YINGJIE LI

https://lyj1201.github.io/yingjieli/ (435) 695-3478 \(\phi\) yingjie.li@utah.edu

EDUCATION & EMPLOYMENT

University of Utah

2020-present

Doctor of Philosophy, Computer Engineering

Advisor: Cunxi Yu

Selected courses: Adv Digital VLSI, Deep Learning Systems, Graduate Algorithms, CAD of Digital

Circuits, Computer Architecture

DELL EMC, Shanghai, China

2019-2020

Hardware Engineer

Cornell University

2018-2019

M.Eng, Electrical and Computer Engineering

Huazhong University of Science and Technology

2014-2018

B.S., Electrical and Computer Engineering (Honor)

AWARDS

DAC Young Student Fellow, 2020 (winning presentation) and 2021

Outstanding Graduates, Huazhong University of Science and Technology, 2018

PROJECTS

• LightRidge: End-to-end photonic compiler framework for optical neural networks

This work is the first effort in building modern Physics Compiler, specifically, a photonic compiler framework to deal with fundamental optical physics and emerging optical computing systme emulations(https://ycunxi.github.io/lightbridge/index.html). It features with a) heterogeneous HPC accelerated physics engines, b) highly versatile and flexible optical physics modelling, c) user-friendly front-end APIs, d) and backend hardware deployment supports. This enables a complete full-stack design and exploration from ML algorithms, to hardware-software codesign, finally to the hardware and device level.

Publications: ROAD4DNN@DAC21, ISCA22 (to be submitted)

• Discrete and Differentiable Device-to-System Co-Optimization using Gumbel-Softmax This work Realizes quantization with arbitrary digits in Hardware-Software Codesign in Optical Neural Networks. Exploring the best algorithm for Gumbel-Softmax with LightRidge, we can train the model with quantization for the hardware to close the gap between simulation and experiments.

Publications: ICLR'22 (under review)

• Real-world All-optical Multi-task Learning with Physics-aware training We explore two research directions in realizing cost-efficient multi-task learning (MTL) problems using D2NNs – 1) the first one focuses on real-time MTL with single optical detectors and 2) the second one introduces a first-of-its-kind *physical rotation aware* training to enable weights sharing in post-fabrication system, all performed with our LightRidge compiler.

Publications: AAAI'22 (under review), Springer Nature Scientific Report 2021.

• Physical Adversarial Attacks of Diffractive Deep Neural Networks To study vulnerability and robustness of optical neural networks, we develop the first adversarial attack formulations over optical physical meanings, and provide a comprehensive analysis of adversarial robustness of D2NNs under practical adversarial threats over optical domains. This is also the first work on analyzing adversarial robustness of complex-valued neural networks.

Publications: DAC'21.

PUBLICATIONS

- Yingjie Li, Ruiyang Chen, Weilu Gao, and Cunxi Yu. Differentiable Discrete Device-to-System Codesign for Optical Neural Networks via Gumble-Softmax. The International Conference on Learning Representations (ICLR'22) (under review)
- Yingjie Li, Weilu Gao, and Cunxi Yu. Rubik's Optical Neural Networks: Multi-task Learning with Physics-aware Training. Thirty-Sixth AAAI Conference on Artificial Intelligence (AAAI'22). (under review)
- Yingjie Li, Minhan Lou, Ruiyang Chen, Jichao Fan, Berardi Sensale Rodriguez, Weilu Gao and Cunxi Yu. LightRidge: End-to-end Photonic Compiler Framework for Diffractive Optical Neural Networks. Design Automation Conference (DAC'21) ROAD4NN Workshop. San Francisco, December 2021.
- Yingjie Li, Cunxi Yu. Late Breaking Results: Physical Adversarial Attacks of Diffractive Deep Neural Networks. IEEE/ACM 58th Design Automation Conference (DAC'21).
- Yingjie Li, Ruiyang Chen, Berardi Sensale Rodriguez, Weilu Gao, and Cunxi Yu. *Multi-task Learning in Diffractive Deep Neural Networks via Hardware-software Co-design*. Spinger Nature Scientific Reports, 11, 11013 (2021).
- Walter Lau Neto, Matheus Trevisan Moreira, Yingjie Li, Luca Amaru, Cunxi Yu, and Pierre-Emmanuel Gaillardon. SLAP: A Supervised Learning Approach for Priority Cuts Technology Mapping. IEEE/ACM 58th Design Automation Conference (DAC'21).

SKILLS

Programming skills: Python, BASH, LATEX

Platforms: Linux (RHEL, Ubuntu)