

The background is a dark blue gradient. On the left, there is a large, semi-transparent circular image of a circuit board, which is blurred to suggest motion. Overlaid on this are two large, overlapping geometric shapes: a blue parallelogram and a light green parallelogram. In the top right corner, there is a faint, 3D-rendered pattern of interconnected lines and squares, resembling a microchip or a neural network structure.

# Application of Deep Learning on Image Deblurring

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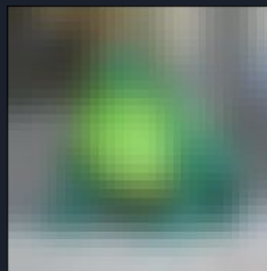
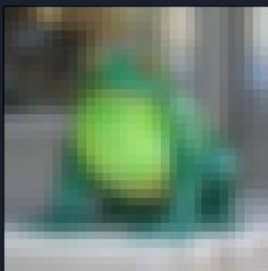
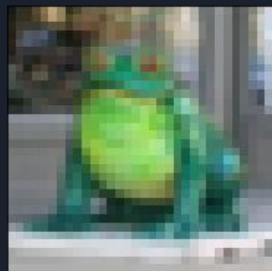
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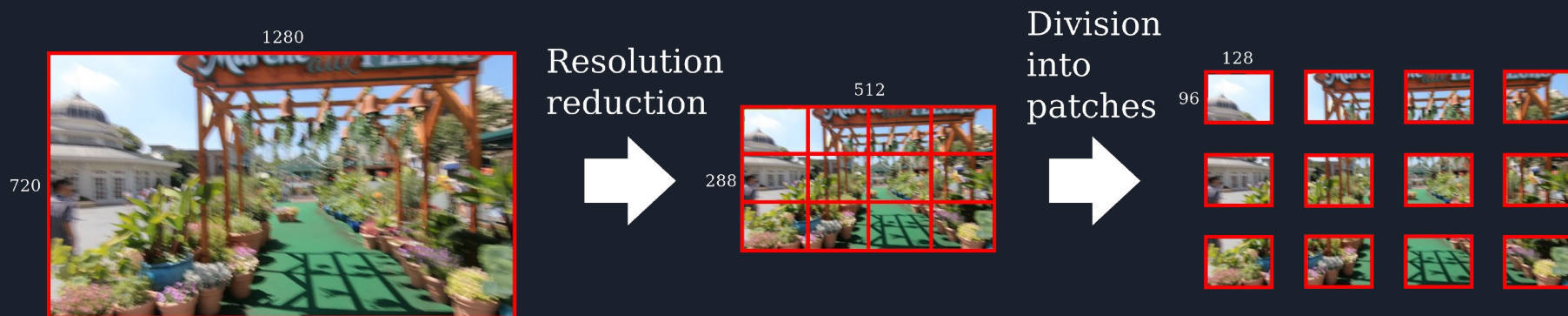
# Datasets - CIFAR10

- Constructed by applying Gaussian blur with random standard deviation between 0 and 3
- Basic data augmentation: horizontal and/or vertical flip



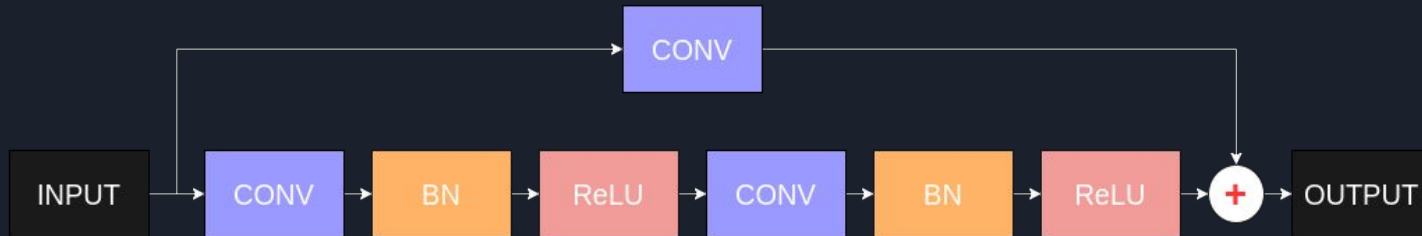
# Datasets - REDS

- Resolution reduction from 1280x720 to 512x288
- Patch-based approach: each image is splitted into 12 patches analysed separately
- Basic data augmentation: horizontal and/or vertical flip



