

Machine Learning: Fisher's Linear Discriminant

Lecture 05

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Supervised Learning

- **Task** = learn an (unkown) function $t : X \rightarrow T$ that maps input instances $\mathbf{x} \in X$ to output targets $t(\mathbf{x}) \in T$:
 - **Classification**:
 - The output $t(\mathbf{x}) \in T$ is one of a finite set of discrete categories.
 - **Regression**:
 - The output $t(\mathbf{x}) \in T$ is continuous, or has a continuous component.
- Target function $t(\mathbf{x})$ is known (only) through (noisy) set of training examples:
$$(\mathbf{x}_1, t_1), (\mathbf{x}_2, t_2), \dots (\mathbf{x}_n, t_n)$$

Three Parametric Approaches to Classification

- 1) **Discriminant Functions**: construct $f: X \rightarrow T$ that directly assigns a vector \mathbf{x} to a specific class C_k .
 - Inference and decision combined into a single learning problem.
 - *Linear Discriminant*: the decision surface is a hyperplane in X :
 - Fisher 's Linear Discriminant
 - Perceptron
 - Support Vector Machines

Three Parametric Approaches to Classification

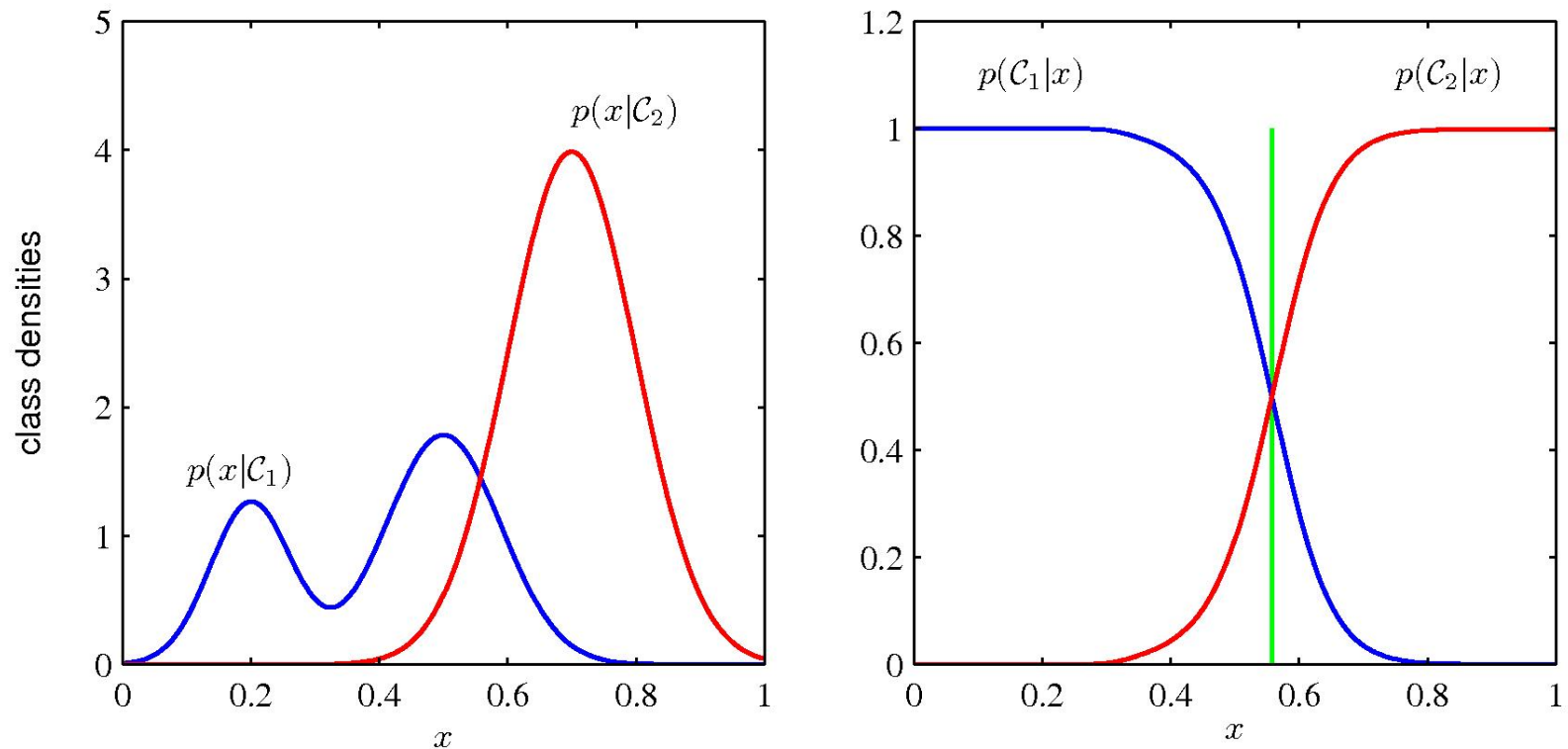
- 2) **Probabilistic Discriminative Models**: directly model the posterior class probabilities $p(C_k | \mathbf{x})$.
- Inference and decision are separate.
 - Less data needed to estimate $p(C_k | \mathbf{x})$ than $p(\mathbf{x} | C_k)$.
 - Can accommodate many overlapping features.
 - Logistic Regression
 - Conditional Random Fields

