Numerical Method: Assignment 1

1. (30%) The function $f(x) = x^2 + \sin(x) - \frac{e^x}{4} - 1$ has zeros for two values near x = 0. Please compute both roots, starting with [-2, 0] and [0, 2], to attain an accuracy of 10^{-5} using the following methods: (a) the bisection method (b) the secant method, and (c) Newton's method.

Ans: Bisection method: 0.911896 and -1.431824 / Secant method: 0.911917 and -1.431807 / Newton's method: 0.911919 and -1.431809

(a) Bisection Method - m = (upper_bound + lower_bound) / 2

```
Root in [0, 2]
(N=1) a = 0.000000, b = 2.000000, root = 1.000000
(N=2) a = 0.000000, b = 1.000000, root = 1.000000
(N=3) a = 0.500000, b = 1.000000, root = 0.500000
(N=4) a = 0.750000, b = 1.000000, root = 0.750000
(N=5) a = 0.875000, b = 1.000000, root = 0.875000
(N=6) a = 0.875000, b = 0.937500, root = 0.937500
(N=7) a = 0.906250, b = 0.937500, root = 0.906250
(N=8) a = 0.906250, b = 0.921875, root = 0.921875
(N=9) a = 0.906250, b = 0.914062, root = 0.914062
(N=10) a = 0.910156, b = 0.914062, root = 0.910156
(N=11) a = 0.910156, b = 0.912109, root = 0.912109
(N=12) a = 0.911133, b = 0.912109, root = 0.911133
(N=13) a = 0.911621, b = 0.912109, root = 0.911621
(N=14) a = 0.911865, b = 0.912109, root = 0.911865
(N=15) a = 0.911865, b = 0.911987, root = 0.911987
(N=16) a = 0.911865, b = 0.911926, root = 0.911926
(N=17) a = 0.911896, b = 0.911926, root = 0.911896
```

```
Root in [-2, 0]
(N=1) a = -2.000000, b = 0.000000, root = -1.000000
(N=2) a = -2.000000, b = -1.000000, root = -1.000000
(N=3) a = -1.500000, b = -1.000000, root = -1.500000
(N=4) a = -1.500000, b = -1.250000, root = -1.250000
(N=5) a = -1.500000, b = -1.375000, root = -1.375000
(N=6) a = -1.437500, b = -1.375000, root = -1.437500
(N=7) a = -1.437500, b = -1.406250, root = -1.406250
(N=8) a = -1.437500, b = -1.421875, root = -1.421875
(N=9) a = -1.437500, b = -1.429688, root = -1.429688
(N=10) a = -1.433594, b = -1.429688, root = -1.433594
(N=11) a = -1.433594, b = -1.431641, root = -1.431641
(N=12) a = -1.432617, b = -1.431641, root = -1.432617
(N=13) a = -1.432129, b = -1.431641, root = -1.432129
(N=14) a = -1.431885, b = -1.431641, root = -1.431885
(N=15) a = -1.431885, b = -1.431763, root = -1.431763
(N=16) a = -1.431824, b = -1.431763, root = -1.431824
```

(b) Secant Method -x2 = x1 - f(x1)*(x0-x1)/[f(x0)-f(x1)]

```
Root in [0, 2]

(N=1) root = 0.754823

(N=2) root = 0.902232

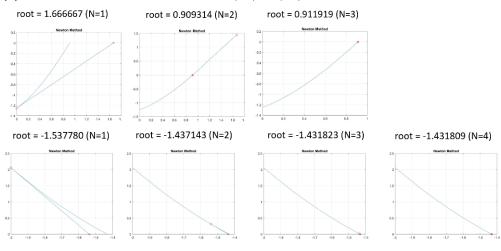
(N=3) root = 0.911491

(N=4) root = 0.911899

(N=5) root = 0.911917
```

```
Root in [-2, 0]
(N=1) root = -0.756002
                          (N=6)
                                 root = -1.431142
(N=2) root = -1.221968
                          (N=7)
                                 root = -1.431655
(N=3)
     root = -1.379027
                          (N=8)
                                 root = -1.431773
(N=4)
      root = -1.419369
                          (N=9) root = -1.431800
      root = -1.428924
(N=5)
                          (N=10) root = -1.431807
```

