ODE SOLVERS: MULTI-STEP METHODS

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ABSTRACT.

CONTENTS

1. I	Multi-Steps Methods	1
1.1.	Notation	1
1.2.	Schemes	2
1.3.	Truncation error	3
1.4.	Adams-Bashforth and Adams-Moulton methods	3

We consider numerical methods for solving the nonlinear ODE

(1)
$$y' = f(x, y), \quad y(a) = y_0,$$

where $t \in \mathbb{R}$ is the independent variable, $y = y(x) \in \mathbb{R}^d$ may be a vector-valued function, and the function f(x,y) is given. The independent variable is change back to x as the multi-step schemes is highly related to the interpolation of function f(x).

1. Multi-Steps Methods

1.1. **Notation.** It will be useful to introduce the following symbols representing indices, function value and derivative at various locations.

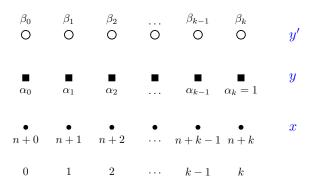


FIGURE 1. Notation for multi-step methods

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LONG CHEN

We use subscript to indicates the function evaluated at the corresponding grid points. For $i=0,1,\ldots,k$

$$x_{n+i} = x_n + ih$$
, $y_{n+i} = y(x_{n+i})$, $f_{n+i} = f(x_{n+i}, y(x_{n+i}))$.

To simply the notation and easy of analysis, we apply the change of variable

$$u(\hat{x}) = y(x_n + \hat{x}h), \quad \hat{x} \in [0, k] \to x = x_n + \hat{x}h \in [x_n, x_{n+k}].$$

Therefore

2

(2)
$$u_i = y_{n+i}, \quad dx = h d\hat{x}, \quad u'(\hat{x}) = hy'(x_n + \hat{x}h).$$

1.2. **Schemes.** We can use more information on the previous steps to get a higher order methods. A general form is

(3)
$$\sum_{i=0}^{k} \alpha_i y_{n+i} = h \sum_{i=0}^{k} \beta_i f(x_{n+i}, y_{n+i}).$$

Without loss of generality, we can assume $\alpha_k = 1$.

- 1. $\beta_k = 0$: the scheme is explicit.
- 2. $\beta_k \neq 0$: the scheme is implicit. Need to solve a nonlinear equation

$$y_{n+k} = \dots h\beta_k f(x_{n+k}, y_{n+k}).$$

In total we have 2(k+2) parameters, or equivalently, we know function value at k+1 points and its derivative at k+1 points, ideally we can fit a polynomial of degree $p \le 2k+3$.

We define residual operators by

$$(Rv)(x) := v'(x) - f(x, v(x)), \quad v \in C^{1}[a, b],$$

$$(T_{h})_{n} = (R_{h} \boldsymbol{v})_{n} := \frac{1}{h} \sum_{s=0}^{k} \alpha_{s} v_{n+s} - \sum_{s=0}^{k} \beta_{s} f(x_{n+s}, v_{n+s}), \boldsymbol{v} \in \Gamma_{h}[a, b].$$

To study the truncation error, we introduce the linear operator

$$Lu := \sum_{s=0}^{k} \left[\alpha_s u(s) - \beta_s u'(s) \right], \quad u \in C^1[\mathbb{R}].$$

Notice that the coordinate is changing to $\hat{x} \in [0, k]$ and due to the relation (2), no h is in front of u'.

The scheme has degree p if Lu = 0 for all $u \in \mathbb{P}_p$. By linearity, this is equivalent to

(5)
$$Lt^r = 0, \quad r = 0, 1, \dots, p$$

Indeed we can use (5) to determine the coefficients (α_i, β_i) . For example, we obtain the relation

$$p = 0: \quad \alpha_0 + \alpha_1 = 0,$$

 $p = 1: \quad \alpha_0 + \alpha_1 = 0, \alpha_0 + \beta_0 + \beta_1 = 1.$

Here we give several popular examples.

1.3. **Truncation error.** For $u \in \mathbb{C}^{p+1}[0,k]$, we expand u by its Taylor series at $\hat{x}=0$ using the Peano kernel

(6)
$$u(\hat{x}) = \sum_{i=0}^{p} \frac{1}{i!} u^{(i)}(0) \hat{x}^i + \frac{1}{p!} \int_0^{\hat{x}} (\hat{x} - \sigma)^p u^{(p+1)}(\sigma) d\sigma.$$

By the order condition (5), apply L to the Taylor expansion (6), we get

$$Lu = \frac{1}{p!} \int_0^k \lambda_p(\sigma) u^{(p+1)}(\sigma) d\sigma, \quad \lambda_p(\sigma) = L(t-\sigma)_+^p.$$

Using the mean value theorem (or Lagrange remainder), we also have

$$Lu = \ell_{p+1}u^{(p+1)}(\bar{\sigma}), \quad 0 < \bar{\sigma} < k; \quad \ell_{p+1} = \frac{1}{(p+1)!}Lt^{p+1}.$$

By change of variable, we get the order of the convergence.

