

# Gauss-Newton Methods

- Problem Formulation
- Gauss-Newton Methods
- Local Convergence Analysis

# Contents

- Problem Formulation
- Gauss-Newton Methods
- Local Convergence Analysis

## Problem Formulation

Given a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  we are searching for solutions of the nonlinear least-squares problem

$$\min_x \frac{1}{2} \|f(x)\|_2^2 .$$

### Examples:

- For  $f(x) = Ax - b$  this amounts to solving a standard least-squares problem,
- If we want to estimate the parameters  $x$  of a nonlinear model  $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$  from given measurements, we often set

$$f(x) = h(x) - \eta .$$

## Problem Formulation

Given a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  we are searching for solutions of the nonlinear least-squares problem

$$\min_x \frac{1}{2} \|f(x)\|_2^2 .$$

### Examples:

- For  $f(x) = Ax - b$  this amounts to solving a standard least-squares problem,
- If we want to estimate the parameters  $x$  of a nonlinear model  $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$  from given measurements, we often set

$$f(x) = h(x) - \eta .$$

## Problem Formulation

Given a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  we are searching for solutions of the nonlinear least-squares problem

$$\min_x \frac{1}{2} \|f(x)\|_2^2 .$$

### Examples:

- For  $f(x) = Ax - b$  this amounts to solving a standard least-squares problem,
- If we want to estimate the parameters  $x$  of a nonlinear model  $h : \mathbb{R}^n \rightarrow \mathbb{R}^m$  from given measurements, we often set

$$f(x) = h(x) - \eta .$$

# Contents

- Problem Formulation
- Gauss-Newton Methods
- Local Convergence Analysis

## Gauss-Newton method

In order to solve the nonlinear least-squares optimization problem  $f(x)$ , we start with an initial guess  $x_0$  and solve the standard least-squares problem

$$\min_{\Delta x_k} \frac{1}{2} \|f(x_k) + f'(x_k)\Delta x_k\|_2^2 ,$$

and update  $x_{k+1} = x_k + \alpha_k \Delta x_k$  for  $k \in \{0, 1, 2, \dots\}$ , where  $\alpha_k \in (0, 1]$  is a line search parameter.

If the Jacobian matrix  $f'(x_k)$  has full-rank, the step direction can alternatively be written in the form

$$\Delta x_k = - (f'(x_k)^T f'(x_k))^{-1} f'(x_k)^T f(x_k) .$$

## Gauss-Newton method

In order to solve the nonlinear least-squares optimization problem  $f(x)$ , we start with an initial guess  $x_0$  and solve the standard least-squares problem

$$\min_{\Delta x_k} \frac{1}{2} \|f(x_k) + f'(x_k)\Delta x_k\|_2^2 ,$$

and update  $x_{k+1} = x_k + \alpha_k \Delta x_k$  for  $k \in \{0, 1, 2, \dots\}$ , where  $\alpha_k \in (0, 1]$  is a line search parameter.

If the Jacobian matrix  $f'(x_k)$  has full-rank, the step direction can alternatively be written in the form

$$\Delta x_k = - (f'(x_k)^T f'(x_k))^{-1} f'(x_k)^T f(x_k) .$$



## Interpretation as Newton-type methods

If we apply a Newton-type method to solve the minimization problem

$$\min_x F(x) \quad \text{with} \quad F(x) = \frac{1}{2} \|f(x)\|_2^2$$

we obtain a step direction of the form

$$\Delta x_k = -M(x_k)^{-1} F'(x_k)^T = -M(x_k)^{-1} f'(x_k)^T f(x_k) .$$

Thus, Gauss-Newton methods are special class of Newton type methods which employ the Hessian approximation

$$F''(x_k) \approx M(x_k) = f'(x_k)^T f'(x_k) .$$

# Properties of Gauss-Newton Hessian approximations

The exact Hessian matrix is given by

$$F''(x_k) = f''(x_k)^T f(x_k) + f'(x_k)^T f'(x_k) = f''(x_k)^T f(x_k) + M(x_k) .$$

- The approximation error  $f''(x_k)^T f(x_k)$  is small if either the residuum  $f(x_k)$  or the second derivative  $f''(x_k)$  is small.
- The Gauss-Newton Hessian approximation  $M(x_k) = f'(x_k)^T f'(x_k)$  is always positive semi-definite.
- Similar to exact Newton methods, Gauss-Newton methods are invariant under scaling.
- $M(x_k)$  depends on first order derivatives only.

