# KEVIN LAU

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## Education

#### Imperial College London

Oct 2022 - Jun 2026

## MEng Electronic and Information Engineering (Computer Engineering)

- Predicted 1st class honours, starting penultimate year
- Modules of interest: Instruction Set Architecture and Compilers, Advanced Computer Architecture, Digital Systems
   Design, Information Processing, Graphics, Embedded Systems

## Work Experience

## 3D Gaussian Splatting Quantisation and Acceleration Hardware Research

Jul 2024 - ongoing

## Deep Wok Lab (Imperial x Cambridge Research Team) §

- Designing quantised hardware for 3D Gaussian Splatting in **SystemVerilog** with custom **cocotb** testbenches
- Implemented quantisation-aware training for 3DGS using PyTorch, achieving similar PSNR benchmarks to the official CUDA implementation
- Applied in-house compiler MASE's custom quantisers to evaluate the best quantisation scheme for hardware design

## University Course FPGA Module Design

Jul - Sept 2024

## Imperial College London (Department of Electrical and Electronic Engineering)

- Redesigned the 2nd year Information Processing module teaching content and lab practicals from scratch
- Introduced concepts of hardware-software codesign and embedded development with Verilog, C++ and Python
- Emphasized on practical skills development with the Xilinx FPGA toolchain and edge-computing applications

## Undergraduate Teaching Assistant

Oct 2023 - Mar 2024

#### Imperial College London (Department of Electrical and Electronic Engineering)

- Worked with the department to provide learning support to 1st year students in Programming for Engineers module
- Guided students on learning fundamental C++ concepts and developing object-oriented programming skills

## Full-Stack Web Developer

Jul - Sept 2023

#### DiTa Limousine Limited §

- Developed a responsive and interactive website using ReactJS and Framer Motion for the company website, which
  enhanced user engagement and contributed to a 50% increase in new limousine service bookings
- Hosted the website on a self-managed Ubuntu Virtual Private Server, gaining experience with the Linux shell and server management using NGINX

### Projects

## Graphics Processing Unit (TauriGPU) & | System Verilog, Python, GLSL

Jul 2024 – ongoing

- Developing an open-source programmable GPU compatible with **OpenGL ES2** and **Xilinx FPGAs**
- In progress of building an LLVM backend for TauriGPU's ISA to enable GLSL compilation

## C90 to RISC-V Compiler $\mathcal{O} \mid C++$ , RISC-V Assembly

Dec - Mar 2024

- Developed a compiler with advanced features, e.g. N-dimensional array support and efficient memory management
- Placed 1st out of 48 teams, achieving 90% pass rate in seen and unseen test cases

## **RISC-V CPU** $\boldsymbol{\mathscr{O}} \mid SystemVerilog, C++, RISC-V Assembly$

Nov - Dec 2023

- Developed a single-cycle RISC-V 32I processor that runs all base instructions using SystemVerilog
- Implemented pipelining and direct-mapped cache to improve processing and memory access speed
- Placed 1st out of 24 teams in both quality of verification and codebase documentation

## Software-Hardware Low Latency Algorithmic Trading System with FPGA | Xilinx, Python

Feb 2024

- Utilised the PYNQ-Z1 FPGA to accelerate moving average indicators to identify market opening convergence opportunities using the Xilinx toolchain
- Top 5 finalist at IC Hack 24's Optiver trading challenge out of 20+ teams, invited to present trading strategy to
   Optiver representatives

#### FPGA Computer Vision Acceleration for ESP32 WiFi Car Racing System | Xilinx, C++ Feb - Mar 2024

- Built a commercializable hardware racing game with AWS cloud backend and implemented powerups using OpenCV
- Developed hardware IPs for local OpenCV acceleration on the PYNQ-Z1 FPGA using the Xilinx toolchain

#### Autonomous Balance Bot with Incident Management Platform @ | Python, ROS 2

May - June 2024

- Led development of the autonomous navigation and physical incident detection system using SLAM and ROS 2
- Developed a Frontier-based exploration algorithm to enable autonomous exploration capabilities in completely unknown dynamic environments
- Physically implemented system on a Raspberry Pi 4 with a 2D LiDAR sensor and a camera

## Skills and Awards

## Technical Skills

Programming Languages: C, C++, Python, JavaScript, RISC-V Assembly

Hardware Description Languages: SystemVerilog, Verilog, VHDL

Technologies: CUDA, OpenGL, PyTorch, Git, Verilator, cocotb, ROS 2, NumPy, OpenCV, ReactJS, NGINX, Conda

FPGA toolchain: AMD Xilinx (Vivado, Vitis), Intel Quartus Prime

Languages: English (native), Cantonese (native), Mandarin Chinese (fluent)

## Awards

Hong Kong Scholarship for Excellence Scheme: Awarded title of Hong Kong Scholar (since 2022)

Diocesan Boys' School: Top International Baccalaureate scorer (44/45 marks), Subject prize scholarship (2022)