exponent -2, initial seed $x=.03$, costs Uniform[1,5], $v(d)=d$



Tetracycline Adoption

(Coleman, Katz, and Menzel, 1966)

Summary:

- Location matters:
 - $v(d,x)$ increasing in d
 - more connected adopt “earlier,” at higher rate
 - have higher expected payoffs

Summary:

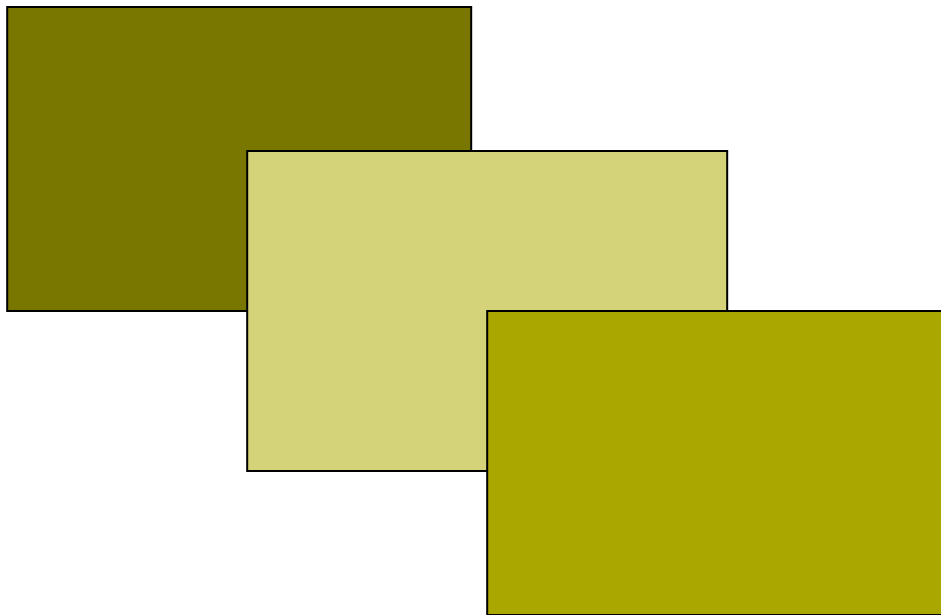
□ Location matters:

- $v(d,x)$ increasing in d
 - more connected adopt “earlier,” at higher rate
 - have higher expected payoffs

□ Structure matters:

- Lower tipping points, higher stable equilibria if:
 - lower costs (downward shift FOSD of H)
 - increase in connectedness (FOSD shift of P)
 - MPS of p if v, H (weakly) convex
 - match higher propensity $v(d)$ to more prevalent degrees $p(d)d$ (want *decreasing* v for power laws)
- adoption speeds vary over time depending on curvature of the cost distribution

The End



Stability at 0

$\varphi(x) < x$ in a neighborhood around 0
(joint condition on H , $v(d, x)$, $P(d)$)

If H is continuous, and 0 is stable, then
“generically”: next unstable (first **tipping point**, where volume of adopters grows), next is stable, etc.

“Regular” environment: No tangencies

Speed of adoption over time

If $H(0)=0$ and H is C^2 and increasing

- If H is concave, then $\varphi(x)/x$ is decreasing
 - Convergence upward slows down, convergence downward speeds up
- If H is convex, then $\varphi(x)/x$ is increasing
 - Convergence upward speeds up, convergence downward slows down