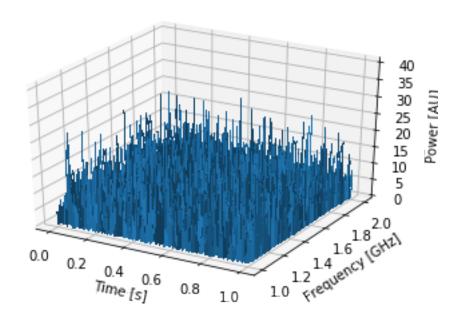
q_pulsar_dispersion_measure_ipynb

October 31, 2021

```
In [1]: %matplotlib inline
        import numpy as np
        import matplotlib.pyplot as plt
        from matplotlib import cm
        from mpl_toolkits.mplot3d import Axes3D
        from scipy.stats.mstats import gmean
        import time
        import pylab as pl
        from IPython import display
        from pprint import pprint
In [2]: float_formatter = "{0:0.2e}".format
        np.set_printoptions(formatter={'float_kind':float_formatter})
In [3]: q = 5e-10 \# esu, electron charge
        m_e = 1e-27 \# g, electron mass
        c = 3e10 # cm/s, speed of light
        cm2pc = 3.24077929e-19
        prefactor = q**2 / (2*np.pi * m_e * c)
        def estimate_DM(nu0, nu1, t0, t1):
                nu0/1: Float. Frequencies (in Hz) of peaks.
                t0/1: Float. Time of arrival of the peaks.
                DM: An estimate of the dispersion measure (i.e. column density of electrons)
                in electrons/cm^2.
              prefactor = 4140 * 1e6**2 * cm2pc
            prefactor = q**2 / (2*np.pi * m_e * c)
            DM = (t1-t0) / (prefactor * (1/nu1**2 - 1/nu0**2))
            return DM
  2
```

2.1

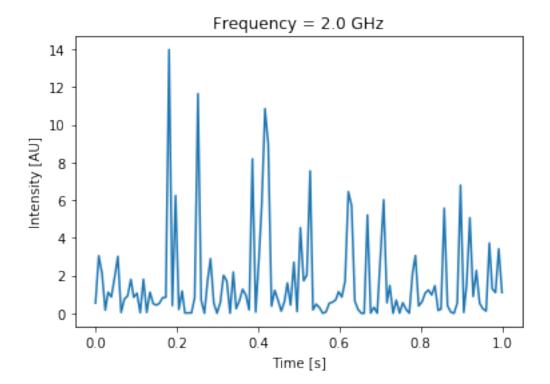
```
In [4]: fname_pulsar = './pulsar.dat'
        # Getting frequencies
        with open(fname_pulsar) as f:
            column headers = f.readlines()[0].strip().split('] [')
        nu_vec = np.array([1e9*float(nu_str.replace('GHz', '').replace(']', '')) for nu_str in
        # Data
        data_raw = np.loadtxt(fname_pulsar)
        t_vec = data_raw[:,0]
        t_mesh, nu_mesh = np.meshgrid(t_vec, nu_vec/1e9)
        data_pulsar = data_raw[:,1:].transpose()
        # Plot the surface
        fig, ax = plt.subplots(subplot_kw={"projection": "3d"})
        surf = ax.plot_surface(t_mesh, nu_mesh, data_pulsar, linewidth=0, antialiased=False)
        ax.set_xlabel('Time [s]')
        ax.set_ylabel('Frequency [GHz]')
        ax.set_zlabel('Power [AU]')
        # for i in range(0, 100, 10):
             plt.figure()
             plt.plot(t_vec, data_pulsar[i])
             plt.title(f'{nu_vec[i]} GHz')
        # Data too noisy for cross-correlations of raw data
        # for d in data_pulsar[11:20]:
            plt.figure()
             cross_corr = np.convolve(data_pulsar[0], d[::-1], mode='same')
             cross_corr_norm = cross_corr/max(cross_corr)
             plt.plot(t_vec, cross_corr_norm)
        # print(len(column_headers))
        # print(len(set(column headers)))
        # print(column_headers.index('1.022 GHz'))
        # print(column headers[23])
        # print(column_headers[24])
Out[4]: Text(0.5,0,'Power [AU]')
```