(c) Newton's Method -x1 = x0 - f(x0)/df(x0)



Previous result shows that

- Bisection method has two roots, 0.911896 and -1.431824
 - Divide the bracket length into half each time, check whether the root is in the left or right side of the bracket, and renew the upper or lower bound with the middle value.
- Secant method has two roots, 0.911917 and -1.431807
 Update the intersection as the bisection does, instead of taking the middle point as the new value, extract x2 from the point intersected by x-axis and secant line.
- Newton's method has two roots, 0.911919 and -1.431809

 Approximate the root by using the first derivative, extract the point that tangent line intersect with x-axis.

```
Bisection Method
main.m × bisection.m × newton.m × secant.m × +
      function [x1, xa, xb, N] = bisection(f, a, b, tol, save)
      N = 1;
      X(1) = (a+b)/2;
      A(1) = a;
      B(1) = b;
      while abs(f((a+b)/2)) > tol
          N = N+1;
          m = (a+b)/2;
          if (f(a)*f(m)<0)
10
              b = m;
          else
11
          a = m;
end
12
13
14
          if save==1
15
             X(N) = m;
16
              A(N) = a;
17
              B(N) = b;
18
19
20
21
      if save == 1
22
          x1 = X;
23
          xa = A:
24
          xb = B;
```

```
Secant Method
  main.m × bisection.m × newton.m × secant.m × +
      function [xn, N] = secant(f, x0, x1, tol, save)
 1 -
 2
       N = 2;
 3
       X(1) = x0;
      X(2) = x1;
 4
 5
       x2 = x1;
 6 E
      while abs(f(x2)) > tol
 7
          N = N+1;
           x2 = x1 - f(x1)*(x0-x1)/(f(x0)-f(x1));
 9
          if (f(x0)*f(x2)<0)
10
               x1 = x2;
11
              x0 = x2;
12
13
14
          if save==1
15
              X(N) = x2;
16
17
       end
18
19
       if save == 1
20
          xn = X:
21
```

```
Newton Method
main.m × bisection.m × newton.m × secant.m × +
      function [x1, N] = newton(f, df, x0, tol, save)
      N = 1;
2
3
      X(1) = x0;
      while abs(f(x0)) > tol
4 =
          N = N+1;
5
 6
          x1 = x0 - f(x0)/df(x0);
7
          if save == 1
8
              X(N) = x1;
9
10
          x0 = x1;
11
      end
12
13
      if save == 1
14
          x1 = X;
15 L
```

2. (25%) Use Newton's method on the polynomial $P(x) = (x-2)^3 (x-4)^2$ with $x_0 = 3$. Does it converge? To which root? Is convergence quadratic?

Ans: Converges, root x=2, the convergence is quadratic

The polynomial $P(x) = (x-2)^3 (x-4)^2$ with $x_0 = 3$ as starting value, converges at root x=2.

By Newton's method, we get the value of root=1.998900 which is the approximate value of x=2.

Since P(x) has root x=2 with multiplicity k=3, we can factor out $(x-r)^k$ from P(x) to get $P(x) = (x-r)^k * Q(x)$.

With slightly modified Newton's method, $x_{n+1} = x_n - k * \frac{p(x_n)}{p'(x_n)} = g_k(x_n)$. Although the Newton's method in fixed-point iteration form is modified, it still remains the properties:

- $\bullet \quad g'_{k}(r) = 0$
- Newton's method still converges quadratically at a root=r of multiplicity k

Therefore, the Newton.m code is slightly modified as the formula above, $x_{n+1} = x_n - k * \frac{p(x_n)}{p'(x_n)}$ when calculating the new x.

To check whether the polynomial P(x) converges at root=1.998900, we must make sure that $|g'(x)| = |\frac{p(x) p''(x)}{[p'(x)]^2}| < 1$. With the code main.m below, we can find p(x), p'(x), p''(x) at line 8, 9, 10, knowing the 3 formulas allows us to obtain the result |g'(1.998900)| = 0.00000 < 1.

To check whether the convergence is quadratic, we combine the results of

- |g'(r)| = 0 < 1
- $g(x_n) = g(r) + g'(r) * (r x_n) + g''(\alpha) * (r x_n)^2 / 2$

Therefore, $g'(r) * (r - x_n)$ can be eliminated. we get $g(x_n) = g(r) + g''(\alpha) * (r - x_n)^2 / 2$, which can be represent in the error formula.