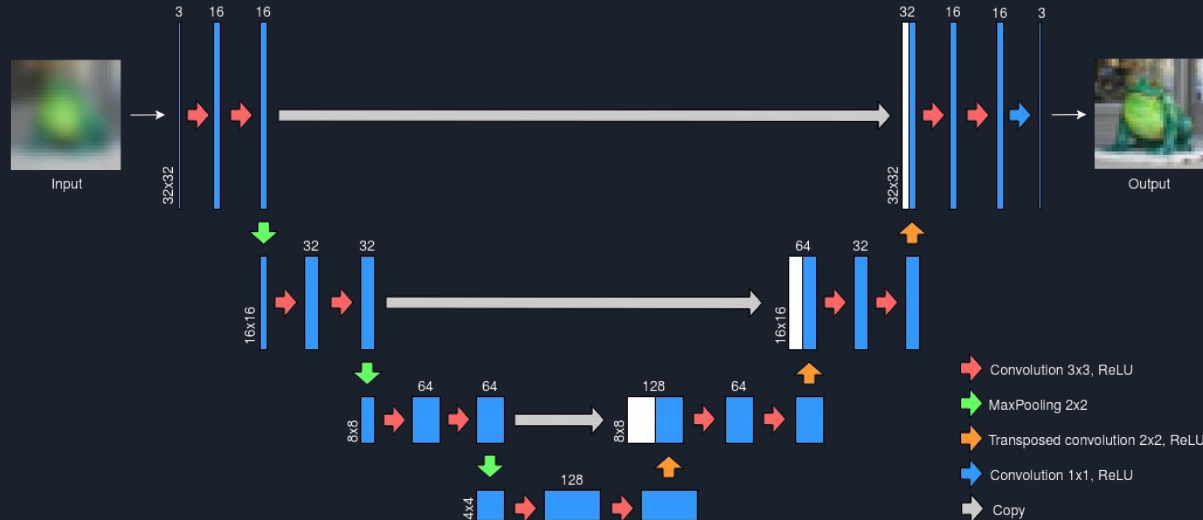
# Convolutional Autoencoders - ResNet16

- It comprises an encoder and a decoder, each made of 4 residual blocks:
  - the encoder shrinks the input image using standard strided convolutions
  - the decoder enlarges the latent image using transposed strided convolutions
- Residual connections inspired by ResNet50 (for image classification)



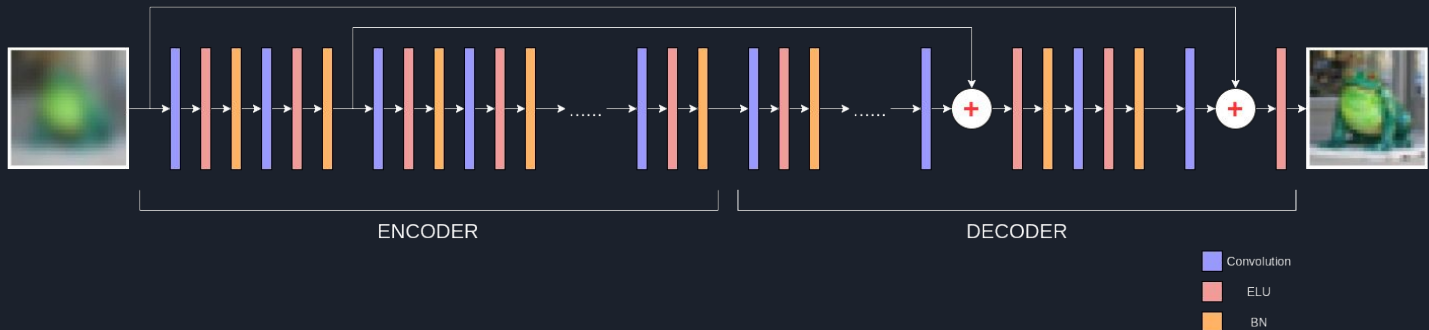
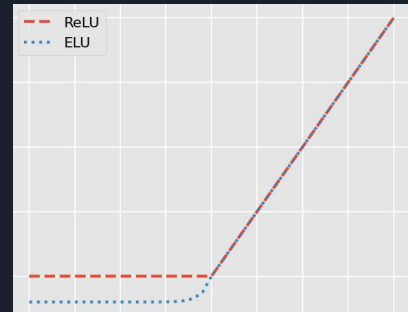
# Convolutional Autoencoders - UNet16