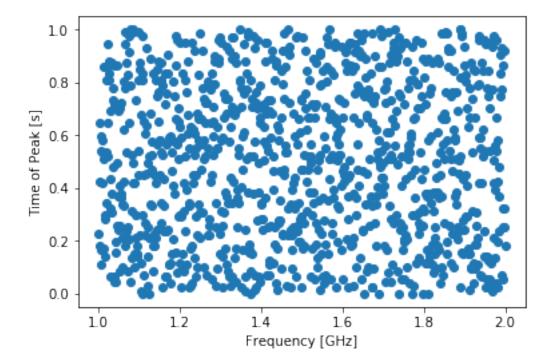
```
In [5]: # Indices of top 2 peaks for a given frequency
        idx_pk_dict = dict()
        for i,nu in enumerate(nu_vec):
            idx_pk = np.argsort(data_pulsar[i])[::-1][0:2]
            idx_pk_dict[i] = idx_pk
        # Filter to get (indices of) frequencies which have a single "clearly" distinguishable
        # (defined by a minimum difference in two max peaks' respective heights)
        # The keys are the indices matching up to nu_vec.
        # The threshold for what constitutes a single clearly distinguishable peak
        diff_threshold_dict = {i:np.max(data_pulsar[i])*0.6 for i,_ in enumerate(nu_vec)}
        # The difference between peaks at a given time
       diff_pk_dict = {i:(data_pulsar[i][idx_pk[0]]-data_pulsar[i][idx_pk[1]]) for i,idx_pk in
        # The indices (in nu_vec) for which the max is sufficiently large relative to other ti.
        idx_pk_visible_vec = [i for i,v in diff_pk_dict.items() if v>=diff_threshold_dict[i]]
        print(len(idx_pk_visible_vec))
        # print(idx_pk_visible_vec)
```

Initial Estimate Method 1: Find the Time of Peak for a Given Frequency

7



```
t0 = t_vec[np.argmax(data_pulsar[idx0])]
                                                t1 = t_vec[np.argmax(data_pulsar[idx1])]
                                                DM_array[i][j] = estimate_DM(nu0, nu1, t0, t1)
                                                      print(f'\{"\{0:2e\}".format(nu0)\}/\{"\{0:2e\}".format(nu1)\} \rightarrow \{DM\_array[i][j]\}')
                        #
                        #
                                                      if DM array[i][j] > 0:
                                                                  plt.figure()
                                                                  for n in (idx0, idx1):
                                                                              plt.plot(t\_vec, data\_pulsar[n], label=f'nu=\{"\{0:.3f\}".format(nu\_vec[n], label=f'nu=\{n\}, labe
                                                                              plt.legend()
                                                                              plt.xlabel('Time [s]')
                        #
                                                                              plt.ylabel('Power [AU]')
                        #
                       pprint(DM_array)
                       DM_array_frequency = np.array(DM_array, copy=True)
array([[nan, nan, nan, nan, nan, nan, nan],
                     [5.51e+20, nan, nan, nan, nan, nan, nan],
                     [-1.57e+19, -5.00e+19, nan, nan, nan, nan, nan],
                     [1.60e+21, 1.66e+21, 3.27e+22, nan, nan, nan, nan],
                     [3.21e+20, 3.12e+20, 1.08e+21, -3.13e+21, nan, nan, nan],
                     [6.14e+19, 4.50e+19, 1.63e+20, -2.23e+21, -1.12e+21, nan, nan],
                     [6.59e+20, 6.63e+20, 1.55e+21, -7.40e+20, 2.19e+21, 4.64e+23, nan]])
        Initial Estimate Method 2: Use Prior Knowledge (t=0 @ Start of Pulse Arrival)
In [8]: t_pk_vec = [t_vec[np.argmax(data_pulsar[i])] for i,_ in enumerate(nu_vec)]
                       plt.figure()
                       plt.plot(nu_vec*1e-9, t_pk_vec, 'o')
                       plt.xlabel('Frequency [GHz]')
                       plt.ylabel('Time of Peak [s]')
Out[8]: Text(0,0.5,'Time of Peak [s]')
```



There's not enough rhyme or reason to the above to comfortably throw something like least squares at the raw data.

General curiosity: You could rotate this and treat it as tracking a moving object (where the object's position is the frequency of the peak) with variable acceleration, then throw an extended Kalman filter at it to figure out the DM with the initial estimate calculated using either of the methods above

2.2

```
# caused by noise overwhelming the real pulse
         DM_vec = DM_array_frequency.flatten() # DM_array_frequency.flatten()/DM_vec_frequenc
         DM_vec = DM_vec[~np.isnan(DM_vec)]
         DM_vec = DM_vec[DM_vec > 0]
         DM = gmean(DM vec) # np.mean/median(DM vec)
         print(f'DM Estimate:\t\t{"{0:2e}}".format(DM)} electrons/cm^2')
         d = DM/n_e \# cm
         print(f'Distance Estimate:\t{"{0:2e}".format(d)} cm = {d*cm2pc} pc')
DM Estimate:
                            1.032229e+21 electrons/cm<sup>2</sup>
Distance Estimate:
                          3.440765e+22 cm = 11150.758494193946 pc
  The value for distance seems high.
  2.3
In [11]: omega_p = np.sqrt(4*np.pi * n_e * q**2 / m_e)
         print(f'Plasma Frequency: {"{0:2e}".format(omega_p/(2*np.pi))} Hz')
Plasma Frequency: 1.545097e+03 Hz
  2.4
In [12]: sigma_Thomson = 8*np.pi/3 * (q**2/(m_e*c**2))**2
         alpha_Thomson = n_e * sigma_Thomson
         tau_Thomson = alpha_Thomson * d
         print(f'Optical Depth: {tau_Thomson}')
Optical Depth: 0.0006672518908541399
```