Three Parametric Approaches to Classification

3) Probabilistic Generative Models:

- Model class-conditional $p(\mathbf{x} | C_k)$ as well as the priors $p(C_k)$, then use Bayes's theorem to find $p(C_k | \mathbf{x})$.
 - or model $p(\mathbf{x}, C_k)$ directly, then marginalize to obtain the posterior probabilities $p(C_k | \mathbf{x})$.
- Inference and decision are separate.
- Can use $p(\mathbf{x})$ for *outlier* or *novelty detection*.
- Need to model dependencies between features.
 - Naïve Bayes.
 - Hidden Markov Models.

Generative vs. Discriminative



Left-hand mode has no effect on posterior class probabilities.

Linear Discriminant Functions:

Two classes ($K = 2$)

- Use a linear function of the input vector:

$$y(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + w_0$$

weight vector

bias = - threshold

- Decision:

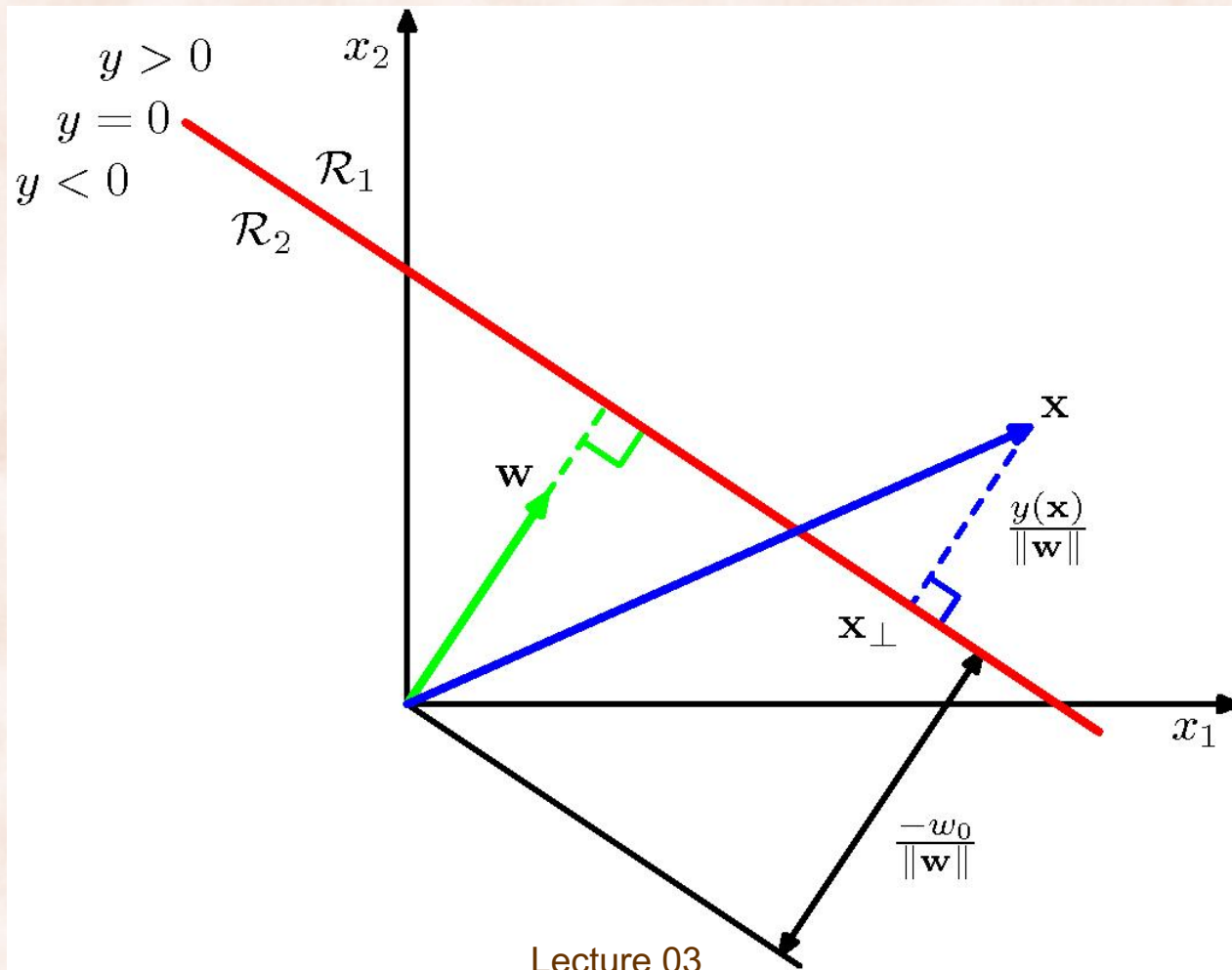
$\mathbf{x} \in C_1$ if $y(\mathbf{x}) \geq 0$, otherwise $\mathbf{x} \in C_2$.

\Rightarrow decision boundary is hyperplane $y(\mathbf{x}) = 0$.

- Properties:

- \mathbf{w} is orthogonal to vectors lying within the decision surface.
- w_0 controls the location of the decision hyperplane.

