

Apache Cassandra multi-dc essentials

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iland cloud?

- public / private cloud provider
- footprint in U.S., EU and Asia
- compliance, advanced security
- custom SLA
- Apache Cassandra users since 1.2
 C* summit 2015 presentation: http://www.slideshare.net/anguenot/leveraging-cassandra-for-realtime-multidatacenter-public-cloud-analytics

Apache Cassandra spanning 6 datacenters.

http://www.iland.com







key notions & configuration

What is Apache Cassandra?

- distributed partitioned row store
- physical multi-datacenter native support
- tailored (features) for multi-datacenter deployment



Why multi-dc deployments?

- multi-datacenter distributed application
- performances
 - read / write isolation or geographical distribution
- disaster recovery (DR)
 failover and redundancy
- analytics



Essentially...

- sequential writes in commit log (flat files)
- indexed and written in **memtables** (in-memory: write-back cache)
- serialized to disk in a SSTable data file
- writes are partitioned and replicated automatically in cluster
- SSTables consolidated though compaction to clean tombstones
- repairs to ensure consistency cluster wide



Cassandra hierarchy of elements

cluster datacenter(s) rack(s) server(s)





Cassandra cluster

- the sum total of all the servers in your database throughout all datacenters
- span physical locations
- defines one or more keyspaces
- no cross-cluster replication



cassandra.yaml: `cluster_name`

```
# The name of the cluster. This is mainly used to prevent machines in # one logical cluster from joining another. cluster name: 'my little cluster'
```



Cassandra datacenter

- grouping of nodes
- synonymous with replication group
- a grouping of nodes configured together for replication purposes
- each datacenter contains a complete token ring
- collection of Cassandra racks



Cassandra rack

- collection of servers
- at least one (1) rack per datacenter
- one (1) rack is the most simple and common setup



Cassandra server

- Cassandra (the software) instance installed on a machine
- AKA node
- contains virtual nodes (or **Vnodes**). 256 by default



Virtual nodes (Vnodes)

- C*>= 1.2
- data storage layer within a server
- tokens automatically calculated and assigned randomly for all Vnodes
- automatic rebalancing
- no manual token generation and assignment
- default to 256 (num_tokens in cassandra.yaml)

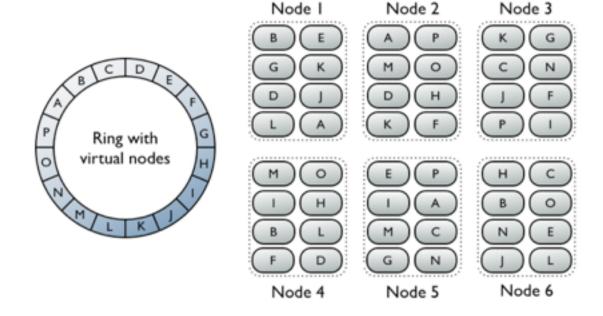


cassandra.yaml: `num_tokens`

```
# This defines the number of tokens randomly assigned to this node on the ring
# The more tokens, relative to other nodes, the larger the proportion of data
# that this node will store. You probably want all nodes to have the same number
# of tokens assuming they have equal hardware capability.
#
# If you leave this unspecified, Cassandra will use the default of 1 token for
legacy compatibility.
# and will use the initial_token as described below.
#
# Specifying initial token will override this setting on the node's initial start,
# on subsequent starts, this setting will apply even if initial token is set.
#
# If you already have a cluster with 1 token per node, and wish to migrate to
# multiple tokens per node, see http://wiki.apache.org/cassandra/Operations
num tokens: 256
```



Ring with Vnodes





Partition

- individual unit of data
- partitions are replicated across multiple Vnodes
- each copy of the partition is called a replica



Vnodes and consistent hashing

- allows distribution of data across a cluster
- Cassandra assigns a hash value to each partition key
- each Vnode in the cluster is responsible for a range of data based on the hash value
- Cassandra places the data on each node according to the value of the partition key and the range that the node is responsible for



Partitioner (1/2)

- partitions the data across the cluster
- function for deriving a token representing a row from its partition key
- hashing function
- each row of data is then distributed across the cluster by the value of the token



Partitioner (2/2)

- Murmur3Partitioner (default C* >= 1.2)
 uniformly distributes data across the cluster based on
 MurmurHash hash values
- RandomPartitioner (default C* < 1.2)
 uniformly distributes data across the cluster based on MD5
 hash values
- ByteOrderedPartitioner (BBB)
 keeps an ordered distribution of data lexically by key bytes



cassandra.yaml: `partitioner`

```
# The partitioner is responsible for distributing groups of rows (by
# partition key) across nodes in the cluster. You should leave this
# alone for new clusters. The partitioner can NOT be changed without
# reloading all data, so when upgrading you should set this to the
# same partitioner you were already using.
#
# Besides Murmur3Partitioner, partitioners included for backwards
# compatibility include RandomPartitioner, ByteOrderedPartitioner, and
# OrderPreservingPartitioner.
#
partitioner: org.apache.cassandra.dht.Murmur3Partitioner
```