- Based on UNet model for image segmentation:
  - contracting path (convolutional layers + max pooling)
  - expansive path (common + transposed convolutions)



# Convolutional Autoencoders - REDNet30

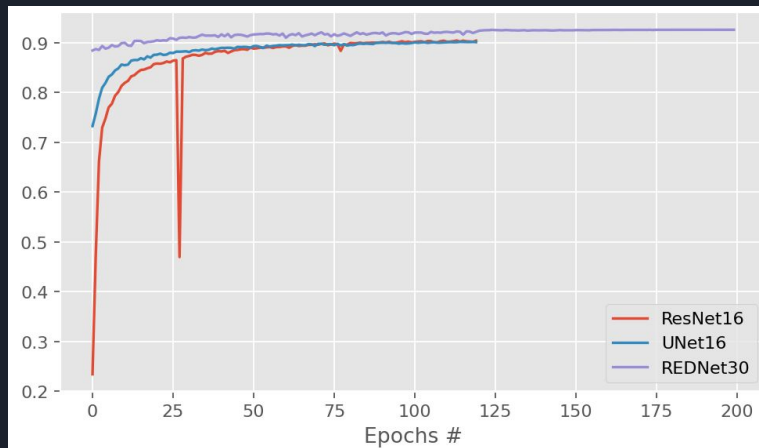
- 30 blocks made of:
  - Convolution 3x3 with stride 1 and padding
  - Exponential Linear Unit
  - Batch Normalization
- Symmetrical residual connections every 2 blocks
- No bottleneck: spatial size remains constant



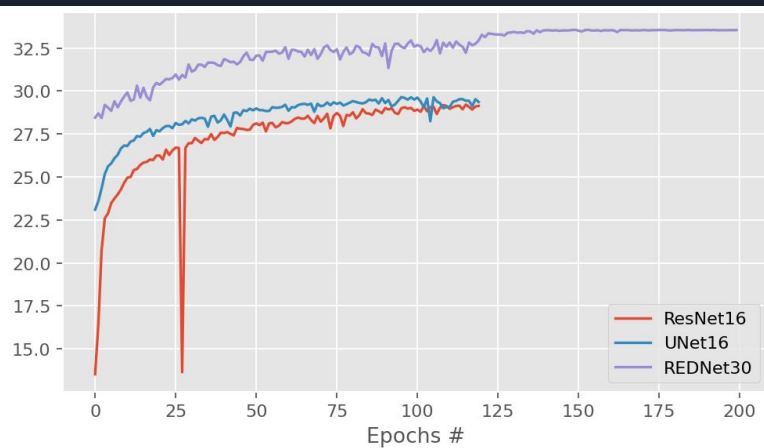
# (CAE) Training phase on CIFAR-10

- Batch size: 32 (x8 TPU's replicas)
- 120 epochs (+ extra 80 epochs for REDNet30)
- Adam optimizer
- Learning rate: 0.001 (+ exp. decay in REDNet30's last 80 epochs)
- LogCosh loss function (more robust than MSE and differentiable unlike MAE)
- SSIM and PSNR metrics to assess image similarity

