

# Low-Rank Matrix Updates

- Problem Formulation
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# Problem Formulation

We have learned that Newton type methods for (unconstrained) optimization proceed by implementing iterates of the form

$$x^+ = x - M(x)^{-1} F'(x)^T .$$

Here,  $M(x) \in \mathbb{R}^{n \times n}$  is an approximation of  $F''(x)$ .

Problem: Can we construct “cheap” approximation of  $F''(x)$  such that

- we don't have to evaluate second order derivatives and
- we can cheaply compute  $M(x)^{-1}$  even if  $n$  is large?

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# Low-rank matrices

Storing “big” matrices of the form  $A \in \mathbb{R}^{n \times n}$  can be a problem if  $n$  is large. One exception are matrices that can be represented in the form

$$A = UV^T$$

with  $U, V \in \mathbb{R}^{n \times m}$  where  $m \ll n$ . Matrices of this form are not invertible and are called low-rank matrices.

An important special case is obtained for  $m = 1$ , where  $U$  and  $V$  are vectors, which yields rank-1 matrices.

## Woodbury's matrix inversion formula

One way to represent invertible matrices is by considering matrices of the form

$$A = B + UV^T$$

where  $B \in \mathbb{R}^{n \times n}$  is an “easy-to-store” matrix that is invertible and  $U, V \in \mathbb{R}^{n \times m}$ .

If the matrix  $B$  is easy to invert (or we know  $B^{-1}$  already), the inverse of the matrix  $A$  can be found from

$$(B + UV^T)^{-1} = B^{-1} - B^{-1}U(I + V^TB^{-1}U)^{-1}V^TB^{-1}$$

# Woodbury's matrix inversion formula

The inversion formula

$$(B + UV^T)^{-1} = B^{-1} - B^{-1}U(I + V^TB^{-1}U)^{-1}V^TB^{-1}$$

is known under the name Woodbury formula (or Sherman-Morrison-Woodbury formula).

For the special case  $m = 1$  the matrix  $(I + V^TB^{-1}U)$  is scalar and can be trivially inverted. In general, we only need to invert an  $(m \times m)$ -matrix instead of a  $(n \times n)$ -matrix.

## Proof of Woodbury's matrix inversion formula

A proof Woodbury's matrix inversion formula can be obtained by direct verification:

$$\begin{aligned} & (B + UV^T) \left( B^{-1} - B^{-1}U(I + V^TB^{-1}U)^{-1}V^TB^{-1} \right) \\ &= I + UV^TB^{-1} - (U + UV^TB^{-1}U)(I + V^TB^{-1}U)^{-1}V^TB^{-1} \\ &= I + UV^TB^{-1} - U(I + V^TB^{-1}U)(I + V^TB^{-1}U)^{-1}V^TB^{-1} \\ &= I + UV^TB^{-1} - UV^TB^{-1} = I . \end{aligned}$$



## Some other useful results from matrix analysis

The derivative of a function  $f : \mathbb{R}^{n \times n} \rightarrow D$  in the direction  $\Delta \in \mathbb{R}^{n \times n}$  can be defined as

$$\frac{\partial f(X)}{\partial X} \circ \Delta = \lim_{h \rightarrow 0} \frac{f(X + h\Delta) - f(X)}{h}$$

Important examples:

- $\frac{\partial \text{Tr}(AX)}{\partial X} \circ \Delta = \text{Tr}(A\Delta).$
- $\frac{\partial X^{-1}}{\partial X} \circ \Delta = -X^{-1}\Delta X^{-1}.$
- $\frac{\partial \text{Tr}(AXBX^T C)}{\partial X} \circ \Delta = \text{Tr}(A\Delta B X^T C + A X B \Delta^T C) = \text{Tr}([BX^T C A + B^T X^T C^T A^T] \Delta).$

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# Exploiting Gradient Information

When implementing Newton type methods of the form

$$x = x^- - (M^-)^{-1} F'(x^-)^T, \quad x^+ = x - M^{-1} F'(x)^T, \quad \text{and so on}$$

we have to compute the gradient  $F'(x^-)$  at the previous iterate and the gradient  $F'(x)^T$  at the current iterate.

Since we evaluate the gradient at two points anyhow, we can obtain the directional estimate

$$F''(x)(x - x^-) \approx F'(x)^T - F'(x^-)^T$$

Can we use this relation to improve our next Hessian approximation

$$M^+ \approx F''(x^+)?$$

# Exploiting Gradient Information

Let  $M$  be our current Hessian approximation. The relation

$$F''(x)d \approx y \quad \text{with} \quad d = x - x^- \quad \text{and} \quad y = F'(x)^T - F'(x^-)^T$$

motivates to improve our current estimate of  $F''$  constructing  $M^+$  by solving

$$\min_{M^+} \frac{1}{2} \|M^+ - M\|^2 \quad \text{s.t.} \quad M^+ d = y$$

for a suitable matrix norm  $\|\cdot\|$ .