Finally, $e_{n+1} = g(r) - g(x_n) = -g''(\alpha) * (r - x_n)^2 / 2$, in other words the convergence is quadratic.

```
Main.m
 main.m × Newton.m × +
                                                                                                     Variables - N
            clear all;
             clf;
             save = 1;
             x0 = 3;
             k=3;
             tol = 10^{(-7)};
            p = inline('x.^5 - 14*x.^4 + 76*x.^3 - 200*x.^2 + 256*x - 128', 'x');
dp = inline('5*x.^4 - 56*x.^3 + 228*x.^2 - 400*x + 256', 'x');
ddp = inline('20*x.^3 - 168*x.^2 + 456*x - 400', 'x');
g = inline('x - 3*(x.^5 - 12*x.^4 + 76*x.^3 - 200*x.^2 + 256*x - 128)/(5*x.^4 - 48*x.^3 + 228*x.^2 - 400*x + 256)', 'x');
 9
10
11
12
            [Xn, N] = Newton(p, dp, x0, k, tol, save);

dg = p(Xn(N))*ddp(Xn(N))/dp(Xn(N))*dp(Xn(N));
13
15
16
             if abs(dg)<1
17
                 fprintf("dg:%f\t-> Convergence\n", dg);
             else
18
                 fprintf("dg:%f\t-> Divergence\n", dg);
19
             end
20
             fprintf("root = %f\n", Xn(N));
21
22
            X = linspace(Xn(1), Xn(N), 100);
23
            for i=1:N-1
25
26
                  clf;
27
                  plot(X,Y);
28
                  hold on;
                  line([Xn(i), Xn(i+1)],[p(Xn(i)), 0]);
29
                  plot(Xn(i), p(Xn(i)), 'ro');
plot(Xn(i+1), 0, 'r*');
30
31
32
33
                   fprintf('(N=%i)\terror = g(2) - g(xn) = %f - %f = %f\n', i, g(2), g(Xn(i+1)), g(2)-g(Xn(i+1)));
34
35
             end
```

```
Newton.m
main.m × Newton.m × +
1 🖃
      function [x1,N] = Newton(f, df, x0, k, tol, save)
      N = 1;
2
3
      X(1) = x0;
4 🗀
      while abs(f(x0)) > tol
5
          N = N+1;
6
          x1 = x0 - k*f(x0)/df(x0);
7
          if save == 1
8
             X(N) = x1;
          end
9
10
          x0 = x1;
          f(val = f(x0))
11
12
      end
13
14
      if save == 1
15
          x1 = X;
16
      end
```

3. (30%) Below are three different g(x) functions. All are rearrangements of the same f(x). What is f(x)?

(a)
$$\frac{(4+2x^3)}{x^2}$$
 - 2x (b) $\sqrt{4/x}$ (c) $(16+x^3)/(5x^2)$

Which of them converge? What x-value is obtained? Are there starting values for which one or more diverge? Which diverge?

Ans: $f(x) = x^3-4$, (b) converges to x=1.587400 when $x\neq 0$, x=0 as starting value makes (a), (b) and (c) diverged, (a) and (c) diverges anyway

(a)
$$(4+2x^3)/x^2 - 2x = x$$

 $(4+2x^3)/x^2 = 3x$
 $4+2x^3 = 3x^3$
 $4 = x^3$
(b) $(4/x)^1/2 = x$
 $4/x = x^2$
 $4 = x^3$
(c) $(16+x^3)/(5x^2) = x$
 $16+x^3 = 5x^3$
 $16 = 4x^3$
 $4 = x^3$

From above mathematic derivation, we know $f(x) = x^3 - 4$.

When taking x0 = 0 as the starting value, the three equations all diverge. As a consequence, I set x0 = 1 as the starting value.

Only equation B converges, which converges to root x = 1.587400 when $x \neq 0$. To proof f(x) converges at root=1.587402, I calculated that $|g'(x)| = |\frac{f(x) f''(x)}{[f'(x)]^2}| = 0.000001 < 1$, which implies that root=1.587402 converges in Newton's method.

