

Theorems

Invertible Matrix Theorem

The following are all equivalent:

- ① $A \in \mathbb{R}^{n \times m}$ is invertible
- ② A is row-equivalent to I
- ③ A has n pivots.
- ④ $Ax = b$ has a unique solution for any $b \in \mathbb{R}^n$
- ⑤ $Ax = 0$ has only the solution $x = 0$.
- ⑥ The columns of A are linearly independent
- ⑦ $\text{Col}(A)$ spans all of \mathbb{R}^n \rightarrow columns of A form a basis for \mathbb{R}^n
- ⑧ A^T is invertible.
- ⑨ A has a one-sided inverse
- ⑩ $\dim(\text{Col}(A)) = n$
- ⑪ $\text{rank}(A) = \dim(\text{Col}(A)) = n$
- ⑫ $\text{Null}(A) = \{ \underline{0} \}$
- ⑬ $\dim(\text{Null}(A)) = 0$

Miscellaneous

- ① row rank A = column rank A
- ② n LI vectors in \mathbb{R}^n span \mathbb{R}^n and form a basis for it
- ③ Bases are never unique
- ④ # of columns of $A = \dim(\text{Col}(A)) + \dim(\text{Null}(A))$
- ⑤ any vector v_\perp perpendicular to vector c satisfies $c^T v_\perp = 0$

Proof Tactics

Diff $\text{Null}(A) = \emptyset$, piv in every column
 $\Rightarrow n$ LI vecs ~~span~~ basis \mathbb{R}^n
Diff A cols are basis \mathbb{R}^n , any b in \mathbb{R}^n can be made of LC's of A cols i.e. is in $\text{Col}(A)$. Since $Ax = b$ expands to a LC of A 's cols, $Ax = b$ has unique basis-vec-rep sol'n for every b

Miscellaneous (II)

- ① any vector in \mathbb{R}^n can be represented as a unique linear combination of vectors in a basis for \mathbb{R}^n
- ② If you show something to be true for each of the standard basis vectors of a vector space \mathbb{R}^n , you have shown it to be true for every vector $v \in \mathbb{R}^n$

Important Subspaces

Dimensions

Column Space ($\text{Col}(A)$)

The span of all Linearly Independent columns of A

$$\begin{aligned}\dim(\text{Col}(A)) &= \# \text{ Pivot vars} \\ &= \# \text{ Pivot columns} \\ &= r\end{aligned}$$

Null Space ($\text{Null}(A)$)

Span of all vecs \underline{x}

Such that $A\underline{x} = \underline{0}$

$$\begin{aligned}\dim(\text{Null}(A)) &= \# \text{ Free vars} \\ &= \# \text{ cols } A \\ &\quad - \# \text{ piv cols} \\ &= n - r\end{aligned}$$

Row Space ($\text{Col}(A^T)$)

Span of all LI rows of A

$$\dim(\text{Col}(A^T)) = r$$

Left Null ($\text{Null}(A^T)$)

$$\dim(\text{Null}(A^T)) = m - r$$

Short Version:

$$\dim(\text{Col}(A)) = \# \text{ pivots} = p$$

$$\dim(\text{Col}(A^T)) = p$$

$$\dim(\text{Null}(A)) = \# \text{ free} = n - p$$

$$\dim(\text{Null}(A^T)) = m - p$$

Def

Linear Independence

A set of vectors v_1, \dots, v_k are Linearly Independent if no vector can be written as a linear combination of the others. Otherwise, the set is Linearly Dependent.

Proving Linear Independence

Vectors are LI if:

- ① The REF matrix constructed from them has a pivot in every column
- ② The eqn.
 $c_1 v_1 + \dots + c_n v_n = 0$
has only solution
all $c_i = 0$
- ③ The determinant of the square matrix constructed from them $\neq 0$
- ④ The matrix constructed from them satisfies a condition of the Invertible Matrix Thm

Rank

$$\text{rank}(A) = \dim(\text{Col}(A)) = \# \text{ pivots}$$

Thm: subspace dims

The only subspace of \mathbb{R}^n w/ dimension n is \mathbb{R}^n

Standard Basis Vectors

of space \mathbb{R}^n are

$$\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

and form most intuitive basis of \mathbb{R}^n

Proving Basis Vector Representations Are Unique

- $u \in S$, basis = $\{v_1, \dots, v_k\}$
- $u = c_1 v_1 + \dots + c_k v_k$
- if u also = $d_1 v_1 + \dots + d_k v_k$,
then $u - u = 0 = (c_1 - d_1)v_1, \dots$
- and all coeffs = 0 bc $\{v_1, \dots, v_k\}$ are LI
- so $c_1 - d_1 = 0$
 $c_1 = d_1$
- $\therefore u$ is unique