Theorem 1.1. A multistep method (3) of polynomial degree p has order p whenever the exact solution $\mathbf{y}(x)$ of (6.1) is in the smoothness class $C^{p+1}[a,b]$. If the associated functional L is definite, then

$$(T_h)_n = \ell_{p+1} y^{(p+1)} (\bar{x}_n) h^p, \quad x_n < \bar{x}_n < x_{n+k}$$

where $\ell_{p+1} = \frac{1}{(p+1)!} Lt^{p+1}$. Moreover, for the principal error function τ of the method, whether definite or not, we have, if $y \in C^{p+2}[a,b]$,

$$\tau(x) = \ell_{p+1} y^{(p+1)}(x).$$

1.4. Adams-Bashforth and Adams-Moulton methods.

1.4.1. Adams-Bashforth method. We take $\alpha_{k-1} = -1, \alpha_k = 1$ and write out the solution y' = f(x, y) as

(7)
$$y_{n+k} = y_{n+k-1} + \int_{x_{n+k-1}}^{x_{n+k}} y'(t) dt = y_{n+k-1} + \int_{x_{n+k-1}}^{x_{n+k}} f(x, y(x)) dx.$$

Suppose we know function values y_{n+i} for $i=0,\ldots,k-1$, we can evaluate to get f_{n+i} and fit the data (x_{n+i},f_{n+i}) with a polynomial of degree k-1. For example, the Lagrange interpolant f_I to f can be written as

$$p_n(f; [x_n, x_{n+1}, \dots, x_{n+k-1}]; x) = \sum_{i=0}^{k-1} \ell_i(x) f_{n+i},$$

where $\ell_i(x) \in \mathbb{P}_{k-1}$ and $\ell_i(x_{n+j}) = \delta_{ij}$.

FIGURE 2. Adams-Bashforth method

4 LONG CHEN

Approximate f by f_I and let

$$\beta_i = \frac{1}{h} \int_{x_{n+k-1}}^{x_{n+k}} p_i(x) \, \mathrm{d}x,$$

we then obtain the Adams-Bashforth method

(8)
$$u_{n+k} = u_{n+k-1} + h \sum_{i=0}^{k-1} \beta_i f_{n+i}.$$

When studying the truncation error, we assume the function value y_{n+i} is known for $i=0,1,\ldots,k-1$. Then the truncation error

$$T_h^{AB} := \frac{1}{h} (u_{n+k} - y_{n+k}) = \frac{1}{h} \int_{x_{n+k-1}}^{x_{n+k}} (f_I - f) \, \mathrm{d}x = \frac{1}{h} \int_{x_{n+k-1}}^{x_{n+k}} ((y')_I - y') \, \mathrm{d}x.$$

We switch the integrand to y' since now the remainder can be written as derivative of exact solution y. As the Lagrange interpolant preserves polynomial

1.4.2. Adams-Moulton method. The only difference is the point (x_{n+k}, f_{n+k}) is included to fit the polynomial.

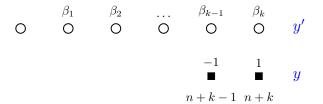


FIGURE 3. Adams-Moulton method

Now the Lagrange interpolant f_I to f will be

$$f_I(x) = \sum_{i=0}^k p_i^*(x) f_{n+i},$$

where $p_i^*(x) \in \mathbb{P}_k$ and $p_i^*(x_{n+j}) = \delta_{ij}$ for $i, j = 0, 1, \dots, k$. The superscript * is introduced to distinguish the same quantity used in A-B method.

Approximate f by f_I and let

$$\beta_i^* = \frac{1}{h} \int_{x_{n+k-1}}^{x_{n+k}} p_i^*(x) \, \mathrm{d}x,$$

we then obtain the Adams-Moultion method

(9)
$$u_{n+k} = u_{n+k-1} + h \sum_{i=0}^{k-1} \beta_i^* f_{n+i} + h \beta_k^* f(x_{n+k}, u_{n+k}).$$

Here we single out the last term to emphasize A-M method is an implicit method and an iteration is needed to solve the nonlinear equation (9).