Linear Discriminant Functions: Two Classes ($K = 2$)



Linear Discriminant Functions: Multiple Classes ($K > 2$)

- 1) Train K or $K-1$ *one-versus-the-rest* classifiers.
- 2) Train $K(K-1)/2$ *one-versus-one* classifiers.

- 3) Train K linear functions:

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \boldsymbol{\varphi}(\mathbf{x}) + w_{k0}$$

- Decision:

$\mathbf{x} \in C_k$ if $y_k(\mathbf{x}) > y_j(\mathbf{x})$, for all $j \neq k$.

\Rightarrow decision boundary between classes C_k and C_j is hyperplane defined by $y_k(\mathbf{x}) = y_j(\mathbf{x})$ i.e. $(\mathbf{w}_k - \mathbf{w}_j)^T \boldsymbol{\varphi}(\mathbf{x}) + (w_{k0} - w_{j0}) = 0$

\Rightarrow same geometrical properties as in binary case.

Linear Discriminant Functions: Multiple Classes ($K > 2$)

4) More general ranking approach:

$$y(\mathbf{x}) = \arg \max_{t \in T} \mathbf{w}^T \varphi(\mathbf{x}, t) \quad \text{where} \quad T = \{c_1, c_2, \dots, c_K\}$$

- It subsumes the approach with K separate linear functions.
- Useful when T is very large (e.g. exponential in the size of input \mathbf{x}), assuming inference can be done efficiently.