The reason why equation A diverges is that the root value(x) accidently equals 0 during the Newton's approaching process. However, we know that 0 can't be divided by any number. Therefore, when x was substituted with 0 in equation A, the number become infinity, which diverges.

As for equation C, the reason why it diverges is that the root values are looped, the g value of roots are switching between g(x) = 43.094011 and g(x) = 3.094011.

```
Equation C
            Equation A
                                             Equation B
                                          root = 2.000000
root = 2.777778
                                                                val = 43.094011
val = 3.094011
                                          root = 1.414214
                                                                 val = 43.094011
root = 0.518400
                                          root = 1.681793
root = 14.884355
                                                               val = 3.094011

val = 43.094011

val = 3.094011

val = 43.094011

val = 43.094011
                                          root = 1.542211
root = 0.018055
                                          root = 1.610490
root = 12270.437031
                                          root = 1.575981
root = 0.000000
                                          root = 1.593142
root = 5665237650236087.000000
                                          root = 1.584538
                                                                val = 3.094011
root = 0.000000
                                          root = 1.588834
                                                                 Operation terminated by user during inlineeva
root = Inf
                                          root = 1.586685
                                          root = 1.587759
root = NaN
                                          root = 1.587222
                                          root = 1.587491
                                          root = 1.587356
                                          root = 1.587423
                                          root = 1.587390
                                          root = 1.587407
                                          root = 1.587398
                                          root = 1.587402
                                          root = 1.587400
```

```
main.m × Newton.m × +
           clear all;
 1
 2
           clf;
           save = 1;
3
           f = inline('x.^3 - 4','x');
4
           df = inline('3*x.^2', 'x');
ddf = inline('6*x', 'x');
 5
 6
           %g = inline('(4+2*x.^3)/x.^2 - 2*x', 'x');
           g = inline('2/(x.^(1/2))', 'x');
%g = inline('(16+x.^3)/(5*x.^2)', 'x');
8
9
10
           x0 = 1;
11
           tol = 0.00001;
           [Xn, N] = Newton(f,g,x0,tol,save);
12
           dg = f(Xn(N))*ddf(Xn(N))/(df(Xn(N))*df(Xn(N)));
fprintf("dg = %f\n", dg)
13
14
15
16
           X = linspace(Xn(1), Xn(N), 100);
           Y = f(X);
17
           for i=1:N-1
18
                clf;
19
                plot(X,Y);
20
21
                hold on;
                line([Xn(i), Xn(i+1)],[f(Xn(i)), 0]);
plot(Xn(i), f(Xn(i)), 'ro');
22
23
24
                plot(Xn(i+1), 0, 'r*');
25
                fprintf('root = %f\n', Xn(i+1));
26
27
                pause();
28
           end
```

```
main.m × Newton.m × +
      function [x1,N] = Newton(f,g,x0,tol,save)
1 -
2
      N = 1;
3
      X(1) = x0;
4
      while abs(f(x0)) > tol
5
          N = N+1;
6
          x1 = g(x0);
7
          if save == 1
              X(N) = x1;
8
9
          end
          x0 = x1;
10
11
          fprintf('val = %f\n', abs(f(x0)))
12
13
14
      if save == 1
         x1 = X;
15
16
```

4. (30%) Solve the following system of nonlinear equations using Newton's method or fixed-point method.

$$x-3y-z^{2} = -3$$

$$2x^{3} + y - 5z^{2} = -2$$

$$4x^{2} + y + z = 7$$

Hints: There are six solutions to this system. Two of the real solutions are near (1, 1, 1) and (1.3, 0.9, -1.2). Your score of this question will depend on how many solutions you find.

Ans:

- 1. (1.111408, 0.988210, 1.070878)
- 2. (1.353748, 0.925431, -1.255969)
- 3. (31.151405, -3768.157126, -106.482969)
- 4. (32.884631, -4434.086620, 115.490885)
- 5. (-1.25060 0.04899i, 0.66505 + 0.01341i, 0.08859 0.50359i)
- 6. (-1.25060 + 0.04899i, 0.66505 0.01341i, 0.08859 + 0.50359i)

In mainNewtonRaphson.m, the three for loops aim to traverse through the range around the given solution with x decreases -0.001, y decreases -0.001 and z increases 0.1 each time. To find complex solution, use complex(a, b) function as a+bi, and modify the input and output format as 6 number with 3 pairs of (a, b).

