

# CS 524: Introduction to Optimization

## Lecture 34 : Stochastic Programming

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# Stochastic Programming

## \$64 Question

- What does “Programming” mean in “Mathematical Programming”, “Linear Programming”, etc...?

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- **Answer:** Planning.
  - Mathematical Programming (Optimization) is about decision making, or planning.
  - Stochastic Programming is about decision making *under uncertainty*.
  - View it as “Mathematical Programming with random parameters”

# Dealing With Randomness

- Typically, randomness is ignored, or it is dealt with by
  - ▶ Sensitivity analysis
    - ★ Look at effects of certain perturbations of the data
    - ★ For large-scale problems, sensitivity analysis is useless
  - ▶ “Careful” determination of instance parameters
    - ★ No matter how careful you are, you can’t get rid of inherent randomness.
- Stochastic Programming is **the** way!<sup>1</sup>

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<sup>1</sup>This is not necessarily true, but humor me for the time being

# Applications of Optimization under Uncertainty

- Generation of electrical power
  - ▶ Utilities must decide how much power to produce **before knowing demand**
  - ▶ Wind supply is also highly stochastic
- Reservoir operation
  - ▶ Flood control or recreation or irrigation or power supply
  - ▶ How much water can/should be released?
- Portfolio Selection: Returns are uncertain
- Inventory management: our newsvendor problem today

# Three Ways for Modeling Uncertainty

- ① Deterministic modeling: The uncertainty plays no role.
  - ▶ Often, modelers know there are obviously important uncertainties, but can use only a “point estimate” (e.g. mean values) of the uncertainty.
  - ▶ Not enough is known about the uncertainty
  - ▶ They don't have software available for getting numerical solutions
- ② Stochastic Modeling
  - ▶ Uncertain elements are treated as random variables, so probability theory may be applied
  - ▶ The elements must have a “known” probability distribution
  - ▶ Sometimes the distribution comes from a statistical model, or it is an educated guess (subjective probabilities): mathematical treatment is the same
- ③ Range Modeling (robust optimization)
  - ▶ Uncertain probabilities: The actual distribution will be chosen by “an adversary” (Mother Nature) from a limited range of distributions.
  - ▶ Range modeling can be combined with stochastic modeling, by assuming that a probability distribution is present, but not completely known.

# Hot Off the Presses

- A paperboy (news vendor) needs to decide how many papers  $x$  to buy in order to maximize his profit.
- He doesn't know at the beginning of the day how many papers he can sell (his demand).
  - ▶ Each newspaper costs  $c$ .
  - ▶ He can sell each newspaper for a price of  $q$ .
  - ▶ He can return each unsold newspaper at the end of the day for  $r$ .
  - ▶ The demand is  $D$ .

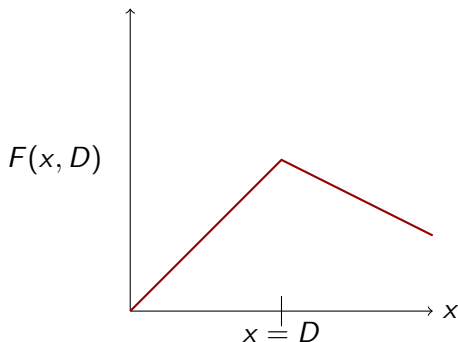
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## News vendor Profit

$$F(x, D) = \begin{cases} (q - c)x & \text{if } x \leq D \\ qD + r(x - D) - cx & \text{if } x > D \end{cases}$$

# Profit Function

- Marginal profit:  $(q - c)$  if can sell all:  $x \leq D$
  - Marginal loss:  $(c - r)$  if have to salvage
- 



$$F(x, D) = \min\{(q - c)x, (q - r)D + (r - c)x\}$$

# What Should We Do?

- Optimize, silly:

$$\max_{x \geq 0} F(x, D).$$

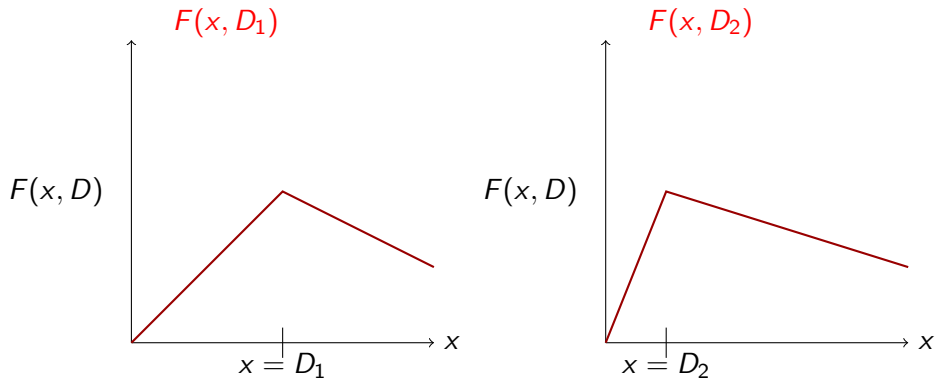


- This problem **does not make sense!**
- You can't optimize something random!