Partitioner example (1/4)

name	age	car	gender
jim	36	camaro	M
carol	37	bmw	F
johnny	12		М
suzy	10		F

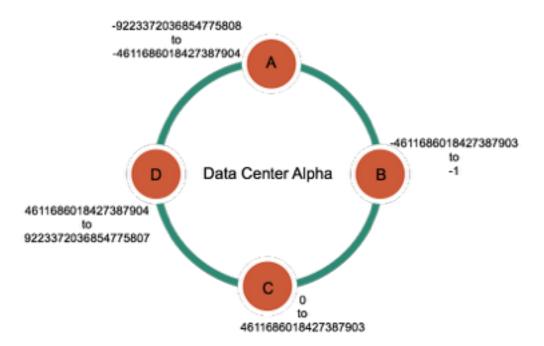


Partitioner example (2/4)

Partition key	Murmur3 hash value
jim	-2245462676723223822
carol	7723358927203680754
johnny	-6723372854036780875
suzy	1168604627387940318



Partitioner example (3/4)





Partitioner example (4/4)

Node	Start range	End range	Partition key	Hash value
А	-9223372036854775808	-4611686018427387904	johnny	-6723372854036780875
В	-4611686018427387903	-1	jim	-2245462676723223822
С	0	4611686018427387903	suzy	1168604627387940318
D	4611686018427387904	9223372036854775807	carol	7723358927203680754



Cassandra hierarchy of elements (recap)

cluster datacenter(s) rack(s) server(s) Vnode(s)



Cassandra Keyspace (KS)

- namespace container that defines how data is replicated on nodes
- cluster defines KS
- contains tables
- defines the replica placement strategy and the number of replicas



Data replication

- process of storing copies (replicas) on multiple nodes
- KS has a replication factor (RF) and replica placement strategy
- max (RF) = max(number of nodes) in one (1) data center
- data replication is defined per datacenter



Replica placement strategy

there are two (2) available replication strategies:

- 1. SimpleStrategy (single DC)
- 2. NetworkTopologyStrategy (recommended cause easier to expand)

choose strategy depending on **failure scenarios** and application needs for **consistency level**



Consistency Level (CL)

- how many nodes must ACK operation at client level?
- tunable consistency at client level
- ANY
- ONE
- ALL
- QUORUM / LOCAL_QUORUM (DC only)
- SERIAL and conditional updates (IF DOES NOT EXIST)



local_quorum examples

- nodes=3, RF=3 can tolerate 1 replica being down
- nodes=5, RF=3 can tolerate 2 replica being down
- etc.



snitch (1/3)

- determines which data centers & racks nodes belong to
- informs Cassandra about the network topology
- effective routing
- replication strategy places the replicas based on snitch



snitch (2/3)

- SimpleSnitch single DC only
- GossipingPropertySnitch cassandra-rackdc.properties
- PropertyFileSnitch
 cassandra-topology.properties
- RackInferringSnitch
 determined by rack and data center, which are 3rd and 2nd octet of
 each node's IP respectively



Snitch files (examples)

cassandra-rackdc.properties

These properties are used with GossipingPropertyFileSnitch and will indicate the rack and dc for this individual node only

dc=west-dc rack=rack1

cassandra-topology.properties

These properties are used with PropertyFileSnitch and will be identical on every nodes. # Cassandra Node IP=Data Center:Rack

192.168.1.100=east-dc:rack1 192.168.1.101=east-dc:rack1 192.168.1.102=east-dc:rack1

192.168.2.100=west-dc:rack1 192.168.2.101=west-dc:rack1 192.168.2.102=west-dc:rack1



snitch (3/3)

 more deployment specific snitches for EC2, Google, Cloudstack etc.