SSIM



PSNR





# (CAE) Experimental results on CIFAR-10

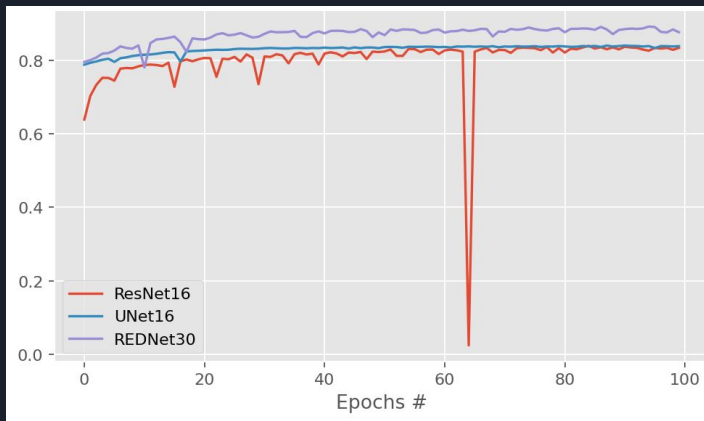
Model	ResNet16	UNet16	<b>REDNet30</b>	Baseline
Loss [ $10^{-4}$ ]	9.794	10.44	<b>6.966</b>	34.48
SSIM	0.9034	0.9001	<b>0.9258</b>	0.7135
PSNR	29.09	29.32	<b>33.52</b>	24.67
MSE [ $10^{-3}$ ]	1.965	2.095	<b>1.398</b>	6.317
MAE [ $10^{-2}$ ]	2.888	2.898	<b>2.165</b>	4.517



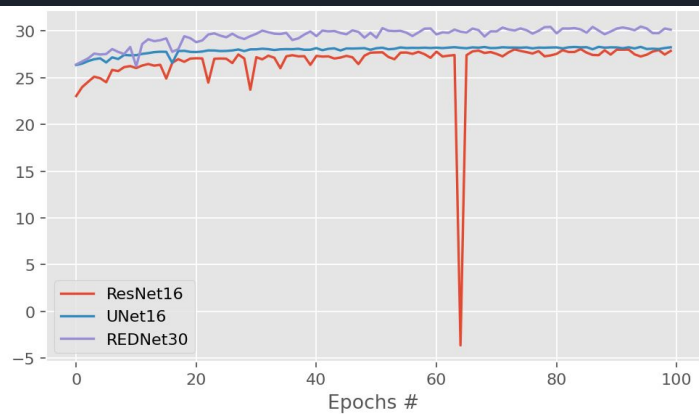
# (CAE) Training phase on REDS

- 100 epochs instead of 120
- Other parameters remained unchanged

SSIM



PSNR



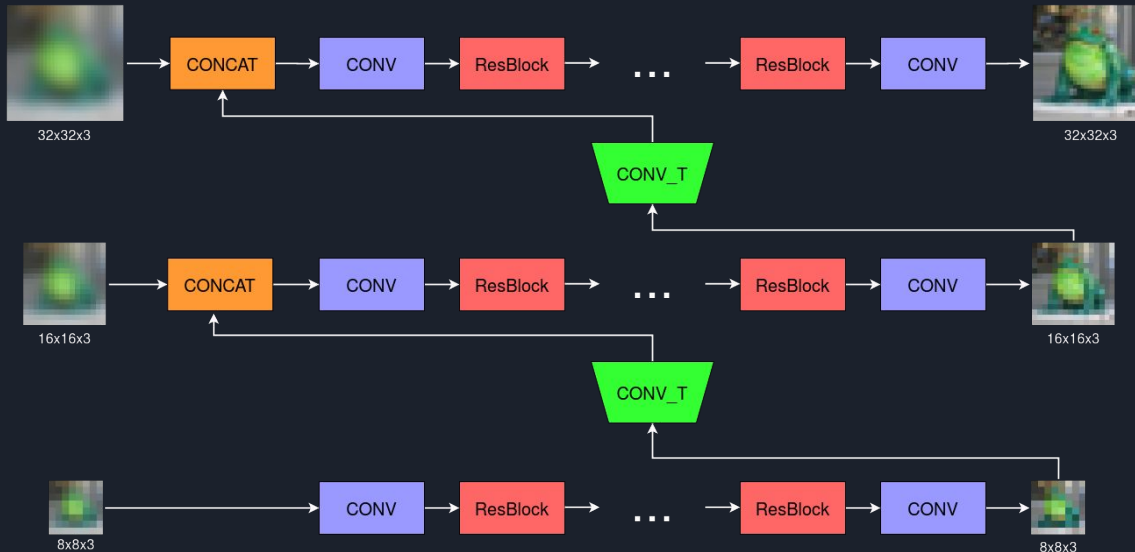
# (CAE) Experimental results on REDS

Model	ResNet16	UNet16	<b>REDNet30</b>	Baseline
Loss [ $10^{-4}$ ]	8.669	8.763	<b>5.793</b>	19.54
SSIM	0.8554	0.8646	<b>0.8976</b>	0.8237
PSNR	29.49	30.41	<b>31.98</b>	28.80
MSE [ $10^{-3}$ ]	1.742	1.761	<b>1.163</b>	2.594
MAE [ $10^{-2}$ ]	2.536	2.312	<b>1.884</b>	2.118



