

MTH 341 4/2/2019

CH 1

- a matrix is a rectangular array of numbers or variables

- Example: $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ A is a 2×2

- $A = (A_{ij}) = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}$ A_{ij} is i^{th} row, j^{th} col

NOTE: A is used in place of "a" here.

- a real number is a 1×1 matrix, i.e. $(b)_{1 \times 1}$

- A vector is a 3×1 matrix: $v = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}_{3 \times 1}$

→ can also be row vector \downarrow column vector

$$v = (0 \ 1 \ 2)_{1 \times 3}$$

Matrix Addition

→ if two matrices A and B have same size then their sum is $A+B$.

→ Then: $(A+B)_{ij} = (A)_{ij} + (B)_{ij}$

→ Also: if $A = (a_{ij})_{m \times n}$

$$B = (b_{ij})_{m \times n}$$

Then: $A+B = (a_{ij} + b_{ij})_{m \times n}$

→ EX: $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 2 \\ 3 & 5 \end{pmatrix}$

Matrix Difference

- $A-B = (a_{ij} - b_{ij})_{m \times n}$

- EX: $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ 3 & 3 \end{pmatrix}$

Scalar Multiplication

- multiplying the whole matrix as a constant.

- EX: $3A \mid A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

$$3A = \begin{pmatrix} 3 & 6 \\ 9 & 12 \end{pmatrix}$$

Zero Matrix

- simple: $(0)_{m \times n}$. this represents a matrix whose entries are zero.

Zero Matrix

- Also note: $A_{m \times n} + 0_{m \times n} = A_{m \times n}$

Equality of Matrices

- $A=B$ if:

→ ① A, B have same size

→ ② $a_{ij} = b_{ij}$ for all i, j .

Multiplication (Product)

- Define $A_{m \times k}$ and $B_{k \times n}$

(rows of B = cols of A)

- Product $(AB)_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots$

- EX:

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1k} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mk} \end{pmatrix}_{m \times k} \quad B = \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{k1} & b_{k2} & \dots & b_{kn} \end{pmatrix}_{k \times n}$$

- EX 2:

$$A = \begin{pmatrix} 1 & 2 & 3 \\ -1 & 0 & 4 \end{pmatrix}_{2 \times 3} \quad B = \begin{pmatrix} -1 & 0 \\ 4 & 2 \\ 1 & 3 \end{pmatrix}_{3 \times 2}$$

OK! Sizes

$$AB = \begin{pmatrix} \text{first row} + \text{first col} & \dots \\ \vdots & \text{last row last col} \end{pmatrix} = \begin{pmatrix} 10 & 13 \\ 5 & 12 \end{pmatrix}$$

- matrix product is not commutative

EX: $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$

$$AB = \begin{pmatrix} (1 \cdot 1) + (2 \cdot 0) & (1 \cdot 0) + (2 \cdot 0) \\ (3 \cdot 1) + (4 \cdot 0) & (3 \cdot 0) + (4 \cdot 0) \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 3 & 0 \end{pmatrix}$$

$$BA = \begin{pmatrix} (1 \cdot 1) + (0 \cdot 3) & (1 \cdot 2) + (0 \cdot 4) \\ (0 \cdot 1) + (0 \cdot 3) & (0 \cdot 2) + (0 \cdot 4) \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}$$

$AB \neq BA \therefore$ not commutative

- EX: $A = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \quad B = \begin{pmatrix} 1 & 2 \end{pmatrix}$

$$AB = \begin{pmatrix} 2 & 4 \\ 3 & 6 \end{pmatrix}_{2 \times 2} \quad BA = \begin{pmatrix} 8 \end{pmatrix}_{1 \times 1}$$

Rotation Matrix

$$- \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

- usage: rotating point $(x, y) \rightarrow (x', y')$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

Multiplication

- note: $ABC \Rightarrow A(BC) = (AB)C$

Double Rotation Matrix

$$- \begin{pmatrix} \cos \phi \cos \theta - \sin \phi \sin \theta & -\cos \phi \sin \theta - \sin \phi \cos \theta \\ \sin \phi \cos \theta + \cos \phi \sin \theta & -\sin \phi \sin \theta + \cos \phi \cos \theta \end{pmatrix}$$
$$= \begin{pmatrix} \cos(\phi + \theta) & -\sin(\phi + \theta) \\ \sin(\phi + \theta) & \cos(\phi + \theta) \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

- If $A = (a_{ij})$ then $A^t = (a_{ji})$

- If AB is defined:

$$\rightarrow (AB)^t = B^t A^t$$

NOTE: $(AB)^t \neq A^t B^t$

Square Matrix

- is a matrix with the same number of rows as columns

- $\rightarrow A_{n \times n}$

Identity Matrix

- the identity matrix I_n has ones on the diagonal and 0's elsewhere

$$- I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}_{3 \times 3}$$

- $I_n = (a_{ij})$ where $a_{ii} = 1$ and $a_{ij} = 0$ (where $i \neq j$)

- Ex: AI is A , IA is A

Properties of Matrices

① If AB and AC are defined,

$$\text{then } A(B+C) = AB + AC$$

② If AB is defined, and c is a scalar,

$$\text{then } A(cB) = (cA)B = c(AB)$$

Inverses

- if $BA = I = AB$ then

B is inverse of A and

A is inverse of B

$$\hookrightarrow B = A^{-1}, A = B^{-1}$$

Transposition of Matrices

- transpose of A is defined as A^t

- first row of A becomes first col of A^t

...

Also:

$$- \text{Ex: } A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}_{3 \times 2} \quad A^t = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix}_{2 \times 3}$$

- If $A_{m \times n}$ then $A^t_{n \times m}$ (sizes swap)

$$- AB = I \rightarrow C(AB) = CI \rightarrow C(AB) = C$$