cassandra.yaml: `endpoint_snitch`

You can use a custom Snitch by setting this to the full class name # of the snitch, which will be assumed to be on your classpath. endpoint snitch: RackInferringSnitch



seed node

- bootstrapping the gossip process for new nodes joining the cluster
- use the same list of seed nodes for all nodes in a cluster
- include at least one (1) node of each datacenter in seeds list



cassandra.yaml: `seed_provider`



Gossip

- peer-to-peer communication protocol
- discover and share location and state information about the other nodes in a Cassandra cluster
- persisted by each node
- nodes exchange state messages on regular basis





operations pain points

operations pain points

- bootstrapping new nodes / new DCs
- repairs
- hints
- tombstones
- compactions
- indexes
- sick nodes



bootstrapping new nodes / new DCs

- slow if dense nodes
- don't expect to "just add a new node" to accommodate load as it comes.
- use C* >= 2.2 (nodetool bootstrap resume)
- pressure on network
- first seed node: *nodetool rebuild -- <dc>* stream timeouts / throughput params



```
# Throttles all outbound streaming file transfers on this node to the # given total throughput in Mbps. This is necessary because Cassandra does # mostly sequential IO when streaming data during bootstrap or repair, which # can lead to saturating the network connection and degrading rpc performance. # When unset, the default is 200 Mbps or 25 MB/s.

stream_throughput_outbound_megabits_per_sec: 200
```

Throttles all streaming file transfer between the datacenters,
this setting allows users to throttle inter dc stream throughput in addition
to throttling all network stream traffic as configured with
stream_throughput_outbound_megabits_per_sec
When unset, the default is 200 Mbps or 25 MB/s
inter dc stream throughput outbound megabits per sec: 200



- # Set socket timeout for streaming operation.
- # The stream session is failed if no data/ack is received by any of the participants
- # within that period, which means this should also be sufficient to stream a large
- # sstable or rebuild table indexes.
- # Default value is 86400000ms, which means stale streams timeout after 24 hours.
- # A value of zero means stream sockets should never time out.
- # streaming_socket_timeout_in_ms: 86400000



repairs

- Anti-Entropy: QUORUM & ALL replicas compared for CF and discrepancies fixed.
- must run before `gc_grace_period` (10 days by default)
- cluster pressure
- network pressure (same as bootstrapping)
- GC fun...
- plan extra cluster capability for repairs



repairs: what to do then?

- you must define a repair strategy from the beginning
 - custom tooling
 - DSE and OpsCenter
 - Spotify Cassandra Reaper:

 https://github.com/spotify/cassandra-reaper
 https://github.com/adejanovski/cassandra-reaper
- do not necessary repair everything all the time (know your data)

hints

- if node down: spool and redelivery
- slow and broken until 3.0: must truncate manually as some are left off
- < 3.0: SSTables (which means compactions)
- >= 3.0 flat files with compression
- >= 3.0 disablehintsfordc / enablehintsfordc to selectively disable or enable hinted handoffs for a data center.
- increase hint delivery threads along with # of DCs



cassandra.yaml: `hints`

```
max hints delivery_threads: 2
# Directory where Cassandra should store hints.
# If not set, the default directory is $CASSANDRA HOME/data/hints.
# hints directory: /var/lib/cassandra/hints
# Compression to apply to the hint files. If omitted, hints files
# will be written uncompressed. LZ4, Snappy, and Deflate compressors
# are supported.
#hints compression:
   - class_name: LZ4Compressor
#
      parameters:
#
```



compactions

- process of merging SSTables to single files
- IO heavy: GC / CPU / eat disk space
- removes tombstones
- high write throughout on a single table from every nodes of every DC might eat your CPU w/ compactions: choose compaction strategy wisely!
- increment # of compactors



cassandra.yaml: `concurrent_compactors`

```
[...]
concurrent_compactors: 2
[...]
```



tombstones

- monitor for tombstones warnings
- maintenance ops issue or application level issue?



cassandra.yaml: `tombstone_warn_threshold`

```
# When executing a scan, within or across a partition, we need to keep the
# tombstones seen in memory so we can return them to the coordinator, which
# will use them to make sure other replicas also know about the deleted rows.
# With workloads that generate a lot of tombstones, this can cause performance
# problems and even exaust the server heap.
# (http://www.datastax.com/dev/blog/cassandra-anti-patterns-queues-and-queue-like-datasets)
# Adjust the thresholds here if you understand the dangers and want to
# scan more tombstones anyway. These thresholds may also be adjusted at runtime
# using the StorageService mbean.
tombstone warn threshold: 1000
```



tombstone failure threshold: 100000

indexes

- secondary indexes? SASI?
- if looking for search:
 - use DSE and its integrated search
 - check https://github.com/vroyer/elassandra
 - use another service to do the job outside C* and move / sync data



sick nodes

- what is the issue?
- remove "sick nodes" from the ring when it happens



must reads

- Datastax Apache Cassandra documentation
 - http://docs.datastax.com/en//cassandra/3.0/cassandra/ cassandraAbout.html
- Al's Cassandra 2.1 tuning guide
 - https://tobert.github.io/pages/als-cassandra-21-tuningguide.html
- cassandra-user mailing list
 - http://www.planetcassandra.org/apache-cassandra-mailing-lists/





Q&A

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