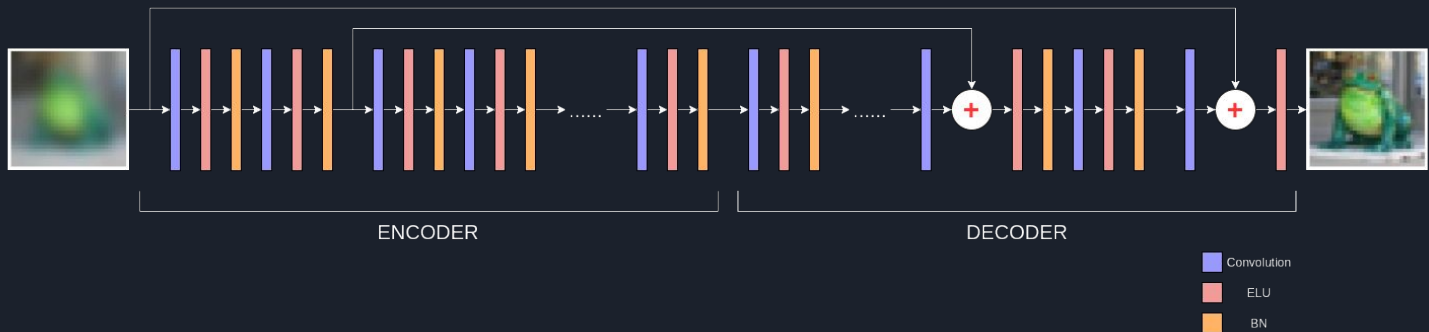
# WGANs - MSDeblurWGAN generator

- It comprises three branches, each made of 19 ResBlocks:
  - branch for coarsest resolution
  - branch for middle resolution (which relies on the coarsest one)
  - branch for finer resolution (which relies on the middle one)



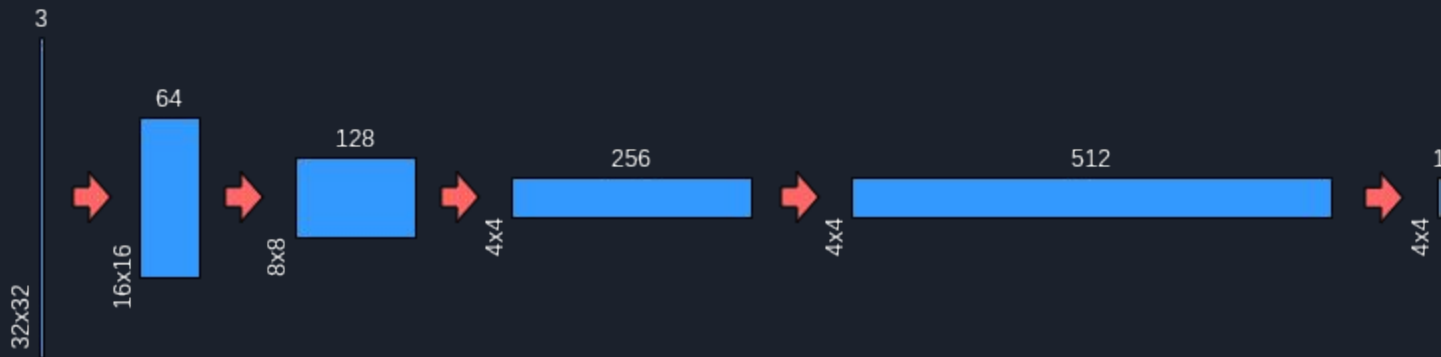
# WGANs - REDNet30WGAN generator

- The architecture of the generator is the same as the one of REDNet30, since it performed well as a standard CAE