[http://en.wikipedia.org/wiki/Chewbacca\\_defense](http://en.wikipedia.org/wiki/Chewbacca_defense)



# The Function is Random



- One  $x$  can't simultaneously optimize both functions

## (Silly) Idea

- Let's assume that  $D$  is a random variable with cumulative distribution function (cdf)  $H(t) \stackrel{\text{def}}{=} \text{Prob}(D \leq t)$
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### Plan for Average Case

- Let  $\mu \stackrel{\text{def}}{=} \mathbb{E}[D]$  be the mean value of demand
- In this case: (proof by picture)

$$\max_{x \geq 0} F(x, \mu) \Rightarrow x^* = \mu.$$

- In this case, the optimal policy is to purchase  $\mu$
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### The Flaw of Averages

- We will see that this can be *far* from optimal when your problem takes more uncertainty into account

# Scenario Modeling

- The most common representation of uncertainty (in stochastic programming) is via a list of **scenarios**, which are specific representations of how the future will unfold.
- Think of these as  $\xi^1, \xi^2, \dots, \xi^S$ , with  $\xi^j \in \Xi$

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## What we CAN'T do

- Planners often generate a **solution for each scenario** generated—“What-if” analysis.
- Each solution yields a prescription of what should be done **if** the scenario occurs, but there is no theoretical guidance about the compromise between those prescriptions
- Is there a **systematic** way to generate **one** solution or policy to follow that will achieve a “good” objective with respect to all scenarios?

# Stages and Decisions

- The newsvendor problem is a classical “recourse problem”:
    - ① We make a decision now (**first-stage decision**)
    - ② Nature makes a random decision (**“stuff” happens**)
    - ③ We make a second-stage decision that attempts to repair the havoc wrought by nature in (2) (**recourse**)
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## Key Idea

The **evolution** of information is of paramount importance

# Newsvendor SP

- Suppose that

$$\Omega = \{d_1, d_2, \dots, d_{|S|}\}$$

- So there are a finite set of **scenarios**  $S$ , each with associated probability  $p_s$ . ( $\sum_{s \in S} p_s = 1$ )

## Parameters

- $d_s$ : Demand for newspapers in scenario  $s$
- $p_s$ : Probability of scenario  $s$

## Variables

- $x$ : Number to purchase
- $y_s$ : Number to sell in scenario  $s$
- $z_s$ : Number to salvage in scenario  $s$

# News vendor Stochastic LP (newsvendor.gms)

Note: in our example first stage decision is  $x$ , random decision is  $D$  and second-stage decisions are amount to sell  $y$  and amount to return  $z$

$$\max -cx + \sum_{s \in S} p_s(qy_s + rz_s)$$

s.t.

$$\begin{aligned}d_s &\geq y_s & \forall s \in S \\x - y_s &= z_s & \forall s \in S \\x &\geq 0 \\y_s, z_s &\geq 0 & \forall s \in S\end{aligned}$$

$$F(x, D) = \min\{(q - c)x, (q - r)D + (r - c)x\}$$

- $q = 2, c = 0.3, r = 0.05$
- $D$  a random variable with cdf  $H_D(t)$
- Demand: Normally distributed.  $\mu = 100, \sigma = 20$

## • Mean Value Solution

- ▶ Buy 100.
- ▶ TRUE long run profit  $\approx 155$

(Duh!)

## • Stochastic Solution

- ▶ Buy 123 =  $H^{-1}(2 - 0.3/(2 - 0.05))$  (e.g. `stolib.icdfnormal`)
- ▶ TRUE long run profit  $\approx 163$
- ▶ Note: we can show that

$$x^* = H^{-1}\left(\frac{q - c}{q - r}\right).$$

- The difference between the two solutions ( $163 - 155$ ) is called the *value of the stochastic solution*.

# Out of sample testing

- Make sure you kick the model around by testing on similar but not identical data (sensitivity)
- If you solve a stochastic program, ensure that you **a-posteriori** take a completely new sample and evaluate your solution on that sample: **this is called out-of-sample testing**
- Once we have a solution  $x^*$  we can evaluate the **true solution** or an out of sample estimate of it by:
  - 1 generate lots of new samples  $\hat{d}_1, \hat{d}_2, \dots, \hat{d}_N$
  - 2 evaluate

$$\frac{1}{N} \sum_{i=1}^N F(x^*, \hat{d}_i)$$

(no optimization, just evaluation of  $F$ )

- this is an estimate of the true solution (as reported above)



## Put Another Way

- We could write the objective for the newsvendor problem in the form:

$$F(x, D) = -cx + \mathbb{E}Q(x, D),$$

where

$$Q(x, D) = \max_{y \geq 0, z \geq 0} \{qy + rz \mid y \leq D, y + z = x\}.$$

- $Q(x, D)$  is the **optimal recourse function**: Given that we have chosen  $x$  and observed demand  $D$ , what should I do to maximize profit?

# It's Not Always So Easy

- For the newsvendor the recourse function:  $Q(x, D)$  has a simple closed form:

$$Q(x, D) = \min\{qx, qD + r(x - D)\}$$

but in general it will not. For two-stage stochastic linear programming, it will be the optimal value of a linear program (as we demonstrated even in this case above)

- Note that sampling in GAMS is demonstrated in the `newsvendor.gms` file, and more information is available at [https://www.gams.com/latest/docs/UG\\_ExtrinsicFunctions.html](https://www.gams.com/latest/docs/UG_ExtrinsicFunctions.html)

# A Take Away Message

## The “Flaw” of Averages

- The flaw of averages occurs when uncertainties are replaced by “single average numbers” planning.
    - ▶ Did you hear the one about the statistician who drowned fording a river with an average depth of three feet.
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## Point Estimates

- If you are planning a point estimates, then you are planning sub-optimally
- It doesn't matter how carefully you choose the point estimate – it is impossible to hedge against future uncertainty by considering **one** realization of the uncertainty in your planning process