# Properties of Gauss-Newton Hessian approximations

The exact Hessian matrix is given by

$$F''(x_k) = f''(x_k)^T f(x_k) + f'(x_k)^T f'(x_k) = f''(x_k)^T f(x_k) + M(x_k) .$$

- The approximation error  $f''(x_k)^T f(x_k)$  is small if either the residuum  $f(x_k)$  or the second derivative  $f''(x_k)$  is small.
- The Gauss-Newton Hessian approximation  $M(x_k) = f'(x_k)^T f'(x_k)$  is always positive semi-definite.
- Similar to exact Newton methods, Gauss-Newton methods are invariant under scaling.
- $M(x_k)$  depends on first order derivatives only.

# Properties of Gauss-Newton Hessian approximations

The exact Hessian matrix is given by

$$F''(x_k) = f''(x_k)^T f(x_k) + f'(x_k)^T f'(x_k) = f''(x_k)^T f(x_k) + M(x_k) .$$

- The approximation error  $f''(x_k)^T f(x_k)$  is small if either the residuum  $f(x_k)$  or the second derivative  $f''(x_k)$  is small.
- The Gauss-Newton Hessian approximation  $M(x_k) = f'(x_k)^T f'(x_k)$  is always positive semi-definite.
- Similar to exact Newton methods, Gauss-Newton methods are invariant under scaling.
- $M(x_k)$  depends on first order derivatives only.

# Properties of Gauss-Newton Hessian approximations

The exact Hessian matrix is given by

$$F''(x_k) = f''(x_k)^T f(x_k) + f'(x_k)^T f'(x_k) = f''(x_k)^T f(x_k) + M(x_k) .$$

- The approximation error  $f''(x_k)^T f(x_k)$  is small if either the residuum  $f(x_k)$  or the second derivative  $f''(x_k)$  is small.
- The Gauss-Newton Hessian approximation  $M(x_k) = f'(x_k)^T f'(x_k)$  is always positive semi-definite.
- Similar to exact Newton methods, Gauss-Newton methods are invariant under scaling.
- $M(x_k)$  depends on first order derivatives only.

# Properties of Gauss-Newton Hessian approximations

The exact Hessian matrix is given by

$$F''(x_k) = f''(x_k)^T f(x_k) + f'(x_k)^T f'(x_k) = f''(x_k)^T f(x_k) + M(x_k) .$$

- The approximation error  $f''(x_k)^T f(x_k)$  is small if either the residuum  $f(x_k)$  or the second derivative  $f''(x_k)$  is small.
- The Gauss-Newton Hessian approximation  $M(x_k) = f'(x_k)^T f'(x_k)$  is always positive semi-definite.
- Similar to exact Newton methods, Gauss-Newton methods are invariant under scaling.
- $M(x_k)$  depends on first order derivatives only.

# Contents

- Problem Formulation
- Gauss-Newton Methods
- Local Convergence Analysis

## Local Convergence Analysis

As Gauss-Newton methods are special Newton-type methods the local convergence bound has the form

$$\|x_{k+1} - x^*\| \leq \kappa \|x_k - x^*\| + \frac{\omega}{2} \|x_k - x^*\|_2^2 ,$$

where

$$\|I - M(x_k)^{-1} F''(x_k)\| \leq \|M(x_k)^{-1}\| \|f(x_k)\| \|f''(x_k)\| \leq \kappa$$

- If we have  $f''(x) = 0$ , the method converges in one step.
- If we have  $f(x^*) = 0$  at the limit point  $x^*$ , we have

$$\kappa \leq \mathbf{O}(\|x_k - x^*\|)$$

and the method converges with locally quadratic rate.



## Local Convergence Analysis

As Gauss-Newton methods are special Newton-type methods the local convergence bound has the form

$$\|x_{k+1} - x^*\| \leq \kappa \|x_k - x^*\| + \frac{\omega}{2} \|x_k - x^*\|_2^2 ,$$

where

$$\|I - M(x_k)^{-1} F''(x_k)\| \leq \|M(x_k)^{-1}\| \|f(x_k)\| \|f''(x_k)\| \leq \kappa$$

- If we have  $f''(x) = 0$ , the method converges in one step.
- If we have  $f(x^*) = 0$  at the limit point  $x^*$ , we have

$$\kappa \leq \mathbf{O}(\|x_k - x^*\|)$$

and the method converges with locally quadratic rate.

## Local Convergence Analysis

As Gauss-Newton methods are special Newton-type methods the local convergence bound has the form

$$\|x_{k+1} - x^*\| \leq \kappa \|x_k - x^*\| + \frac{\omega}{2} \|x_k - x^*\|_2^2 ,$$

where

$$\|I - M(x_k)^{-1} F''(x_k)\| \leq \|M(x_k)^{-1}\| \|f(x_k)\| \|f''(x_k)\| \leq \kappa$$

- If we have  $f''(x) = 0$ , the method converges in one step.
- If we have  $f(x^*) = 0$  at the limit point  $x^*$ , we have

$$\kappa \leq \mathbf{O}(\|x_k - x^*\|)$$

and the method converges with locally quadratic rate.