In NewtonRaphson.m, make sure the founded solution is under $e = 10^{-5}$, and check whether the founded solution already exists.

```
mainNewtonRaphson.m × NewtonRaphson_nl_print.m × main.m × Newton.m × +
             \begin{array}{l} fn = @(v) \; [v(1) - 3^*v(2) - v(3)^2 + 3 \; ; \; 2^*v(1)^3 + v(2) - 5^*v(3)^2 + 2 \; ; \; 4^*v(1)^2 + v(2) + v(3) - 7]; \\ jacob\_fn = @(v) \; [1 \; -3 \; -2^*v(3); 6^*v(1)^2 \; 1 \; -10^*v(3); 8^*v(1) \; 1 \; 1]; \end{array} 
             error = 10^-5 :
            x_init = 2.5;
y_init = 1;
             z_init = -0.2;
             no itr = 20 ;
             roots = [];
fprintf('
                                 Iteration | x | y | z
                                                                                          | Error
11
             start = 200;
            distance = -0.2;
theand = 150;
13
            for xi = -1.865:-0.001:-1.875
15
                  for yi = 3.1:-0.001:3
for zi = 15:0.1:25
16
17
18
19
                            x_init = xi;
y_init = yi;
                             z_init = zi;
v = [x_init;y_init;z_init];
20
21
                             %fprintf("\n\% \%f\%",v(1),v(2),v(3))
[v1,no_itr,norm1,success,exists,roots]=NewtonRaphson_nl_print(v,fn,jacob_fn,no_itr,error,roots);
22
23
                             if success == 1

new = [v1(1) v1(2) v1(3)];
24
25
26
27
                                  roots = [roots;new];
28
29
                                  %s= size(roots);
30
31
                                  %display(size(roots));
                                  %display(s(2))
                                  %for j = 1:s(1)
% fprintf("%f %f %f",roots(j,1),roots(j,2),roots(j,3));
32
33
34
35
36
37
38
                  end
39
40
             s = size(roots);
41
             for j = 1:s(1)
                  fprintf("\n%f %f %f",roots(j,1),roots(j,2),roots(j,3));
42
             fprintf("\n");
```

```
mainNewtonRaphson.m × NewtonRaphson_nl_print.m × main.m × Newton.m × +
       function [v1 , no_itr, norm1, success,exists, roots] = NewtonRaphson_nl_print(v,fn,jacob_fn,no_itr,error,roo
1 -
           v1 = v;
2
           fnv1 = feval(fn,v1);
3
4
          i = 0;
5
           success=0;
7
           exists=0;
           while true
              norm1 = norm(fnv1);
%fprintf('%10d |%10.4f| %10.4f| %10.4f| %10.4d |\n',i,v1(1),v1(2),v1(3),norm1)
9
10
               jacob_fnv1 = feval(jacob_fn,v1);
11
              H = jacob_fnv1\fnv1;
12
13
               v1 = v1 - H;
14
               fnv1 = feval(fn,v1);
15
               i = i + 1;
16
               norm1 = norm(fnv1);
17
               if norm1 < error</pre>
18
                   success=1;
19
20
                   s=size(roots);
21
                   for i = 1:s(1)
22
                       dis1= abs(v1(1)-roots(i,1));
                       dis2= abs(v1(2)-roots(i,2));
23
24
                       dis3= abs(v1(3)-roots(i,3));
25
                      if (dis1+dis2+dis3)<3*1e-4</pre>
26
                          exists=1;
27
                       end
28
                   end
29
                   if exists == 0
                      fprintf('%10d
                                       |%10.4f| %10.4f | %10.4f| %10.4d |\n',i,v1(1),v1(2),v1(3),norm1)
30
                   end
31
32
                  break
               end
33
34
               if i > no_itr% && norm1 > error
35
                   fprintf("
                                fail");
36
                   %fprintf('%10d
                                     |%10.4f| %10.4f | %10.4f| %10.4d | fail\n',i,v1(1),v1(2),v1(3),norm1)
37
                   break;
38
               end
39
```