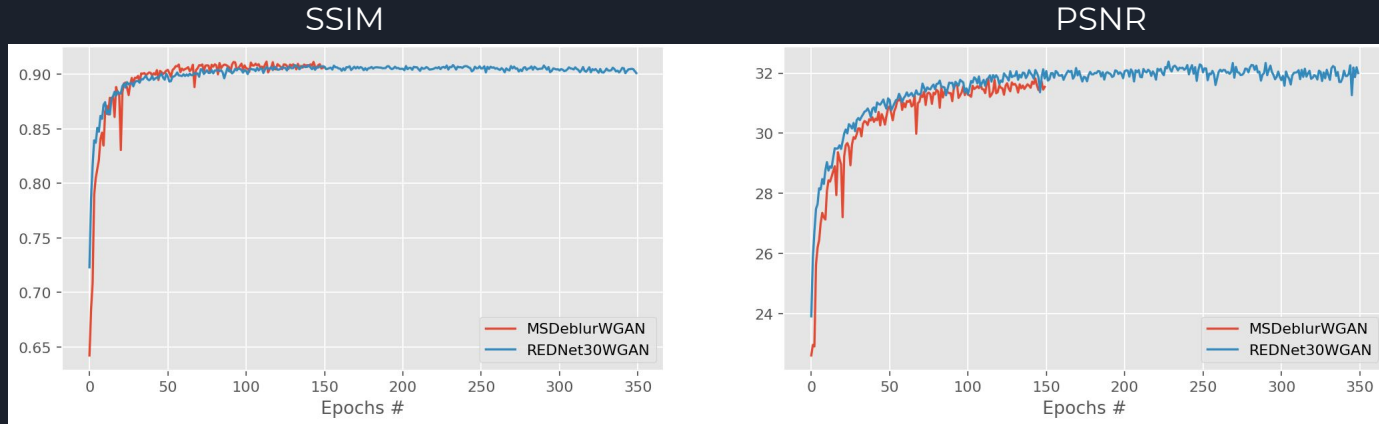
# WGANs - PatchGAN critic

- The discriminator in WGANs (called *critic*) computes a 1-Lipschitz continuous function:
  - apply basic 4x4 convolution with stride 2
  - use of Layer Normalization
- To obtain the image score the last 16 values are averaged to get a single value



# (WGAN) Training phase on CIFAR-10

- Batch size: 32 (x8 TPU's replicas)
- 150 epochs for MSDeblurWGAN, 350 epochs for REDNet30WGAN
- Adam optimizer
- Learning rate:  $2 \bullet 10^{-4}$
- Content loss: LogCosh (multi-scale version for MSDeblurWGAN)
- Adversarial loss: negated critic's score
- SSIM and PSNR metrics to assess image similarity
- Gradient penalty technique to enforce 1-Lipschitz constraint
- At every generator's train step, the critic is trained 5 times



# (WGAN) Experimental results on CIFAR-10

Model	MSDeblur WGAN	REDNet30 WGAN	<b>REDNet30</b>	Baseline
Loss	0.1254	-0.0057	---	---
SSIM	0.9054	0.9012	<b>0.9258</b>	0.7135
PSNR	31.49	31.98	<b>33.52</b>	24.67
MSE [ $10^{-3}$ ]	1.734	1.900	<b>1.398</b>	6.317
MAE [ $10^{-2}$ ]	2.471	2.482	<b>2.165</b>	4.517