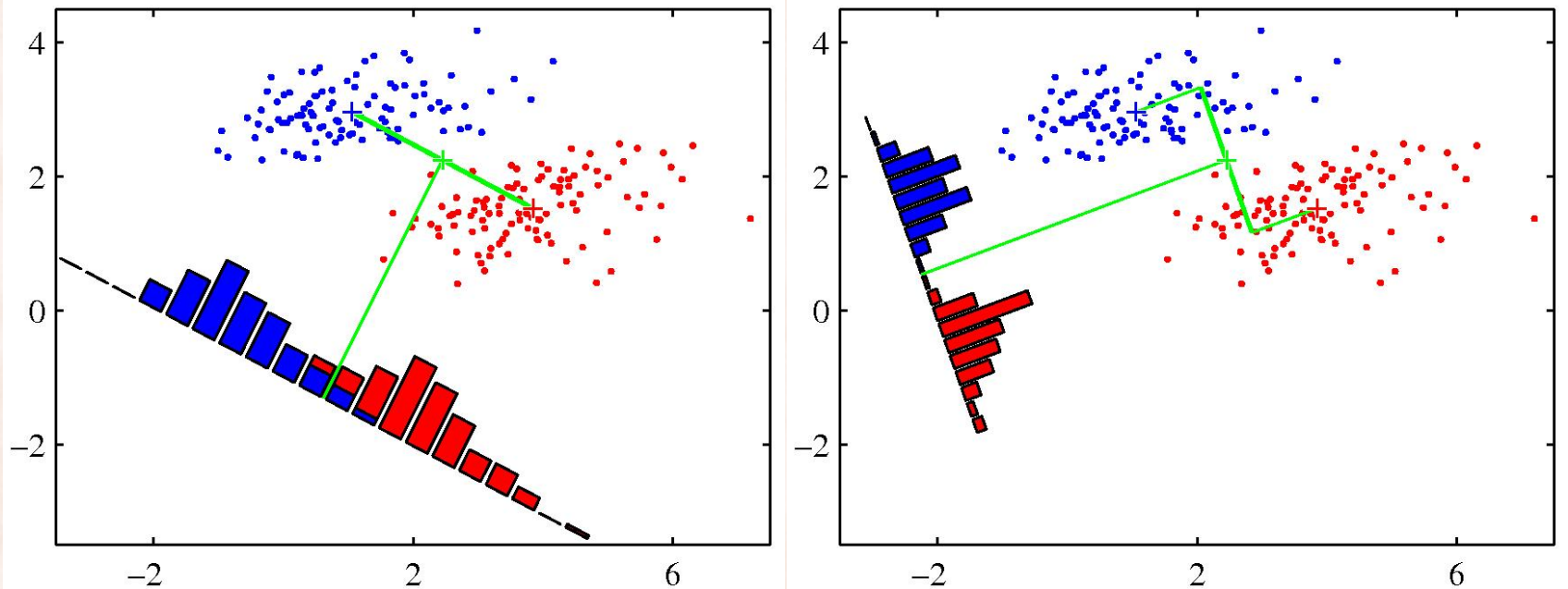
Linear Discriminant Functions: Two Classes ($K = 2$)

- What algorithms can be used to learn $y(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + w_0$?
Assume a training dataset of $N = N_1 + N_2$ examples in C_1 and C_2 .
 - Fisher's Linear Discriminant
 - Perceptron:
 - Voted/Averaged Perceptron
 - Kernel Perceptron
 - Support Vector Machines:
 - Linear
 - Kernel

Fisher's Linear Discriminant

- Discriminant function $y(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0$ can be interpreted as follows:
 1. Project D-dimensional \mathbf{x} down to one dimension $\Rightarrow \mathbf{w}^T \mathbf{x}$
 2. Use a threshold $-w_0$ to classify $\mathbf{x} \Rightarrow$
 $\mathbf{x} \in C_1$, if $\mathbf{w}^T \mathbf{x} \geq -w_0$
 $\mathbf{x} \in C_2$, otherwise.
- Fisher's idea:
 - Maximize the **between-class separation** of projected dataset.
 - Minimize the **within-class variance** of projected dataset.

Fisher's Linear Discriminant



Line joining the class means vs. Line inferred with Fisher's criterion.

