

# Homework 4 · Lyell Read

279: 5.2.8(a), 5.2.9(a) | 290: 5.4.1 | 307: 5.6.6 | 314: 5.7.2

321: 5.8.3 |

5.2.8 (a)

$$T \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x+2y+3z \\ 2y-3x+z \end{bmatrix}$$

Linearity Check: (1)

$$T \left( \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} \right) = T \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + T \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}$$

Linearity Check (2)

$$T \left( 2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right) = 2 \left( T \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right) : \longrightarrow$$

$$\begin{cases} T \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix} = \begin{bmatrix} 2+4+6 \\ 4-6+2 \end{bmatrix} = \begin{bmatrix} 12 \\ 0 \end{bmatrix} \\ 2 \left[ \begin{bmatrix} 1+2+3 \\ 2-3+1 \end{bmatrix} \right] = 2 \begin{bmatrix} 6 \\ 0 \end{bmatrix} = \begin{bmatrix} 12 \\ 0 \end{bmatrix} \end{cases}$$

↳ Linearity "confirmed"

$$T(x) = Ax, \quad A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & -3 & 1 \end{pmatrix}$$

5.2.9 (a)

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{bmatrix} x+2y+3z+1 \\ 2y-3x+z \end{bmatrix}$$

check linearity (1)

$$T \left( \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} + \begin{pmatrix} x_4 \\ x_5 \\ x_6 \end{pmatrix} \right) = T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} + T \begin{pmatrix} x_4 \\ x_5 \\ x_6 \end{pmatrix}$$

↳ probably is equal... don't need to solve

check linearity (2)

$$T \left( c \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \right) = c T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \longrightarrow \begin{cases} T \begin{pmatrix} cx_1 \\ cx_2 \\ cx_3 \end{pmatrix} = \begin{bmatrix} cx_1 + 2cx_2 + 3cx_3 + 1 \\ 2cx_2 - 3cx_1 + cx_3 \end{bmatrix} \\ c T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = c \begin{bmatrix} x_1 + 2x_2 + 3x_3 + 1 \\ 2x_2 - 3x_1 + x_3 \end{bmatrix} = \begin{bmatrix} cx_1 + 2cx_2 + 3cx_3 + c \\ 2cx_2 - 3cx_1 + cx_3 \end{bmatrix} \end{cases}$$

NOT LINEAR



5.4.1:

find matrix for linear transformation that rotates every vector in  $\mathbb{R}^2$  through  $\theta = \pi/3$ .

$$f\begin{pmatrix} x \\ y \end{pmatrix} \rightarrow \begin{pmatrix} x' \\ y' \end{pmatrix} : \mathbb{R}^2 \rightarrow \mathbb{R}^2.$$

$$= A \begin{pmatrix} x \\ y \end{pmatrix}$$

derived from  
rotated  $\theta$   
In degrees...

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$f\begin{pmatrix} x \\ y \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} \cos \frac{\pi}{3} x - \sin \frac{\pi}{3} y \\ \sin \frac{\pi}{3} x + \cos \frac{\pi}{3} y \end{bmatrix}$$

5.6.6:

$$T: \mathbb{R}^4 \rightarrow \mathbb{R}^3 \text{ defined by } Tx = \begin{bmatrix} 3 & 2 & 1 & 8 \\ 2 & 2 & -2 & 6 \\ 1 & 1 & -1 & 3 \end{bmatrix} \cdot \vec{x}$$

$$\text{Im}(T) = \text{Range}(T) = \text{col. space of } A$$

$$\rightarrow \begin{bmatrix} 3 & 2 & 1 & 8 \\ 1 & 1 & -1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{1-3\text{②}} \begin{bmatrix} 0 & -1 & 4 & -1 \\ 1 & 1 & -1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 & 3 \\ 0 & 1 & -4 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\Delta \Delta$   
free free  $\rightarrow$  exist...