Thm: dims of $\text{Col}(A)$, $\text{Nul}(A)$

$$A \in \mathbb{R}^{m \times n}$$

$$\dim(\text{Col}(A)) + \dim(\text{Nul}(A)) = \text{total \# columns} = n$$

Bases From k Vectors (Thm)

Given $S \subseteq V$,

- ① If S is dim k , any set of k LI vectors forms a basis for S
- ② " " " " , any set of k vecs that span S form a basis for it

Basis

A basis for a subspace S of a vector space V is a set of vectors in S which

- ① are Linearly Independent
- ② span the subspace

And any vector in S can be written as a Linear Combination

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

of the basis vectors, which is unique.

$\text{Col}(A)$

$$= \text{span}\{\text{LI cols } A\}$$

$\text{Nul}(A)$

$$= \text{solutions to } Ax = 0$$

Dimension

of a subspace S with basis $\{v_1, \dots, v_k\}$ of k many vectors = # vectors in basis = k

Linear Dependent

$$\alpha x + \beta y = 0$$

Proving a Span is a Subspace

If you can construct every basis vector from an LC of span vectors, then whole space is in span, and, bc of dimensions, span = space.

② Determine if a set of vectors is Linearly Independent

⇒ if $C_1 \underline{v}_1 + C_2 \underline{v}_2 + \dots + C_k \underline{v}_k = \underline{0}$ is only solvable for all $C = 0$, LI

⇒ Combine vectors into a matrix

[
⇒ REF matrix
⇒ if pivot in every column, vecs are LI.
⇒ Calc determinant (if square)
⇒ if $\det \neq 0$, vecs are LI.
]

③ Find Perpendicular Vector \underline{v}_\perp to vec u

solve

$$\underline{u}^T \underline{v}_\perp = 0$$

④ is u in $\text{Col}(A)$ or $\text{Nul}(A)$?

construct $\begin{bmatrix} A & \underline{u} \end{bmatrix}$ and solve. If consistent,

it is.

Problems

- ① Compute bases and dimensions of each of the four fundamental subspaces of a matrix A .

Col(A)

- ① reduce to echelon form
- ② identify pivots
- ③ identify pivot columns
- ④ same columns in A form basis of column space
- ⑤ $\dim(\text{Col}(A)) = \# \text{ pivot variables}$

Col(A^T)

- ① Calc A^T
- ② RREF A^T
- ③ pivot columns
- ④ basis is pivot columns from original A
- ⑤ $\dim(\text{Col}(A^T)) = \dim(\text{Col}(A))$

Nul(A)

- ⑥ to find basis, just characterize the solution set to $A\mathbf{x} = \mathbf{0}$

- ① reduce to echelon form
- ② identify non-pivot columns (columns without pivots)

~~③ Form new matrix of non-pivot columns~~
~~④ construct one equation per row, $= 0$~~
~~⑤ Express pivot variables as functions of other variables; all "non-pivot-column" variables = free~~

- ⑤ go to reduced-row echelon form
- ⑥ pivot vars as functions of free vars
- ⑦ non-pivot vars = free
- ⑧ write solution set in vector form
- ⑨ the vectors you just constructed are the basis vectors for $\text{Nul}(A)$

$$\textcircled{10} \dim(\text{Nul}(A)) = \# \text{ columns}$$

$$- \# \text{ pivot columns}$$

$$= \# \text{ vecs in basis}$$

Nul(A^T)

- ① variable ans from RREF A^T
- ② eliminate as many vars as possible
- ③ vecs in vector form of solution set form basis $= \# \text{ rows} - \# \text{ pivs}$
- ④ $\dim(\text{Nul}(A)) = m - \# \text{ pivs} = \# \text{ vecs in basis}$

DEFINITIONS

Basis: if a set of vectors in \mathbb{R}^n

("The smallest span")

① are Linearly Independent, and

② span the space \mathbb{R}^n ,

then the vectors form a basis of \mathbb{R}^n .

This means that any vector $\underline{v} \in \mathbb{R}^n$ can be constructed from a unique linear combination of vectors in the basis set.