## Exploiting Gradient Information

If we work with Frobenius norms, we can solve the optimization problem

$$\min_{M^+} \frac{1}{2} \|M^+ - M\|_F^2 \quad \text{s.t.} \quad M^+ d = y$$

explicitly. Here, the Frobenius norm is given by

$$\|X\|_F^2 = \text{Tr}(XX^T) .$$

For this aim, we work out the optimality conditions

$$0 = (M^+ - M)^T + d\lambda^T \quad \text{and} \quad M^+ d = y .$$

## Broyden's update formula

The multiplier  $\lambda$  can be found by eliminating  $M^+$  from the stationarity condition,

$$M^+ = M - \lambda d^T ,$$

and substituting into the directional equality constraint,

$$M^+ d = (M - \lambda d^T) d = y$$

which yields  $\lambda = \frac{1}{d^T d} (Md - y)$ . The corresponding update formula,

$$M^+ = M - \frac{(Md - y) d^T}{d^T d}$$

is called Broyden's matrix update.

## Inverse Broyden's update formula

Broyden's updates turns out to be a rank-1 update,

$$M^+ = M - \frac{(Md - y)d^T}{d^T d}.$$

Assuming that we have already computed  $M^{-1}$ , Woodbury's matrix inversion formula yields a direct update of the inverse:

$$\begin{aligned}(M^+)^{-1} &= M^{-1} + M^{-1} \frac{Md - y}{d^T d} \left( 1 - d^T M^{-1} \frac{Md - y}{d^T d} \right)^{-1} d^T M^{-1} \\ &= M^{-1} + \frac{(d - M^{-1}y)d^T M^{-1}}{d^T M^{-1}y}.\end{aligned}$$

# Inverse Broyden's update formula

Broyden's update formula

$$(M^+)^{-1} = M^{-1} + \frac{(d - M^{-1}y)d^T M^{-1}}{d^T M^{-1}y} .$$

solves two problems at the same time:

- we don't need to compute any second order derivatives
- we can directly compute  $(M^+)^{-1}$ , no inversion needed.

But:  $M^+$  may be non-symmetric even if the original matrix  $M$  was symmetric.



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## Broyden-Fletcher-Goldfarb-Shanno Updates

Broyden, Fletcher, Goldfarb, and Shanno suggested a technique to improve Broyden's original update formula. The idea is to maintain the symmetry of the updates by solving

$$\min_{M^+} \frac{1}{2} \|M^+ - M\|^2 \quad \text{s.t.} \quad \begin{cases} (M^+)^T d = y \\ M^+ d = y . \end{cases}$$

Here, the norm is (mainly for computational reasons) weighted in very particular way (assume  $M$  is positive definite):

$$\|M^+ - M\|^2 = \text{Tr} \left( W^{\frac{1}{2}} (M^+ - M)^T M^{-1} (M^+ - M) W^{\frac{1}{2}} \right) ,$$

where  $W^{\frac{1}{2}}$  can be any symmetric positive definite weighting matrix satisfying  $Wy = d$ .

## Broyden-Fletcher-Goldfarb-Shanno Updates

The first order necessary (and sufficient) optimality conditions take the form

$$0 = W(M^+ - M)^T M^{-1} + d\lambda^T + \mu d^T \quad \text{and} \quad \begin{cases} (M^+)^T d = y \\ M^+ d = y \end{cases}$$

Here, we assume  $M = M^T$ . It is easy to check that these conditions are satisfied for the symmetric rank-2 update

$$M^+ = M + \frac{yy^T}{y^T d} - \frac{Mdd^T M}{d^T M d}.$$

This is called the BFGS update formula; symmetry is maintained.

## Broyden-Fletcher-Goldfarb-Shanno Updates

Similar to Broyden updates the BFGS update can be applied through Woodbury's formula. This yields a direct update for the inverse of  $M$ , which has the form

$$(M^+)^{-1} = \left( I - \frac{dy^T}{d^T y} \right) M^{-1} \left( I - \frac{dy^T}{d^T y} \right)^T + \frac{dd^T}{d^T y}.$$

Notice that if  $F$  is strictly convex, the term

$$d^T y = (x - x^-)^T (F'(x)^T - F'(x^-)^T) \approx (x - x^-)^T F''(x) (x - x^-)$$

can be expected to be positive. (there are many variants of BFGS around; some additionally maintain the positive definiteness of  $M$ ; others work with “limited memory”)