$$\text{Im}(T) = \text{span} \left\{ \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix}, \begin{pmatrix} 8 \\ 6 \\ 3 \end{pmatrix} \right\}$$

$$\text{as } \begin{bmatrix} 3 & 2 & 1 & 8 \\ 2 & 2 & -2 & 6 \\ 1 & 1 & -1 & 3 \end{bmatrix} \begin{pmatrix} s \\ t \\ u \\ v \end{pmatrix} = s \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} + u \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix} + v \begin{pmatrix} 8 \\ 6 \\ 3 \end{pmatrix}$$

$$\begin{bmatrix} 3 & 2 & 1 & 8 \\ 2 & 2 & -2 & 6 \\ 1 & 1 & -1 & 3 \end{bmatrix} \xrightarrow{\text{③} \cdot 2} \begin{bmatrix} 3 & 2 & 1 & 8 \\ 2 & 2 & -2 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{②} \cdot 2} \begin{bmatrix} 3 & 2 & 1 & 8 \\ 3 & 3 & -3 & 9 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow$$

$1 - (2(-4))$

$$\xrightarrow{\text{②} \cdot 1} \begin{bmatrix} 3 & 2 & 1 & 8 \\ 0 & 1 & -4 & 1 \\ \text{---} & \text{---} & \text{---} & \text{---} \end{bmatrix} \xrightarrow{\text{①} - 2\text{②}} \begin{bmatrix} 3 & 0 & 9 & 6 \\ 0 & 1 & -4 & 1 \\ \text{---} & \text{---} & \text{---} & \text{---} \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 3 & 2 \\ & 1 & -4 & 1 \\ & & & \end{bmatrix} \rightarrow \begin{cases} \text{NEXT} \\ \text{PG} \end{cases}$$



$$\begin{cases} x_1 + 3x_3 + 2x_4 = 0 \\ x_2 - 4x_3 + x_4 = 0 \end{cases} \rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 3 \\ 2 \end{pmatrix} s + \begin{pmatrix} 0 \\ 1 \\ -4 \\ 1 \end{pmatrix} t + \ker(T)$$

$= \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 3 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -4 \\ 1 \end{pmatrix} \right\}$

5.7.2:

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\text{Im}(T) = \text{Range}(T) \rightarrow \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \rightarrow \begin{cases} x+y=0 \\ x=-y \end{cases}$$

$R(T) = \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) \text{span}$

$$\ker(T) = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \rightarrow \begin{cases} x+y=0 \\ x=-y \end{cases}$$

$$\downarrow \begin{pmatrix} x \\ y \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 0 \quad \ker = \text{span} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

5.8.3

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad T \left( \begin{bmatrix} a \\ b \end{bmatrix} \right) = \begin{bmatrix} a+b \\ a-b \end{bmatrix} \quad \text{consider } \begin{cases} B_1 = \{v_1, v_2\} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\} \\ B_2 = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\} \end{cases}$$

Find  $M_{B_2, B_1}$  of  $T$  w.r.t  $B_1, B_2$ .

$$A \text{ for } T = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}$$

$u_2 \quad z \cdot T$

See other side for corrected solution  $\rightarrow$

$S = \text{standard basis}$

$$S \rightarrow B_1 = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$S \rightarrow B_2 = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$B_1 \rightarrow B_2 = B_1 \rightarrow S \rightarrow B_2$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 1 & -1 \end{pmatrix}$$

Not sure about this, but I'll be asking.

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$$T\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}$$

$$B_1 = \left\{ \underset{v_1}{\begin{pmatrix} 1 \\ 0 \end{pmatrix}}, \underset{v_2}{\begin{pmatrix} -1 \\ 1 \end{pmatrix}} \right\}$$

$$B_2 = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ -1 \end{pmatrix} \right\}$$

$$T(v_1) = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}^w$$

$$T(v_2) = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -2 \end{pmatrix} = -w_1 + w_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$$

$$\hookrightarrow \boxed{\begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}}$$

(based on the solution you worked out after class 5/23)