Fisher's Linear Discriminant

- 1) Measure of the separation between the classes is the *between class variance*:

$$\left. \begin{aligned} \mathbf{m}_1 &= \frac{1}{N_1} \sum_{n \in C_1} \mathbf{x}_n \\ \mathbf{m}_2 &= \frac{1}{N_2} \sum_{n \in C_2} \mathbf{x}_n \end{aligned} \right\} \Rightarrow m_2 - m_1 = \mathbf{w}^T (\mathbf{m}_2 - \mathbf{m}_1) \Rightarrow (m_2 - m_1)^2$$

Fisher's Linear Discriminant

2) Measure of the *within-class variance*:

$$\left. \begin{aligned} s_1^2 &= \sum_{n \in C_1} (\mathbf{w}^T \mathbf{x}_n - m_1)^2 \\ s_2^2 &= \sum_{n \in C_2} (\mathbf{w}^T \mathbf{x}_n - m_2)^2 \end{aligned} \right\} \Rightarrow s_1^2 + s_2^2$$

Fisher's Linear Discriminant

- Maximize the between-class separation and minimize the within-class variance \Rightarrow Fisher's criterion:

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} J(\mathbf{w}) \quad , \text{ where } J(\mathbf{w}) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2}$$

- The objective function can be rewritten as:

$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

where

$$\mathbf{S}_B = (\mathbf{m}_2 - \mathbf{m}_1)(\mathbf{m}_2 - \mathbf{m}_1)^T$$

$$\mathbf{S}_W = \sum_{n \in C_1} (\mathbf{x}_n - \mathbf{m}_1)(\mathbf{x}_n - \mathbf{m}_1)^T + \sum_{n \in C_2} (\mathbf{x}_n - \mathbf{m}_2)(\mathbf{x}_n - \mathbf{m}_2)^T$$

Fisher's Linear Discriminant

- Optimization formulation:

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} J(\mathbf{w}) = \arg \max_{\mathbf{w}} \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

- Solution:

$$\frac{\partial J(\mathbf{w})}{\partial \mathbf{w}} = 0 \Rightarrow (\overbrace{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}) \mathbf{S}_B \mathbf{w} = (\overbrace{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}) \mathbf{S}_W \mathbf{w}$$

$$\Rightarrow \mathbf{S}_B \mathbf{w} = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}} \mathbf{S}_W \mathbf{w} \Rightarrow \boxed{\mathbf{S}_B \mathbf{w} = \lambda \mathbf{S}_W \mathbf{w}}$$

generalized eigenvalue problem

- If \mathbf{S}_W is nonsingular:

$$\Rightarrow \boxed{\mathbf{S}_W^{-1} \mathbf{S}_B \mathbf{w} = \lambda \mathbf{w}}$$

conventional eigenvalue problem

Fisher's Linear Discriminant

- No need to solve the eigenvalue problem:

$\mathbf{S}_B \mathbf{w} = (\mathbf{m}_2 - \mathbf{m}_1)(\mathbf{m}_2 - \mathbf{m}_1)^T \mathbf{w}$ is a vector in the direction $(\mathbf{m}_2 - \mathbf{m}_1)$

- The norm of \mathbf{w} is immaterial, only its direction is important.

\Rightarrow can take

$$\mathbf{w} = \mathbf{S}_W^{-1} (\mathbf{m}_2 - \mathbf{m}_1)$$

- How to find w_0 :
 - Assume $p(\mathbf{w}^T \mathbf{x} | C_1)$ and $p(\mathbf{w}^T \mathbf{x} | C_2)$ are Gaussians.
 - Estimate means and variances using maximum likelihood.
 - Use decision theory to find \mathbf{w}_0 i.e. $p(-\mathbf{w}_0 | C_1) = p(-\mathbf{w}_0 | C_2)$

Supplementary Reading

- PRML Section 1.4 (The Curse of Dimensionality).
- PRML Section 1.5 (Decision Theory).
- PRML Section 4 (Linear Models for Classification):
 - 4.1.1 to 4.1.4.