Span: ~~a set of vectors spans \mathbb{R}^n~~

The span of a set of vectors is the set of all ~~linear combin~~ vectors that can be made from LC's of the span vectors

$$\text{span} \{ \underline{v}_1, \underline{v}_2, \dots, \underline{v}_n \}$$

$$= \{ \underline{x} : \underline{x} = c_1 \underline{v}_1 + \dots + c_n \underline{v}_n \}$$

- Spans are subspaces by definition

Standard Basis Vectors

For a vector space \mathbb{R}^n there are n standard

basis vectors

$$\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

which form a basis of \mathbb{R}^n

Col(A)

A

Nul(A)

REF A

RREF A

find
pivots

their
columns

(row 1 eqn) = 0
⋮
(row n eqn) = 0

eliminate variables

express pivot vars as
function of non-pivot vars

non-pivot vars = free

basis vcs
are pivot
columns from
original A

$\dim(\text{Col}(A)) = \# \text{Pivots}$

Solution =

$$\underline{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = x_1 \begin{bmatrix} \text{coefficients} \end{bmatrix} + \dots$$

as few
x's as possible

$$+ x_n \begin{bmatrix} \text{coefficients} \end{bmatrix}$$

Vectors from solution
vector are basis vcs

$\dim(\text{Nul}(A)) = \# \text{Cols}$
 $- \# \text{Pivots}$

A

A^T

Nul(A^T)

Col(A^T)

REF
 A^T

RREF
 A^T

$\dim(\text{Col}(A^T))$
 $= \dim(\text{Col}(A))$

$\dim(\text{Nul}(A^T))$
 $= \# \text{rows} - \# \text{Pivots}$

Geometric Interp of

- pivots: we'll revisit

- dim

- 2D subspace is plane

- 1D

line

- 0D

pt

- dim is most important for telling how many basis vectors you're looking for.

(7) if $\underline{x}^T \underline{y} = 0$, $\underline{y} \in \mathbb{R}^n$, then $\underline{x} = \underline{0}$

* $\underline{x}^T \underline{y} = 0 \rightarrow$ two vecs are \perp .

Trick: if $\{\underline{b}_1, \dots, \underline{b}_n\}$ is a basis for \mathbb{R}^n ,

and $\underline{x}^T \underline{b}_i = 0$ for all basis vectors \underline{b}_i ,

then $\underline{x}^T \underline{y} = 0$ for all $\underline{y} \in \mathbb{R}^n$

(*)
To show true
for all \underline{y} ,
show true for
all basis vectors

\rightarrow (bc any $\underline{y} \in \mathbb{R}^n$ is a combination of the vectors \underline{b}_i in a ~~base~~ basis of \mathbb{R}^n)

$$\hookrightarrow \underline{y} = c_1 \underline{b}_1 + c_2 \underline{b}_2 + \dots + c_n \underline{b}_n$$

$$\underline{x}^T \underline{y} = \underline{x}^T (c_1 \underline{b}_1 + c_2 \underline{b}_2 + \dots + c_n \underline{b}_n)$$

$$= \underline{x}^T (c_1 \underline{b}_1) + \dots + \underline{x}^T (c_n \underline{b}_n)$$

$$= c_1 (\underline{x}^T \underline{b}_1) + \dots + c_n (\underline{x}^T \underline{b}_n)$$

$$\text{If } \underline{x}^T \underline{b}_i = 0, = 0 + \dots + 0$$

$$= \underline{x}^T \underline{y} = 0$$

Proof
of
trick

17) Now, Prove lemma/precondition

$$\underline{x}^T \underline{b} = 0$$

So consider standard basis for \mathbb{R}^n

$$\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

$e_1 \qquad e_2 \qquad e_n$

Since $\underline{x}^T \underline{y} = 0$ for any \underline{y} , this
will be true if $\underline{y} = e_1, e_2, \text{etc.}$

$$\begin{aligned} \underline{x}^T e_1 = 0 &= x_1(1) + x_2(0) + \dots + 0 = x_1 \\ \underline{x}^T e_2 = 0 &\longrightarrow x_2 = 0 \\ &\vdots \\ \underline{x}^T e_n = 0 &\longrightarrow x_n = 0 \end{aligned}$$

$x_1 = 0$
 $x_2 = 0$
 $x_n = 0$

for all x_i . Thus,

3d) big red flag: unique

$$\underline{x} = \underline{0}$$

26) false bc will always have 0