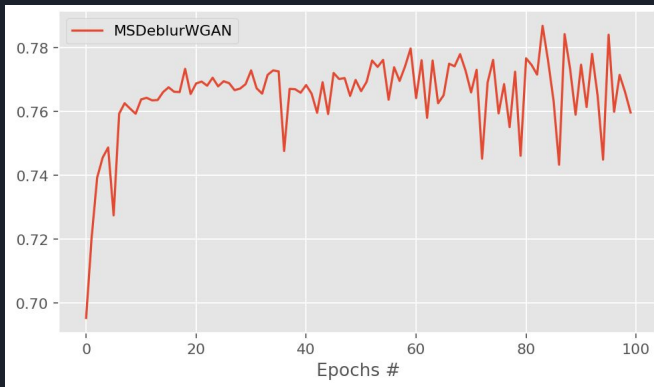




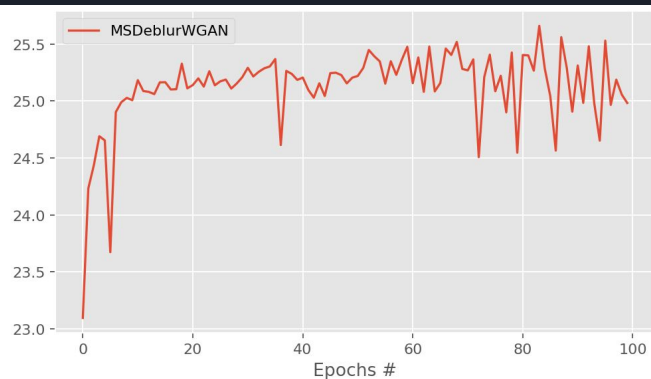
# (WGAN) Training phase on REDS

- 100 epochs (MSDeblurWGAN only)
- Number of ResBlocks reduced from 19 to 5
- Lower image resolution (256x144 instead of 512x288)

SSIM

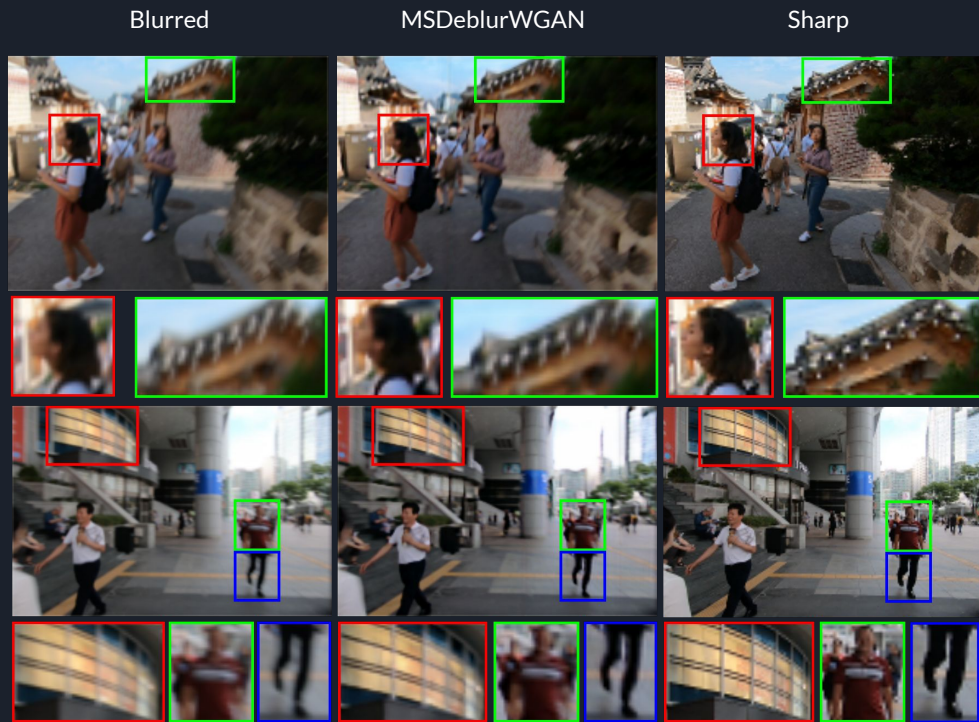


PSNR



# (WGAN) Experimental results on REDS

Model	MSDeblurWGAN	REDNet30	Baseline
Loss	0.2195	---	---
SSIM	0.8031	<b>0.8976</b>	0.8359
PSNR	27.11	<b>31.98</b>	27.68
MSE [ $10^{-3}$ ]	1.729	<b>1.163</b>	3.120
MAE [ $10^{-2}$ ]	2.495	<b>1.884</b>	2.390





# Tools

- Google Colab's TPU:
  - training performed in parallel across 8 replicas
  - results are reduced into a single value
- Files in tfrecord format on Google Cloud Storage
- Brain floating point:
  - half bits employed (16) w.r.t. standard 32-bit floating point
  - same dynamic range

# REDNet30 on GOPRO

- REDNet30 trained on REDS dataset
- Does not reach Nah's DeepDeblur's performance
- Still able to reconstruct smaller details in GOPRO test images
- Some generalization capabilities

